

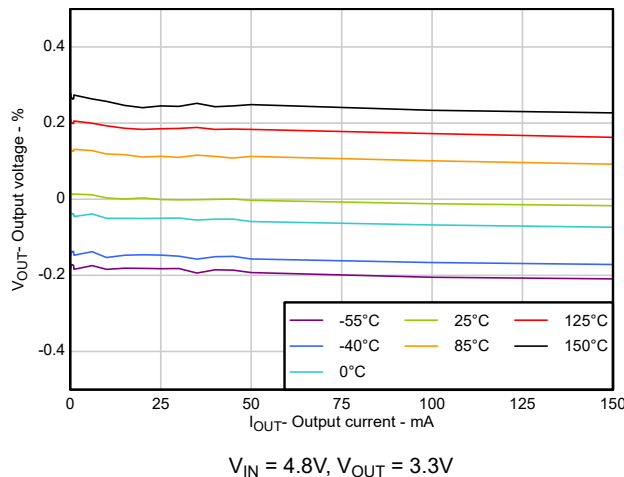
# TPS7E81 150mA, 40V, 2.8μA Low I<sub>Q</sub> Low-Dropout Regulator

## 1 Features

- Input voltage range: 3.0V to 40V (42V max)
- Available output voltage options:
  - Fixed: 1.8V to 12V
  - Adjustable: 1.2V to 38V
- Output current: Up to 150mA
- ±1.2% accuracy across line, load and temperature
- Ultra-low I<sub>Q</sub>: 2.8μA at I<sub>OUT</sub> = 0mA
- Stable with 2.2μF or larger ceramic capacitors
  - ESR range: 0Ω to 1Ω
- Dropout voltage: 450mV (typical) at 150mA
- High PSRR:
  - 70dB at 1kHz
  - 45dB at 100kHz
- Over-current, over-power and over-temperature limiting
- Package:
  - 5-pin SOT-23 (DBV) [R<sub>θJA</sub>: 190.9°C/W]
  - 6-pin WSON (DRV) [R<sub>θJA</sub>: 90.2°C/W]
- Operating junction temperature: –40°C to +125°C

## 2 Applications

- [Appliances](#)
- [Home and building automation](#)
- [Retail automation and payment](#)
- [Grid infrastructure](#)
- [Medical applications](#)
- [Lighting applications](#)



**Figure 2-1. V<sub>OUT</sub> Accuracy vs I<sub>OUT</sub>**

## 3 Description

The TPS7E81 low-dropout (LDO) linear voltage regulator is a low quiescent current device and supports a wide input voltage range of 3V to 40V. The wide output range is 1.2V to 38V for the adjustable configuration, 1.8V to 12V for the fixed configuration, and a load current of up to 150mA is supported. With only a 2.8μA quiescent current at no-load, the device is designed to power microcontrollers and other low-power loads for battery-powered applications.

The TPS7E81 supports very tight DC accuracy of ±1.2% over line, load, and temperature range. The device responds quickly to line and load transients. The low quiescent current (2.8μA typically) during regulation and controlled I<sub>Q</sub> even in dropout operation (12μA typically in no-load dropout) makes this device designed for battery-powered or always-on systems that require very little idle-state power dissipation.

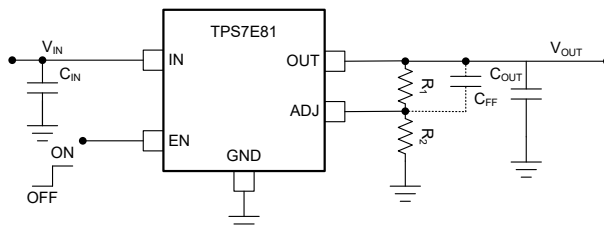
The TPS7E81 supports a low dropout of typically 450mV at 150mA of load current. The device has a built-in protection mechanism for over-current, over-temperature, and over-power delivery for reliable operation of the LDO. The TPS7E81 is stable with an output capacitor range of 2.2μF to 100μF.

### Package Information

PART NUMBER	PACKAGE <sup>(1)</sup>	PACKAGE SIZE <sup>(2)</sup>
TPS7E81	DBV (SOT-23, 5)	2.9mm × 2.8mm
	DRV (WSON, 6)	2.0mm × 2.0mm

- (1) For more information, see the [Mechanical, Packaging, and Orderable Information](#).
- (2) The package size (length × width) is a nominal value and includes pins, where applicable.



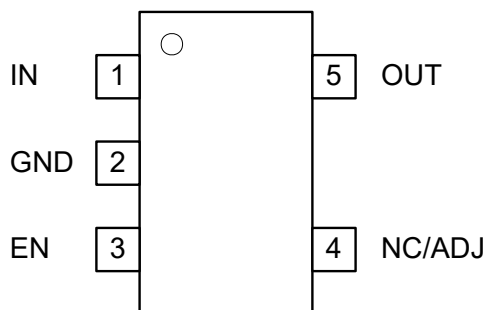


**Typical Application**

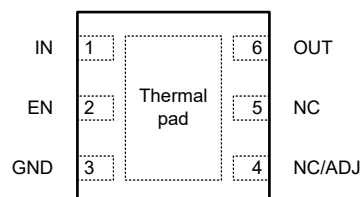
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## 4 Pin Configuration and Functions



**Figure 4-1. DBV Package, (Fixed/ADJ), 5-Pin SOT-23 (Top View)**



**Figure 4-2. DRV Package (Fixed/ADJ), 6-Pin WSON (Top View)**

**Table 4-1. Pin Functions**

PIN			TYPE	DESCRIPTION
NAME	No.			
	DBV	DRV		
GND	2	3	—	Ground pin.
IN	1	1	Input	Input supply pin. See the <a href="#">Recommended Operating Conditions</a> table and the <a href="#">Input and Output Capacitor Selection</a> section for more information.
OUT	5	6	Output	Output of the regulator. A capacitor is required from OUT to ground for stability. For best transient response, use the nominal recommended value or larger ceramic capacitor from OUT to ground; see the <a href="#">Recommended Operating Conditions</a> table and the <a href="#">Input and Output Capacitor Selection</a> section. Place the output capacitor as close to output of the device as possible.
EN	3	2	Input	Enable pin. Driving the enable pin high enables the device. Driving this pin low disables the device. High and low thresholds are listed in the <a href="#">Electrical Characteristics</a> table. This pin has a weak internal pullup and can be left floating to enable the device or the pin can be connected to the input pin. Refer to the <a href="#">Enable (EN)</a> section for more details.
NC/ADJ	4	4	Input	When using the adjustable device, this pin sets the output voltage with the help of a feedback divider. In the adjustable configuration, this pin must be connected through a resistor divider to the output for the device to function. If using a fixed output device, this pin is not internally connected and can either be left floating or connected to GND.
NC	—	5	—	Not internally connected. Leave this pin open or connected to any potential. Tie this pin to ground for improved thermal performance.
Thermal pad				Thermal pad. Connect the pad to GND for the best possible thermal performance. See the <a href="#">Layout</a> section for more information.

## 5 Specifications

### 5.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted)<sup>(1)</sup>

		MIN	MAX	UNIT
Voltage	V <sub>IN</sub>	−0.3	42.0	V
	V <sub>OUT</sub> (for fixed device only)	2 × V <sub>OUT(nom)</sub> or −0.3 V <sub>IN</sub> + 0.3 or 15.0 (whichever is lower)		
	V <sub>OUT</sub> (for adjustable device only)	−0.3	V <sub>IN</sub> + 0.3 <sup>(2)</sup>	
	V <sub>FB</sub> (Feedback voltage)	−0.3	3.6	
	V <sub>EN</sub> (Enable voltage)	−0.3	42.0	
Current	I <sub>OUT</sub> (Output current)	Internally limited		mA
Temperature	T <sub>J</sub> , Operating junction	−55	150	°C
	T <sub>stg</sub> , Storage	−65	150	°C

- (1) Operation outside the *Absolute Maximum Ratings* may cause permanent device damage. *Absolute Maximum Ratings* do not imply functional operation of the device at these or any other conditions beyond those listed under *Recommended Operating Conditions*. If used outside the *Recommended Operating Conditions* but within the *Absolute Maximum Ratings*, the device may not be fully functional, and this may affect device reliability, functionality, performance, and shorten the device lifetime.
- (2) The absolute maximum rating is V<sub>IN</sub> + 0.3V or 42.0V, whichever is smaller.

### 5.2 ESD Ratings

				VALUE	UNIT
V <sub>(ESD)</sub>	Electrostatic discharge	Human body model (HBM), per AEC Q100-002 <sup>(1)</sup>		±2000	V
		Charged device model (CDM), per AEC Q100-011	Corner pins	±750	
			Other pins	±750	

- (1) AEC Q100-002 indicates that HBM stressing shall be in accordance with the ANSI/ESDA/JEDEC JS-001 specification.

### 5.3 Recommended Operating Conditions

over operating junction temperature range (unless otherwise noted)

		MIN	NOM	MAX	UNIT
V <sub>IN</sub>	Input supply voltage range	3.0		40	V
V <sub>OUT</sub>	Output voltage range (Fixed only) <sup>(1)</sup>	1.2		12	V
V <sub>OUT</sub>	Output voltage range (Adjustable only) <sup>(1)</sup>	1.2		38	V
V <sub>EN</sub>	Enable voltage range	0		40	V
I <sub>OUT</sub>	Output current	0		150	mA
C <sub>IN</sub>	Input capacitor <sup>(2)</sup>		0.47		μF
C <sub>OUT</sub>	Output capacitor <sup>(3)</sup>	2.2		100	μF
C <sub>FB</sub>	ADJ to GND capacitor <sup>(4)</sup>			15	pF
C <sub>FF</sub>	Feed-forward capacitor <sup>(5)</sup>		10		nF
T <sub>J</sub>	Operating junction temperature	−40		125	°C

- (1) This output voltage range does not include device accuracy or accuracy of the feedback resistors.
- (2) An input capacitor is not required for LDO stability. However, an input capacitance with an effective value of 0.1μF minimum is recommended to counteract the effect of source resistance and inductance, which can in some cases cause symptoms of system level instability such as ringing or oscillation, especially in the presence of load transients.
- (3) All capacitor values listed are the nominal value and the effective capacitance is assumed to derate to 50% of the nominal capacitor value.
- (4) The upper limit for the capacitor on the ADJ pin with respect to GND impacts the stable operation of the voltage regulator in adjustable configuration. For C<sub>FB</sub> capacitor higher than limits mentioned in *Recommended Operating Conditions* table, use C<sub>FF</sub> capacitor.

- (5) The  $C_{FF}$  capacitor improves transient, noise, and PSRR performance, but is not required for regulator stability. Using a higher capacitance  $C_{FF}$  is permissible but start-up time increases.

## 5.4 Thermal Information

THERMAL METRIC <sup>(1)</sup>		TPS7E81		UNIT
		DRV (WSON) <sup>(2)</sup>	DBV (SOT-23) <sup>(2)</sup>	
		6 PINS	5 PINS	
$R_{\theta JA}$	Junction-to-ambient thermal resistance	90.2	190.9	°C/W
$R_{\theta JC(top)}$	Junction-to-case (top) thermal resistance	113.5	89.6	°C/W
$R_{\theta JB}$	Junction-to-board thermal resistance	55.7	60.0	°C/W
$\Psi_{JT}$	Junction-to-top characterization parameter	13.0	28.3	°C/W
$\Psi_{JB}$	Junction-to-board characterization parameter	55.3	59.7	°C/W
$R_{\theta JC(bot)}$	Junction-to-case (bottom) thermal resistance	30.6	n/a	°C/W

- (1) For more information about traditional and new thermal metrics, see the [Semiconductor and IC Package Thermal Metrics](#) application note.
- (2) Thermal performance results are based on the JEDEC standard of 2s2p PCB configuration. These thermal metric parameters are further improved by 35-55% based on thermally optimized PCB layout designs. See the analysis of the [Impact of board layout on LDO thermal performance](#) application note.

## 5.5 Electrical Characteristics

Over operating junction temperature range ( $T_J = -40^{\circ}\text{C}$  to  $+150^{\circ}\text{C}$ ),  $V_{IN} = 3.0\text{V}$  or  $V_{IN} = V_{OUT(nom)} + 0.5\text{V}$  (whichever is greater),  $I_{OUT} = 1\text{mA}$ ,  $V_{EN} = 2.0\text{V}$ ,  $C_{IN} = 1.0\mu\text{F}$ ,  $C_{OUT} = 2.2\mu\text{F}$ , unless otherwise noted. Typical values are at  $T_J = 25^{\circ}\text{C}$ .

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
$V_{FB}$	Feedback voltage			1.2		V
$V_{UVLO+}$	Rising input supply UVLO	$V_{IN}$ rising		2.8	2.91	V
$V_{UVLO-}$	Falling input supply UVLO	$V_{IN}$ falling	2.6	2.7		V
$V_{UVLO(HYST)}$	$V_{UVLO}$ hysteresis			100		mV
$V_{OUT}$	Output voltage	$V_{IN} = V_{OUT} + 0.5\text{V}$ , $I_{OUT} = 1\text{mA}$ , $T_J = 25^{\circ}\text{C}$	-0.3		0.3	%
$V_{OUT}$	Output voltage	$V_{OUT} + 1.0\text{V} \leq V_{IN} \leq 40\text{V}$ , $I_{OUT} = 35\text{mA}$ , $T_J = 25^{\circ}\text{C}$	-0.7		0.7	%
		$V_{OUT} + 1.0\text{V} \leq V_{IN} \leq 40\text{V}$ , $I_{OUT} = 35\text{mA}$	-1.2		1.2	
		$1\text{mA} \leq I_{OUT} \leq 150\text{mA}$ , $1.0\text{V} \leq V_{IN} - V_{OUT} \leq 25\text{V}$	-1.2		1.2	
$\Delta V_{OUT}(\Delta V_{IN})$	Line regulation	$I_{OUT} = 1\text{mA}$ , $V_{OUT} + 0.5\text{V} \leq V_{IN} \leq 40\text{V}$			10	mV
$\Delta V_{OUT}(\Delta I_{OUT})$	Load regulation	$1\text{mA} \leq I_{OUT} \leq 150\text{mA}$ , $V_{IN} = V_{OUT} + 1.0\text{V}$			18	mV
$\Delta\%V_{OUT}/\Delta I_{OUT}$					2	%/A
$V_{DO}$	Dropout voltage	$I_{OUT} = 150\text{mA}$		0.46	0.85	V
		$I_{OUT} = 150\text{mA}$ , for adjustable		0.49	0.9	
$V_{DO}$	Dropout voltage	$I_{OUT} = 100\text{mA}$		0.3	0.55	V
		$I_{OUT} = 100\text{mA}$ , for adjustable		0.32	0.56	
$I_{LIM}$	Output current limit	$V_{OUT}$ forced at $0.9 \times V_{OUT(nom)}$ , $V_{IN} = V_{OUT(nom)} + 1.0\text{V}$	180	250	325	mA
$I_{SC}$	Short-circuit current limit	$R_{LOAD} = 20\text{ m}\Omega$	10	30	55	mA
$I_{PLIMIT}$	Current limit at max headroom	$V_{IN} = 40\text{V}$ , $V_{OUT} = 1.2\text{V}$			15	mA
$V_{HEADROOM}$	Max headroom at full load	$V_{OUT} = 1.2\text{V}$			25	V
$I_{FB}$	Feedback current	$V_{IN} = 40\text{V}$			25	nA
$I_Q$	Quiescent current	$3.0\text{V} \leq V_{IN} \leq V_{OUT} - 0.2\text{V}$ , $I_{OUT} = 0\text{mA}$		12.5	25	$\mu\text{A}$
		$I_{OUT} = 0\text{mA}$		2.8	6.0	
		$V_{OUT} + 0.5\text{V} \leq V_{IN} \leq 40\text{V}$ , $I_{OUT} = 0\text{mA}$			7.6	

Over operating junction temperature range ( $T_J = -40^{\circ}\text{C}$  to  $+150^{\circ}\text{C}$ ),  $V_{IN} = 3.0\text{V}$  or  $V_{IN} = V_{OUT(nom)} + 0.5\text{V}$  (whichever is greater),  $I_{OUT} = 1\text{mA}$ ,  $V_{EN} = 2.0\text{V}$ ,  $C_{IN} = 1.0\mu\text{F}$ ,  $C_{OUT} = 2.2\mu\text{F}$ , unless otherwise noted. Typical values are at  $T_J = 25^{\circ}\text{C}$ .

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
$I_{GND}$	Ground current	$I_{OUT} = 1\text{mA}$		16.5	25	$\mu\text{A}$
$I_{GND}$	Ground current	$V_{IN} = V_{OUT} + 1.0\text{V}$ , $I_{OUT} = 150\text{mA}$			370	$\mu\text{A}$
$I_{SHUTDOWN}$	Shutdown current	$V_{EN} = 0\text{V}$ , $T_J = 25^{\circ}\text{C}$		0.45		$\mu\text{A}$
		$V_{OUT} + 0.5\text{V} \leq V_{IN} \leq 40\text{V}$ , $V_{EN} = 0\text{V}$			1.5	
$T_{start-up}$	Start-up time	$V_{IN}$ , $V_{EN}$ tied together, $V_{IN}$ ramped to $V_{OUT(nom)} + 0.5\text{V}$ , $I_{OUT} = 0\text{mA}$		500		$\mu\text{s}$
$I_{EN}$	EN pin current	$0\text{V} \leq V_{EN} \leq 40\text{V}$ , $V_{IN}$ and $V_{EN}$ tied together			0.3	$\mu\text{A}$
		$0\text{V} \leq V_{IN} \leq 40\text{V}$ , $V_{EN} = 0\text{V}$	-0.5			
$V_{IL(EN)}$	EN pin low-level input voltage (disable device)				0.46	V
$V_{IH(EN)}$	EN pin high-level input voltage (enable device)		1.1			
$V_{HYST(EN)}$	EN pin hysteresis (enable device)			0.13		V
PSRR	Power-supply ripple rejection	$V_{IN} - V_{OUT} = 2.0\text{V}$ , $I_{OUT} = 150\text{mA}$ , $f = 100\text{kHz}$		45		dB
$V_n$	Output noise voltage	Bandwidth = 10Hz to 100kHz, $V_{IN} - V_{OUT} = 2.0\text{V}$ , $I_{OUT} = 150\text{mA}$		650		$\mu\text{VRMS}$
$T_{sd+}$	Thermal shutdown temperature increasing	Shutdown, temperature increasing	163			$^{\circ}\text{C}$
$T_{sd-}$	Thermal shutdown temperature decreasing	Reset, temperature decreasing	150			$^{\circ}\text{C}$
$R_{Discharge}$	Output discharge resistance	$V_{IN} = 3.0\text{V}$ , $V_{EN} = 0\text{V}$ , $T_J = 25^{\circ}\text{C}$ , $I_{OUT} = 1\text{mA}$		780		$\Omega$
$I_{SINK}$	Sink current on output	$V_{OUT} = V_{OUT} \times 1.05$ , $T_J = 25^{\circ}\text{C}$		3.3		mA

## 5.6 Typical Characteristics

at operating junction temperature  $T_J = 25^\circ\text{C}$ ,  $V_{IN} = 3.0\text{V}$  or  $V_{IN} = V_{OUT}(\text{nom}) + 1.0\text{V}$  (whichever is greater),  $C_{IN} = 1\mu\text{F}$ ,  $C_{OUT} = 2.2\mu\text{F}$ ,  $V_{EN} = 2\text{V}$ , and  $I_{OUT} = 1\text{mA}$  (unless otherwise noted)

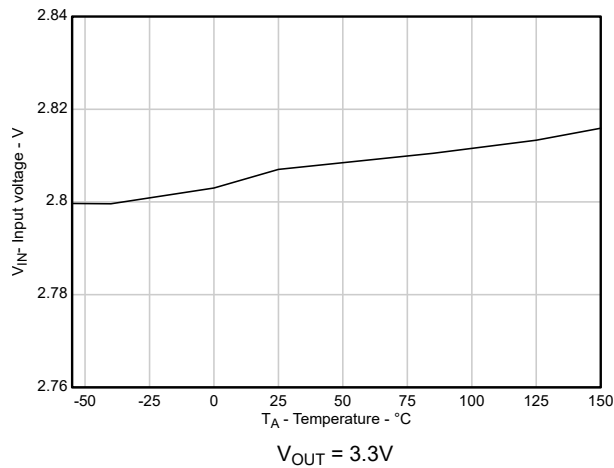


Figure 5-1. Rising Input Supply UVLO vs Temperature

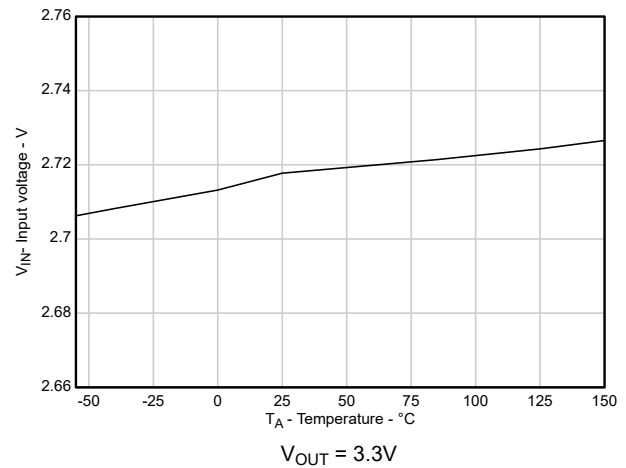


Figure 5-2. Falling Input Supply UVLO vs Temperature

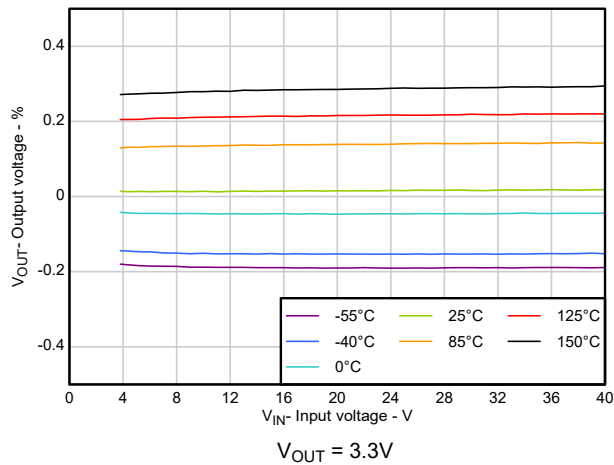


Figure 5-3. Accuracy vs Input Voltage

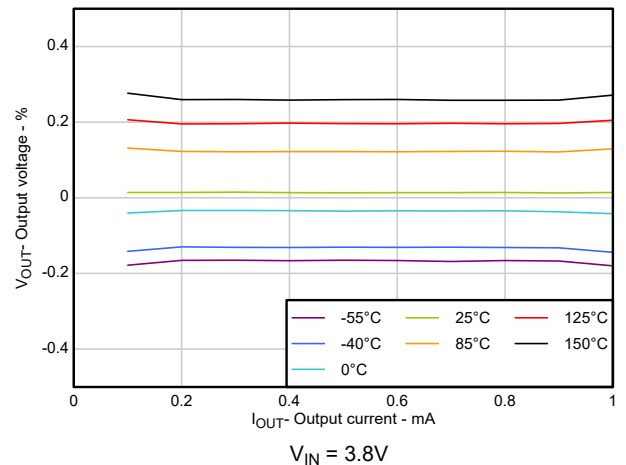


Figure 5-4. Accuracy vs Output Current

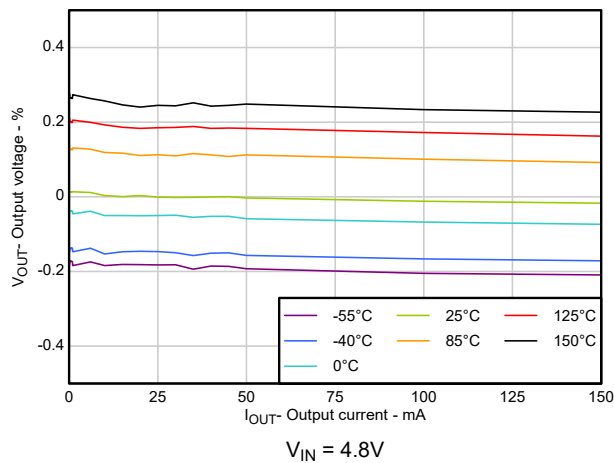


Figure 5-5. Accuracy vs Output Current

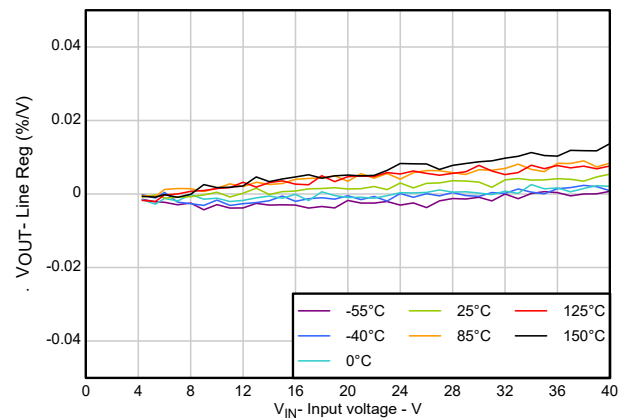
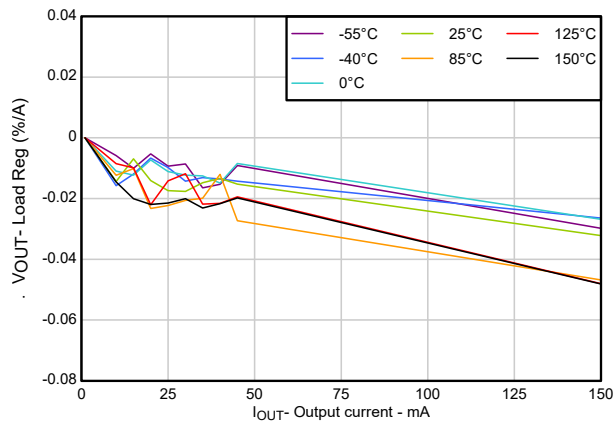


Figure 5-6. Line Regulation vs Input Voltage

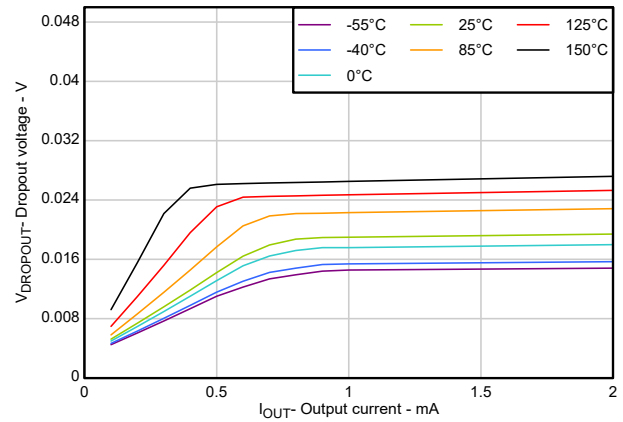


## 5.6 Typical Characteristics (continued)

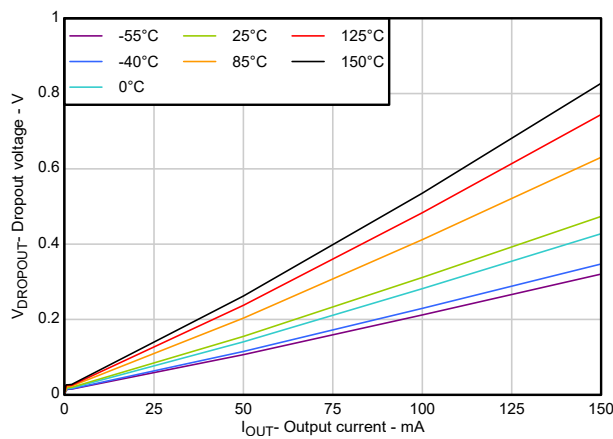
at operating junction temperature  $T_J = 25^\circ\text{C}$ ,  $V_{IN} = 3.0\text{V}$  or  $V_{IN} = V_{OUT}(\text{nom}) + 1.0\text{V}$  (whichever is greater),  $C_{IN} = 1\mu\text{F}$ ,  $C_{OUT} = 2.2\mu\text{F}$ ,  $V_{EN} = 2\text{V}$ , and  $I_{OUT} = 1\text{mA}$  (unless otherwise noted)



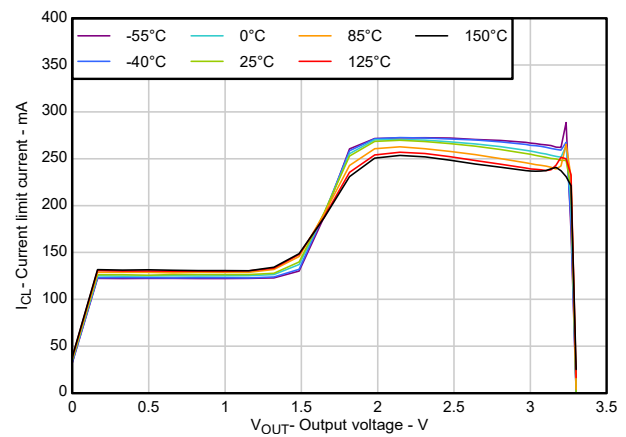
**Figure 5-7. Load Regulation vs Output Current**



**Figure 5-8. Dropout Voltage vs Output Current, Light Loads**



**Figure 5-9. Dropout vs Output Current**



**Figure 5-10. Current Limit vs Output Voltage**

## 5.6 Typical Characteristics (continued)

at operating junction temperature  $T_J = 25^\circ\text{C}$ ,  $V_{IN} = 3.0\text{V}$  or  $V_{IN} = V_{OUT}(\text{nom}) + 1.0\text{V}$  (whichever is greater),  $C_{IN} = 1\mu\text{F}$ ,  $C_{OUT} = 2.2\mu\text{F}$ ,  $V_{EN} = 2\text{V}$ , and  $I_{OUT} = 1\text{mA}$  (unless otherwise noted)

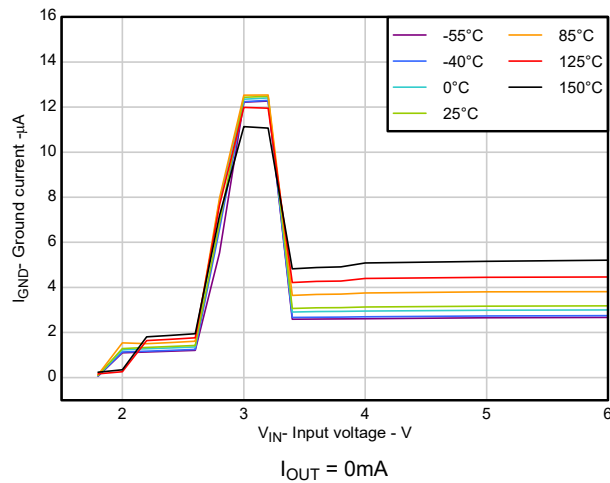


Figure 5-11. Ground Current vs Input Voltage

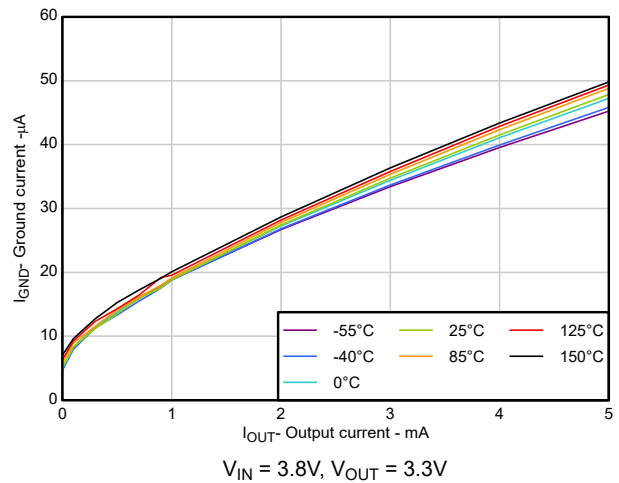


Figure 5-12. Ground Current vs Output Current

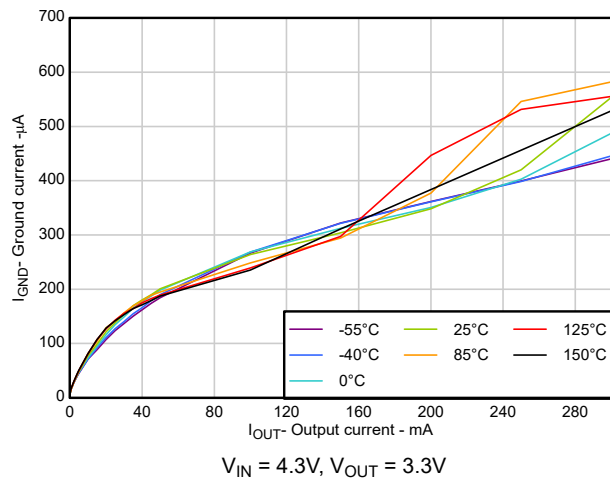


Figure 5-13. Ground Current vs Output Current

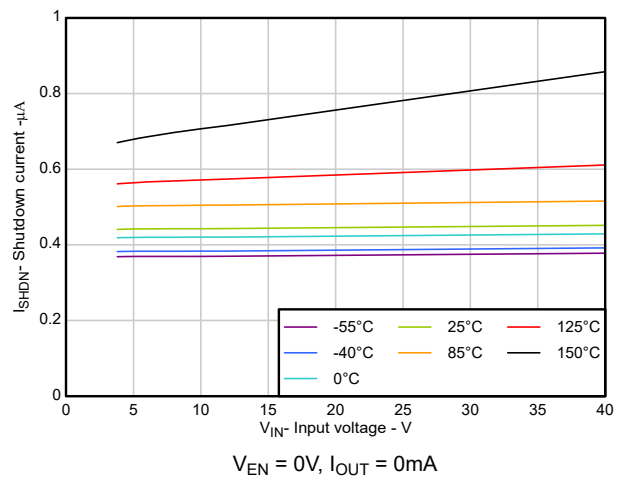


Figure 5-14. Shutdown Current vs Input Voltage

## 5.6 Typical Characteristics (continued)

at operating junction temperature  $T_J = 25^\circ\text{C}$ ,  $V_{IN} = 3.0\text{V}$  or  $V_{IN} = V_{OUT}(\text{nom}) + 1.0\text{V}$  (whichever is greater),  $C_{IN} = 1\mu\text{F}$ ,  $C_{OUT} = 2.2\mu\text{F}$ ,  $V_{EN} = 2\text{V}$ , and  $I_{OUT} = 1\text{mA}$  (unless otherwise noted)

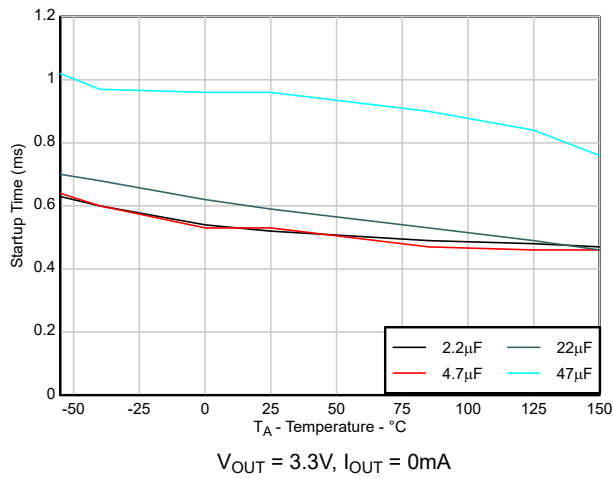


Figure 5-15. Start-up Time vs Temperature,  $C_{OUT}$

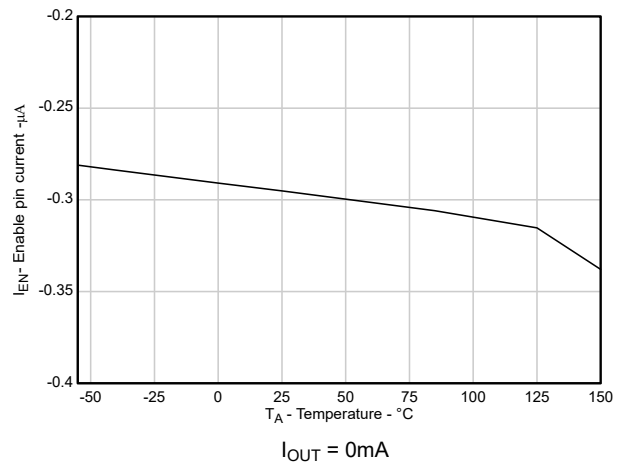


Figure 5-16. Enable Pin Leakage Current vs Temperature

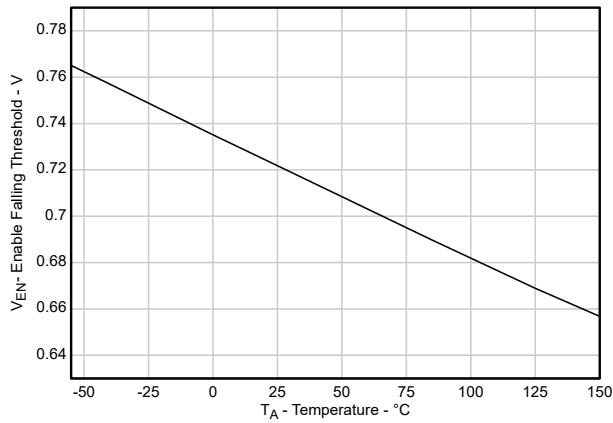


Figure 5-17. Enable Pin Low-Level Input Voltage vs Temperature

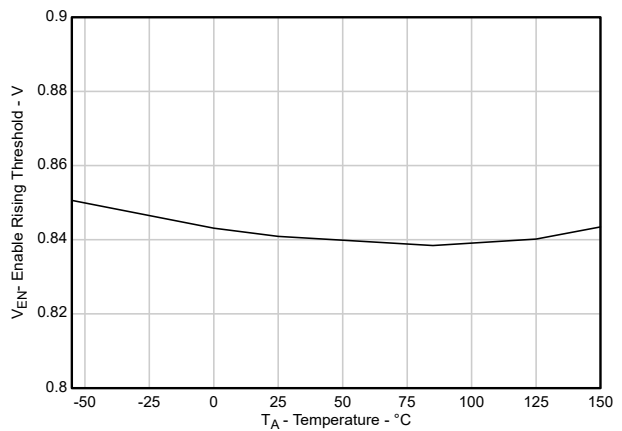


Figure 5-18. Enable Pin High-Level Input Voltage vs Temperature

## 5.6 Typical Characteristics (continued)

at operating junction temperature  $T_J = 25^\circ\text{C}$ ,  $V_{IN} = 3.0\text{V}$  or  $V_{IN} = V_{OUT}(\text{nom}) + 1.0\text{V}$  (whichever is greater),  $C_{IN} = 1\mu\text{F}$ ,  $C_{OUT} = 2.2\mu\text{F}$ ,  $V_{EN} = 2\text{V}$ , and  $I_{OUT} = 1\text{mA}$  (unless otherwise noted)

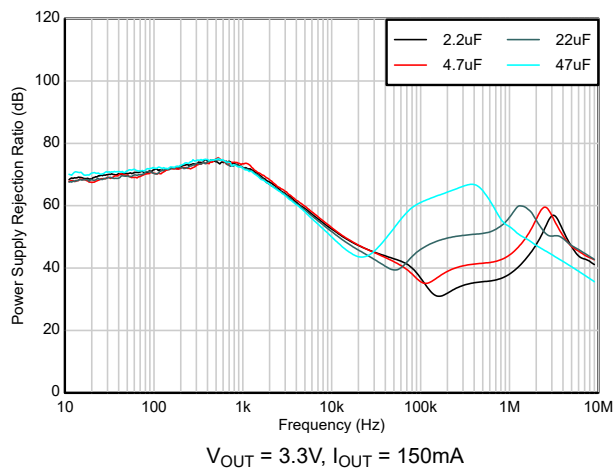


Figure 5-19. Ripple Rejection vs Frequency,  $C_{OUT}$

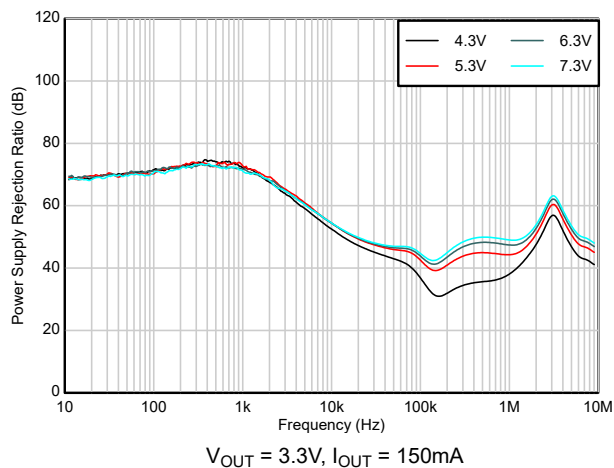


Figure 5-20. Ripple Rejection vs Frequency, Input Voltage

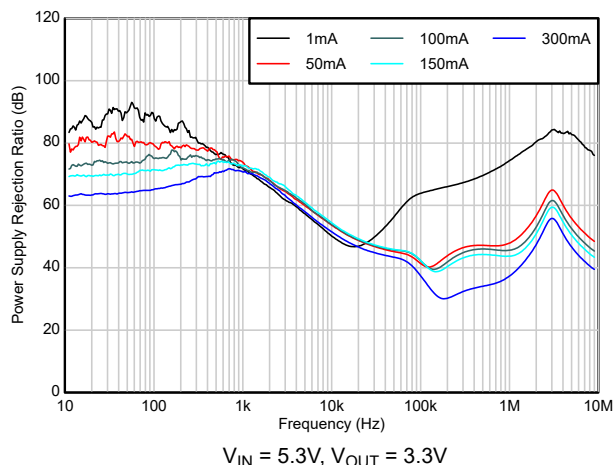


Figure 5-21. Ripple Rejection vs Frequency, Output Current

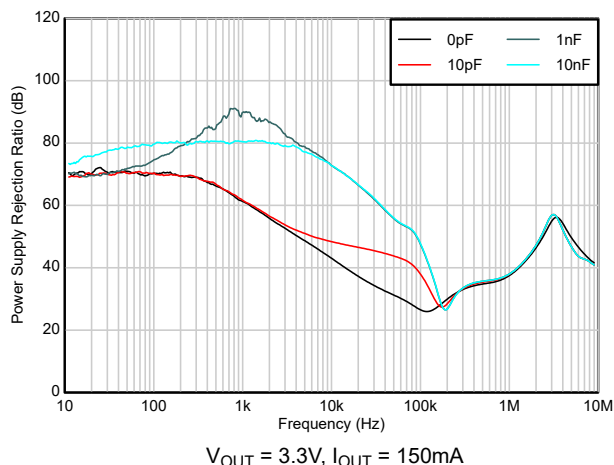


Figure 5-22. Ripple Rejection vs Frequency,  $C_{FF}$

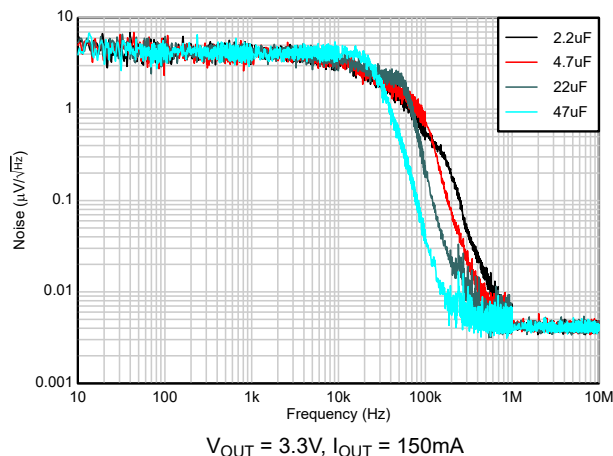


Figure 5-23. Output Noise vs Frequency,  $C_{OUT}$

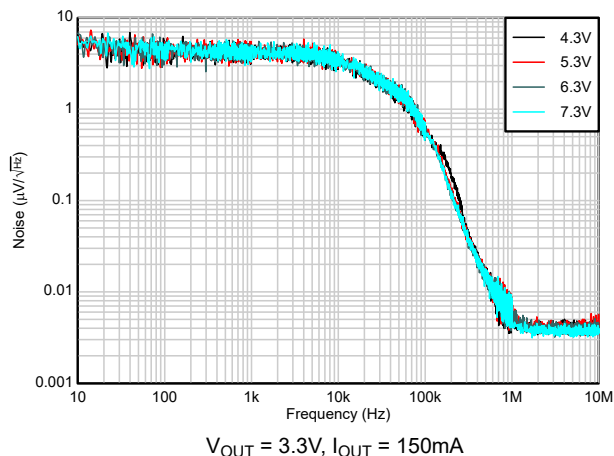


Figure 5-24. Output Noise vs Frequency, Input Voltage

## 5.6 Typical Characteristics (continued)

at operating junction temperature  $T_J = 25^\circ\text{C}$ ,  $V_{IN} = 3.0\text{V}$  or  $V_{IN} = V_{OUT}(\text{nom}) + 1.0\text{V}$  (whichever is greater),  $C_{IN} = 1\mu\text{F}$ ,  $C_{OUT} = 2.2\mu\text{F}$ ,  $V_{EN} = 2\text{V}$ , and  $I_{OUT} = 1\text{mA}$  (unless otherwise noted)

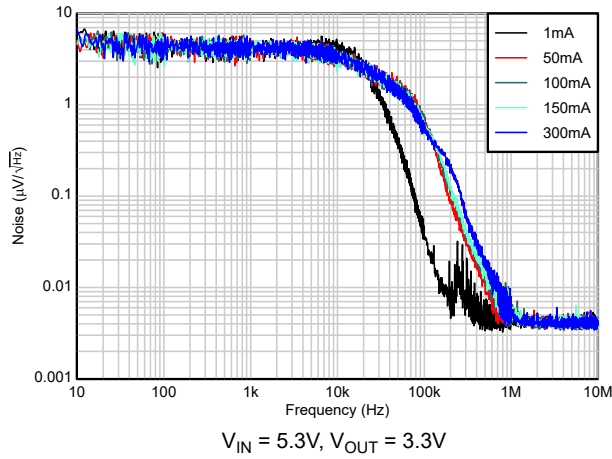


Figure 5-25. Output Noise vs Frequency, Output Current

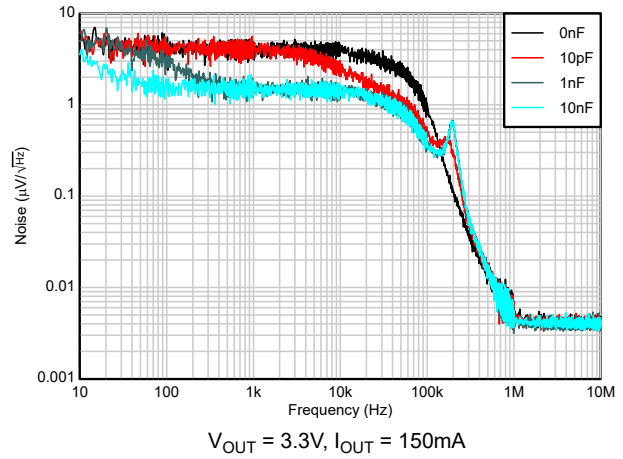


Figure 5-26. Output Noise vs Frequency,  $C_{FF}$

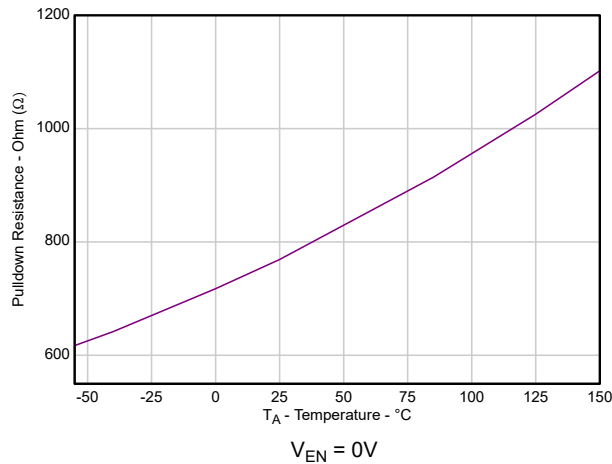


Figure 5-27. Output Discharge Resistance vs Temperature

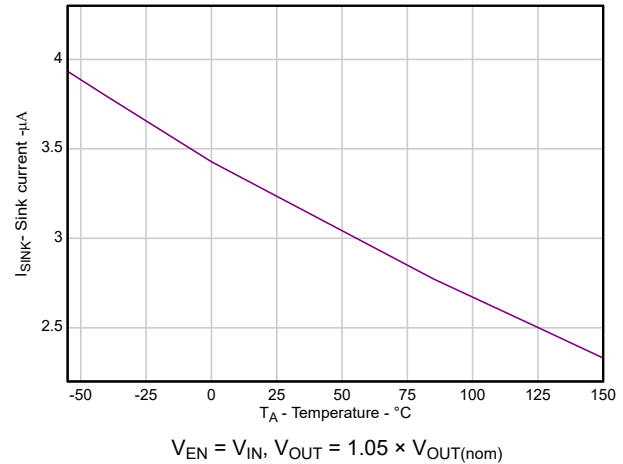


Figure 5-28. Output Sink Current vs Temperature

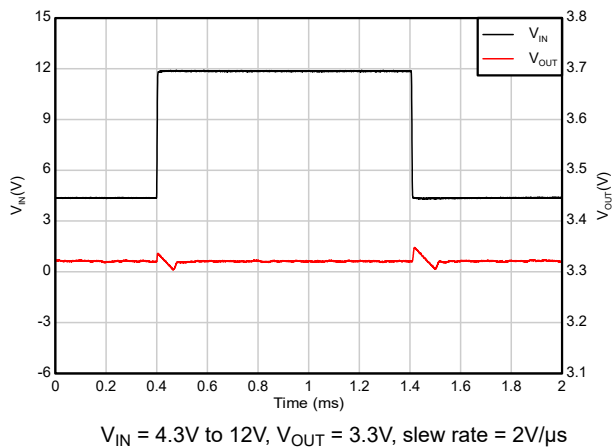


Figure 5-29. Line Transient

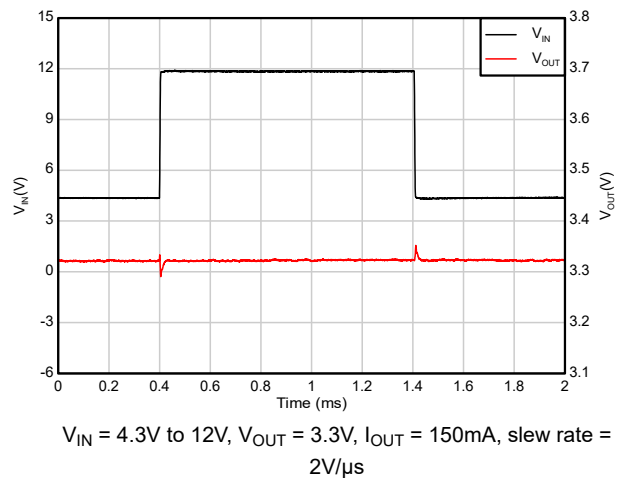
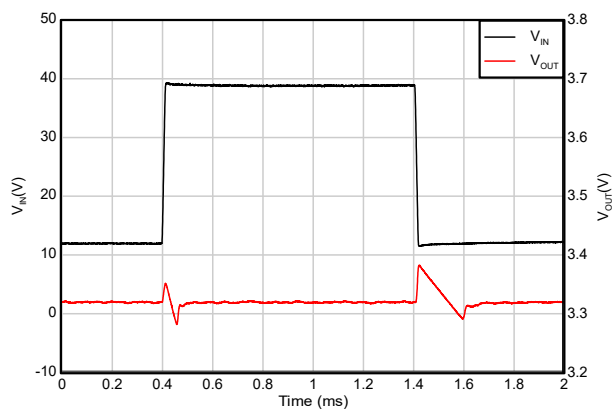


Figure 5-30. Line Transient

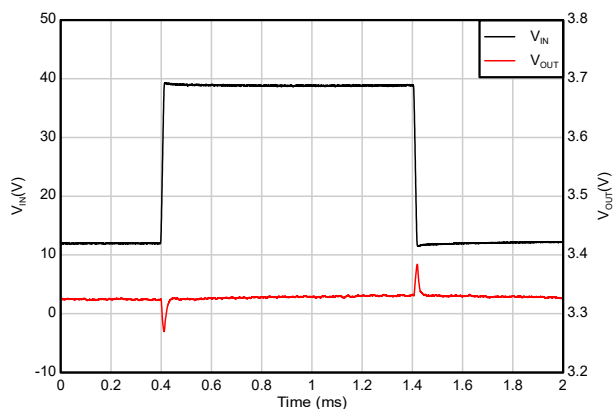
## 5.6 Typical Characteristics (continued)

at operating junction temperature  $T_J = 25^\circ\text{C}$ ,  $V_{IN} = 3.0\text{V}$  or  $V_{IN} = V_{OUT}(\text{nom}) + 1.0\text{V}$  (whichever is greater),  $C_{IN} = 1\mu\text{F}$ ,  $C_{OUT} = 2.2\mu\text{F}$ ,  $V_{EN} = 2\text{V}$ , and  $I_{OUT} = 1\text{mA}$  (unless otherwise noted)



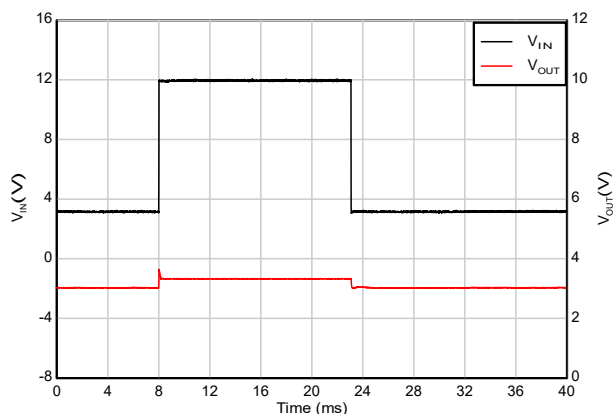
$V_{IN} = 12\text{V to } 40\text{V}$ ,  $V_{OUT} = 3.3\text{V}$ , slew rate =  $2\text{V}/\mu\text{s}$

**Figure 5-31. Line Transient**



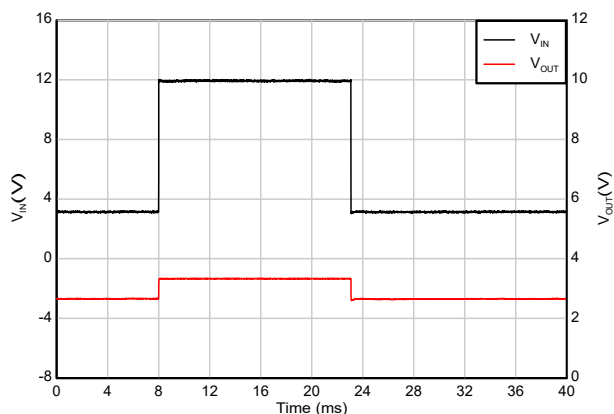
$V_{IN} = 12\text{V to } 40\text{V}$ ,  $V_{OUT} = 3.3\text{V}$ ,  $I_{OUT} = 150\text{mA}$ , slew rate =  $2\text{V}/\mu\text{s}$

**Figure 5-32. Line Transient**



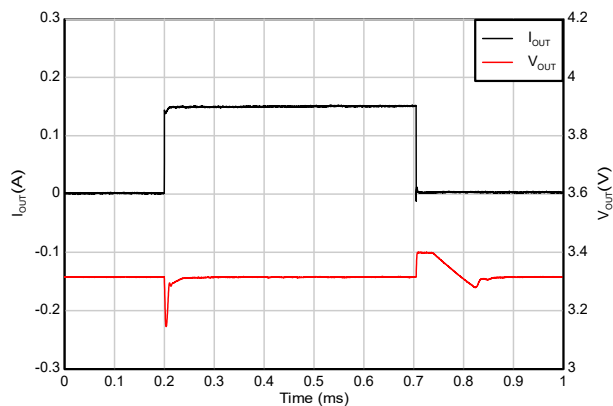
$V_{IN} = 3\text{V to } 12\text{V}$ ,  $V_{OUT} = 3.3\text{V}$ , slew rate =  $2\text{V}/\mu\text{s}$

**Figure 5-33. Cold Crank Recovery**



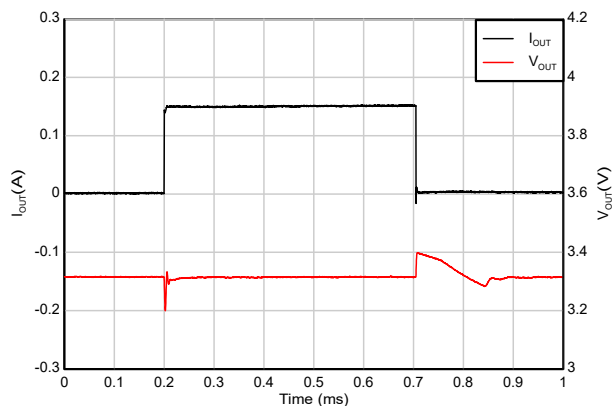
$V_{IN} = 3\text{V to } 12\text{V}$ ,  $V_{OUT} = 3.3\text{V}$ ,  $I_{OUT} = 150\text{mA}$ , slew rate =  $2\text{V}/\mu\text{s}$

**Figure 5-34. Cold Crank Recovery**



$I_{OUT} = 0\text{mA to } 150\text{mA}$ ,  $V_{OUT} = 3.3\text{V}$ , slew rate =  $2\text{A}/\mu\text{s}$

**Figure 5-35. Load Transient**

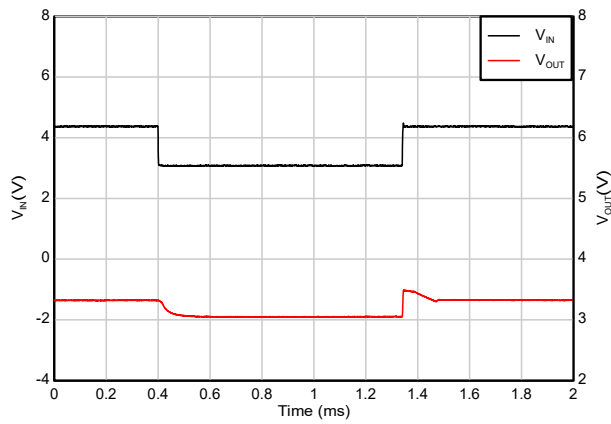


$I_{OUT} = 1\text{mA to } 150\text{mA}$ ,  $V_{OUT} = 3.3\text{V}$ , slew rate =  $2\text{A}/\mu\text{s}$

**Figure 5-36. Load Transient**

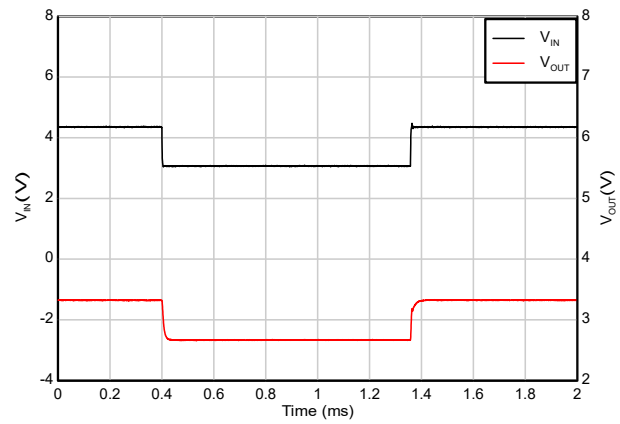
## 5.6 Typical Characteristics (continued)

at operating junction temperature  $T_J = 25^\circ\text{C}$ ,  $V_{IN} = 3.0\text{V}$  or  $V_{IN} = V_{OUT}(\text{nom}) + 1.0\text{V}$  (whichever is greater),  $C_{IN} = 1\mu\text{F}$ ,  $C_{OUT} = 2.2\mu\text{F}$ ,  $V_{EN} = 2\text{V}$ , and  $I_{OUT} = 1\text{mA}$  (unless otherwise noted)



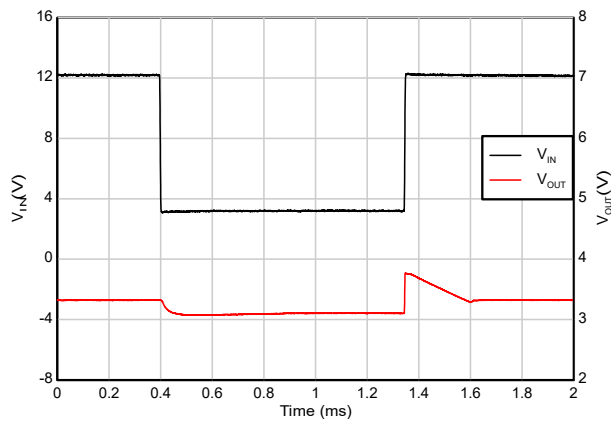
$V_{IN} = 4.3\text{V}$  to  $3\text{V}$ ,  $V_{OUT} = 3.3\text{V}$ , slew rate =  $2\text{V}/\mu\text{s}$

**Figure 5-37. Dropout Recovery**



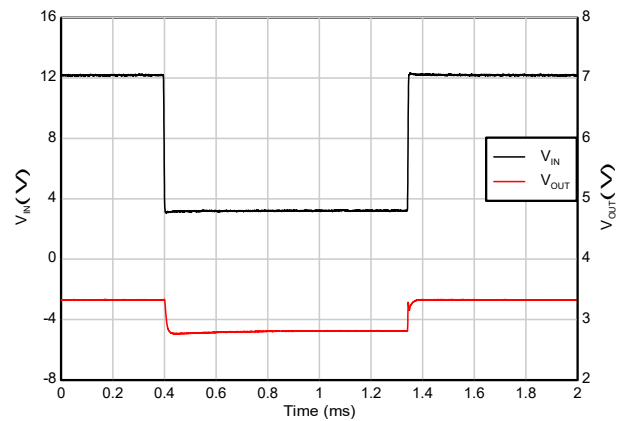
$V_{IN} = 4.3\text{V}$  to  $3\text{V}$ ,  $V_{OUT} = 3.3\text{V}$ ,  $I_{OUT} = 150\text{mA}$ , slew rate =  $2\text{V}/\mu\text{s}$

**Figure 5-38. Dropout Recovery**



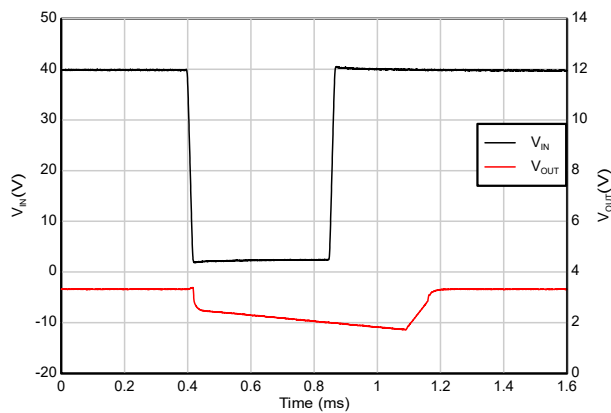
$V_{IN} = 12\text{V}$  to  $3\text{V}$ ,  $V_{OUT} = 3.3\text{V}$ , slew rate =  $2\text{V}/\mu\text{s}$

**Figure 5-39. Dropout Recovery**



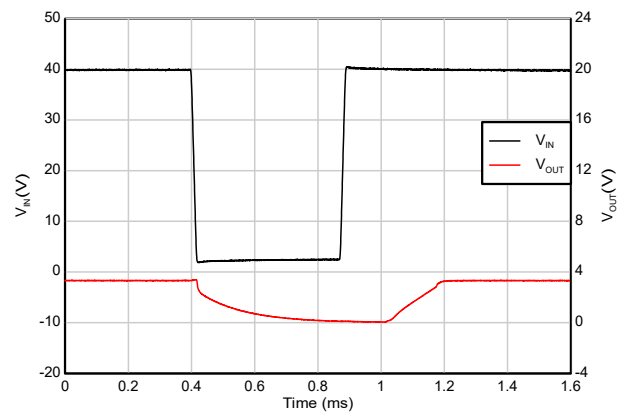
$V_{IN} = 12\text{V}$  to  $3\text{V}$ ,  $V_{OUT} = 3.3\text{V}$ ,  $I_{OUT} = 100\text{mA}$ , slew rate =  $2\text{V}/\mu\text{s}$

**Figure 5-40. Dropout Recovery**



$V_{IN} = 40\text{V}$  to  $2\text{V}$ ,  $V_{OUT} = 3.3\text{V}$ , slew rate =  $2\text{V}/\mu\text{s}$

**Figure 5-41. Brownout Recovery**

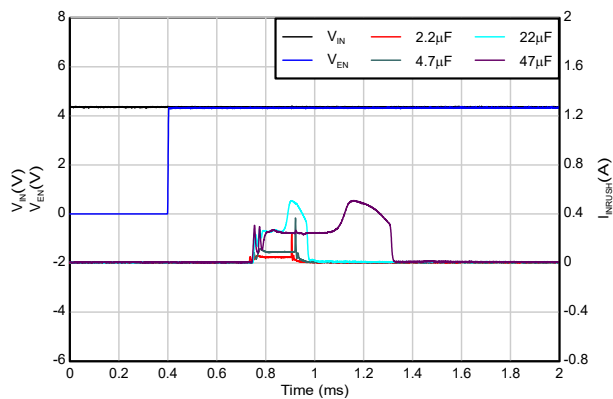


$V_{IN} = 40\text{V}$  to  $2\text{V}$ ,  $V_{OUT} = 3.3\text{V}$ ,  $I_{OUT} = 50\text{mA}$ , slew rate =  $2\text{V}/\mu\text{s}$

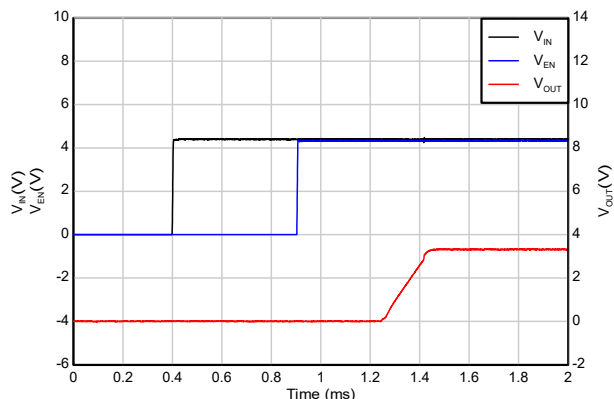
**Figure 5-42. Brownout Recovery**

## 5.6 Typical Characteristics (continued)

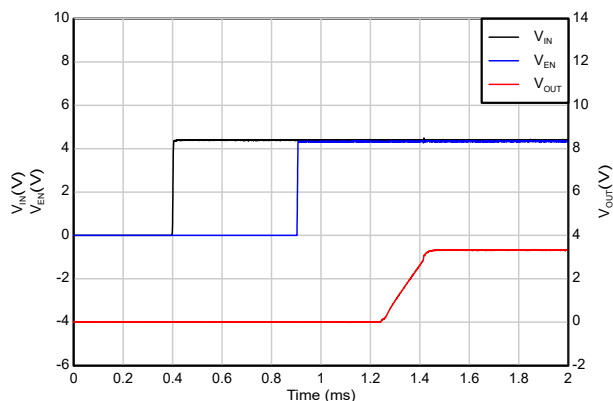
at operating junction temperature  $T_J = 25^\circ\text{C}$ ,  $V_{IN} = 3.0\text{V}$  or  $V_{IN} = V_{OUT}(\text{nom}) + 1.0\text{V}$  (whichever is greater),  $C_{IN} = 1\mu\text{F}$ ,  $C_{OUT} = 2.2\mu\text{F}$ ,  $V_{EN} = 2\text{V}$ , and  $I_{OUT} = 1\text{mA}$  (unless otherwise noted)



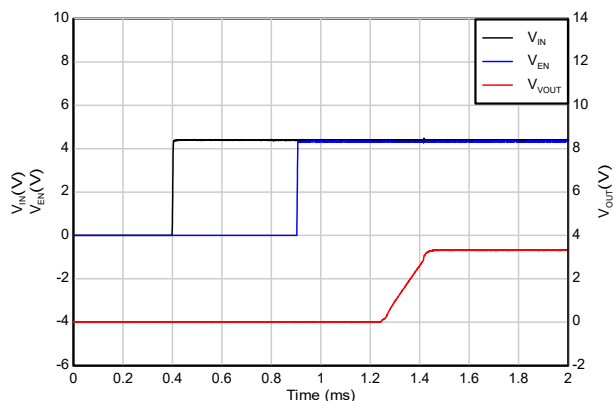
**Figure 5-43. Start-up Inrush Current**



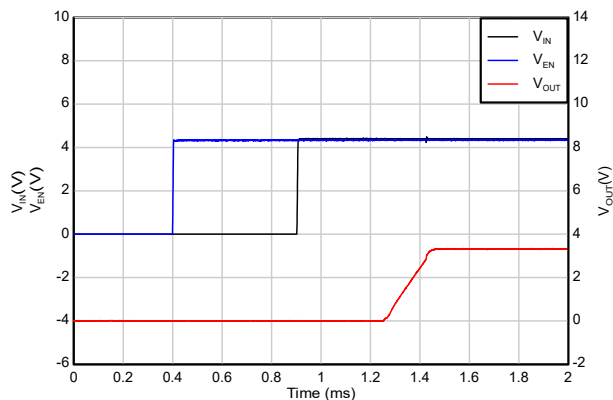
**Figure 5-44. Start-up with Sequencing (EN after IN)**



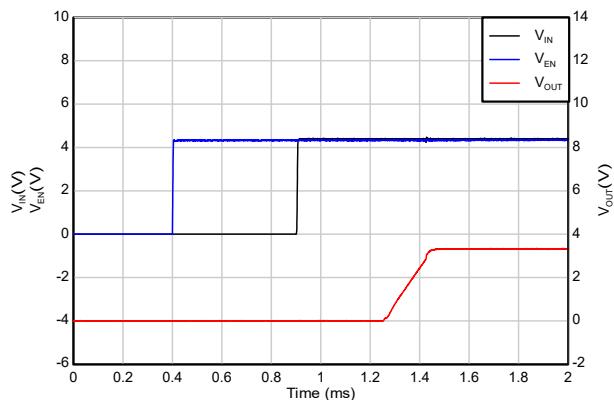
**Figure 5-45. Start-up with Sequencing (EN after IN)**



**Figure 5-46. Start-up with Sequencing (EN after IN)**



**Figure 5-47. Start-up with Sequencing (IN after EN)**

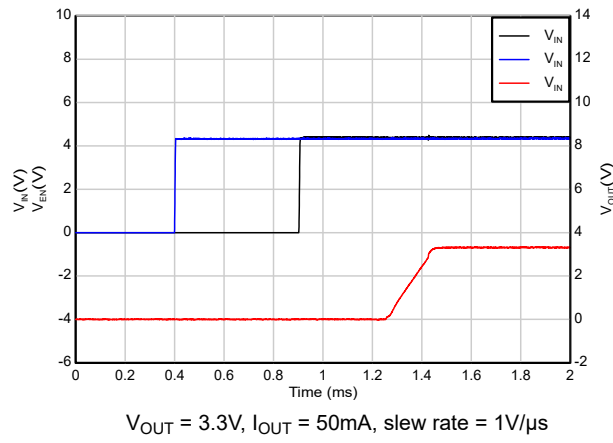


**Figure 5-48. Start-up with Sequencing (IN after EN)**

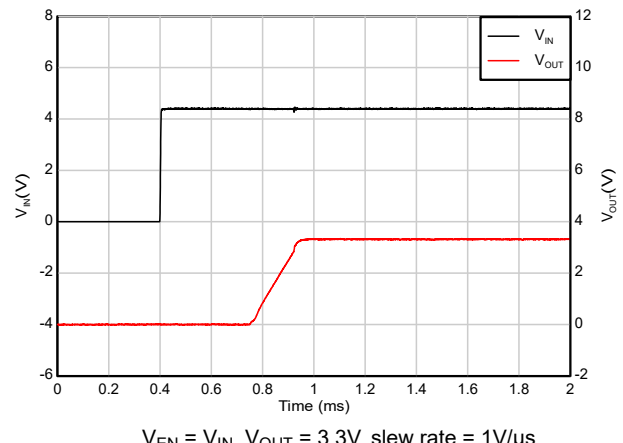


## 5.6 Typical Characteristics (continued)

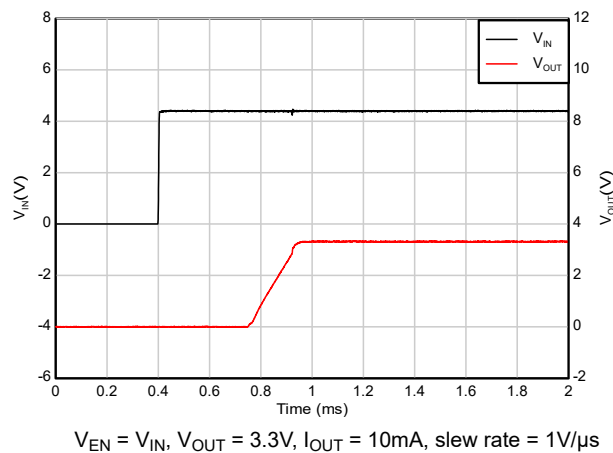
at operating junction temperature  $T_J = 25^\circ\text{C}$ ,  $V_{IN} = 3.0\text{V}$  or  $V_{IN} = V_{OUT}(\text{nom}) + 1.0\text{V}$  (whichever is greater),  $C_{IN} = 1\mu\text{F}$ ,  $C_{OUT} = 2.2\mu\text{F}$ ,  $V_{EN} = 2\text{V}$ , and  $I_{OUT} = 1\text{mA}$  (unless otherwise noted)



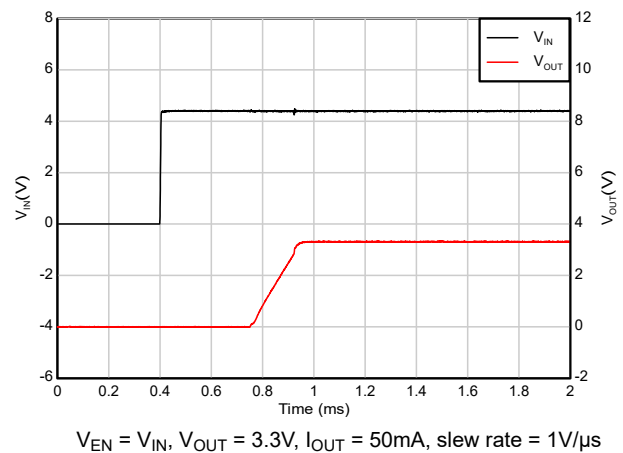
**Figure 5-49. Start-up with Sequencing (IN after EN)**



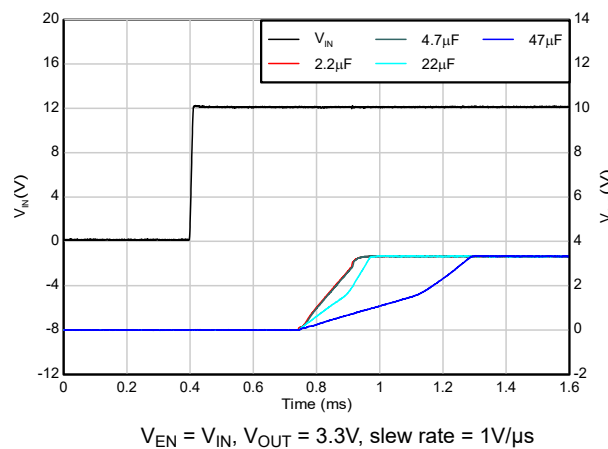
**Figure 5-50. Start-up with IN & EN Tied Together**



**Figure 5-51. Start-up with IN & EN Tied Together**



**Figure 5-52. Start-up with IN & EN Tied Together**



**Figure 5-53. Start-up with IN & EN Tied Together,  $C_{OUT}$**

## 6 Detailed Description

### 6.1 Overview

The TPS7E81 low-dropout regulator (LDO) consumes ultra-low quiescent current (2.8 $\mu$ A (typ)) at no-load current. The device offers a wide input voltage range (3.0V to 40V) and wide output range (1.2V to 38V, in adjustable config) and supports up to 150mA of load current. The device is stable with the output capacitor range of 2.2 $\mu$ F to 100 $\mu$ F.

The low quiescent current across the complete load current range and controlled  $I_Q$  in no-load dropout situations makes the TPS7E81 suitable for powering battery-operated applications. The TPS7E81 has an internal soft-start mechanism that provides a uniform start-up with controlled inrush current. This LDO also has over-current (fold-back), over-power and thermal protection during a load-short or fault condition on the output for better reliability.

### 6.2 Functional Block Diagrams

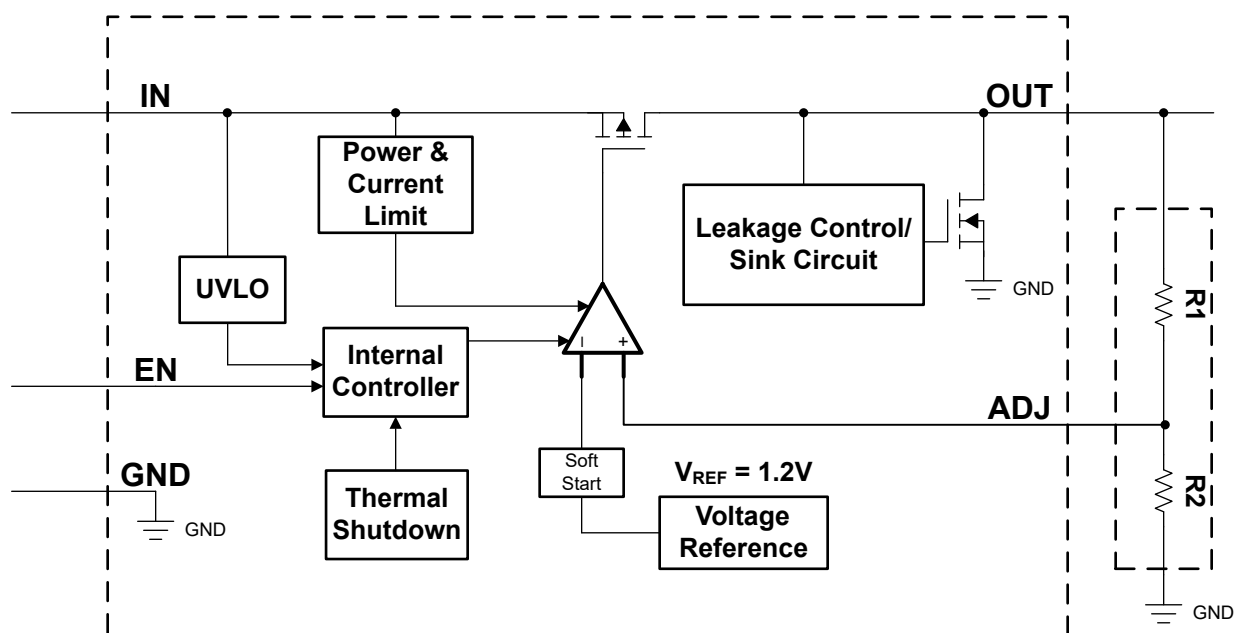


Figure 6-1. Functional Block Diagram: Adjustable Version

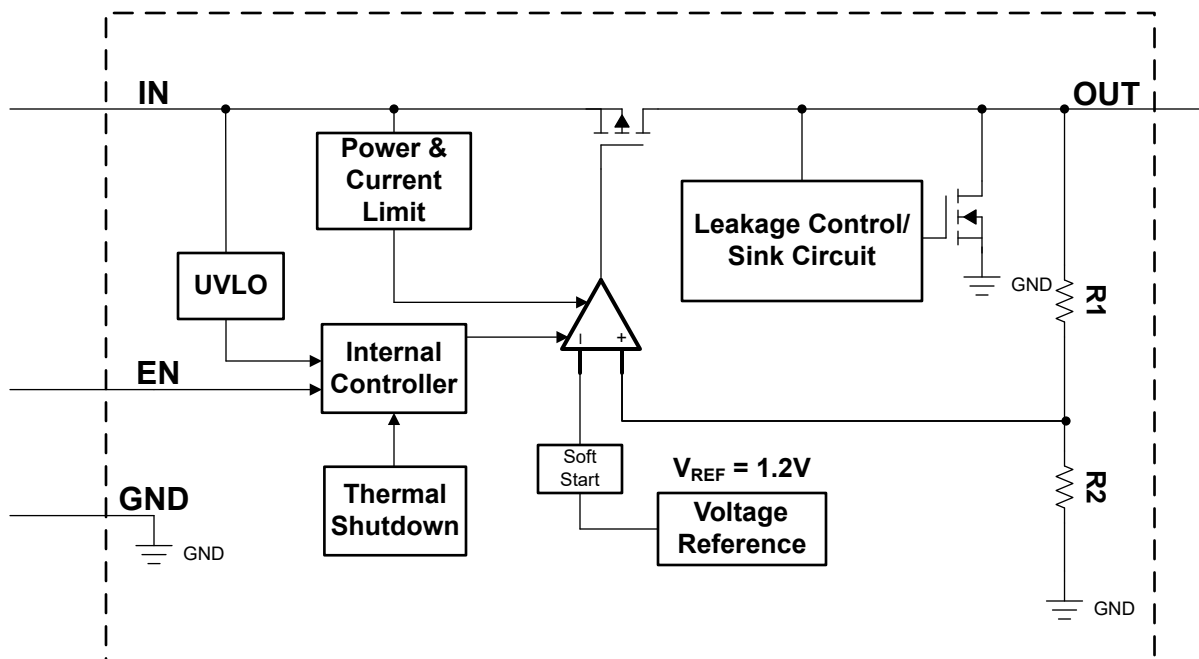


Figure 6-2. Functional Block Diagram: Fixed Version

## 6.3 Feature Description

### 6.3.1 Enable (EN)

The enable pin for the device is an active-high pin. The output voltage is enabled when the voltage of the enable pin is greater than the high-level input voltage ( $V_{IH}$ ) of the EN pin and disabled with the enable pin voltage is less than the low-level input voltage ( $V_{IL}$ ) of the EN pin. High and low thresholds are listed in [Section 5.5](#). If independent control of the output voltage is not needed, connect the enable pin to the input of the device.

The EN pin also has a weak internal pull-up and the EN pin can be left floating to enable the device. The internal pull-up current on the EN pin is captured in the [Section 5.5](#) table as Enable pull-up current. However, care must be taken to verify that pin leakage (from board pollution or some other source) does not inadvertently pull this pin low. Leakage must be restricted to 25nA or less to avoid unintentional disabling of the device.

### 6.3.2 Dropout Voltage

Dropout voltage ( $V_{DO}$ ) is defined as the input voltage minus the output voltage ( $V_{IN} - V_{OUT}$ ) at the rated output current ( $I_{RATED}$ ), where the pass transistor is fully on.  $I_{RATED}$  is the maximum  $I_{OUT}$  listed in the [Section 5.3](#) table. The pass transistor is in the ohmic or triode region of operation, and acts as a switch. The dropout voltage indirectly specifies a minimum input voltage greater than the nominal programmed output voltage at which the output voltage is expected to stay in regulation. If the input voltage falls to less than the nominal output regulation, then the output voltage falls as well.

For a CMOS regulator, the dropout voltage is determined by the drain-source on-state resistance ( $R_{DS(ON)}$ ) of the pass transistor. Therefore, if the linear regulator operates at less than the rated current, the dropout voltage for that current scales accordingly. The following equation calculates the  $R_{DS(ON)}$  of the device.

$$R_{DS(ON)} = \frac{V_{DO}}{I_{RATED}} \quad (1)$$

### 6.3.3 Undervoltage Lockout

The device has an independent undervoltage lockout (UVLO) circuit that monitors the input voltage, allowing a controlled and consistent turn on and off of the output voltage. To prevent the device from turning off if the input drops during turn on, the UVLO has in-built hysteresis. The UVLO limits are specified in the [Section 5.5](#) table.

### 6.3.4 Thermal Shutdown

The device contains a thermal shutdown protection circuit to disable the device when the junction temperature ( $T_J$ ) of the pass transistor rises to  $T_{SD+}$  (typical). Thermal shutdown hysteresis verifies that the device resets (turns on) when the temperature falls to  $T_{SD-}$  (typical).

The thermal time-constant of the semiconductor die is fairly short, thus the device can cycle on and off when thermal shutdown is reached until power dissipation is reduced. Power dissipation during startup can be high from large  $V_{IN} - V_{OUT}$  voltage drops across the device or from high inrush currents charging large output capacitors. Under some conditions, the thermal shutdown protection disables the device before startup completes.

For reliable operation, limit the junction temperature to the maximum listed in the [Section 5.3](#) table. Operation above this maximum temperature causes the device to exceed the operational specifications. Although the internal protection circuitry of the device is designed to protect against thermal overall conditions, this circuitry is not intended to replace proper heat sinking. Continuously running the device into thermal shutdown or above the maximum recommended junction temperature reduces long-term reliability.

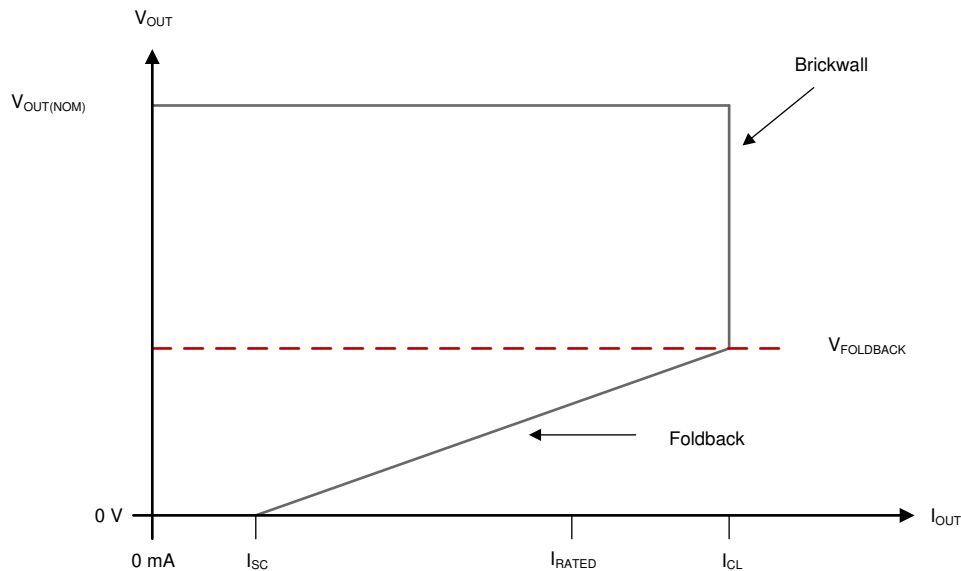
### 6.3.5 Foldback Current Limit

The device has an internal current limit circuit that protects the regulator during transient high-load current faults or shorting events. The current limit is a hybrid brickwall-foldback scheme. The current limit transitions from a brickwall scheme to a foldback scheme at the foldback voltage ( $V_{FOLDBACK}$ ). In a high-load current fault with the output voltage above  $V_{FOLDBACK}$ , the brickwall scheme limits the output current to the current limit ( $I_{CL}$ ). When the voltage drops below  $V_{FOLDBACK}$ , a foldback current limit activates that scales back the current as the

output voltage approaches GND. When the output is shorted, the device supplies a typical current called the short-circuit current limit ( $I_{SC}$ ).  $I_{CL}$  and  $I_{SC}$  are listed in the [Section 5.5](#) table.

The output voltage is not regulated when the device is in current limit. When a current limit event occurs, the device begins to heat up because of the increase in power dissipation. When the device is in brickwall current limit, the pass transistor dissipates power  $[(V_{IN} - V_{OUT}) \times I_{CL}]$ . When the device output is shorted and the output is below  $V_{FOLDBACK}$ , the pass transistor dissipates power  $[(V_{IN} - V_{OUT}) \times I_{SC}]$ . If thermal shutdown is triggered, the device turns off. After the device cools down, the internal thermal shutdown circuit turns the device back on. If the output current fault condition continues, the device cycles between current limit and thermal shutdown. For more information on current limits, see the [Know Your Limits application note](#).

Figure 6-3 shows a diagram of the foldback current limit.



**Figure 6-3. Foldback Current Limit**

### 6.3.6 Power Limit

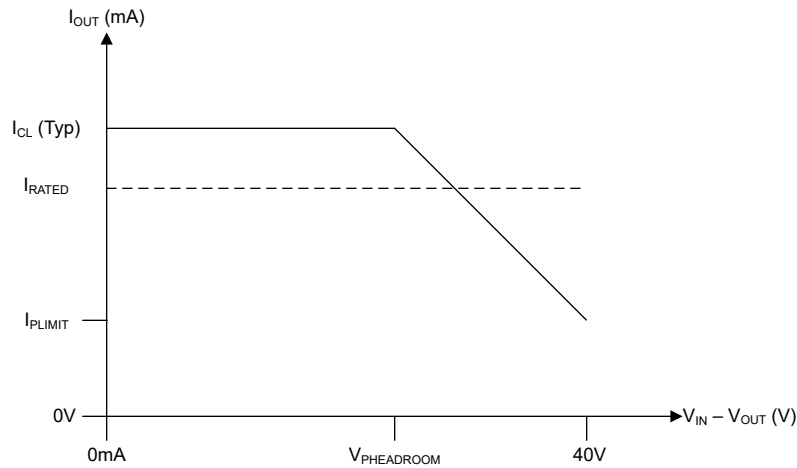
The device has an internal over-power limit circuit that limits the power dissipated across the LDO within the internal SOA (safe operating area) limits. The SOA limits for the LDO factor in safe operation for both silicon components and bondwires used in packaging. These limits verify reliable operation of the device and prevent the device failure from overheating, breakdown, or other damaging effects.

The power dissipated ( $P_{Dissip}$ ) across the LDO is defined by voltage drop across LDO ( $V_{IN} - V_{OUT}$ ) and load current ( $I_L$ ) flowing through the LDO.

$$P_{Dissip} = (V_{IN} - V_{OUT}) \times I_{OUT} \quad (2)$$

The power limiting circuit monitors both the voltage drop (headroom,  $V_{IN} - V_{OUT}$ ) across LDO and output load current ( $I_{OUT}$ ) flowing through the LDO. If  $P_{Dissip}$  crosses the defined SOA limits, the power limiting circuit limits the load current ( $I_{OUT}$ ) flowing through the LDO. The output voltage is not regulated when the device is in power limit operation. The maximum supported current ( $I_{PLIMIT}$ ) at full headroom ( $V_{IN} - V_{OUT} = 40V$ ) and maximum supported headroom ( $V_{PHEADROOM}$ ) at full load current are captured in [Section 5.5](#).

Figure 6-4 shows a diagram of the power limiting.



**Figure 6-4. Power Limiting**

### 6.3.7 Output Pulldown

The device has an output pulldown circuit.  $V_{OUT}$  pulldown sink to ground capability is listed in the [Section 5.5](#) table. The output pulldown activates under the following conditions:

- $V_{EN} < V_{IL(EN)}$
- $1.0V < V_{IN} < V_{UVLO}$

The output pulldown resistance for this device is  $750\Omega$  typical, listed as  $R_{Discharge}$  in the [Section 5.5](#) table.

Do not rely on the output pulldown circuit for discharging a large amount of output capacitance after the input supply has collapsed because reverse current can flow from the output to the input. This reverse current flow can cause damage to the device. See the [Section 7.1.4](#) for more details.

## 6.4 Device Functional Modes

### 6.4.1 Device Functional Mode Comparison

[Device Functional Mode Comparison](#) shows the conditions that lead to the different modes of operation. See the [Electrical Characteristics](#) table for parameter values.

**Table 6-1. Device Functional Mode Comparison**

OPERATING MODE	PARAMETER			
	$V_{IN}$	$V_{EN}$	$I_{OUT}$	$T_J$
Normal operation	$V_{IN} > V_{OUT(nom)} + V_{DO}$ and $V_{IN} > V_{IN(min)}$	$V_{EN} > V_{EN(HI)}$	$I_{OUT} < I_{OUT(max)}$	$T_J < T_{SD(shutdown)}$
Dropout operation	$V_{IN(min)} < V_{IN} < V_{OUT(nom)} + V_{DO}$	$V_{EN} > V_{EN(HI)}$	$I_{OUT} < I_{OUT(max)}$	$T_J < T_{SD(shutdown)}$
Disabled (any true condition disables the device)	$V_{IN} < V_{UVLO}$	$V_{EN} < V_{EN(LOW)}$	Not applicable	$T_J > T_{SD(shutdown)}$

### 6.4.2 Normal Operation

The device regulates to the nominal output voltage under the following conditions:

- The input voltage is greater than the nominal output voltage plus the dropout voltage ( $V_{OUT(nom)} + V_{DO}$ )
- The headroom across the LDO ( $V_{IN} - V_{OUT}$ ) is less than  $V_{HEADROOM}$  for required  $I_{OUT}$ , such that power limit is not engaged
- The output current is less than the current limit ( $I_{OUT} < I_{LIM}$ )
- The device junction temperature is greater than  $-40^{\circ}\text{C}$  and less than  $+150^{\circ}\text{C}$
- The device junction temperature is less than the thermal shutdown temperature ( $T_J < T_{SD}$ )
- The enable voltage has previously exceeded the enable rising threshold voltage and has not yet decreased to less than the enable falling threshold

### 6.4.3 Dropout Operation

If the input voltage is lower than the nominal output voltage plus the specified dropout voltage, but all other conditions are met for normal operation, the device operates in dropout mode. In this mode, the output voltage tracks the input voltage. During this mode, the transient performance of the device becomes significantly degraded because the pass transistor is in the ohmic or triode region, and acts as a switch. Line or load transients in dropout can result in large output-voltage deviations.

When the device is in a steady dropout state (defined as when the device is in dropout,  $V_{IN} < V_{OUT(NOM)} + V_{DO}$ , directly after being in a normal regulation state, but *not* during startup), the pass transistor is driven into the ohmic or triode region. When the input voltage returns to a value greater than or equal to the nominal output voltage plus the dropout voltage ( $V_{OUT(NOM)} + V_{DO}$ ), the output voltage can overshoot for a short period of time while the device pulls the pass transistor back into the linear region.

The TPS7E81 keeps the IQ controlled in dropout operation to much lower values (12µA (typ) in no-load dropout) compared to conventional linear voltage regulators which avoids the battery drainage, once the battery levels falls below the required input voltage levels.

### 6.4.4 Disabled

The output of the device can be shutdown by forcing the voltage of the enable pin to less than the maximum EN pin low-level input voltage (see [Section 5.5](#)). When disabled, the pass transistor is turned off, internal circuits are shutdown, and the output voltage is actively discharged to ground by an internal discharge circuit from the output to ground.

## 7 Application and Implementation

### Note

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes, as well as validating and testing their design implementation to confirm system functionality.

### 7.1 Application Information

#### 7.1.1 Adjustable Device Feedback Resistor Selection

The adjustable-version device requires external feedback divider resistors to set the output voltage.  $V_{OUT}$  is set using the feedback divider resistors,  $R_1$  and  $R_2$ , according to the following equation:

$$V_{OUT} = V_{FB} \times (1 + R_1 / R_2) \quad (3)$$

To ignore the FB pin current error term in the  $V_{OUT}$  equation, set the feedback divider current to 100x the FB pin current ( $I_{FB}$ ) listed in the [Section 5.5](#) table. This setting provides the maximum feedback divider series resistance, as shown in the following equation:

$$R_1 + R_2 \leq V_{OUT} / (I_{FB} \times 100) \quad (4)$$

#### 7.1.2 Recommended Capacitor Types

The device is designed to be stable using low equivalent series resistance (ESR) ceramic capacitors at the input and output. Multilayer ceramic capacitors have become the industry standard for these types of applications and are recommended, but must be used with good judgment. Ceramic capacitors that employ X7R-, X5R-, and C0G-rated dielectric materials provide relatively good capacitive stability across temperature, whereas the use of Y5V-rated capacitors is discouraged because of large variations in capacitance.

Regardless of the ceramic capacitor type selected, the effective capacitance varies with operating voltage and temperature. As a general rule, expect the effective capacitance to decrease by as much as 50%. The input and output capacitors recommended in the [Section 5.3](#) table account for an effective capacitance of approximately 50% of the nominal value.

#### 7.1.3 Input and Output Capacitor Selection

The TPS7E81 requires an output capacitor of 2.2 $\mu$ F or larger (1.0 $\mu$ F or larger capacitance) for stability and an equivalent series resistance (ESR) between 0.0 $\Omega$  and 1 $\Omega$ . For best transient performance, use X5R- and X7R-type ceramic capacitors because these capacitors have minimal variation in value and ESR over temperature. When choosing a capacitor for a specific application, be mindful of the DC bias characteristics for the capacitor. Higher output voltages cause a significant derating of the capacitor. For best performance, the maximum recommended output capacitance is 100 $\mu$ F.

Although an input capacitor is not required for stability, good analog design practice is to connect a capacitor from IN to GND. Some input supplies have a high impedance, thus placing the input capacitor on the input supply helps reduce the input impedance. This capacitor counteracts reactive input sources and improves transient response, input ripple, and PSRR. If the input supply has a high impedance over a large range of frequencies, several input capacitors can be used in parallel to lower the impedance over frequency. Use a higher-value capacitor if large, fast, rise-time load transients are anticipated, or if the device is located several inches from the input power source.

#### 7.1.4 Reverse Current

Excessive reverse current can damage this device. Reverse current flows through the intrinsic body diode of the pass transistor instead of the normal conducting channel. At high magnitudes, this current flow degrades the long-term reliability of the device.

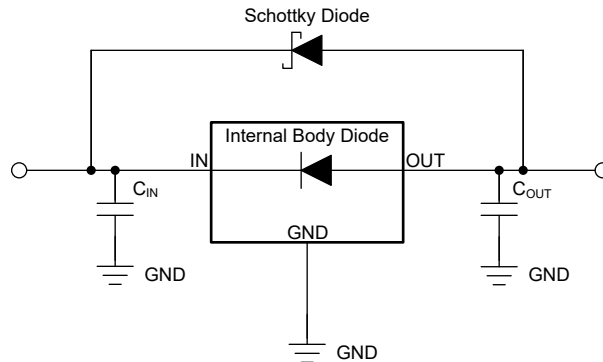


Conditions where reverse current can occur are outlined in this section, all of which can exceed the absolute maximum rating of  $V_{OUT} \leq V_{IN} + 0.3 \text{ V}$ .

- If the device has a large  $C_{OUT}$  and the input supply collapses with little or no load current
- The output is biased when the input supply is not established
- The output is biased above the input supply

If reverse current flow is expected in the application, external protection is recommended to protect the device. Reverse current is not limited in the device, so external limiting is required if extended reverse voltage operation is anticipated.

Figure 7-1 shows one approach for protecting the device.



**Figure 7-1. Example Circuit for Reverse Current Protection Using a Schottky Diode**

### 7.1.5 Feed-Forward Capacitor

For the adjustable-voltage version device, a feed-forward capacitor ( $C_{FF}$ ) can be connected from the OUT pin to the FB pin.  $C_{FF}$  improves transient, noise, and PSRR performance, but is not required for regulator stability. Recommended  $C_{FF}$  values are listed in the [Section 5.3](#) table. A higher capacitance  $C_{FF}$  can be used; however, the start-up time increases. For a detailed description of  $C_{FF}$  tradeoffs, see the [Pros and Cons of Using a Feedforward Capacitor with a Low-Dropout Regulator](#) application note.

$C_{FF}$  and  $R_1$  form a zero in the loop gain at frequency  $f_Z$ , while  $C_{FF}$ ,  $R_1$ , and  $R_2$  form a pole in the loop gain at frequency  $f_P$ .  $C_{FF}$  zero and pole frequencies can be calculated from the following equations:

$$f_Z = 1 / (2 \times \pi \times C_{FF} \times R_1) \quad (5)$$

$$f_P = 1 / (2 \times \pi \times C_{FF} \times (R_1 \parallel R_2)) \quad (6)$$

### 7.1.6 Dropout Voltage

Dropout voltage ( $V_{DO}$ ) is defined as the input voltage minus the output voltage ( $V_{IN} - V_{OUT}$ ) at the rated output current ( $I_{RATED}$ ), where the pass transistor is fully on.  $I_{RATED}$  is the maximum  $I_{OUT}$  listed in the [Section 5.3](#) table. The pass transistor is in the ohmic or triode region of operation, and acts as a switch. The dropout voltage indirectly specifies a minimum input voltage greater than the nominal programmed output voltage at which the output voltage is expected to stay in regulation. If the input voltage falls to less than the nominal output regulation, then the output voltage falls as well.

For a CMOS regulator, the dropout voltage is determined by the drain-source on-state resistance ( $R_{DS(ON)}$ ) of the pass transistor. Therefore, if the linear regulator operates at less than the rated current, the dropout voltage for that current scales accordingly. The following equation calculates the  $R_{DS(ON)}$  of the device.

$$R_{DS(ON)} = \frac{V_{DO}}{I_{RATED}} \quad (7)$$

### 7.1.7 Estimating Junction Temperature

The JEDEC standard now recommends using psi ( $\Psi$ ) thermal metrics to estimate the LDO junction temperatures when in-circuit on a typical PCB board application. These metrics are not strictly speaking thermal resistances, but rather offer practical and relative means of estimating junction temperatures. These psi metrics are determined to be significantly independent of the copper-spreading area. The key thermal metrics ( $\Psi_{JT}$  and  $\Psi_{JB}$ ) are used in accordance with [Equation 8](#) and are given in the [Section 5.5](#) table.

$$\begin{aligned}\Psi_{JT}: T_J &= T_T + \Psi_{JT} \times P_D \\ \Psi_{JB}: T_J &= T_B + \Psi_{JB} \times P_D\end{aligned}\tag{8}$$

where:

- $P_D$  is the power dissipated as explained in [Equation 11](#)
- $T_T$  is the temperature at the center-top of the device package
- $T_B$  is the PCB surface temperature measured 1mm from the device package and centered on the package edge

The JEDEC standard now recommends using psi ( $\Psi$ ) thermal metrics to estimate the linear regulator junction temperatures when in-circuit on a typical PCB board application. These metrics are not thermal resistance parameters and instead offer a practical and relative way to estimate junction temperature. These psi metrics are determined to be significantly independent of the copper area available for heat-spreading. The [Section 5.4](#) table lists the primary thermal metrics, which are the junction-to-top characterization parameter ( $\psi_{JT}$ ) and junction-to-board characterization parameter ( $\psi_{JB}$ ). These parameters provide two methods for calculating the junction temperature ( $T_J$ ), as described in the following equations. Use the junction-to-top characterization parameter ( $\psi_{JT}$ ) with the temperature at the center-top of device package ( $T_T$ ) to calculate the junction temperature. Use the junction-to-board characterization parameter ( $\psi_{JB}$ ) with the printed circuit board (PCB) surface temperature 1mm from the device package ( $T_B$ ) to calculate the junction temperature.

$$T_J = T_T + \psi_{JT} \times P_D\tag{9}$$

where:

- $P_D$  is the dissipated power
- $T_T$  is the temperature at the center-top of the device package

$$T_J = T_B + \psi_{JB} \times P_D\tag{10}$$

where:

- $T_B$  is the PCB surface temperature measured 1mm from the device package and centered on the package edge

For detailed information on the thermal metrics and how to use the metrics, see the [Semiconductor and IC Package Thermal Metrics](#) application note.

### 7.1.8 Power Dissipation ( $P_D$ )

Circuit reliability requires proper consideration of the device power dissipation, location of the circuit on the printed circuit board (PCB), and correct sizing of the thermal plane. Verify the PCB area around the regulator has few or no other heat-generating devices that cause added thermal stress.

To first-order approximation, power dissipation in the regulator depends on the input-to-output voltage difference and load conditions. The following equation calculates power dissipation ( $P_D$ ).

$$P_D = (V_{IN} - V_{OUT}) \times I_{OUT}\tag{11}$$

### Note

Power dissipation is minimized, and thus greater efficiency achieved, by proper selection of the system voltage rails. Proper selection allows the minimum input-to-output voltage differential to be obtained. The low dropout of the device allows for maximum efficiency across a wide range of output voltages.

For devices with a thermal pad, the primary heat conduction path for the device package is through the thermal pad to the PCB. Solder the thermal pad to a copper pad area under the device. This pad area contains an array of plated vias that conduct heat to additional copper planes for increased heat dissipation.

The maximum power dissipation determines the maximum allowable ambient temperature ( $T_A$ ) for the device. Power dissipation and junction temperature are most often related by the  $R_{\theta JA}$  of the combined PCB and device package and the  $T_A$ .  $R_{\theta JA}$  is the junction-to-ambient thermal resistance and  $T_A$  is the temperature of the ambient air. The following equation describes this relationship.

$$T_J = T_A + (R_{\theta JA} \times P_D) \quad (12)$$

The following equation rearranges this relationship for output current.

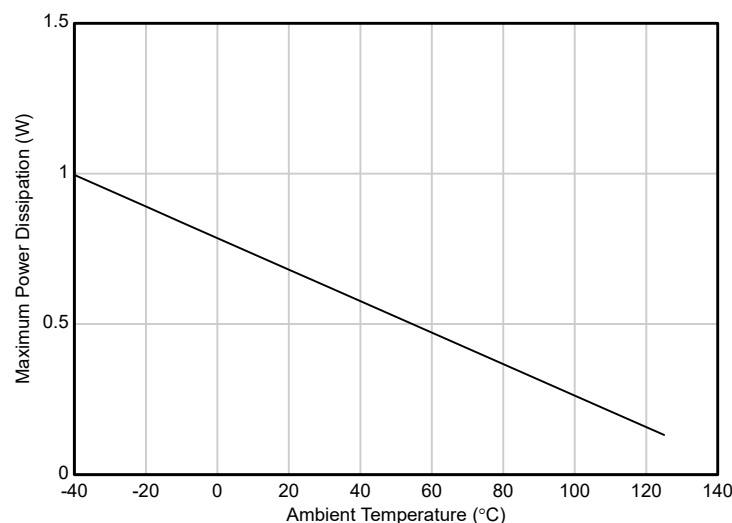
$$I_{OUT} = (T_J - T_A) / [R_{\theta JA} \times (V_{IN} - V_{OUT})] \quad (13)$$

Thermal resistance ( $R_{\theta JA}$ ) is highly dependent on the heat-spreading capability built into the particular PCB design. This resistance therefore varies according to the total copper area, copper weight, and location of the planes. The junction-to-ambient thermal resistance listed in the [Section 5.4](#) table is determined by the JEDEC standard PCB and copper-spreading area.  $R_{\theta JA}$  is used as a relative measure of package thermal performance. For packages with thermal pad and a well-designed thermal layout,  $R_{\theta JA}$  is actually the sum of the package's  $R_{\theta JCBot}$  plus the thermal resistance contribution by the PCB copper.  $R_{\theta JCBot}$  is the junction-to-case (bottom) thermal resistance, as given in the [Section 5.4](#) table.

### 7.1.9 Power Dissipation Versus Ambient Temperature

[Figure 7-2](#) and [Figure 7-3](#) are based off of a JESD51-7 4-layer, high-K board. The allowable power dissipation is estimated using the following equation. As discussed in the [An empirical analysis of the impact of board layout on LDO thermal performance application note](#), thermal dissipation can be improved in the JEDEC high-K layout by adding top layer copper and increasing the number of thermal vias. If a good thermal layout is used, the allowable thermal dissipation can be improved by up to 50%.

$$T_A + R_{\theta JA} \times P_D \leq 125^\circ\text{C} \quad (14)$$



**Figure 7-2. TPS7E81 (DBV/A) Allowable Power Dissipation**

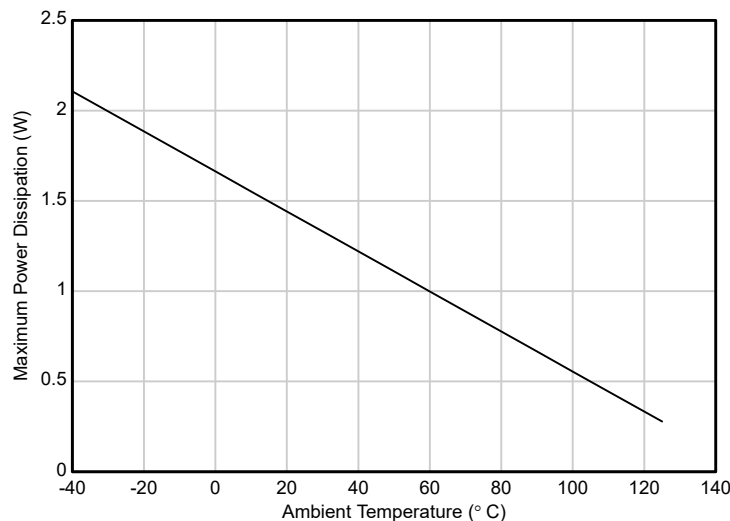


Figure 7-3. TPS7E81 (DRV) Allowable Power Dissipation

## 7.2 Typical Application

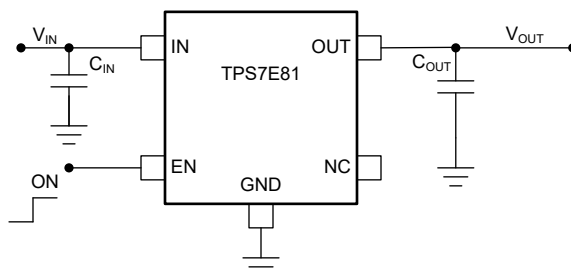


Figure 7-4. TPS7E81 Typical Application Circuit (Fixed-Voltage Version)

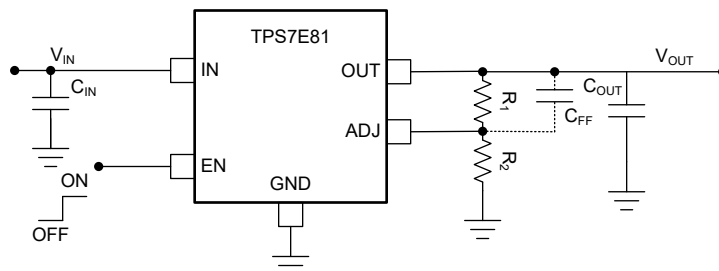


Figure 7-5. TPS7E81 Adjustable LDO Regulator Programming

NOTE: Dotted lines indicate an optional input capacitor and feed-forward capacitor. See the [Section 7.1.3](#) and [Section 7.1.5](#) sections and the [Section 5.3](#) table.

Table 7-1. Adjustable Output Voltage for Resistors R<sub>1</sub> and R<sub>2</sub>

OUTPUT VOLTAGE (V)	R <sub>1</sub> (MΩ)	R <sub>2</sub> (MΩ)
1.8	0.499	1
2.8	1.33	1
5.0	3.16	1

### 7.2.1 Design Requirements

For this design example, use the parameters listed in [Table 7-2](#) as the input parameters.

**Table 7-2. Design Parameters**

DESIGN PARAMETER	EXAMPLE VALUE
Input voltage range	6V to 40V
Output voltage	5V
Output current	150mA
Output capacitor	4.7μF

### 7.2.2 Choose Feedback Resistors

For this design example,  $V_{OUT}$  is set to 3.3V. The following equations set the feedback divider resistors for the desired output voltage:

$$V_{OUT} = V_{FB} \times (1 + R_1 / R_2) \quad (15)$$

$$R_1 + R_2 \leq V_{OUT} / (I_{FB} \times 100) \quad (16)$$

For improved output accuracy, use Equation 16 and  $I_{FB} = 10\text{nA}$  as listed in the Section 5.5 table to calculate the upper limit for series feedback resistance ( $R_1 + R_2 \leq 3.3\text{M}\Omega$ ).

The control-loop error amplifier drives the FB pin to the same voltage as the internal reference ( $V_{FB} = 1.2\text{V}$ , as listed in the Section 5.5 table). Use Equation 15 to determine the ratio of  $R_1 / R_2 = 1.75$ . Use this ratio and solve Equation 16 for  $R_1$ . Now calculate the upper limit for  $R_1 \leq 2.1\text{M}\Omega$ . Select a standard value resistor for  $R_1 = 1.75\text{M}\Omega$ .

Reference Equation 17 and solve for  $R_2$ :

$$R_2 = R_1 / [(V_{OUT} / V_{FB}) - 1] \quad (17)$$

From Equation 17,  $R_2 = 1\text{M}\Omega$  is determined. Select a standard value resistor for  $R_2 = 1\text{M}\Omega$ . Verify that the feedback divider current is greater than the minimum value in the Section 5.3 table.

The following equation calculates the feedback divider current.

$$I_{FB\_Divider} = V_{OUT} / (R_1 + R_2) \quad (18)$$

### 7.2.3 Power Supply Recommendations

The TPS7E81 is designed to operate from an input voltage supply range between 3.0V and 40V. The input voltage range provides adequate headroom for the device to have a regulated output. If the input supply is noisy, additional input capacitors with low ESR help improve output noise performance.

### 7.2.4 Layout

#### 7.2.4.1 Layout Guidelines

For best overall performance, follow the guidelines in this section. Place all circuit components on the same side of the printed circuit board (PCB) and as near as practical to the respective LDO pin connections. Place ground return connections for the input and output capacitors as close to the GND pin as possible, using wide, component-side, copper planes. Do not use vias and long traces to create LDO circuit connections to the input capacitor, output capacitor, or resistor divider. This practice negatively affects system performance. This grounding and layout scheme minimizes inductive parasitics, and thereby reduces load current transients, minimizes noise, and increases circuit stability. A ground reference plane is also recommended and is embedded in the PCB or located on the bottom side of the PCB opposite the components. This reference plane serves to provide accuracy of the output voltage and shield the LDO from noise. To improve the thermal performance of the device, and to maximize the current output at high ambient temperature, spread the copper under the thermal pad as far as possible and place enough thermal vias on the copper under the thermal pad. Figure 7-6 and Figure 7-7 show example layout for TPS7E81 packages.

### 7.2.4.2 Layout Example

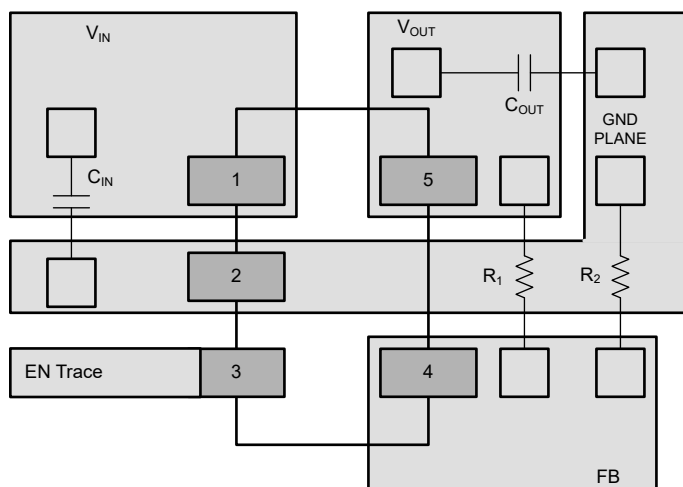


Figure 7-6. Example layout for TPS7E81, DBV Package

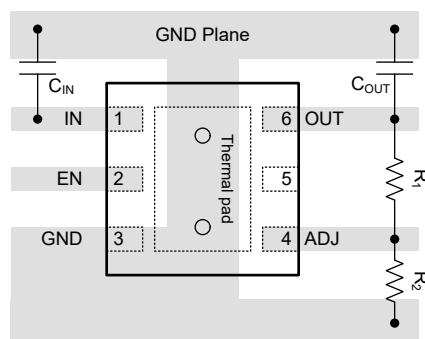


Figure 7-7. Example layout for TPS7E81, DRV Package

## 8 Device and Documentation Support

TI offers an extensive line of development tools. Tools and software to evaluate the performance of the device, generate code, and develop solutions are listed in this section.

### 8.1 Device Support

#### 8.1.1 Development Support

An evaluation module (EVM) is available to assist in the initial circuit performance evaluation using the TPS7E81. The [Universal EVM](#) (and related [user's guide](#)) can be requested at the TI website through the product folders or purchased directly from [the TI eStore](#).

#### 8.1.2 Device Nomenclature

**Table 8-1. Device Nomenclature**

PRODUCT <sup>(1)</sup>	DESCRIPTION
TPS7E81xx yyy z	<p><b>xx</b> is the nominal output voltage. For example, 33 = 3.3V, 50 = 5.0V, 01 = Adjustable.</p> <p><b>yyy</b> is the package designator. For example, DBV = SOT-23, DRV = WSON.</p> <p><b>z</b> indicates the package quantity. R is for large reel (3000 pieces).</p>

(1) For the most current package and ordering information see the Package Option Addendum at the end of this document, or visit the device product folder on [www.ti.com](#).

### 8.2 Documentation Support

#### 8.2.1 Related Documentation

For related documentation, see the following:

- Texas Instruments, [Know Your Limits application note](#)

### 8.3 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on [ti.com](#). Click on *Notifications* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

### 8.4 Support Resources

[TI E2E™ support forums](#) are an engineer's go-to source for fast, verified answers and design help — straight from the experts. Search existing answers or ask your own question to get the quick design help you need.

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### 8.5 Trademarks

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### 8.6 Electrostatic Discharge Caution



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

### 8.7 Glossary

[TI Glossary](#) This glossary lists and explains terms, acronyms, and definitions.

## 9 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

**Changes from Revision \* (October 2025) to Revision A (December 2025)****Page**

- Changed the device status from Advanced to Production Data..... [1](#)



## 10 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

## PACKAGING INFORMATION

Orderable part number	Status (1)	Material type (2)	Package   Pins	Package qty   Carrier	RoHS (3)	Lead finish/ Ball material (4)	MSL rating/ Peak reflow (5)	Op temp (°C)	Part marking (6)
<a href="#">PTPS7E8101DBVR</a>	Active	Preproduction	SOT-23 (DBV)   5	3000   LARGE T&R	-	Call TI	Call TI	-40 to 125	
<a href="#">PTPS7E8133DBVR</a>	Active	Preproduction	SOT-23 (DBV)   5	3000   LARGE T&R	-	Call TI	Call TI	-40 to 125	
<a href="#">PTPS7E8150DBVR</a>	Active	Preproduction	SOT-23 (DBV)   5	3000   LARGE T&R	-	Call TI	Call TI	-40 to 125	
<a href="#">TPS7E8101DBVR</a>	Active	Production	SOT-23 (DBV)   5	3000   LARGE T&R	Yes	Call TI	Level-1-260C-UNLIM	-40 to 125	3UDF
<a href="#">TPS7E8150DBVR</a>	Active	Production	SOT-23 (DBV)   5	3000   LARGE T&R	Yes	Call TI	Level-1-260C-UNLIM	-40 to 125	3UIF

<sup>(1)</sup> **Status:** For more details on status, see our [product life cycle](#).

<sup>(2)</sup> **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

<sup>(3)</sup> **RoHS values:** Yes, No, RoHS Exempt. See the [TI RoHS Statement](#) for additional information and value definition.

<sup>(4)</sup> **Lead finish/Ball material:** Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

<sup>(5)</sup> **MSL rating/Peak reflow:** The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

<sup>(6)</sup> **Part marking:** There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

**Important Information and Disclaimer:**The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

**OTHER QUALIFIED VERSIONS OF TPS7E81 :**

- Automotive : [TPS7E81-Q1](#)

NOTE: Qualified Version Definitions:

- Automotive - Q100 devices qualified for high-reliability automotive applications targeting zero defects

## TAPE AND REEL INFORMATION



\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
TPS7E8101DBVR	SOT-23	DBV	5	3000	180.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
TPS7E8150DBVR	SOT-23	DBV	5	3000	180.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3

## TAPE AND REEL BOX DIMENSIONS



\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
TPS7E8101DBVR	SOT-23	DBV	5	3000	210.0	185.0	35.0
TPS7E8150DBVR	SOT-23	DBV	5	3000	210.0	185.0	35.0



# EXAMPLE BOARD LAYOUT

DBV0005A

SOT-23 - 1.45 mm max height

SMALL OUTLINE TRANSISTOR



LAND PATTERN EXAMPLE  
EXPOSED METAL SHOWN  
SCALE:15X



SOLDER MASK DETAILS

4214839/K 08/2024

NOTES: (continued)

6. Publication IPC-7351 may have alternate designs.
7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.

## EXAMPLE STENCIL DESIGN

DBV0005A

SOT-23 - 1.45 mm max height

SMALL OUTLINE TRANSISTOR



SOLDER PASTE EXAMPLE  
BASED ON 0.125 mm THICK STENCIL  
SCALE:15X

4214839/K 08/2024

NOTES: (continued)

8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
9. Board assembly site may have different recommendations for stencil design.



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