



TPS65653-Q1 dual 3 A buck converters

1 Features

- AEC-Q100 qualified with the following results:
 - Device temperature grade 1: -40°C to $+125^{\circ}\text{C}$ ambient operating temperature
- Input voltage: 2.8 V to 5.5 V
- Two high-efficiency step-down DC/DC converters:
 - Output voltage: 1 V to 3.36 V
 - Maximum output current 3 A
 - Programmable output-voltage slew rate from 0.5 mV/ μs to 10 mV/ μs
 - 4-MHz Switching frequency
 - Spread-spectrum mode and phase interleaving for EMI reduction
- Configurable general-purpose output signals (GPO, GPO2)
- I²C-compatible interface supporting standard (100 kHz), fast (400 kHz), fast+ (1 MHz), and high-speed (3.4 MHz) modes
- Interrupt function with programmable masking
- Programmable power-good signal (PGOOD)
- External clock input to synchronize switching
- Output short-circuit and overload protection
- Overtemperature warning and protection
- Overvoltage protection (OVP) and undervoltage lockout (UVLO)
- 28-pin, 5-mm × 5-mm VQFN package with wettable flanks

2 Applications

- Radar system ECU
- Automotive head unit and cluster
- Automotive camera module
- Surround view system ECU
- Automotive display

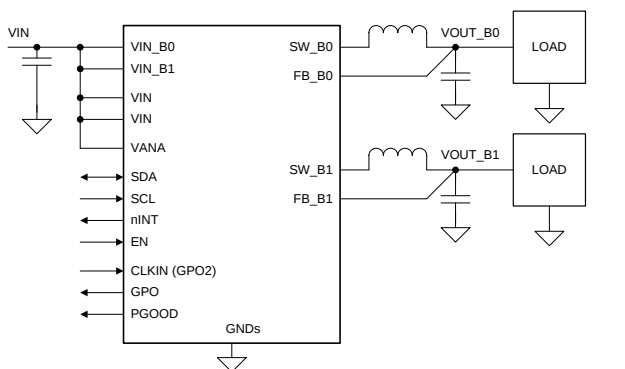
3 Description

The TPS65653-Q1 is designed to provide a tight power specification for noise sensitive applications, such as radar. The device contains two step-down DC/DC converters and general-purpose digital-output signals. The device is controlled by an I²C-compatible serial interface and by an enable signal.

The automatic PWM/PFM (AUTO mode) operation gives high efficiency over a wide output-current range. The TPS65653-Q1 supports remote voltage sensing to compensate IR drop between the regulator output and the point-of-load (POL) thus improving the accuracy of the output voltage. In addition the switching clock can be forced to PWM mode and also synchronized to an external clock to minimize the disturbances.

The TPS65653-Q1 device supports programmable start-up and shutdown delays and sequences including GPO signals synchronized to the enable signal. During start-up and voltage change, the device controls the output slew rate to minimize output voltage overshoot and the in-rush current.

Simplified Schematic



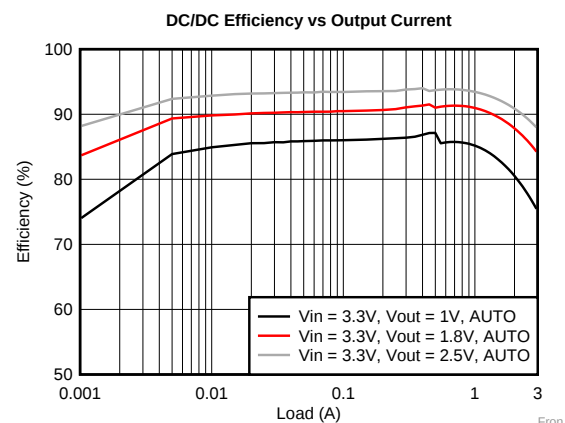
Copyright © 2018, Texas Instruments Incorporated

Device Information

PART NUMBER	PACKAGE	BODY SIZE (NOM)
TPS65653-Q1	VQFN (28)	5.00 mm × 5.00 mm

- (1) For all available packages, see the orderable addendum at the end of the data sheet.

DC/DC Efficiency vs Output Current



From



Table of Contents

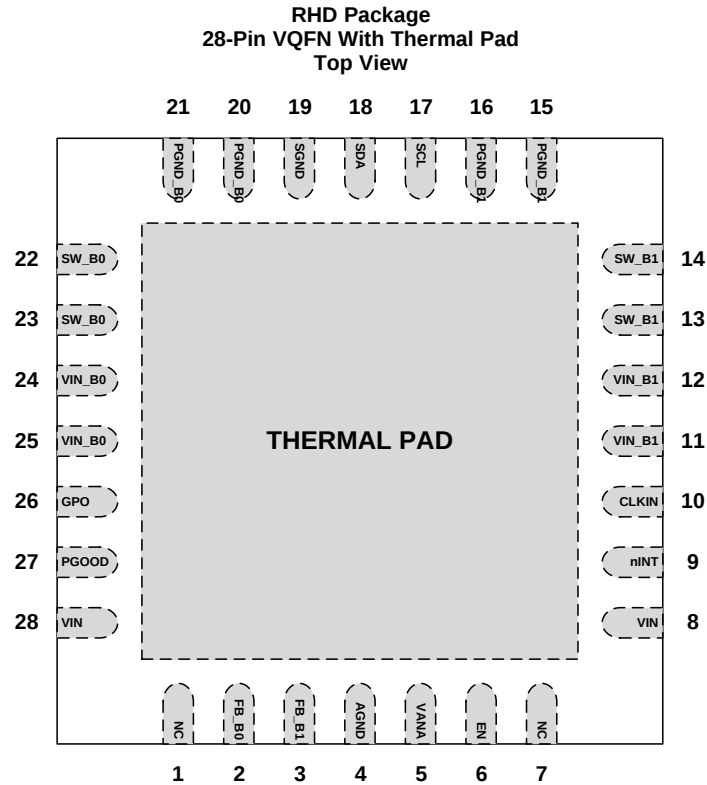
1 Features	1	7.4 Device Functional Modes.....	29
2 Applications	1	7.5 Programming.....	30
3 Description	1	7.6 Register Maps	33
4 Revision History	2	8 Application and Implementation	47
5 Pin Configuration and Functions	3	8.1 Application Information.....	47
6 Specifications	5	8.2 Typical Application	47
6.1 Absolute Maximum Ratings	5	9 Power Supply Recommendations	53
6.2 ESD Ratings	5	10 Layout	53
6.3 Recommended Operating Conditions.....	5	10.1 Layout Guidelines	53
6.4 Thermal Information	6	10.2 Layout Example	54
6.5 Electrical Characteristics.....	6	11 Device and Documentation Support	55
6.6 I ² C Serial Bus Timing Parameters	10	11.1 Device Support.....	55
6.7 Typical Characteristics	12	11.2 Receiving Notification of Documentation Updates	55
7 Detailed Description	13	11.3 Community Resources.....	55
7.1 Overview	13	11.4 Trademarks	55
7.2 Functional Block Diagram	14	11.5 Electrostatic Discharge Caution.....	55
7.3 Feature Description	14	11.6 Glossary	55

4 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

DATE	REVISION	NOTES
March 2019	*	Initial release

5 Pin Configuration and Functions



Pin Functions

PIN		TYPE ⁽¹⁾	DESCRIPTION
NUMBER	NAME		
1	NC	O	Unused. Leave this pin floating.
2	FB_B0	A	Output voltage feedback (positive) for Buck 0
3	FB_B1	A	Output voltage feedback (positive) for Buck 1
4	AGND	G	Ground
5	VANA	P/I	Supply voltage for analog and digital blocks. Must be connected to same node with VIN_Bx.
6	EN	D/I	Programmable enable signal for regulators and GPOs. If the pin is not used, leave the pin floating.
7	NC	O	Unused. Leave this pin floating.
8	VIN	I	Unused. Connect this pin to VANA.
9	nINT	D/O	Open-drain interrupt output. Active LOW. If the pin is not used, connect the pin to ground.
10	CLKIN	D//O	External clock input. Alternative function is general-purpose digital output (GPO2). If the pin is not used, leave the pin floating.
11, 12	VIN_B1	P/I	Input for Buck 1. The separate power pins VIN_Bx are not connected together internally - VIN_Bx pins must be connected together in the application and be locally bypassed.
13, 14	SW_B1	P/O	Buck 1 switch node. If the Buck 1 is not used, leave the pin floating.
15, 16	PGND_B1	P/G	Power ground for Buck 1
17	SCL	D/I	Serial interface clock input for I ² C access. Connect a pullup resistor. If the I ² C interface is not used, connect the pin to Ground.
18	SDA	D//O	Serial interface data input and output for I ² C access. Connect a pullup resistor. If the I ² C interface is not used, connect the pin to Ground.
19	SGND	G	Ground

(1) A: Analog Pin, D: Digital Pin, G: Ground Pin, P: Power Pin, I: Input Pin, O: Output Pin

Pin Functions (continued)

PIN		TYPE ⁽¹⁾	DESCRIPTION
NUMBER	NAME		
20, 21	PGND_B0	P/G	Power ground for Buck 0
22, 23	SW_B0	P/O	Buck 0 switch node. If the Buck 0 is not used, leave the pin floating.
24, 25	VIN_B0	P/I	Input for Buck 0. The separate power pins VIN_Bx are not connected together internally - VIN_Bx pins must be connected together in the application and be locally bypassed.
26	GPO	D/O	General-purpose digital output. If the pin is not used, leave the pin floating.
27	PGOOD	D/O	Power-good indication signal. If the pin is not used, leave the pin floating.
28	VIN	I	Unused. Connect this pin to VANA.
Thermal Pad	—	—	Connect to PCB ground plane using multiple vias for good thermal performance.

6 Specifications

6.1 Absolute Maximum Ratings

Over operating free-air temperature range (unless otherwise noted)⁽¹⁾⁽²⁾

		MIN	MAX	UNIT
VIN, VIN_Bx, VANA	Voltage on power connections (must use the same input supply)	−0.3	6	V
SW_Bx	Voltage on buck switch nodes	−0.3	(VIN_Bx + 0.3 V) with 6-V maximum	V
FB_Bx	Voltage on buck voltage sense nodes	−0.3	(VANA + 0.3 V) with 6-V maximum	V
SDA, SCL, nINT, EN	Voltage on logic pins (input or output pins)	−0.3	(VANA + 0.3 V) with 6-V maximum	V
PGOOD, GPO, CLKIN (GPO2)	Voltage on logic pins (input or output pins)	−0.3	(VANA + 0.3 V) with 6-V maximum	V
T _{J-MAX}	Junction temperature	−40	150	°C
T _{stg}	Storage temperature	−65	150	
Maximum lead temperature (soldering, 10 seconds)			260	

- (1) Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Conditions*. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.
- (2) All voltage values are with respect to network ground.

6.2 ESD Ratings

		VALUE	UNIT
V _(ESD)	Electrostatic discharge	Human-body model (HBM), per AEC Q100-002 ⁽¹⁾	±2000
		Charged-device model (CDM), per AEC Q100-011	±500
		All pins	±750
		Corner pins (1, 7, 8, 14, 15, 21, 22, 28)	

- (1) AEC Q100-002 indicates that HBM stressing shall be in accordance with the ANSI/ESDA/JEDEC JS-001 specification.

6.3 Recommended Operating Conditions

Over operating free-air temperature range (unless otherwise noted)

		MIN	MAX	UNIT
INPUT VOLTAGE				
VIN, VIN_Bx, VANA	Voltage on power connections (must use the same input supply)	2.8	5.5	V
EN, nINT	Voltage on logic pins (input or output pins)	0	5.5	V
CLKIN	Voltage on logic pins (input pin)	0	VANA	V
PGOOD, GPO, GPO2	Voltage on logic pins (output pins)	0	VANA	V
SCL, SDA	Voltage on I2C interface, Standard (100 kHz), Fast (400 kHz), Fast+ (1 MHz), and High-Speed (3.4 MHz) Modes	0	1.95	V
	Voltage on I2C interface, Standard (100 kHz), Fast (400 kHz), and Fast+ (1 MHz) Modes	0	VANA with 3.6-V maximum	V
TEMPERATURE				
T _J	Junction temperature	−40	140	°C
T _A	Ambient temperature	−40	125	°C

6.4 Thermal Information

THERMAL METRIC ⁽¹⁾		TPS65653-Q1	UNIT
		RHD (VQFN)	
		28 PINS	
R _{θJA}	Junction-to-ambient thermal resistance	36.7	°C/W
R _{θJCTop}	Junction-to-case (top) thermal resistance	26.6	°C/W
R _{θJB}	Junction-to-board thermal resistance	8.9	°C/W
ψ _{JT}	Junction-to-top characterization parameter	0.4	°C/W
ψ _{JB}	Junction-to-board characterization parameter	8.8	°C/W
R _{θJCbott}	Junction-to-case (bottom) thermal resistance	2.2	°C/W

(1) For more information about traditional and new thermal metrics, see the [Semiconductor and IC Package Thermal Metrics](#) application note.

6.5 Electrical Characteristics

Limits apply over the junction temperature range $-40^{\circ}\text{C} \leq T_J \leq +140^{\circ}\text{C}$, specified V_{VANA} , $V_{\text{VIN_Bx}}$, $V_{\text{VOUT_Bx}}$, and I_{OUT} range, unless otherwise noted. Typical values are at $T_J = 25^{\circ}\text{C}$, $V_{\text{VANA}} = V_{\text{VIN_Bx}} = 3.7\text{ V}$, and $V_{\text{OUT}} = 1\text{ V}$, unless otherwise noted.⁽¹⁾⁽²⁾

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
EXTERNAL COMPONENTS						
C _{IN_VANA}	Input filtering capacitance for VANA	Effective capacitance, connected from VANA to AGND	100			nF
C _{IN_BUCK}	Input filtering capacitance for buck regulators	Effective capacitance, connected from VIN_Bx to PGND_Bx	1.9	10		μF
C _{OUT_BUCK}	Output filtering capacitance for buck regulators, local	Effective capacitance	10	22		μF
C _{POL_BUCK}	Point-of-load (POL) capacitance for buck regulators	POL capacitance	22			μF
C _{OUT-TOTAL_BUCK}	Buck output capacitance, total (local and POL)	Total output capacitance, VIN_Bx ≤ 4 V and Slew rate ≤ 3.8 mV/μs			150	μF
		Total output capacitance, VIN_Bx > 4 V			100	μF
		Total output capacitance, Slew rate > 3.8 mV/μs			100	μF
ESR _C	Input and output capacitor ESR	[1-10] MHz	2		10	mΩ
L	Inductor	Inductance of the inductor	0.47			μH
			-30%30%			
DCR _L	Inductor DCR		25			mΩ
BUCK REGULATORS						
V _{(VIN_Bx), V(VANA)}	Input voltage range	VIN_Bx and VANA pins must be connected to the same supply line	2.8	3.3	5.5	V
V _{OUT_Bx}	Output voltage	Programmable voltage range	1	1	3.36	V
		Step size, 1 V ≤ V _{OUT} < 1.4 V	5		mV	
		Step size, 1.4 V ≤ V _{OUT} ≤ 3.36 V	20			
I _{OUT_Bx}	Output current	Output current	3 ⁽³⁾			A
	Input and Output voltage difference	Minimum voltage between V _(VIN_Bx) and V _{OUT} to fulfill the electrical characteristics	0.8			V

(1) All voltage values are with respect to network ground.

(2) Minimum (MIN) and Maximum (MAX) limits are specified by design, test, or statistical analysis. Typical (TYP) numbers are not verified, but do represent the most likely norm.

(3) The maximum output current can be limited by the forward current limit $I_{\text{LIM_FWD}}$. The power dissipation inside the die increases the junction temperature and limits the maximum current depending of the length of the current pulse, efficiency, board and ambient temperature.

Electrical Characteristics (continued)

Limits apply over the junction temperature range $-40^{\circ}\text{C} \leq T_J \leq +140^{\circ}\text{C}$, specified V_{VANA} , $V_{\text{VIN_Bx}}$, $V_{\text{VOUT_Bx}}$, and I_{OUT} range, unless otherwise noted. Typical values are at $T_J = 25^{\circ}\text{C}$, $V_{\text{VANA}} = V_{\text{VIN_Bx}} = 3.7\text{ V}$, and $V_{\text{OUT}} = 1\text{ V}$, unless otherwise noted.⁽¹⁾⁽²⁾

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
$V_{\text{OUT_Bx_DC}}$	DC output voltage accuracy, includes voltage reference, DC load and line regulations, process and temperature	Force PWM mode	-2%		2%	
		PFM mode. Average output voltage level is increased by max. 20 mV	-2%		2% + 20 mV	
Ripple voltage		PWM mode, $L = 0.47\text{ }\mu\text{H}$, $I_{\text{OUT}} = 500\text{ mA}$, $C_{\text{OUT}} = 22\text{ }\mu\text{F} + 22\text{ }\mu\text{F}$ (GCM31CR71A226KE02)		4		$\text{mV}_{\text{p-p}}$
		PFM mode, $L = 0.47\text{ }\mu\text{H}$, $I_{\text{OUT}} = 10\text{ mA}$, $C_{\text{OUT}} = 22\text{ }\mu\text{F} + 22\text{ }\mu\text{F}$ (GCM31CR71A226KE02)		25		
DC_{LNR}	DC line regulation	$I_{\text{OUT}} = 1\text{ A}$		± 0.05		%/V
DC_{LDR}	DC load regulation in PWM mode	$V_{\text{OUT_Bx}} = 1\text{ V}$, I_{OUT} from 0 to $I_{\text{OUT(max)}}$		0.3%		
T_{LDSR}	Transient load step response	$I_{\text{OUT}} = 0\text{ A}$ to 3 A , $T_R = T_F = 1\text{ }\mu\text{s}$, PWM mode, $V_{\text{VIN_Bx}} = 3.3\text{ V}$, $V_{\text{OUT_Bx}} = 1\text{ V}$, $C_{\text{OUT}} = 44\text{ }\mu\text{F}$, $L = 0.47\text{ }\mu\text{H}$, $f_{\text{SW}} = 4\text{ MHz}$		± 60		mV
T_{LNSR}	Transient line response	$V_{\text{(VIN_Bx)}}$ stepping $3\text{ V} \leftrightarrow 3.5\text{ V}$, $T_R = T_F = 10\text{ }\mu\text{s}$, $I_{\text{OUT}} = I_{\text{OUT(max)}}$		± 10		mV
$I_{\text{LIM FWD}}$	Forward current limit per phase (peak for every switching cycle)	Programmable range	1.5		4	A
		Step size		0.5		
		Accuracy, $V_{\text{(VIN_Bx)}} \geq 3\text{ V}$, $I_{\text{LIM}} = 4\text{ A}$	-5%	7.5%	20%	
		Accuracy, $2.8\text{ V} \leq V_{\text{(VIN_Bx)}} < 3\text{ V}$, $I_{\text{LIM}} = 4\text{ A}$	-20%	7.5%	20%	
$I_{\text{LIM NEG}}$	Negative current limit		1.6	2.0	3.0	A
$R_{\text{DS(ON) HS FET}}$	On-resistance, high-side FET	Between VIN_Bx and SW_Bx pins ($I = 1\text{ A}$)		50	110	$\text{m}\Omega$
$R_{\text{DS(ON) LS FET}}$	On-resistance, low-side FET	Between SW_Bx and PGND_Bx pins ($I = 1\text{ A}$)		45	90	$\text{m}\Omega$
f_{SW}	Switching frequency	PWM mode	3.6	4	4.4	MHz
	Start-up time (soft start)	From ENx to $V_{\text{OUT_Bx}} = 0.35\text{ V}$ (slew-rate control begins)		120		μs
Output voltage slew-rate ⁽⁴⁾		$\text{SLEW_RATEx}[2:0] = 010$	-15%	10	15%	$\text{mV}/\mu\text{s}$
		$\text{SLEW_RATEx}[2:0] = 011$		7.5		
		$\text{SLEW_RATEx}[2:0] = 100$		3.8		
		$\text{SLEW_RATEx}[2:0] = 101$		1.9		
		$\text{SLEW_RATEx}[2:0] = 110$		0.94		
		$\text{SLEW_RATEx}[2:0] = 111$		0.47		
$I_{\text{PFM-PWM}}$	PFM-to-PWM - current threshold ⁽⁵⁾			550		mA
$I_{\text{PWM-PFM}}$	PWM-to-PFM - current threshold ⁽⁵⁾			290		mA
$R_{\text{DIS_Bx}}$	Output pulldown resistance	Regulator disabled	150	250	350	Ω

(4) The slew-rate can be limited by the current limit (forward or negative current limit), output capacitance and load current.

(5) The final PFM-to-PWM and PWM-to-PFM switchover current varies slightly and is dependent on the output voltage, input voltage and the inductor current level.

Electrical Characteristics (continued)

Limits apply over the junction temperature range $-40^{\circ}\text{C} \leq T_J \leq +140^{\circ}\text{C}$, specified V_{VANA} , $V_{\text{VIN_BX}}$, $V_{\text{VOUT_BX}}$, and I_{OUT} range, unless otherwise noted. Typical values are at $T_J = 25^{\circ}\text{C}$, $V_{\text{VANA}} = V_{\text{VIN_BX}} = 3.7\text{ V}$, and $V_{\text{OUT}} = 1\text{ V}$, unless otherwise noted.⁽¹⁾⁽²⁾

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
Output voltage monitoring for PGOOD pin and for power-good Interrupt	V _(VIN_BX) and V _(VANA) fixed 3.7 V					
	Overvoltage threshold (compared to DC output voltage level, V _{VOU_T_B_X_DC})		39	50	64	mV
	Undervoltage threshold (compared to DC output voltage level, V _{VOU_T_B_X_DC})		−53	−40	−29	
	Deglitch time during operation and after voltage change		4		15	μs
Gating time for PGOOD signal after regulator enable or voltage change	PGOOD_MODE = 0			800		μs
EXTERNAL CLOCK AND PLL						
f _{EXT_CLK} External input clock ⁽⁶⁾	Nominal frequency		1		24	MHz
	Nominal frequency step size			1		
	Required accuracy from nominal frequency		−10%		10%	
External clock detection	Delay for missing clock detection				1.8	μs
	Delay and debounce for clock detection				20	
Clock change delay (internal to external)	Delay from valid clock detection to use of external clock			600		μs
PLL output clock jitter	Cycle to cycle			300		ps, p-p
PROTECTION FUNCTIONS						
Thermal warning ⁽⁷⁾	Temperature rising, TDIE_WARN_LEVEL = 0		115	125	135	°C
	Temperature rising, TDIE_WARN_LEVEL = 1		127	137	147	
	Hysteresis			20		
Thermal shutdown ⁽⁷⁾	Temperature rising		140	150	160	°C
	Hysteresis			20		
VANA _{OVP} VANA overvoltage	Voltage rising		5.6	5.8	6.1	V
	Voltage falling		5.45	5.73	5.96	
	Hysteresis		40			mV
VANA _{UVLO} VANA undervoltage lockout	Voltage rising		2.51	2.63	2.75	V
	Voltage falling		2.5	2.6	2.7	
Buck short-circuit detection	Threshold		280	360	440	mV
LOAD CURRENT MEASUREMENT FOR BUCK REGULATORS						
Current measurement range	Maximum code				10.22	A
Resolution	LSB			20		mA
Measurement accuracy	I _{OUT} > 1 A			<10%		
Measurement time	PFM mode (automatically changing to PWM mode for the measurement)			45		μs
	PWM mode			4		
CURRENT CONSUMPTION						
Standby current consumption, regulators disabled				9		μA

(6) The external clock frequency must be selected so that buck switching frequency is above 1.7 MHz.

(7) For a given device thermal warning will always happen at a lower temperature than thermal shutdown.

Electrical Characteristics (continued)

Limits apply over the junction temperature range $-40^{\circ}\text{C} \leq T_J \leq +140^{\circ}\text{C}$, specified V_{VANA} , V_{VIN_Bx} , V_{VOUT_Bx} , and I_{OUT} range, unless otherwise noted. Typical values are at $T_J = 25^{\circ}\text{C}$, $V_{VANA} = V_{VIN_Bx} = 3.7\text{ V}$, and $V_{OUT} = 1\text{ V}$, unless otherwise noted.⁽¹⁾⁽²⁾

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
	Active current consumption, one buck regulator enabled in auto mode, internal RC oscillator, PGOOD monitoring enabled	$I_{OUT_Bx} = 0\text{ mA}$, not switching		58		μA
	Active current consumption, two buck regulators enabled in auto mode, internal RC oscillator, PGOOD monitoring enabled	$I_{OUT_Bx} = 0\text{ mA}$, not switching		100		μA
	Active current consumption during PWM operation, one buck regulator enabled	$I_{OUT_Bx} = 0\text{ mA}$		15		mA
	Active current consumption during PWM operation, two buck regulators enabled	$I_{OUT_Bx} = 0\text{ mA}$		30		mA
	PLL and clock detector current consumption	$f_{EXT_CLK} = 1\text{ MHz}$, Additional current consumption when enabled		2		mA
DIGITAL INPUT SIGNALS EN, SCL, SDA, CLKIN						
V_{IL}	Input low level				0.4	V
V_{IH}	Input high level		1.2			
V_{HYS}	Hysteresis of Schmitt Trigger inputs		10	80	200	mV
	EN/CLKIN pulldown resistance	$EN_PD/CLKIN_PD = 1$		500		$\text{k}\Omega$
DIGITAL OUTPUT SIGNALS nINT, SDA						
V_{OL}	Output low level	nINT: $I_{SOURCE} = 2\text{ mA}$			0.4	V
		SDA: $I_{SOURCE} = 20\text{ mA}$			0.4	V
R_P	External pullup resistor for nINT	To VIO Supply		10		$\text{k}\Omega$
DIGITAL OUTPUT SIGNALS PGOOD, GPO, GPO2						
V_{OL}	Output low level	$I_{SOURCE} = 2\text{ mA}$			0.4	V
V_{OH}	Output high level, configured to push-pull	$I_{SINK} = 2\text{ mA}$	$V_{VANA} - 0.4$		V_{VANA}	V
V_{PU}	Supply voltage for external pullup resistor, configured to open-drain				V_{VANA}	V
R_{PU}	External pullup resistor, configured to open-drain			10		$\text{k}\Omega$
ALL DIGITAL INPUTS						
I_{LEAK}	Input current	All logic inputs over pin voltage range	-1		1	μA

6.6 I²C Serial Bus Timing Parameters

These specifications are ensured by design. Unless otherwise noted, $V_{IN_BX} = 3.7$ V. See ⁽¹⁾ and Figure 1.

		MIN	MAX	UNIT
f_{SCL}	Serial clock frequency	Standard mode	100	kHz
		Fast mode	400	
		Fast mode+	1	MHz
		High-speed mode, $C_b = 100$ pF	3.4	
		High-speed mode, $C_b = 400$ pF	1.7	
t_{LOW}	SCL low time	Standard mode	4.7	μ s
		Fast mode	1.3	
		Fast mode+	0.5	
		High-speed mode, $C_b = 100$ pF	0.16	
		High-speed mode, $C_b = 400$ pF	0.32	
t_{HIGH}	SCL high time	Standard mode	4	μ s
		Fast mode	0.6	
		Fast mode+	0.26	
		High-speed mode, $C_b = 100$ pF	0.06	
		High-speed mode, $C_b = 400$ pF	0.12	
$t_{SU;DAT}$	Data setup time	Standard mode	250	ns
		Fast mode	100	
		Fast mode+	50	
		High-speed mode	10	
$t_{HD;DAT}$	Data hold time	Standard mode	10	ns
		Fast mode	10	
		Fast mode+	10	
		High-speed mode, $C_b = 100$ pF	10	
		High-speed mode, $C_b = 400$ pF	10	
$t_{SU;STA}$	Setup time for a start or a repeated start condition	Standard mode	4.7	μ s
		Fast mode	0.6	
		Fast mode+	0.26	
		High-speed mode	0.16	
$t_{HD;STA}$	Hold time for a start or a repeated start condition	Standard mode	4	μ s
		Fast mode	0.6	
		Fast mode+	0.26	
		High-speed mode	0.16	
t_{BUF}	Bus free time between a stop and start condition	Standard mode	4.7	μ s
		Fast mode	1.3	
		Fast mode +	0.5	
$t_{SU;STO}$	Setup time for a stop condition	Standard mode	4	μ s
		Fast mode	0.6	
		Fast mode+	0.26	
		High-speed mode	0.16	
t_{rDA}	Rise time of SDA signal	Standard mode	1000	ns
		Fast mode	20	
		Fast mode+	120	
		High-speed mode, $C_b = 100$ pF	10	
		High-speed mode, $C_b = 400$ pF	20	

(1) C_b refers to the capacitance of one bus line.

I²C Serial Bus Timing Parameters (continued)

These specifications are ensured by design. Unless otherwise noted, $V_{IN_BX} = 3.7$ V. See ⁽¹⁾ and Figure 1.

		MIN	MAX	UNIT
t_{fDA}	Fall time of SDA signal	Standard mode	300	ns
		Fast mode	$20 \times (V_{DD} / 5.5 \text{ V})$	
		Fast mode+	$20 \times (V_{DD} / 5.5 \text{ V})$	
		High-speed mode, $C_b = 100$ pF	10	
		High-speed mode, $C_b = 400$ pF	30	
t_{rCL}	Rise time of SCL signal	Standard mode	1000	ns
		Fast mode	20	
		Fast mode+	120	
		High-speed mode, $C_b = 100$ pF	10	
		High-speed mode, $C_b = 400$ pF	20	
t_{rCL1}	Rise time of SCL signal after a repeated start condition and after an acknowledge bit	High-speed mode, $C_b = 100$ pF	10	ns
		High-speed mode, $C_b = 400$ pF	20	
t_{fCL}	Fall time of a SCL signal	Standard mode	300	ns
		Fast mode	$20 \times (V_{DD} / 5.5 \text{ V})$	
		Fast mode+	$20 \times (V_{DD} / 5.5 \text{ V})$	
		High-speed mode, $C_b = 10 - 100$ pF	10	
		High-speed mode, $C_b = 400$ pF	20	
C_b	Capacitive load for each bus line (SCL and SDA)		400	pF
t_{SP}	Pulse width of spike suppressed (SCL and SDA spikes that are less than the indicated width are suppressed)	Standard mode, fast mode, and fast mode+	50	ns
		High-speed mode	10	

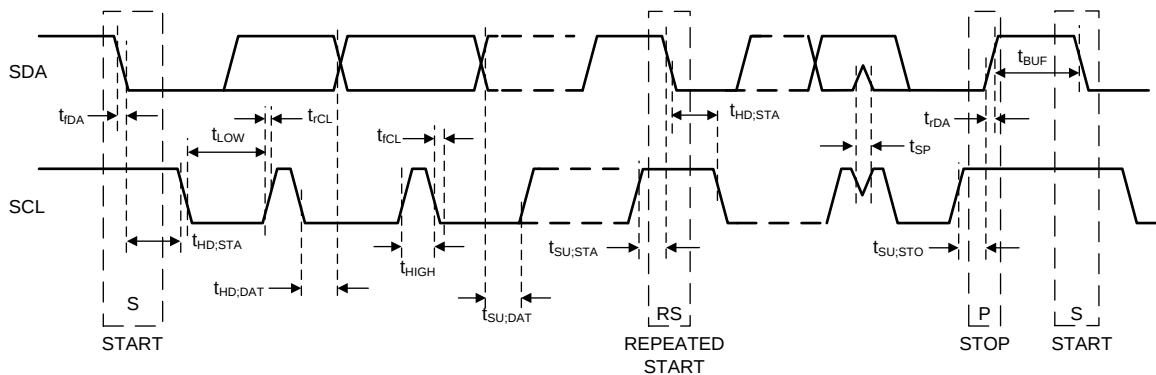
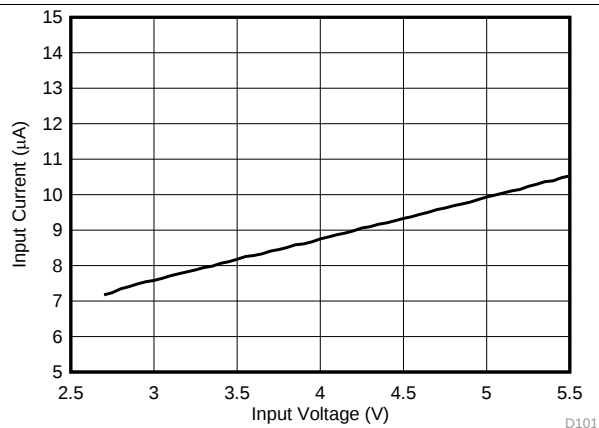


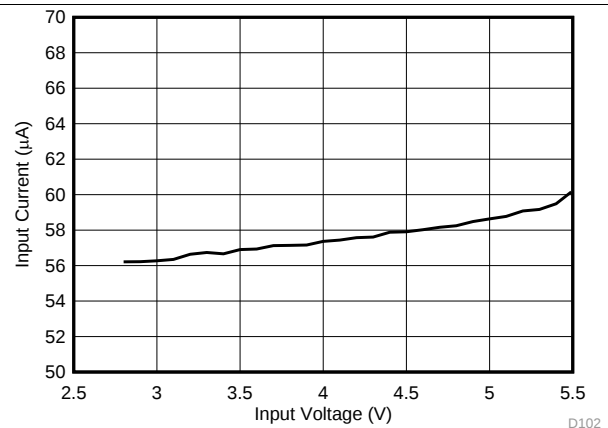
Figure 1. I²C Timing

6.7 Typical Characteristics

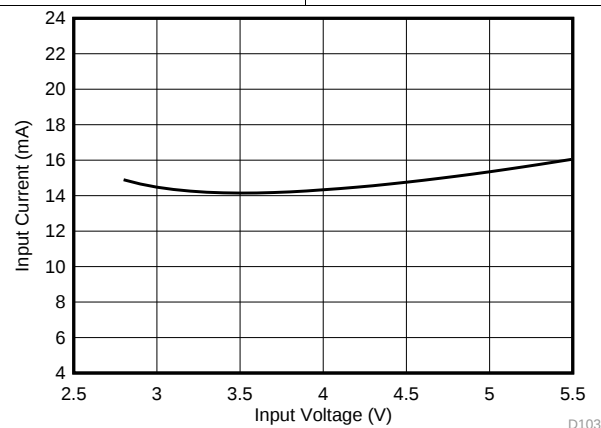
Unless otherwise specified: $V_{(VIN_Bx)} = V_{(VANA)} = 3.7\text{ V}$, $V_{OUT_Bx} = 1\text{ V}$, $T_A = 25^\circ\text{C}$, $L = 0.47\text{ }\mu\text{H}$ (Murata DFE252012PD-R47M), $C_{OUT_BUCK} = 22\text{ }\mu\text{F}$, and $C_{POL_BUCK} = 22\text{ }\mu\text{F}$



Regulators disabled

Figure 2. Standby Current Consumption vs Input Voltage

 $V_{OUT_Bx} = 1\text{ V}$

Load = 0 mA

Figure 3. Active State Current Consumption vs Input Voltage, One Buck Regulator Enabled in PFM Mode

 $V_{OUT_Bx} = 1\text{ V}$

Load = 0 mA

Figure 4. Active State Current Consumption vs Input Voltage, One Buck Regulator Enabled in Forced PWM Mode

7 Detailed Description

7.1 Overview

The TPS65653-Q1 is a high-efficiency, high-performance flexible power supply device with two step-down DC/DC converter cores (Buck0 and Buck1) for automotive applications. [Table 1](#) lists the output characteristics of the regulators.

Table 1. Supply Specification

SUPPLY	OUTPUT		
	V _{OUT} RANGE (V)	RESOLUTION (mV)	I _{MAX} MAXIMUM OUTPUT CURRENT (mA)
Buck0	1 to 3.36	5 (1 V to 1.4 V) 20 (1.4 V to 3.36 V)	3000
Buck1	1 to 3.36	5 (1 V to 1.4 V) 20 (1.4 V to 3.36 V)	3000

The TPS65653-Q1 also supports switching clock synchronization to an external clock (CLKIN pin). The nominal frequency of the external clock can be from 1 MHz to 24 MHz with 1-MHz steps.

Additional features include:

- Soft-start
- Input voltage protection:
 - Undervoltage lockout
 - Overvoltage protection
- Output voltage monitoring and protection:
 - Overvoltage monitoring
 - Undervoltage monitoring
 - Overload protection
- Thermal warning
- Thermal shutdown

The TPS65653-Q1 has one dedicated general purpose digital output (GPO) signal. CLKIN pin can be programmed as a second GPO signal (GPO2) if external clock is not needed. The output type (open-drain or push-pull) is programmable for the GPOs.

Feature Description (continued)

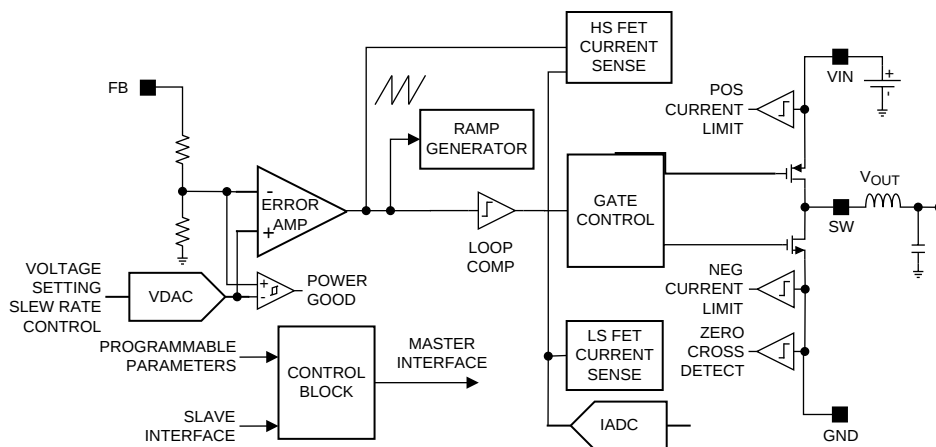
- Soft start
- Power Good flag with maskable interrupt
- Power Good signal (PGOOD) with selectable sources
- Average output current sensing (for PFM entry and load current measurement)

The following parameters can be programmed via registers, the default values are set by OTP bits:

- Output voltage
- Forced PWM operation
- Switch current limit
- Output voltage slew rate
- Enable and disable delays

There are two modes of operation for the buck converter, depending on the output current required: pulse-width modulation (PWM) and pulse-frequency modulation (PFM). The converter operates in PWM mode at high load currents of approximately 600 mA or higher. Lighter output current loads cause the converter to automatically switch into PFM mode for reduced current consumption when forced PWM mode is disabled. The forced PWM mode can be selected to maintain fixed switching frequency at all load current levels.

A block diagram of a single core is shown in Figure 5.



Copyright © 2016, Texas Instruments Incorporated

Figure 5. Detailed Block Diagram Showing One Core

7.3.1.2 Transition Between PWM and PFM Modes

PWM mode operation optimizes efficiency at mid to full load at the expense of light-load efficiency. The TPS65653-Q1 converter operates in PWM mode at load current of about 600 mA or higher. At lighter load current levels the device automatically switches into PFM mode for reduced current consumption when forced PWM mode is disabled (AUTO mode operation). By combining the PFM and the PWM modes a high efficiency is achieved over a wide output-load current range.

7.3.1.3 Buck Converter Load Current Measurement

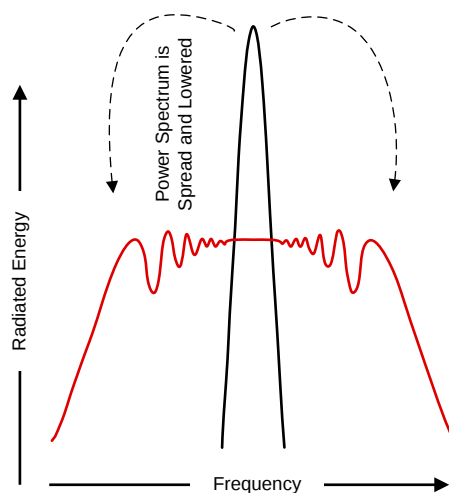
Buck load current can be monitored via I²C registers. The monitored buck converter is selected with the LOAD_CURRENT_BUCK_SELECT bit in SEL_I_LOAD register. A write to this selection register starts a current measurement sequence. The regulator is automatically forced to PWM mode for the measurement period. The measurement sequence is 50 μ s long, maximum.

Feature Description (continued)

TPS65653-Q1 can be configured to give out an interrupt (I_MEAS_INT bit in INT_TOP_1 register) after the load current measurement sequence is finished. Load current measurement interrupt can be masked with I_MEAS_MASK bit (TOP_MASK_1 register). The measurement result can be read from registers I_LOAD_1 and I_LOAD_2. Register I_LOAD_1 bits BUCK_LOAD_CURRENT[7:0] give out the LSB bits and register I_LOAD_2 bit BUCK_LOAD_CURRENT[8] the MSB bit. The measurement result BUCK_LOAD_CURRENT[8:0] LSB is 20 mA, and maximum code value of the measurement corresponds to 10.22 A.

7.3.1.4 Spread-Spectrum Mode

Systems with periodic switching signals may generate a large amount of switching noise in a set of narrowband frequencies (the switching frequency and its harmonics). The usual solution to reduce noise coupling is to add EMI-filters and shields to the boards. The TPS65653-Q1 has register selectable spread-spectrum mode which minimizes the need for output filters, ferrite beads, or chokes. In spread spectrum mode, the switching frequency varies around the center frequency, reducing the EMI emissions radiated by the converter and associated passive components and PCB traces (see Figure 6). This feature is available only when internal RC oscillator is used (EN_PLL bit is 0 in PLL_CTRL register), and it is enabled with the EN_SPREAD_SPEC bit in CONFIG register, and it affects both buck cores.



Where a fixed frequency converter exhibits large amounts of spectral energy at the switching frequency, the spread spectrum architecture of the TPS65653-Q1 spreads that energy over a large bandwidth.

Figure 6. Spread-Spectrum Modulation

7.3.2 Sync Clock Functionality

The TPS65653-Q1 device contains a CLKIN input to synchronize the switching clock of the buck regulators with the external clock. The block diagram of the clocking and PLL module is shown in Figure 7. Depending on the EN_PLL bit in PLL_CTRL register and the external clock availability, the external clock is selected and interrupt is generated as shown in Table 2. The interrupt can be masked with SYNC_CLK_MASK bit in TOP_MASK_1 register. The nominal frequency of the external input clock is set by EXT_CLK_FREQ[4:0] bits in PLL_CTRL register, and it can be from 1 MHz to 24 MHz with 1-MHz steps. The external clock must be inside accuracy limits (–10%/+10%) of the selected frequency for valid clock detection.

The SYNC_CLK_INT interrupt in INT_TOP_1 register is also generated in cases where the external clock is expected but it is not available. These cases are start-up (read OTP-to-standby transition) when EN_PLL is 1 and Buck regulator enable (standby-to-active transition) when EN_PLL is 1.

Feature Description (continued)

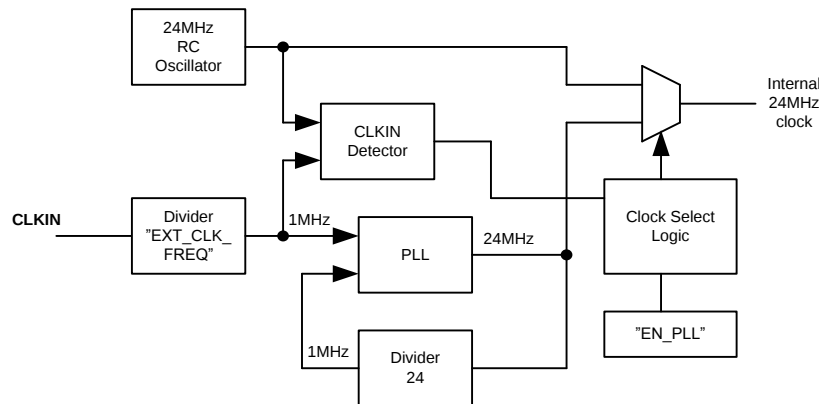


Figure 7. Clock and PLL Module

Table 2. PLL Operation

DEVICE OPERATION MODE	EN_PLL	PLL AND CLOCK DETECTOR STATE	INTERRUPT FOR EXTERNAL CLOCK	CLOCK
STANDBY	0	Disabled	No	Internal RC
ACTIVE	0	Disabled	No	Internal RC
STANDBY	1	Enabled	When external clock appears or disappears	Automatic change to external clock when available
ACTIVE	1	Enabled	When external clock appears or disappears	Automatic change to external clock when available

7.3.3 Power-Up

The power-up sequence for the TPS65653-Q1 is as follows:

- VANA (and VIN_Bx) reach minimum recommended levels ($V_{VANA} > V_{ANA_{UVLO}}$). This initiates power-on-reset (POR), OTP reading, and enables the system I/O interface. The I²C host should allow at least 1.2 ms before writing or reading data to the TPS65653-Q1.
- Device enters standby mode.
- The host can change the default register setting by I²C if needed.
- The regulators can be enabled/disabled and the GPO signals can be controlled by EN pin and by I²C interface.

Transitions between the operating modes are shown in [Modes of Operation](#).

7.3.4 Regulator Control

7.3.4.1 Enabling and Disabling Regulators

The regulators can be enabled when the device is in STANDBY or ACTIVE state. There are two ways for enable and disable the buck regulators:

- Using BUCKx_EN bit in BUCKx_CTRL_1 register (BUCKx_EN_PIN_CTRL bit is 0 in BUCKx_CTRL_1 register)
- Using EN control pin (BUCKx_EN bit is 1 **AND** BUCKx_EN_PIN_CTRL bit is 1)

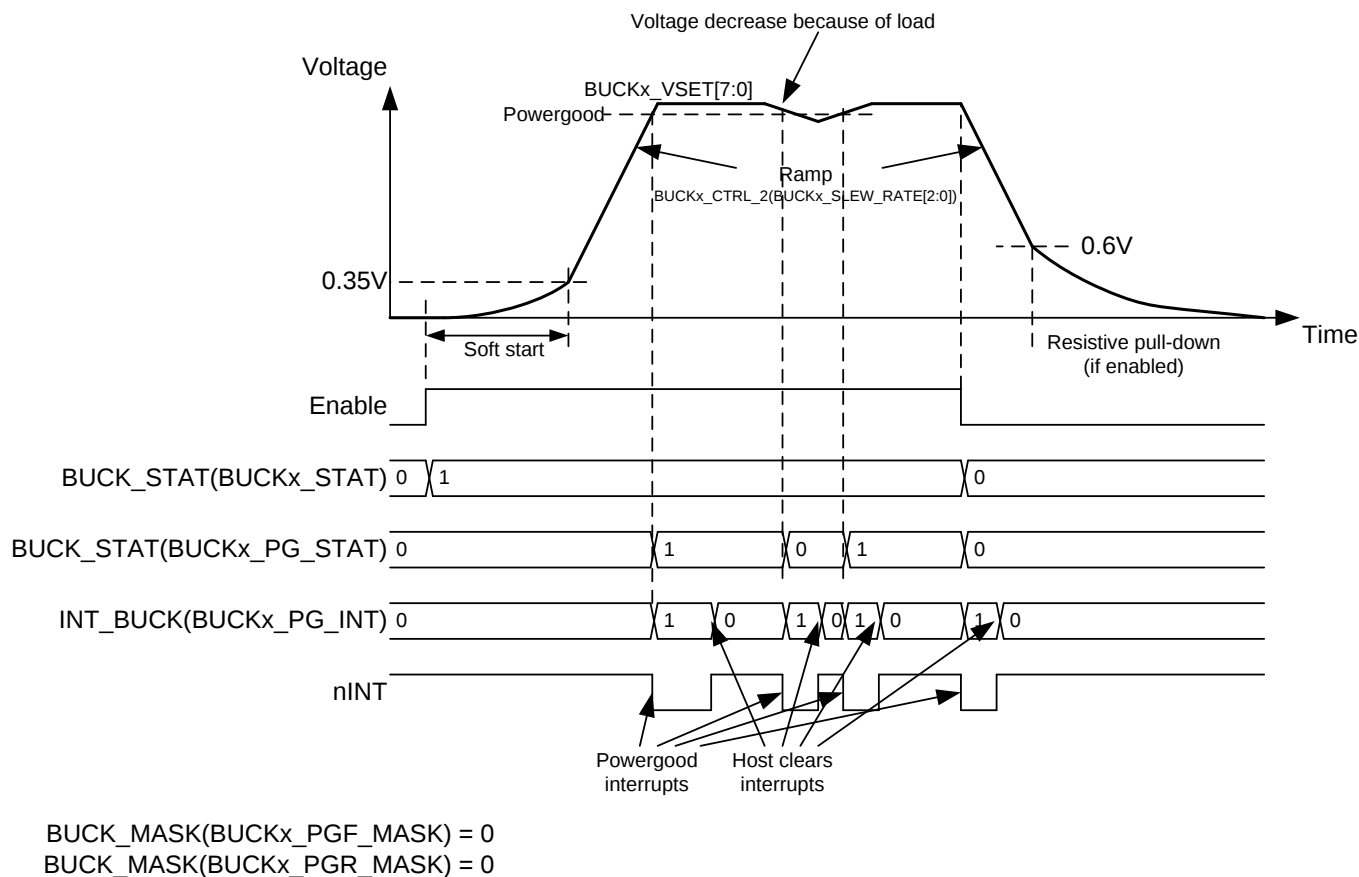
If the EN control pin is used for enable and disable then the delay from the control signal rising edge to start-up is set by BUCKx_STARTUP_DELAY[3:0] bits in BUCKx_DELAY register and the delay from control signal falling edge to shutdown is set by BUCKx_SHUTDOWN_DELAY[3:0] bits in BUCKx_DELAY register. The delays are valid only for EN signal transitions and not for control with I²C writings to the BUCKx_EN bit.

The control of the regulator (with 0-ms delays) is shown in [Table 3](#).

Table 3. Regulator Control

	BUCKx_EN	BUCKx_EN_PIN_CTRL	EN PIN	BUCKx OUTPUT VOLTAGE
Enable/disable control with BUCKx_EN bit	0	Don't Care	Don't Care	Disabled
	1	0	Don't Care	BUCKx_VSET[7:0]
Enable/disable control with EN pin	1	1	Low	Disabled
	1	1	High	BUCKx_VSET[7:0]

The buck regulator is enabled by the EN pin or by I²C writing as shown in [Figure 8](#). The soft-start circuit limits the in-rush current during start-up. When the output voltage rises to a 0.35-V level, the output voltage becomes slew-rate controlled. If there is a short circuit at the output, and the output voltage does not increase above the 0.35-V level in 1 ms or the output voltage drops below 0.35-V level during operation (for minimum of 1 ms), the regulator is disabled, and BUCKx_SC_INT interrupt in INT_BUCK register is set. When the output voltage reaches the Power-Good threshold level the BUCKx_PG_INT interrupt flag in INT_BUCK register is set. The Power-Good interrupt flag when reaching valid output voltage can be masked using BUCKx_PGR_MASK bit in BUCK_MASK register. The Power-Good interrupt flag can be also generated when the output voltage becomes invalid. The interrupt mask for invalid output voltage detection is set by BUCKx_PGF_MASK bit in BUCK_MASK register. A BUCKx_PG_STAT bit in BUCK_STAT register shows always the validity of the output voltage: 1 means valid and 0 means invalid output voltage. A PGOOD_WINDOW_BUCK bit in PGOOD_CTRL_1 register sets the detection method for the valid buck output voltage, either undervoltage detection or undervoltage and overvoltage detection.


Figure 8. Buck Regulator Enable and Disable

The EN input pin has an integrated pulldown resistor. The pulldown resistor is controlled with EN_PD bit in CONFIG register.

7.3.4.2 Changing Output Voltage

The output voltage of the regulator can be changed by writing to the BUCKx_VOUT register. The voltage change for buck regulator is always slew-rate controlled, and the slew-rate is defined by the BUCKx_SLEW_RATE[2:0] bits in BUCKx_CTRL_2 register. During voltage change the forced PWM mode is used automatically. When the programmed output voltage is achieved, the mode becomes the one defined by load current, and the BUCKx_FPWM bit in BUCKx_CTRL_1 register.

The voltage change and Power-Good interrupts are shown in Figure 9.

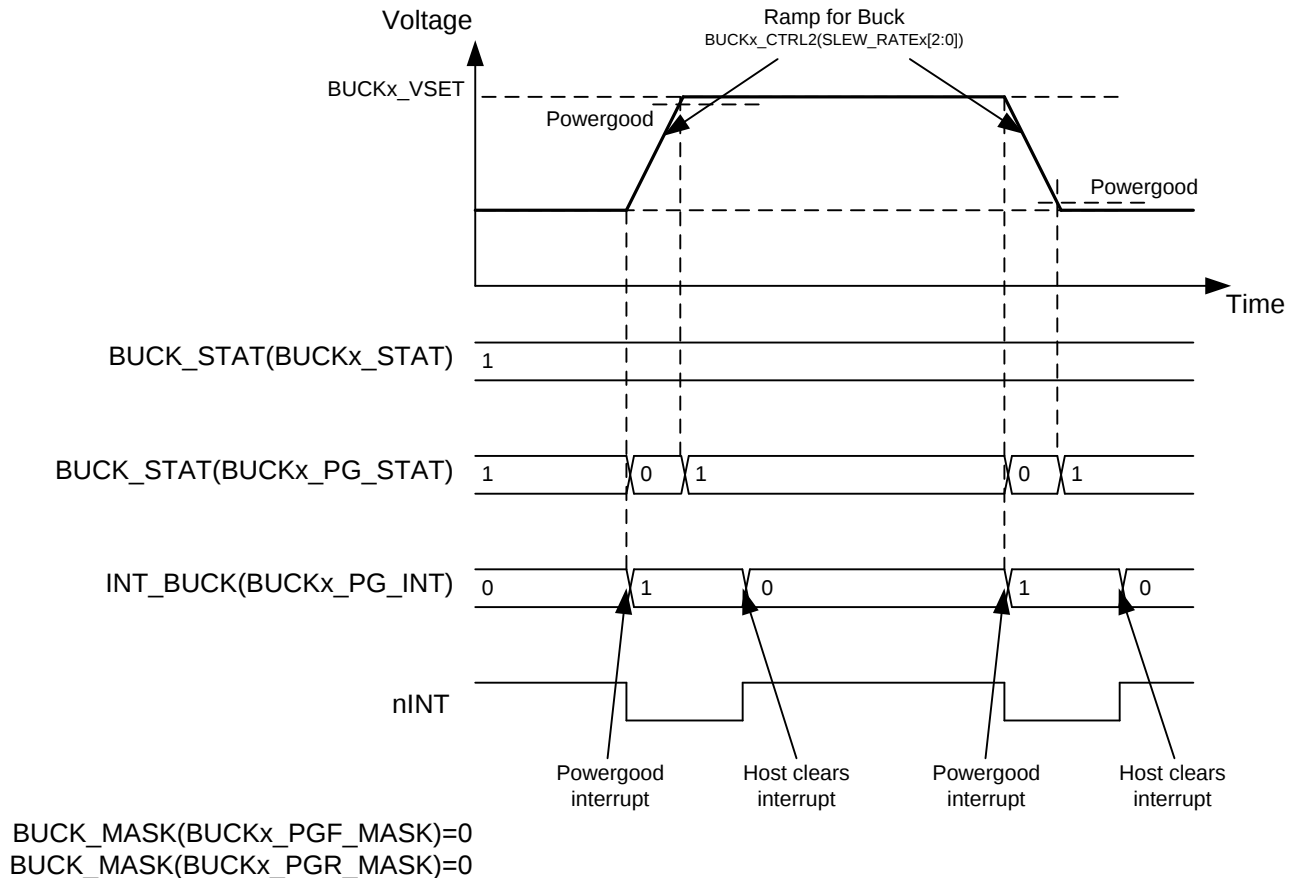


Figure 9. Regulator Output Voltage Change

7.3.5 Enable and Disable Sequences

The TPS65653-Q1 device supports start-up and shutdown sequencing with programmable delays for different regulator outputs using single EN control signal. The Buck regulator is selected for delayed control with:

- BUCKx_EN = 1 in BUCKx_CTRL_1 register
- BUCKx_EN_PIN_CTRL = 1 in BUCKx_CTRL_1 register
- BUCKx_VSET[7:0] bits in BUCKx_VOUT register defines the voltage when EN pin is high
- The delay from rising edge of EN pin to the regulator enable is set by BUCKx_STARTUP_DELAY[3:0] bits in BUCKx_DELAY register and
- The delay from falling edge of EN pin to the regulator disable is set by BUCKx_SHUTDOWN_DELAY[3:0] bits in BUCKx_DELAY register.

The GPO (and GPO2) digital output signals can be also controlled as a part of start-up and shutdown sequencing with the following settings:

- GPOx_EN = 1 in GPO_CTRL register
- GPOx_EN_PIN_CTRL = 1 in GPO_CTRL register
- The delay from rising edge of EN pin to the rising edge of GPO/GPO2 signal is set by

GPOx_STARTUP_DELAY[3:0] bits in GPOx_DELAY register and

- The delay from falling edge of EN pin to the falling edge of GPO/GPO2 signal is set by GPOx_SHUTDOWN_DELAY[3:0] bits in GPOx_DELAY register.

An example of the start-up and shutdown sequences for the buck regulators are shown in Figure 10. The start-up and shutdown delays for the Buck0 regulator are 1 ms and 4 ms; for the Buck1 regulator start-up and shutdown delays are 3 ms and 1 ms. The delay settings are used only for enable/disable control with EN signal.

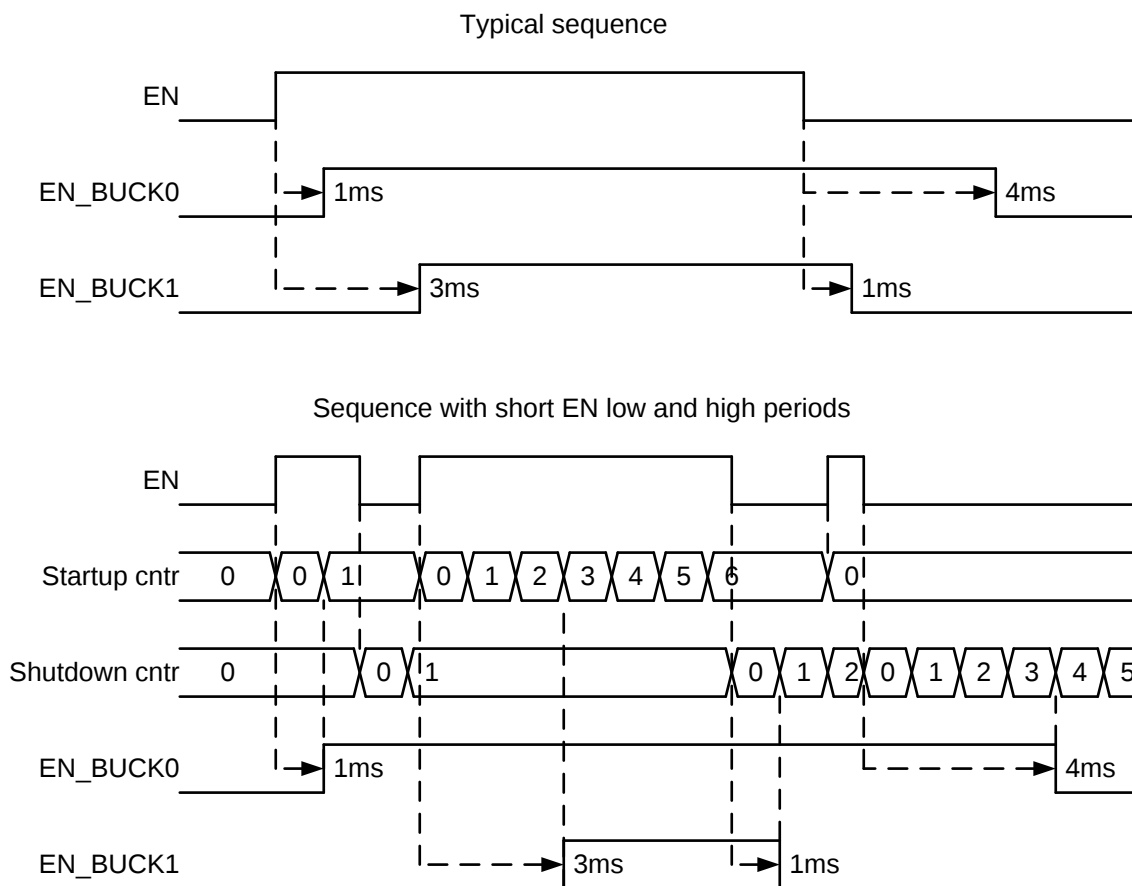


Figure 10. Start-Up and Shutdown Sequencing

7.3.6 Device Reset Scenarios

There are two reset methods implemented on the TPS65653-Q1:

- Software reset with SW_RESET bit in RESET register
- Undervoltage lockout (UVLO) reset from VANA supply

An SW reset occurs when SW_RESET bit is written 1. The bit is automatically cleared after writing. This event disables all the regulators immediately, drives GPO and GPO2 signals low, resets all the register bits to the default values and OTP bits are loaded (see [Figure 15](#)). I²C interface is not reset during software reset.

If VANA supply voltage falls below the UVLO threshold level then all the regulators are disabled immediately, GPO and GPO2 signals are driven low, and all the register bits are reset to the default values. When the VANA supply voltage transition above UVLO threshold level an internal POR occurs. OTP bits are loaded to the registers and a startup is initiated according to the register settings.

7.3.7 Diagnosis and Protection Features

The TPS65653-Q1 is capable of providing four levels of protection features:

- Information of valid regulator output voltage which sets interrupt or PGOOD signal;
- Warnings for diagnosis which sets interrupt;
- Protection events which are disabling the regulators; and
- Faults which are causing the device to shutdown.

The TPS65653-Q1 sets the flag bits indicating what protection or warning conditions have occurred, and the nINT pin is pulled low. nINT is released again after a clear of flags is complete. The nINT signal stays low until all the pending interrupts are cleared.

When a fault is detected or software requested reset, it is indicated by a RESET_REG_INT interrupt flag in INT_TOP_2 register after next start-up. If the RESET_REG_MASK is set to masked in the OTP, the interrupt is not generated. The mask bit change with I²C does not affect, because the RESET_REG_MASK bit is loaded from OTP during reset sequence.

Table 4. Summary of Interrupt Signals

EVENT	OUTCOME	INTERRUPT BIT	INTERRUPT MASK BIT	STATUS BIT	RECOVERY/INTERRUPT CLEAR
Buck current limit triggered	No effect	BUCK_INT BUCKX_ILIM_INT	BUCKX_ILIM_MASK	BUCKX_ILIM_STAT	Write 1 to BUCKX_ILIM_INT bit Interrupt is not cleared if current limit is active
Buck short circuit ($V_{OUT} < 0.35$ V at 1 ms after enable) or overload (V_{OUT} decreasing below 0.35 V during operation, 1-ms debounce)	Regulator disable	BUCK_INT BUCKX_SC_INT	N/A	N/A	Write 1 to BUCKX_SC_INT bit
Thermal warning	No effect	TDIE_WARN_INT	TDIE_WARN_MASK	TDIE_WARN_STAT	Write 1 to TDIE_WARN_INT bit Interrupt is not cleared if temperature is above thermal warning level
Thermal shutdown	All regulators disabled immediately and GPO and GPO2 are set to low	TDIE_SD_INT	N/A	TDIE_SD_STAT	Write 1 to TDIE_SD_INT bit Interrupt is not cleared if temperature is above thermal shutdown level
VANA overvoltage ($VANA_{OVP}$)	All regulators disabled immediately and GPO and GPO2 are set to low	OVP_INT	N/A	OVP_STAT	Write 1 to OVP_INT bit Interrupt is not cleared if VANA voltage is above $VANA_{OVP}$ level
Buck power good, output voltage becomes valid	No effect	BUCK_INT BUCKX_PG_INT	BUCKX_PGR_MASK	BUCKX_PG_STAT	Write 1 to BUCKX_PG_INT bit
Buck power good, output voltage becomes invalid	No effect	BUCK_INT BUCKX_PG_INT	BUCKX_PGF_MASK	BUCKX_PG_STAT	Write 1 to BUCKX_PG_INT bit
PGOOD pin changing from active to inactive state ⁽¹⁾	No effect	PGOOD_INT	PGOOD_MASK	PGOOD_STAT	Write 1 to PGOOD_INT bit
External clock appears or disappears	No effect to regulators	SYNC_CLK_INT ⁽²⁾	SYNC_CLK_MASK	SYNC_CLK_STAT	Write 1 to SYNC_CLK_INT bit
Load current measurement ready	No effect	I_MEAS_INT	I_MEAS_MASK	N/A	Write 1 to I_MEAS_INT bit
Supply voltage $VANA_{UVLO}$ triggered (VANA falling)	Immediate shutdown, registers reset to default values	N/A	N/A	N/A	N/A
Supply voltage $VANA_{UVLO}$ triggered (VANA rising)	Startup, registers reset to default values and OTP bits loaded	RESET_REG_INT	RESET_REG_MASK	N/A	Write 1 to RESET_REG_INT bit
Software requested reset	Immediate shutdown followed by power up, registers reset to default values	RESET_REG_INT	RESET_REG_MASK	N/A	Write 1 to RESET_REG_INT bit

- (1) PGOOD_STAT bit is 1 when the PGOOD pin shows valid voltages. PGOOD_POL bit in PGOOD_CTRL_1 register affects only PGOOD pin polarity, not Power Good and PGOOD_INT interrupt polarity.
- (2) Interrupt is generated during clock-detector operation and if clock is not available when clock detector is enabled.

7.3.7.1 Power-Good Information (PGOOD pin)

In addition to the interrupt-based indication of the current limit and the Power-Good level the TPS65653-Q1 device supports monitoring with PGOOD signal:

- Regulator output voltage,
- Input supply overvoltage,
- Thermal warning and
- Thermal shutdown.

Regulator output voltage monitoring (not current limit monitoring) can be selected for PGOOD indication. This selection is individual for both buck regulators and is set by EN_PGOOD_BUCKx bits in PGOOD_CTRL_1 register. When a regulator is disabled, the monitoring is automatically masked to prevent it forcing PGOOD inactive. A thermal warning can be also selected for PGOOD indication with EN_PGOOD_TWARN bit in PGOOD_CTRL_2 register. The monitoring from all the output rails, thermal warning (TDIE_WARN_STAT), input overvoltage interrupt (OVP_INT), and thermal shutdown interrupt (TDIE_SD_INT) are combined, and PGOOD pin is active only if all the selected sources shows a valid status.

The type of output voltage monitoring for PGOOD signal is selected by PGOOD_WINDOW_x bits in PGOOD_CTRL_1 register. If the bit is 0, only undervoltage is monitored; if the bit is 1, both undervoltage and overvoltage are monitored.

The polarity and the output type (push-pull or open-drain) are selected by the PGOOD_POL and PGOOD_OD bits in the PGOOD_CTRL_1 register.

PGOOD is only *active* or *asserted* when all enabled power resource output voltages are within specified tolerance for each requested/programmed output voltage.

PGOOD is *inactive* or *de-asserted* if any enabled power resource output voltages is outside specified tolerance for each requested/programmed output voltage.

The device OTP setting selects either gated (that is, *unusual*) or continuous (that is, *invalid*) mode of operation.

7.3.7.1.1 PGOOD Pin Gated mode

The gated (or *unusual*) mode of operation is selected by setting PGOOD_MODE bit to 0 in PGOOD_CTRL_2 register.

For the gated mode of operation, PGOOD behaves as follows:

- PGOOD is set to *active* or *asserted* state upon exiting OTP configuration as an initial default state.
- PGOOD status is suspended or unchanged during an 800-μs gated time period, thereby *gating-off* the status indication.
- During normal power-up sequencing and requested voltage changes, PGOOD state is not changed during an 800-μs gated time period. It typically remains *active* or *asserted* for normal conditions.
- During an *abnormal* power-up sequencing and requested voltage changes, PGOOD status could change to *inactive* or *de-asserted* after an 800-μs gated time period if any output voltage is outside of regulation range.
- Using the *gated mode of operation* could allow the PGOOD signal to initiate an immediate power shutdown sequence if the PGOOD signal is wired-OR with signal connected to EN input. This type of circuit configuration provides a smart PORz function for processor that eliminates the need for additional components to generate PORz upon start-up and to monitor voltage levels of key voltage domains.

The fault sets corresponding fault bit 1 in PG_FAULT register. The detected fault must be cleared to continue the PGOOD monitoring. The overvoltage and thermal shutdown are cleared by writing 1 to the OVP_INT and TDIE_SD_INT interrupt bits in INT_TOP_1 register. The regulator fault is cleared by writing 1 to the corresponding register bit in PG_FAULT register. The interrupts can be also cleared with VANA UVLO by toggling the input supply. An example of PGOOD pin operation in gated mode is shown in Figure 11.

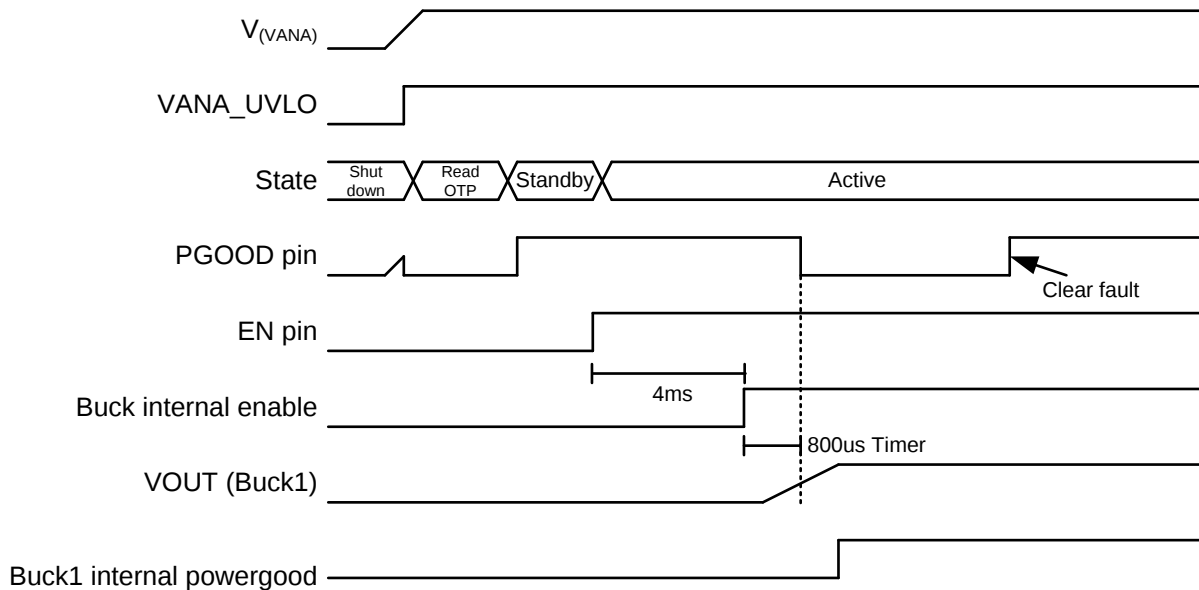


Figure 11. PGOOD Pin Operation in Gated Mode

7.3.7.1.2 PGOOD Pin Continuous Mode

The continuous (or *invalid*) mode of operation is selected by setting PGOOD_MODE bit to 1 in PGOOD_CTRL_2 register.

For the continuous mode of operation, PGOOD behaves as follows:

- PGOOD is set to *active* or *asserted* state upon exiting OTP configuration.

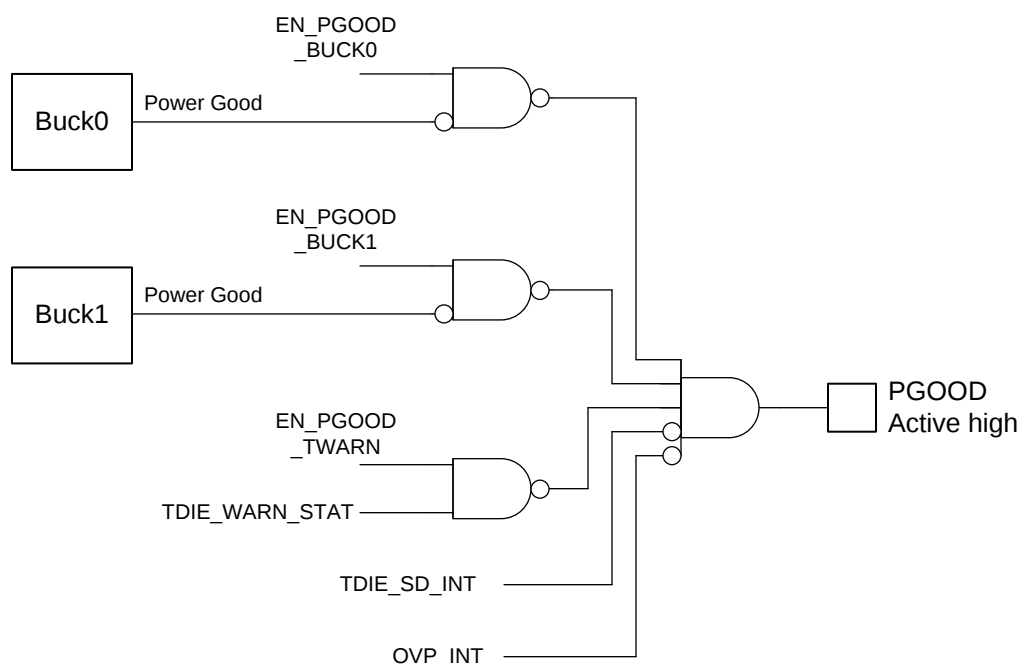
- PGOOD is set to *inactive* or *de-asserted* as soon as regulator is enabled.
- PGOOD status begins indicating output voltage regulation status immediately and continuously.
- During power-up sequencing and requested voltage changes, PGOOD will toggle between *inactive* or *de-asserted* while output voltages are outside of regulation ranges and *active* or *asserted* when inside of regulation ranges.

The PG_FAULT register bits are latched and maintain the fault information until host clears the fault bit by writing 1 to the bit. The PGOOD signal indicates also a thermal shutdown and input overvoltage interrupts, which are cleared by clearing the interrupt bits.

When regulator voltage is transitioning from one target voltage to another, the PGOOD signal is set inactive.

When the PGOOD signal becomes inactive, the source for the fault can be read from PG_FAULT register. If the invalid output voltage becomes valid again the PGOOD signal becomes active. Thus the PGOOD signal shows all the time if the monitored output voltages are valid. The block diagram for this operation is shown in [Figure 12](#) and an example of operation is shown in [Figure 13](#).

The PGOOD signal can be also configured so that it maintains inactive state even when the monitored outputs are valid but there are PG_FAULT_x bits in PG_FAULT register pending clearance. This type of operation is selected by setting PGFAULT_GATES_PGOOD bit to 1 in PGOOD_CTRL_2 register.



Copyright © 2018, Texas Instruments Incorporated

Figure 12. PGOOD Block Diagram (Continuous Mode)

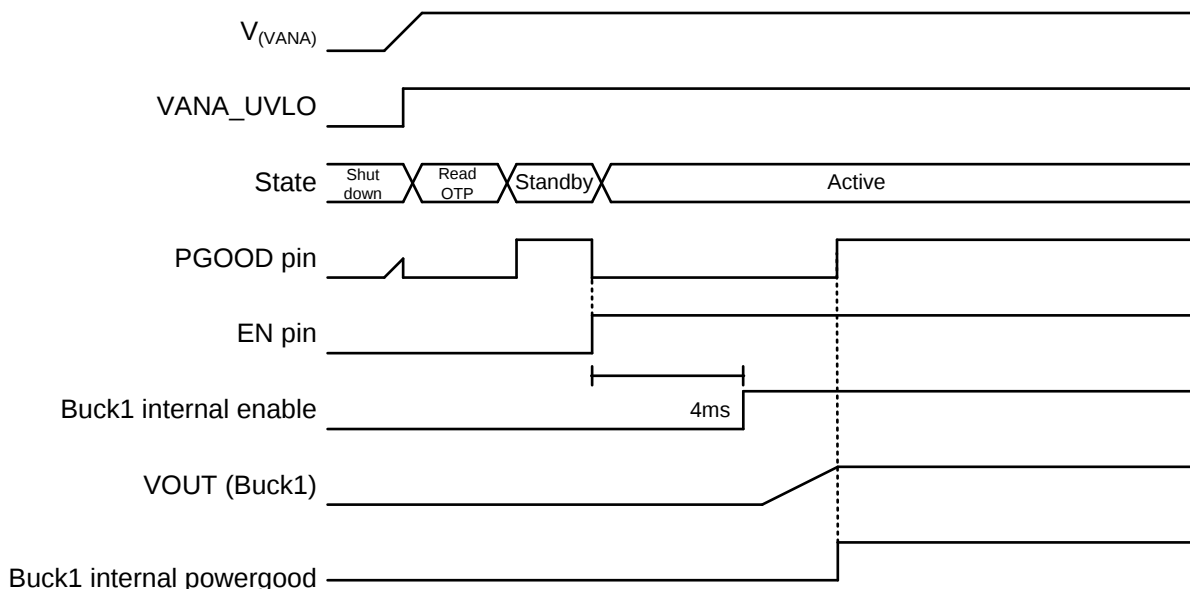


Figure 13. PGOOD Pin Operation in Continuous Mode

7.3.7.2 Warnings for Diagnosis (Interrupt)

7.3.7.2.1 Output Power Limit

The Buck regulators have programmable output peak current limits. The limits are individually programmed for both regulators with BUCKx_ILIM[2:0] bits in BUCKx_CTRL_2 register. If the load current is increased so that the current limit is triggered, the regulator continues to regulate to the limit current level (peak current regulation). The voltage may decrease if the load current is higher than limit current. If the current regulation continues for 20 μ s, the TPS65653-Q1 device sets the BUCKx_ILIM_INT bit in INT_BUCK register and pulls the nINT pin low. The host processor can read BUCKx_ILIM_STAT bits in BUCK_STAT register to see if the regulator is still in peak current regulation mode and the interrupt is cleared by writing 1 to BUCKx_ILIM_INT bit. The current limit interrupt can be masked by setting BUCKx_ILIM_MASK bit in BUCK_MASK register to 1. The Buck overload situation is shown in [Figure 14](#).

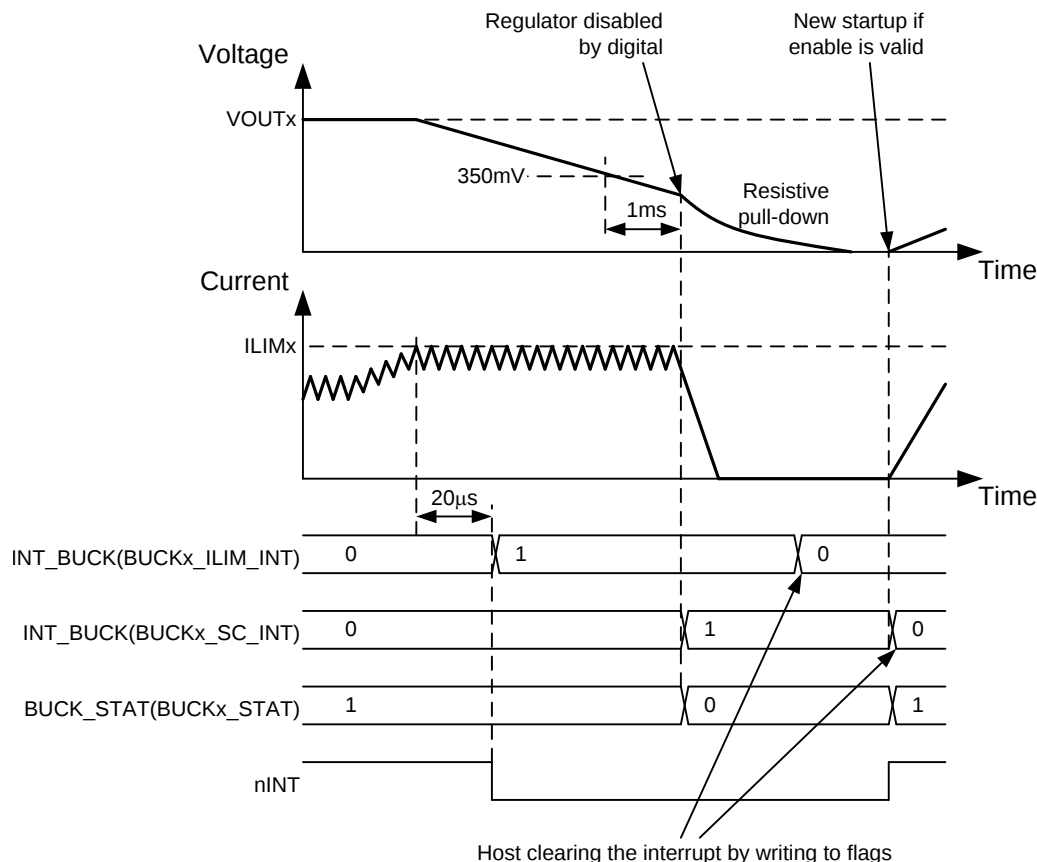


Figure 14. Buck Regulator Overload Situation

7.3.7.2.2 Thermal Warning

The TPS65653-Q1 device includes a protection feature against overtemperature by setting an interrupt for host processor. The threshold level of the thermal warning is selected with TDIE_WARN_LEVEL bit in CONFIG register.

If the TPS65653-Q1 device temperature increases above thermal warning level the device sets TDIE_WARN_INT bit in INT_TOP_1 register and pulls the nINT pin low. The status of the thermal warning can be read from TDIE_WARN_STAT bit in TOP_STAT register, and the interrupt is cleared by writing 1 to TDIE_WARN_INT bit. The thermal warning interrupt can be masked by setting TDIE_WARN_MASK bit in TOP_MASK_1 register to 1.

7.3.7.3 Protection (Regulator Disable)

If the regulator is disabled because of protection or fault (short-circuit protection, overload protection, thermal shutdown, input overvoltage protection, or UVLO), the output power FETs are set to high-impedance mode, and the output pulldown resistor is enabled (if enabled with BUCKx_RDIS_EN bit in BUCKx_CTRL_1 register). The turnoff time of the output voltage is defined by the output capacitance, load current, and the resistance of the integrated pull-down resistor. The pulldown resistors are active as long as VANA voltage is above approximately a 1.2-V level.

7.3.7.3.1 Short-Circuit and Overload Protection

A short-circuit protection feature allows the TPS65653-Q1 to protect itself and external components against short circuit at the output or against overload during start-up. For buck regulators the fault thresholds are about 350 mV, and the protection is triggered and the regulator is disabled if the output voltage is below the threshold level 1 ms after the regulator is enabled.

In a similar way the overload situation is protected during normal operation. If the output voltage falls below 0.35 V and 0.3 V and remains below the threshold level for 1 ms the regulator is disabled.

In buck regulator short-circuit and overload situations the BUCKx_SC_INT bit in INT_BUCK register and the INT_BUCKx bit in INT_TOP_1 register are set to 1, the BUCKx_STAT bit in BUCK_STAT register is set to 0, and the nINT signal is pulled low. The host processor clears the interrupt by writing 1 to the BUCKx_SC_INT bit. Upon clearing the interrupt the regulator makes a new start-up attempt if the regulator is in an enabled state.

7.3.7.3.2 Overvoltage Protection

The TPS65653-Q1 device monitors the input voltage from the VANA pin in standby and active operation modes. If the input voltage rises above V_{ANA_OVP} voltage level, all the regulators are disabled immediately (without switching ramp, no shutdown delays), pulldown resistors discharge the output voltages if they are enabled (BUCKx_RDIS_EN = 1 in BUCKx_CTRL_1 register), GPOs are set to logic low level, nINT signal is pulled low, OVP_INT bit in INT_TOP_1 register is set to 1, and BUCKx_STAT bit in BUCK_STAT register is set to 0. The host processor clears the interrupt by writing 1 to the OVP_INT bit. If the input voltage is above overvoltage detection level the interrupt is not cleared. The host can read the status of the overvoltage from the OVP_STAT bit in TOP_STAT register. Regulators cannot be enabled as long as the input voltage is above overvoltage detection level or the overvoltage interrupt is pending.

7.3.7.3.3 Thermal Shutdown

The TPS65653-Q1 has an overtemperature protection function that operates to protect itself from short-term misuse and overload conditions. When the junction temperature exceeds around 150°C, the regulators are disabled immediately (without switching ramp, no shutdown delays), the TDIE_SD_INT bit in INT_TOP_1 register is set to 1, the nINT signal is pulled low, and the device enters STANDBY. nINT is cleared by writing 1 to the TDIE_SD_INT bit. If the temperature is above thermal shutdown level the interrupt is not cleared. The host can read the status of the thermal shutdown from the TDIE_SD_STAT bit in TOP_STAT register. Regulators cannot be enabled as long as the junction temperature is above thermal shutdown level or the thermal shutdown interrupt is pending.

7.3.7.4 Fault (Power Down)

7.3.7.4.1 Undervoltage Lockout

When the input voltage falls below V_{ANA_UVLO} at the VANA pin, the buck regulators are disabled immediately (without switching ramp, no shutdown delays), and the output capacitor is discharged using the pulldown resistor, and the TPS65653-Q1 device enters SHUTDOWN. When $V_{(VANA)}$ voltage is above V_{ANA_UVLO} threshold level, the device powers up to STANDBY state.

If the reset interrupt is unmasked by default (OTP bit for RESET_REG_MASK is 0 in TOP_MASK_2 register) the RESET_REG_INT interrupt bit in INT_TOP_2 register indicates that the device has been in SHUTDOWN. The host processor must clear the interrupt by writing 1 to the RESET_REG_INT bit. If the host processor reads the RESET_REG_INT interrupt bit after detecting an nINT low signal, it knows that the input supply voltage has been below V_{ANA_UVLO} level (or the host has requested reset with SW_RESET bit in RESET register), and the registers are reset to default values.

7.3.8 Operation of the GPO Signals

The TPS65653-Q1 device supports up to 2 general purpose output signals, GPO and GPO2. The GPO2 signal is multiplexed with CLKIN signal. The selection between CLKIN and GPO2 pin function is set with CLKIN_PIN_SEL bit in CONFIG register.

The GPO pins are configured with the following bits:

- GPOx_OD bit in GPO_CTRL register defines the type of the output, either push-pull with $V_{(VANA)}$ level or open drain

The logic level of the GPOx pin is set by EN_GPOx bit in GPO_CTRL register.

The control of the GPOs can be included to start-up and shutdown sequences. The GPO control for a sequence with EN pin is selected by GPOx_EN_PIN_CTRL bit in GPO_CTRL register. For start-up and shutdown sequence control see [Enable and Disable Sequences](#).

7.3.9 Digital Signal Filtering

The digital signals have a debounce filtering. The signal or supply is sampled with a clock signal and a counter. This results as an accuracy of one clock period for the debounce window.

Table 5. Digital Signal Filtering

EVENT	SIGNAL/SUPPLY	RISING EDGE LENGTH	FALLING EDGE LENGTH
Enable/disable for BUCKx or GPOx	EN	3 μ s ⁽¹⁾	3 μ s ⁽¹⁾
VANA UVLO	VANA	3 μ s ⁽¹⁾ (VANA voltage rising)	Immediate (VANA voltage falling)
VANA overvoltage	VANA	1 μ s (VANA voltage rising)	20 μ s (VANA voltage falling)
Thermal warning	TDIE_WARN_INT	20 μ s	20 μ s
Thermal shutdown	TDIE_SD_INT	20 μ s	20 μ s
Current limit	VOUTx_ILIM	20 μ s	20 μ s
Overload	FB_B0, FB_B1	1 ms	N/V
PGOOD pin and power-good interrupt	PGOOD / FB_B0, FB_B1	6 μ s	6 μ s

(1) No glitch filtering, only synchronization.

7.4 Device Functional Modes

7.4.1 Modes of Operation

SHUTDOWN: The $V_{(VANA)}$ voltage is below $VANA_{UVLO}$ threshold level. All switch, reference, control, and bias circuitry of the TPS65653-Q1 device are turned off.

READ OTP: The main supply voltage $V_{(VANA)}$ is above $VANA_{UVLO}$ level. The regulators are disabled, and the reference and bias circuitry of the TPS65653-Q1 are enabled. The OTP bits are loaded to registers.

STANDBY: The main supply voltage $V_{(VANA)}$ is above $VANA_{UVLO}$ level. The regulators are disabled, and the reference, control and bias circuitry of the TPS65653-Q1 are enabled. All registers can be read or written by the host processor via the system serial interface. The regulators can be enabled if needed.

ACTIVE: The main supply voltage $V_{(VANA)}$ is above $VANA_{UVLO}$ level. At least one regulator is enabled. All registers can be read or written by the host processor via the system serial interface.

The operating modes and transitions between the modes are shown in [Figure 15](#).

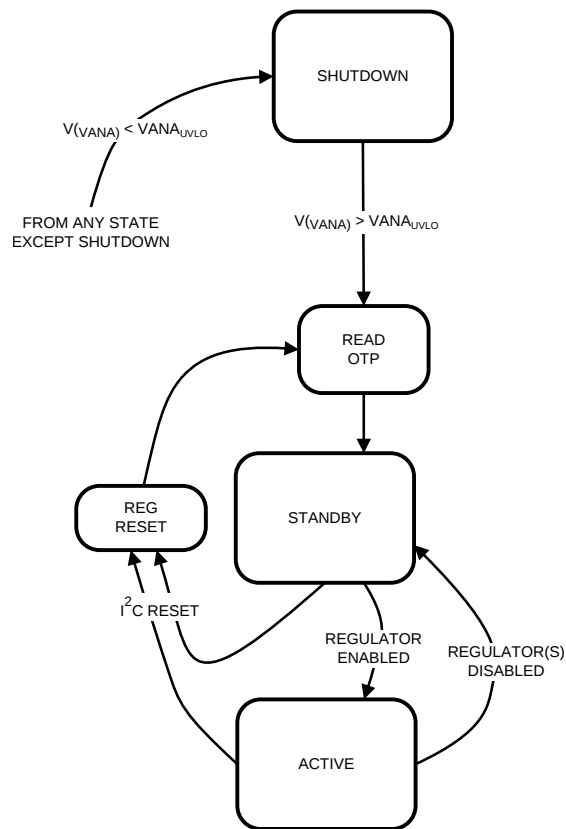


Figure 15. Device Operation Modes

7.5 Programming

7.5.1 I²C-Compatible Interface

The I²C-compatible synchronous serial interface provides access to the programmable functions and registers on the device. This protocol uses a two-wire interface for bidirectional communications between the IC's connected to the bus. The two interface lines are the serial data line (SDA), and the serial clock line (SCL). Every device on the bus is assigned a unique address and acts as either a master or a slave depending on whether it generates or receives the serial clock SCL. The SCL and SDA lines must each have a pullup resistor placed on the line and remain HIGH even when the bus is idle. The TPS65653-Q1 supports standard mode (100 kHz), fast mode (400 kHz), fast mode plus (1 MHz), and high-speed mode (3.4 MHz).

7.5.1.1 Data Validity

The data on the SDA line must be stable during the HIGH period of the clock signal (SCL). In other words, the state of the data line can only be changed when clock signal is LOW.

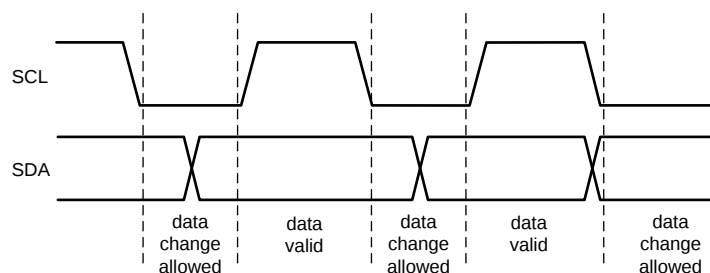


Figure 16. Data Validity Diagram

7.5.1.2 Start and Stop Conditions

The TPS65653-Q1 is controlled via an I²C-compatible interface. START and STOP conditions classify the beginning and end of the I²C session. A START condition is defined as SDA transitions from HIGH to LOW while SCL is HIGH. A STOP condition is defined as SDA transition from LOW to HIGH while SCL is HIGH. The I²C master always generates the START and STOP conditions.

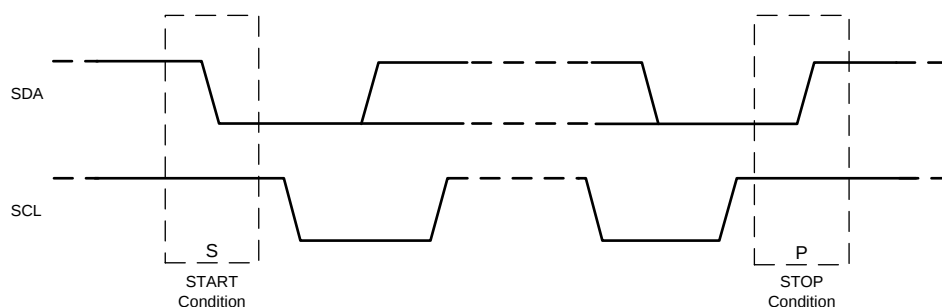


Figure 17. Start and Stop Sequences

The I²C bus is considered busy after a START condition and free after a STOP condition. During data transmission the I²C master can generate repeated START conditions. A START and a repeated START condition are equivalent function-wise. The data on SDA must be stable during the HIGH period of the clock signal (SCL). In other words, the state of SDA can only be changed when SCL is LOW. [Figure 18](#) shows the SDA and SCL signal timing for the I²C-compatible bus. See the [Figure 1](#) for timing values.

Programming (continued)

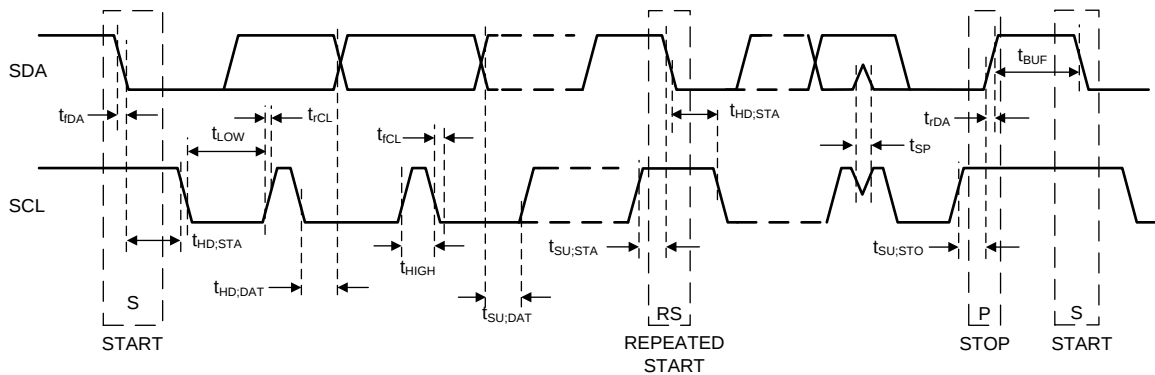


Figure 18. I²C-Compatible Timing

7.5.1.3 Transferring Data

Every byte put on the SDA line must be eight bits long, with the most significant bit (MSB) being transferred first. Each byte of data has to be followed by an acknowledge bit. The acknowledge related clock pulse is generated by the master. The master releases the SDA line (HIGH) during the acknowledge clock pulse. The TPS65653-Q1 pulls down the SDA line during the 9th clock pulse, signifying an acknowledge. The TPS65653-Q1 generates an acknowledge after each byte has been received.

There is one exception to the *acknowledge after every byte* rule. When the master is the receiver, it must indicate to the transmitter an end of data by not-acknowledging (*negative acknowledge*) the last byte clocked out of the slave. This *negative acknowledge* still includes the acknowledge clock pulse (generated by the master), but the SDA line is not pulled down.

NOTE

If the $V_{\text{(VANA)}}$ voltage is below $V_{\text{ANA,UVLO}}$ threshold level during I²C communication the TPS65653-Q1 device does not drive SDA line. The ACK signal and data transfer to the master is disabled at that time.

After the START condition, the bus master sends a chip address. This address is seven bits long followed by an eighth bit which is a data direction bit (READ or WRITE). For the eighth bit, a 0 indicates a WRITE, and a 1 indicates a READ. The second byte selects the register to which the data will be written. The third byte contains data to write to the selected register.

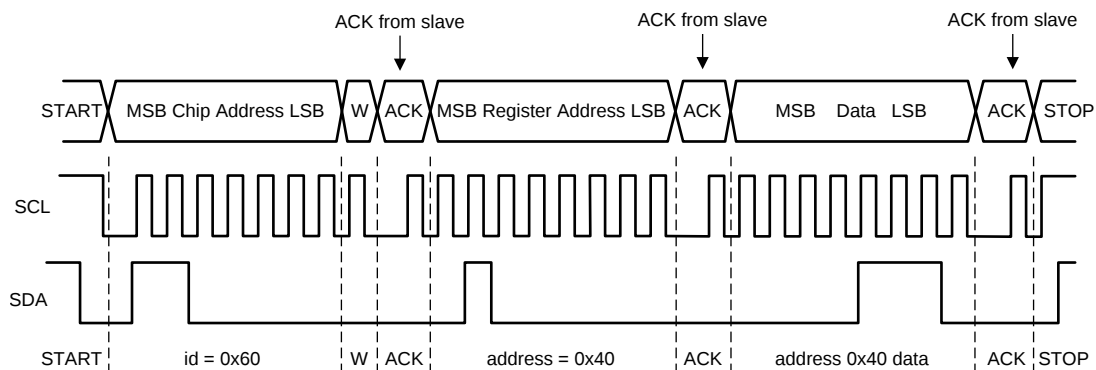
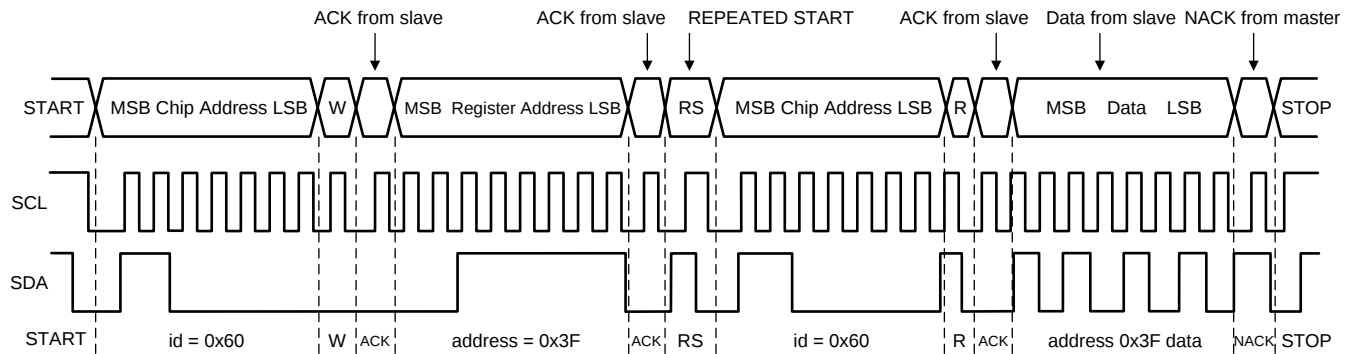


Figure 19. Write Cycle (w = write; SDA = 0). Example Device Address = 0x60

Programming (continued)



When READ function is to be accomplished, a WRITE function must precede the READ function as shown above.

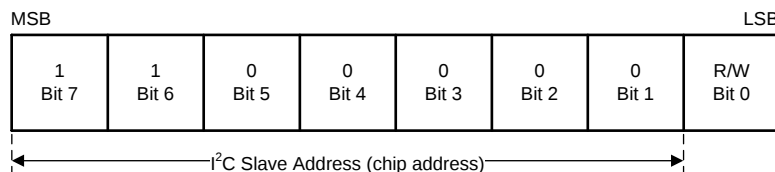
Figure 20. Read Cycle (r = read; SDA = 1). Example Device Address = 0x60

7.5.1.4 I²C-Compatible Chip Address

NOTE

The device address for the TPS65653-Q1 is 0x61.

After the START condition, the I²C master sends the 7-bit address followed by an eighth bit, read or write (R/W). R/W = 0 indicates a WRITE and R/W = 1 indicates a READ. The second byte following the device address selects the register address to which the data is written. The third byte contains the data for the selected register.



Here in an example with device address of 1100000Bin = 60Hex.

Figure 21. Device Address Example

7.5.1.5 Auto-Increment Feature

The auto-increment feature allows writing several consecutive registers within one transmission. Every time an 8-bit word is sent to the TPS65653-Q1, the internal address index counter is incremented by one and the next register is written. Table 6 shows writing sequence to two consecutive registers. Note that auto-increment feature does not work for read.

Table 6. Auto-Increment Example

MASTER ACTION	START	DEVICE ADDRESS S = 0x61	WRITE		REGISTER ADDRESS		DATA		DATA		STOP
TPS65653-Q1				ACK		ACK		ACK		ACK	

7.6 Register Maps

7.6.1 Register Descriptions

The TPS65653-Q1 is controlled by a set of registers through the I²C-compatible interface. The device registers, their addresses and their abbreviations are listed in [Table 7](#). A more detailed description is given in the [DEV_REV](#) to [I_LOAD_1](#) sections.

An "X" indicates register bits which are updated from OTP memory during READ OTP state.

Table 7. Summary of TPS65653-Q1 Control Registers

Addr	Register	Read / Write	D7	D6	D5	D4	D3	D2	D1	D0	
0x00	DEV_REV	R	DEVICE_ID[1:0]		Reserved						
0x01	OTP_REV	R	OTP_ID[7:0]								
0x02	BUCK0_CTRL_1	R/W	Reserved				BUCK0_FP_WM	BUCK0_RDIS_EN	BUCK0_EN_PIN_CTL	BUCK0_EN	
0x03	BUCK0_CTRL_2	R/W	Reserved		BUCK0_ILIM[2:0]			BUCK0_SLEW_RATE[2:0]			
0x04	BUCK1_CTRL_1	R/W	Reserved				BUCK1_FP_WM	BUCK1_RDIS_EN	BUCK1_EN_PIN_CTL	BUCK1_EN	
0x05	BUCK1_CTRL_2	R/W	Reserved		BUCK1_ILIM[2:0]			BUCK1_SLEW_RATE[2:0]			
0x06	BUCK0_VOUT	R/W	BUCK0_VSET[7:0]								
0x07	BUCK1_VOUT	R/W	BUCK1_VSET[7:0]								
0x0C	BUCK0_DELAY	R/W	BUCK0_SHUTDOWN_DELAY[3:0]				BUCK0_STARTUP_DELAY[3:0]				
0x0D	BUCK1_DELAY	R/W	BUCK1_SHUTDOWN_DELAY[3:0]				BUCK1_STARTUP_DELAY[3:0]				
0x10	GPO_DELAY	R/W	GPO_SHUTDOWN_DELAY[3:0]				GPO_STARTUP_DELAY[3:0]				
0x11	GPO2_DELAY	R/W	GPO2_SHUTDOWN_DELAY[3:0]				GPO2_STARTUP_DELAY[3:0]				
0x12	GPO_CTRL	R/W	Reserved	GPO2_OD	GPO2_EN_PIN_CTL	GPO2_EN	Reserved	GPO_OD	GPO_EN_PIN_CTL	GPO_EN	
0x13	CONFIG	R/W	Reserved	STARTUP_DELAY_SEL	SHUTDOWN_DELAY_SEL	CLKIN_PIN_SEL	CLKIN_PD	EN_PD	TDIE_WARN_LEVEL	EN_SPREAD_SPEC	
0x14	PLL_CTRL	R/W	Reserved	EN_PLL	Reserved	EXT_CLK_FREQ[4:0]					
0x15	PGOOD_CTRL_1	R/W	PGOOD_POL	PGOOD_OD	Reserved	PGOOD_WINDOW_BUFFER	Reserved		EN_PGOOD_BUCK1	EN_PGOOD_BUCK0	
0x16	PGOOD_CTRL_2	R/W	Reserved					EN_PGOOD_TWARN	PG_FAULT_GATES_PGOOD	PGOOD_MODE	
0x17	PG_FAULT	R	Reserved						PG_FAULT_BUCK1	PG_FAULT_BUCK0	
0x18	RESET	R/W	Reserved								SW_RESET
0x19	INT_TOP_1	R/W	PGOOD_INT	Reserved	INT_BUCK	SYNC_CLK_INT	TDIE_SD_INT	TDIE_WARN_INT	OVP_INT	I_MEAS_INT	
0x1A	INT_TOP_2	R/W	Reserved								RESET_REG_INT
0x1B	INT_BUCK	R/W	Reserved	BUCK1_PG_INT	BUCK1_SC_INT	BUCK1_ILIM_INT	Reserved	BUCK0_PG_INT	BUCK0_SC_INT	BUCK0_ILIM_INT	
0x1D	TOP_STAT	R	PGOOD_STAT	Reserved		SYNC_CLK_STAT	TDIE_SD_STAT	TDIE_WARN_STAT	OVP_STAT	Reserved	
0x1E	BUCK_STAT	R	BUCK1_STAT	BUCK1_PG_STAT	Reserved	BUCK1_ILIM_STAT	BUCK0_STAT	BUCK0_PG_STAT	Reserved	BUCK0_ILIM_STAT	

PRODUCT PREVIEW

Register Maps (continued)
Table 7. Summary of TPS65653-Q1 Control Registers (continued)

Addr	Register	Read / Write	D7	D6	D5	D4	D3	D2	D1	D0
0x20	TOP_MASK_1	R/W	PGOOD_INT_MASK	Reserved		SYNC_CLK_MASK	Reserved	TDIE_WARN_MASK	Reserved	I_MEAS_MASK
0x21	TOP_MASK_2	R/W	Reserved							RESET_REG_MASK
0x22	BUCK_MASK	R/W	BUCK1_PGF_MASK	BUCK1_PGR_MASK	Reserved	BUCK1_ILIM_MASK	BUCK0_PGF_MASK	BUCK0_PGR_MASK	Reserved	BUCK0_ILIM_MASK
0x24	SEL_I_LOAD	R/W	Reserved							LOAD_CURRENT_BUCK_SELECT
0x25	I_LOAD_2	R	Reserved							BUCK_LOAD_CURRENT[8]
0x26	I_LOAD_1	R	BUCK_LOAD_CURRENT[7:0]							

7.6.1.1 DEV_REV

Address: 0x00

D7	D6	D5	D4	D3	D2	D1	D0
DEVICE_ID[1:0]		Reserved					
Bits	Field	Type	Default	Description			
7:6	DEVICE_ID[1:0]	R	X	Device specific ID code.			
5:0	Reserved	R	00 0010				

7.6.1.2 OTP_REV

Address: 0x01

D7	D6	D5	D4	D3	D2	D1	D0
OTP_ID[7:0]							
Bits	Field	Type	Default	Description			
7:0	OTP_ID[7:0]	R	X	Identification Code of the OTP EPROM Version.			

7.6.1.3 BUCK0_CTRL_1

Address: 0x02

D7	D6	D5	D4	D3	D2	D1	D0
Reserved				BUCK0_FPWM	BUCK0_RDIS_EN	BUCK0_EN_PIN_CTRL	BUCK0_EN
Bits	Field	Type	Default	Description			
7:4	Reserved	R/W	0000				
3	BUCK0_FPWM	R/W	X	Buck0 mode selection: 0 - Automatic transitions between PFM and PWM modes (AUTO mode) 1 - Forced to PWM operation.			
2	BUCK0_RDIS_EN	R/W	1	Enable output discharge resistor (R_{DIS_BX}) when Buck0 is disabled: 0 - Discharge resistor disabled 1 - Discharge resistor enabled.			
1	BUCK0_EN_PIN_CTRL	R/W	X	Enable control for Buck0: 0 - only BUCK0_EN bit controls Buck0 1 - BUCK0_EN bit AND EN pin control Buck0.			
0	BUCK0_EN	R/W	X	Enable Buck0 regulator: 0 - Buck0 regulator is disabled 1 - Buck0 regulator is enabled.			

7.6.1.4 BUCK0_CTRL_2

Address: 0x03

D7	D6	D5	D4	D3	D2	D1	D0
Reserved		BUCK0_ILIM[2:0]			BUCK0_SLEW_RATE[2:0]		

TPS65653-Q1

SLVSF06 – MARCH 2019

www.ti.com

Bits	Field	Type	Default	Description
7:6	Reserved	R/W	00	
5:3	BUCK0_ILIM[2:0]	R/W	X	Sets the switch current limit of Buck0. Can be programmed at any time during operation: 0x0 - 1.5 A 0x1 - 2.0 A 0x2 - 2.5 A 0x3 - 3.0 A 0x4 - 3.5 A 0x5 - 4.0 A 0x6 - Reserved 0x7 - Reserved
2:0	BUCK0_SLEW_RATE[2:0]	R/W	X	Sets the output voltage slew rate for Buck0 regulator (rising and falling edges): 0x0 - Reserved 0x1 - Reserved 0x2 - 10 mV/μs 0x3 - 7.5 mV/μs 0x4 - 3.8 mV/μs 0x5 - 1.9 mV/μs 0x6 - 0.94 mV/μs 0x7 - 0.47 mV/μs

7.6.1.5 BUCK1_CTRL_1

Address: 0x04

D7	D6	D5	D4	D3	D2	D1	D0
Reserved				BUCK1_FPWM	BUCK1_RDIS_EN	BUCK1_EN_PIN_CTRL	BUCK1_EN

Bits	Field	Type	Default	Description
7:4	Reserved	R/W	0000	
3	BUCK1_FPWM	R/W	X	Buck1 mode selection: 0 - Automatic transitions between PFM and PWM modes (AUTO mode) 1 - Forced to PWM operation.
2	BUCK1_RDIS_EN	R/W	1	Enable output discharge resistor (R _{DIS_Bx}) when Buck1 is disabled: 0 - Discharge resistor disabled 1 - Discharge resistor enabled.
1	BUCK1_EN_PIN_CTRL	R/W	X	Enable control for Buck1: 0 - only BUCK1_EN bit controls Buck1 1 - BUCK1_EN bit AND EN pin control Buck1.
0	BUCK1_EN	R/W	X	Enable Buck1 regulator: 0 - Buck1 regulator is disabled 1 - Buck1 regulator is enabled.

7.6.1.6 BUCK1_CTRL_2

Address: 0x05

D7	D6	D5	D4	D3	D2	D1	D0
Reserved		BUCK1_ILIM[2:0]			BUCK1_SLEW_RATE[2:0]		

Bits	Field	Type	Default	Description
7:6	Reserved	R/W	00	
5:3	BUCK1_ILIM[2:0]	R/W	X	Sets the switch current limit of Buck1. Can be programmed at any time during operation: 0x0 - 1.5 A 0x1 - 2.0 A 0x2 - 2.5 A 0x3 - 3.0 A 0x4 - 3.5 A 0x5 - 4.0 A 0x6 - Reserved 0x7 - Reserved
2:0	BUCK1_SLEW_RATE[2:0]	R/W	X	Sets the output voltage slew rate for Buck1 regulator (rising and falling edges): 0x0 - Reserved 0x1 - Reserved 0x2 - 10 mV/μs 0x3 - 7.5 mV/μs 0x4 - 3.8 mV/μs 0x5 - 1.9 mV/μs 0x6 - 0.94 mV/μs 0x7 - 0.47 mV/μs

7.6.1.7 BUCK0_VOUT

Address: 0x06

D7	D6	D5	D4	D3	D2	D1	D0
BUCK0_VSET[7:0]							

Bits	Field	Type	Default	Description
7:0	BUCK0_VSET[7:0]	R/W	X	Sets the output voltage of Buck0 regulator Reserved, DO NOT USE 0x00 ... 0x4C 1 V - 1.4 V, 5 mV steps 0x4C - 1 V ... 0x9D - 1.4 V 1.4 V - 3.36 V, 20 mV steps 0x9E - 1.42 V ... 0xFF - 3.36 V

7.6.1.8 BUCK1_VOUT

Address: 0x07

D7	D6	D5	D4	D3	D2	D1	D0
BUCK1_VSET[7:0]							

Bits	Field	Type	Default	Description
7:0	BUCK1_VSET[7:0]	R/W	X	Sets the output voltage of Buck1 regulator Reserved, DO NOT USE 0x00 ... 0x4C 1 V - 1.4 V, 5 mV steps 0x4C - 1 V ... 0x9D - 1.4 V 1.4 V - 3.36 V, 20 mV steps 0x9E - 1.42 V ... 0xFF - 3.36 V

7.6.1.9 BUCK0_DELAY

Address: 0x0C

D7	D6	D5	D4	D3	D2	D1	D0
BUCK0_SHUTDOWN_DELAY[3:0]				BUCK0_STARTUP_DELAY[3:0]			
Bits	Field	Type	Default	Description			
7:4	BUCK0_SHUTDOWN_DELAY[3:0]	R/W	X	Shutdown delay of Buck0 from falling edge of EN signal: 0x0 - 0 ms 0x1 - 0.5 ms (1 ms if SHUTDOWN_DELAY_SEL=1 in CONFIG register) ... 0xF - 7.5 ms (15 ms if SHUTDOWN_DELAY_SEL=1 in CONFIG register)			
3:0	BUCK0_STARTUP_DELAY[3:0]	R/W	X	Startup delay of Buck0 from rising edge of EN signal: 0x0 - 0 ms 0x1 - 0.5 ms (1 ms if STARTUP_DELAY_SEL=1 in CONFIG register) ... 0xF - 7.5 ms (15 ms if STARTUP_DELAY_SEL=1 in CONFIG register)			

7.6.1.10 BUCK1_DELAY

Address: 0x0D

D7	D6	D5	D4	D3	D2	D1	D0
BUCK1_SHUTDOWN_DELAY[3:0]				BUCK1_STARTUP_DELAY[3:0]			
Bits	Field	Type	Default	Description			
7:4	BUCK1_SHUTDOWN_DELAY[3:0]	R/W	X	Shutdown delay of Buck1 from falling edge of EN signal: 0x0 - 0 ms 0x1 - 0.5 ms (1 ms if SHUTDOWN_DELAY_SEL=1 in CONFIG register) ... 0xF - 7.5 ms (15 ms if SHUTDOWN_DELAY_SEL=1 in CONFIG register)			
3:0	BUCK1_STARTUP_DELAY[3:0]	R/W	X	Startup delay of Buck1 from rising edge of EN signal: 0x0 - 0 ms 0x1 - 0.5 ms (1 ms if STARTUP_DELAY_SEL=1 in CONFIG register) ... 0xF - 7.5 ms (15 ms if STARTUP_DELAY_SEL=1 in CONFIG register)			

7.6.1.11 GPO_DELAY

Address: 0x10

D7	D6	D5	D4	D3	D2	D1	D0
GPO_SHUTDOWN_DELAY[3:0]				GPO_STARTUP_DELAY[3:0]			
Bits	Field	Type	Default	Description			
7:4	GPO_SHUTDOWN_DELAY[3:0]	R/W	X	Delay for GPO falling edge from falling edge of EN signal: 0x0 - 0 ms 0x1 - 0.5 ms (1 ms if SHUTDOWN_DELAY_SEL=1 in CONFIG register) ... 0xF - 7.5 ms (15 ms if SHUTDOWN_DELAY_SEL=1 in CONFIG register)			
3:0	GPO_STARTUP_DELAY[3:0]	R/W	X	Delay for GPO rising edge from rising edge of EN signal: 0x0 - 0 ms 0x1 - 0.5 ms (1 ms if STARTUP_DELAY_SEL=1 in CONFIG register) ... 0xF - 7.5 ms (15 ms if STARTUP_DELAY_SEL=1 in CONFIG register)			

7.6.1.12 GPO2_DELAY

Address: 0x11

D7	D6	D5	D4	D3	D2	D1	D0
GPO2_SHUTDOWN_DELAY[3:0]				GPO2_STARTUP_DELAY[3:0]			

Bits	Field	Type	Default	Description
7:4	GPO2_SHUTDOWN_DELAY[3:0]	R/W	X	Delay for GPO2 falling edge from falling edge of EN signal: 0x0 - 0 ms 0x1 - 0.5 ms (1 ms if SHUTDOWN_DELAY_SEL=1 in CONFIG register) ... 0xF - 7.5 ms (15 ms if SHUTDOWN_DELAY_SEL=1 in CONFIG register)
3:0	GPO2_STARTUP_DELAY[3:0]	R/W	X	Delay for GPO2 rising edge from rising edge of EN signal: 0x0 - 0 ms 0x1 - 0.5 ms (1 ms if STARTUP_DELAY_SEL=1 in CONFIG register) ... 0xF - 7.5 ms (15 ms if STARTUP_DELAY_SEL=1 in CONFIG register)

7.6.1.13 GPO_CTRL

Address: 0x12

D7	D6	D5	D4	D3	D2	D1	D0
Reserved	GPO2_OD	GPO2_EN_PIN_CTRL	GPO2_EN	Reserved	GPO_OD	GPO_EN_PIN_CTRL	GPO_EN

Bits	Field	Type	Default	Description
7	Reserved	R	0	
6	GP02_OD	R/W	X	GPO2 signal type when configured as General Purpose Output (CLKIN pin): 0 - Push-pull output (VANA level) 1 - Open-drain output
5	GPO2_EN_PIN_CTRL	R/W	X	Control for GPO2: 0 - Only GPO2_EN bit controls GPO2 1 - GPO2_EN bit AND EN pin control GPO2.
4	GPO2_EN	R/W	X	Output level of GPO2 signal (when configured as General Purpose Output): 0 - Logic low level 1 - Logic high level
3	Reserved	R	0	
2	GPO_OD	R/W	X	GPO signal type: 0 - Push-pull output (VANA level) 1 - Open-drain output
1	GPO_EN_PIN_CTRL	R/W	X	Control for GPO: 0 - Only GPO_EN bit controls GPO 1 - GPO_EN bit AND EN pin control GPO.
0	GPO_EN	R/W	X	Output level of GPO signal: 0 - Logic low level 1 - Logic high level

7.6.1.14 CONFIG

Address: 0x13

D7	D6	D5	D4	D3	D2	D1	D0
Reserved	STARTUP_DELAY_SEL	SHUTDOWN_DELAY_SEL	CLKIN_PIN_SEL	CLKIN_PD	EN2_PD	TDIE_WARN_LEVEL	EN_SPREAD_SPEC

Bits	Field	Type	Default	Description
7	Reserved	R/W	0	
6	STARTUP_DELAY_SEL	R/W	X	Startup delay range from EN signals. 0 - 0 ms - 7.5 ms with 0.5 ms steps 1 - 0 ms - 15 ms with 1 ms steps
5	SHUTDOWN_DELAY_SEL	R/W	X	Shutdown delay range from EN signals. 0 - 0 ms - 7.5 ms with 0.5 ms steps 1 - 0 ms - 15 ms with 1 ms steps
4	CLKIN_PIN_SEL	R/W	X	CLKIN pin function: 0 - GPO2 1 - CLKIN

TPS65653-Q1

SLVSF06 – MARCH 2019

www.ti.com

Bits	Field	Type	Default	Description
3	CLKIN_PD	R/W	X	Selects the pull down resistor on the CLKIN input pin. (valid also when selected as GPO2) 0 - Pull-down resistor is disabled. 1 - Pull-down resistor is enabled.
2	EN_PD	R/W	X	Selects the pull down resistor on the EN input pin. 0 - Pull-down resistor is disabled. 1 - Pull-down resistor is enabled.
1	TDIE_WARN_LEVEL	R/W	X	Thermal warning threshold level. 0 - 125°C 1 - 137°C.
0	EN_SPREAD_SPEC	R/W	X	Enable spread spectrum feature: 0 - Disabled 1 - Enabled

7.6.1.15 PLL_CTRL

Address: 0x14

D7	D6	D5	D4	D3	D2	D1	D0
Reserved	EN_PLL	Reserved	EXT_CLK_FREQ[4:0]				

Bits	Field	Type	Default	Description
7	Reserved	R/W	0	
6	EN_PLL	R/W	X	Selection of external clock and PLL operation: 0 - Forced to internal RC oscillator. PLL disabled. 1 - PLL is enabled in STANDBY and ACTIVE modes. Automatic external clock use when available, interrupt generated if external clock appears or disappears.
5	Reserved	R/W	0	This bit must be set to '0'.
4:0	EXT_CLK_FREQ[4:0]	R/W	X	Frequency of the external clock (CLKIN): 0x00 - 1 MHz 0x01 - 2 MHz 0x02 - 3 MHz ... 0x16 - 23 MHz 0x17 - 24 MHz 0x18...0x1F - Reserved See electrical specification for input clock frequency tolerance.

7.6.1.16 PGOOD_CTRL_1

Address: 0x15

D7	D6	D5	D4	D3	D2	D1	D0
PGOOD_POL	PGOOD_OD	Reserved	PGOOD_WINDOW_BUCK	Reserved		EN_PGOOD_BUCK1	EN_PGOOD_BUCK0

Bits	Field	Type	Default	Description
7	PGOOD_POL	R/W	X	PGOOD signal polarity. 0 - PGOOD signal high when monitored outputs are valid 1 - PGOOD signal low when monitored outputs are valid
6	PGOOD_OD	R/W	X	PGOOD signal type: 0 - Push-pull output (VANA level) 1 - Open-drain output
5	Reserved	R/W	0	
4	PGOOD_WINDOW_BUCK	R/W	X	Buck Output voltage monitoring method for PGOOD signal: 0 - Only undervoltage monitoring 1 - Overvoltage and undervoltage monitoring.
3:2	Reserved	R/W	00	

Bits	Field	Type	Default	Description
1	EN_PGOOD_BUCK1	R/W	X	PGOOD signal source control from Buck1 0 - Buck1 is not monitored 1 - Buck1 Power-Good threshold voltage monitored
0	EN_PGOOD_BUCK0	R/W	X	PGOOD signal source control from Buck0 0 - Buck0 is not monitored 1 - Buck0 Power-Good threshold voltage monitored

7.6.1.17 PGOOD_CTRL_2

Address: 0x16

D7	D6	D5	D4	D3	D2	D1	D0
Reserved					EN_PGOOD_TWARN	PG_FAULT_GATES_PGOOD	PGOOD_MODE

Bits	Field	Type	Default	Description
7:3	Reserved	R/W	0 0000	
2	EN_PGOOD_TWARN	R/W	X	Thermal warning control for PGOOD signal: 0 - Thermal warning not monitored 1 - PGOOD inactive if thermal warning flag is active.
1	PG_FAULT_GATE_S_PGOOD	R/W	X	Type of operation for PGOOD signal: 0 - Indicates live status of monitored voltage outputs. 1 - Indicates status of PG_FAULT register, inactive when at least one PG_FAULT_x bit is inactive.
0	PGOOD_MODE	R/W	X	Operating mode for PGOOD signal: 0 - Gated mode 1 - Continuous mode

7.6.1.18 PG_FAULT

Address: 0x17

D7	D6	D5	D4	D3	D2	D1	D0
Reserved						PG_FAULT_BUCK1	PG_FAULT_BUCK0

Bits	Field	Type	Default	Description
7:2	Reserved	R/W	00 0000	
1	PG_FAULT_BUCK1	R/W	0	Source for PGOOD inactive signal: 0 - Buck1 has not set PGOOD signal inactive. 1 - Buck1 is selected for PGOOD signal and it has set PGOOD signal inactive. This bit can be cleared by writing '1' to this bit when Buck1 output is valid.
0	PG_FAULT_BUCK0	R/W	0	Source for PGOOD inactive signal: 0 - Buck0 has not set PGOOD signal inactive. 1 - Buck0 is selected for PGOOD signal and it has set PGOOD signal inactive. This bit can be cleared by writing '1' to this bit when Buck0 output is valid.

7.6.1.19 RESET

Address: 0x18

D7	D6	D5	D4	D3	D2	D1	D0
Reserved						SW_RESET	

Bits	Field	Type	Default	Description
7:1	Reserved	R/W	000 0000	
0	SW_RESET	R/W	0	Software commanded reset. When written to 1, the registers will be reset to default values, OTP memory is read, and the I ² C interface is reset. The bit is automatically cleared.

TPS65653-Q1

SLVSF06 – MARCH 2019

www.ti.com

7.6.1.20 INT_TOP_1

Address: 0x19

D7	D6	D5	D4	D3	D2	D1	D0
PGOOD_INT	Reserved	BUCK_INT	SYNC_CLK_INT	TDIE_SD_INT	TDIE_WARN_INT	OVP_INT	I_MEAS_INT

Bits	Field	Type	Default	Description
7	PGOOD_INT	R/W	0	Latched status bit indicating that the PGOOD pin has changed from active to inactive. Write 1 to clear interrupt.
6	Reserved	R	0	
5	BUCK_INT	R	0	Interrupt indicating that Buck1 and/or Buck0 have a pending interrupt. The reason for the interrupt is indicated in INT_BUCK register. This bit is cleared automatically when INT_BUCK register is cleared to 0x00.
4	SYNC_CLK_INT	R/W	0	Latched status bit indicating that the external clock has appeared or disappeared. Write 1 to clear interrupt.
3	TDIE_SD_INT	R/W	0	Latched status bit indicating that the die junction temperature has exceeded the thermal shutdown level. The regulators have been disabled if they were enabled and GPO and GPO2 signals are driven low. The regulators cannot be enabled if this bit is active. The actual status of the thermal shutdown is indicated by TDIE_SD_STAT bit in TOP_STAT register. Write 1 to clear interrupt.
2	TDIE_WARN_INT	R/W	0	Latched status bit indicating that the die junction temperature has exceeded the thermal warning level. The actual status of the thermal warning is indicated by TDIE_WARN_STAT bit in TOP_STAT register. Write 1 to clear interrupt.
1	OVP_INT	R/W	0	Latched status bit indicating that the input voltage has exceeded the over-voltage detection level. The regulators have been disabled if they were enabled and GPO and GPO2 signals are driven low. The actual status of the over-voltage is indicated by OVP_STAT bit in TOP_STAT register. Write 1 to clear interrupt.
0	I_MEAS_INT	R/W	0	Latched status bit indicating that the load current measurement result is available in I_LOAD_1 and I_LOAD_2 registers. Write 1 to clear interrupt.

7.6.1.21 INT_TOP_2

Address: 0x1A

D7	D6	D5	D4	D3	D2	D1	D0
Reserved							RESET_REG_INT

Bits	Field	Type	Default	Description
7:1	Reserved	R/W	000 0000	
0	RESET_REG_INT	R/W	0	Latched status bit indicating that either VANA supply voltage has been below undervoltage threshold level or the host has requested a reset using SW_RESET bit in RESET register. The regulators have been disabled, and registers are reset to default values and the normal startup procedure is done. Write 1 to clear interrupt.

7.6.1.22 INT_BUCK

Address: 0x1B

D7	D6	D5	D4	D3	D2	D1	D0
Reserved	BUCK1_PG_INT	BUCK1_SC_INT	BUCK1_ILIM_INT	Reserved	BUCK0_PG_INT	BUCK0_SC_INT	BUCK0_ILIM_INT

Bits	Field	Type	Default	Description
7	Reserved	R/W	0	
6	BUCK1_PG_INT	R/W	0	Latched status bit indicating that Buck1 Power-Good event has been detected. Write 1 to clear.
5	BUCK1_SC_INT	R/W	0	Latched status bit indicating that the Buck1 output voltage has been over 1 ms below short-circuit threshold level. Write 1 to clear.
4	BUCK1_ILIM_INT	R/W	0	Latched status bit indicating that the Buck1 output current limit has been active. Write 1 to clear.
3	Reserved	R/W	0	
2	BUCK0_PG_INT	R/W	0	Latched status bit indicating that Buck0 Power-Good event has been detected. Write 1 to clear.
1	BUCK0_SC_INT	R/W	0	Latched status bit indicating that the Buck0 output voltage has been over 1 ms below short-circuit threshold level. Write 1 to clear.
0	BUCK0_ILIM_INT	R/W	0	Latched status bit indicating that the Buck0 output current limit has been active. Write 1 to clear.

7.6.1.23 TOP_STAT

Address: 0x1D

D7	D6	D5	D4	D3	D2	D1	D0
PGOOD_STAT	Reserved		SYNC_CLK_STAT	TDIE_SD_STAT	TDIE_WARN_STAT	OVP_STAT	Reserved

Bits	Field	Type	Default	Description
7	PGOOD_STAT	R	0	Status bit indicating the status of PGOOD pin: 0 - PGOOD pin is inactive 1 - PGOOD pin is active
6:5	Reserved	R	00	
4	SYNC_CLK_STAT	R	0	Status bit indicating the status of external clock (CLKIN): 0 - External clock frequency is valid 1 - External clock frequency is not valid.
3	TDIE_SD_STAT	R	0	Status bit indicating the status of thermal shutdown: 0 - Die temperature below thermal shutdown level 1 - Die temperature above thermal shutdown level.
2	TDIE_WARN_STAT	R	0	Status bit indicating the status of thermal warning: 0 - Die temperature below thermal warning level 1 - Die temperature above thermal warning level.
1	OVP_STAT	R	0	Status bit indicating the status of input overvoltage monitoring: 0 - Input voltage below overvoltage threshold level 1 - Input voltage above overvoltage threshold level.
0	Reserved	R	0	

7.6.1.24 BUCK_STAT

Address: 0x1E

D7	D6	D5	D4	D3	D2	D1	D0
BUCK1_STAT	BUCK1_PG_STAT	Reserved	BUCK1_ILIM_STAT	BUCK0_STAT	BUCK0_PG_STAT	Reserved	BUCK0_ILIM_STAT

Bits	Field	Type	Default	Description
7	BUCK1_STAT	R	0	Status bit indicating the enable/disable status of Buck1: 0 - Buck1 regulator is disabled 1 - Buck1 regulator is enabled.
6	BUCK1_PG_STAT	R	0	Status bit indicating Buck1 output voltage validity (raw status) 0 - Buck1 output voltage is valid. 1 - Buck1 output voltage is invalid.

TPS65653-Q1

SLVSF06 – MARCH 2019

www.ti.com

Bits	Field	Type	Default	Description
5	Reserved	R	0	
4	BUCK1_ILIM_STAT	R	0	Status bit indicating Buck1 current limit status (raw status) 0 - Buck1 output current is below current limit level 1 - Buck1 output current limit is active.
3	BUCK0_STAT	R	0	Status bit indicating the enable/disable status of Buck0: 0 - Buck0 regulator is disabled 1 - Buck0 regulator is enabled.
2	BUCK0_PG_STAT	R	0	Status bit indicating Buck0 output voltage validity (raw status) 0 - Buck0 output voltage is valid. 1 - Buck0 output voltage is invalid.
1	Reserved	R	0	
0	BUCK0_ILIM_STAT	R	0	Status bit indicating Buck0 current limit status (raw status) 0 - Buck0 output current is below current limit level 1 - Buck0 output current limit is active.

7.6.1.25 TOP_MASK_1

Address: 0x20

D7	D6	D5	D4	D3	D2	D1	D0
PGOOD_INT_MASK	Reserved		SYNC_CLK_MASK	Reserved	TDIE_WARN_MASK	Reserved	I_LOAD_READY_MASK

Bits	Field	Type	Default	Description
7	PGOOD_INT_MASK	R/W	X	Masking for Power-Good interrupt (PGOOD_INT in INT_TOP_1 register): 0 - Interrupt generated 1 - Interrupt not generated. This bit does not affect PGOOD_STAT status bit in TOP_STAT register.
6:5	Reserved	R/W	00	
4	SYNC_CLK_MASK	R/W	X	Masking for external clock detection interrupt (SYNC_CLK_INT in INT_TOP_1 register): 0 - Interrupt generated 1 - Interrupt not generated. This bit does not affect SYNC_CLK_STAT status bit in TOP_STAT register.
3	Reserved	R/W	0	
2	TDIE_WARN_MASK	R/W	X	Masking for thermal warning interrupt (TDIE_WARN_INT in INT_TOP_1 register): 0 - Interrupt generated 1 - Interrupt not generated. This bit does not affect TDIE_WARN_STAT status bit in TOP_STAT register.
1	Reserved	R/W	0	
0	I_MEAS_MASK	R/W	X	Masking for load current measurement ready interrupt (MEAS_INT in INT_TOP_1 register): 0 - Interrupt generated 1 - Interrupt not generated.

7.6.1.26 TOP_MASK_2

Address: 0x21

D7	D6	D5	D4	D3	D2	D1	D0
			Reserved				RESET_REG_MASK

Bits	Field	Type	Default	Description
7:1	Reserved	R/W	000 0000	
0	RESET_REG_MASK	R/W	X	Masking for register reset interrupt (RESET_REG_INT in INT_TOP_2 register): 0 - Interrupt generated 1 - Interrupt not generated. This change of this bit by I ² C writing has no effect because it will be read from OTP memory during reset.

7.6.1.27 BUCK_MASK

Address: 0x22

D7	D6	D5	D4	D3	D2	D1	D0
BUCK1_PGF_MASK	BUCK1_PGR_MASK	Reserved	BUCK1_ILIM_MASK	BUCK0_PGF_MASK	BUCK0_PGR_MASK	Reserved	BUCK0_ILIM_MASK

Bits	Field	Type	Default	Description
7	BUCK1_PGF_MASK	R/W	X	Masking of Power Good invalid detection for Buck1 power good interrupt (BUCK1_PG_INT in INT_BUCK register): 0 - Interrupt generated 1 - Interrupt not generated. This bit does not affect BUCK1_PG_STAT status bit in BUCK_STAT register.
6	BUCK1_PGR_MASK	R/W	X	Masking of Power Good valid detection for Buck1 Power Good interrupt (BUCK1_PG_INT in INT_BUCK register): 0 - Interrupt generated 1 - Interrupt not generated. This bit does not affect BUCK1_PG_STAT status bit in BUCK_STAT register.
5	Reserved	R	0	
4	BUCK1_ILIM_MASK	R/W	X	Masking for Buck1 current limit detection interrupt (BUCK1_ILIM_INT in INT_BUCK register): 0 - Interrupt generated 1 - Interrupt not generated. This bit does not affect BUCK1_ILIM_STAT status bit in BUCK_STAT register.
3	BUCK0_PGF_MASK	R/W	X	Masking of Power Good invalid detection for Buck0 power good interrupt (BUCK0_PG_INT in INT_BUCK register): 0 - Interrupt generated 1 - Interrupt not generated. This bit does not affect BUCK0_PG_STAT status bit in BUCK_STAT register.
2	BUCK0_PGR_MASK	R/W	X	Masking of Power Good valid detection for Buck0 power good interrupt (BUCK0_PG_INT in INT_BUCK register): 0 - Interrupt generated 1 - Interrupt not generated. This bit does not affect BUCK0_PG_STAT status bit in BUCK_STAT register.
1	Reserved	R	0	
0	BUCK0_ILIM_MASK	R/W	X	Masking for Buck0 current limit detection interrupt (BUCK0_ILIM_INT in INT_BUCK register): 0 - Interrupt generated 1 - Interrupt not generated. This bit does not affect BUCK0_ILIM_STAT status bit in BUCK_STAT register.

7.6.1.28 SEL_I_LOAD

Address: 0x24

D7	D6	D5	D4	D3	D2	D1	D0
Reserved							LOAD_CURRENT_BUCK_SELECT

Bits	Field	Type	Default	Description
7:1	Reserved	R/W	000 0000	
0	LOAD_CURRENT_BUCK_SELECT	R/W	0	Start the current measurement on the selected regulator: 0 - Buck0 1 - Buck1 The measurement is started when register is written.

7.6.1.29 I_LOAD_2

Address: 0x25

D7	D6	D5	D4	D3	D2	D1	D0
Reserved							BUCK_LOAD_CURRENT[8]

TPS65653-Q1

SLVSF06 – MARCH 2019

www.ti.com

Bits	Field	Type	Default	Description
7:1	Reserved	R	000 0000	
0	BUCK_LOAD_CURRENT[8]	R	0	This register describes the MSB bit of the average load current on selected regulator with a resolution of 20 mA per LSB and maximum 10.22-A current.

7.6.1.30 I_LOAD_1

Address: 0x26

D7	D6	D5	D4	D3	D2	D1	D0
BUCK_LOAD_CURRENT[7:0]							

Bits	Field	Type	Default	Description
7:0	BUCK_LOAD_CURRENT[7:0]	R	0000 0000	This register describes 8 LSB bits of the average load current on selected regulator with a resolution of 20 mA per LSB and maximum 10.22-A current.

8 Application and Implementation

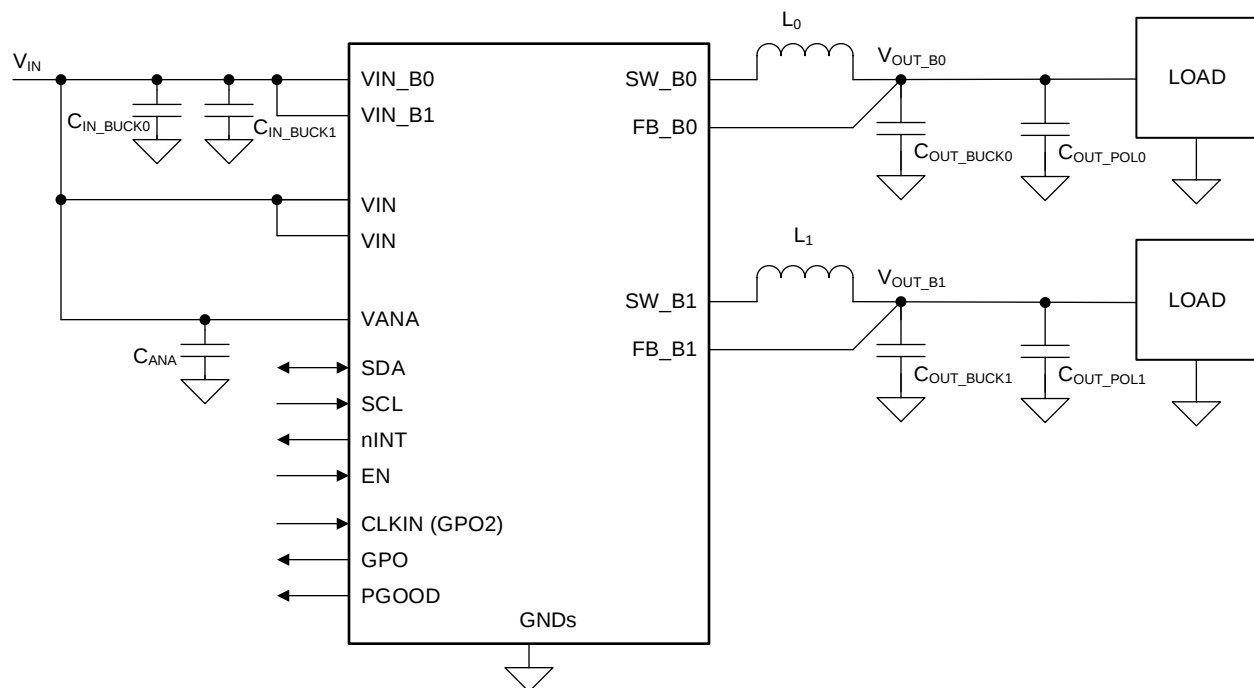
NOTE

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

8.1 Application Information

The TPS65653-Q1 is a power management unit including two step-down regulators and two general-purpose digital output signals.

8.2 Typical Application



Copyright © 2019, Texas Instruments Incorporated

Figure 22. TPS65653-Q1 Typical Application

8.2.1 Design Requirements

8.2.1.1 Inductor Selection

The inductors L_0 and L_1 are shown in the [Typical Application](#). The inductance and DCR of the inductor affects the control loop of the buck regulator. TI recommends using inductors similar to those listed in [Table 8](#). Pay attention to the saturation current and temperature rise current of the inductor. Check that the saturation current is higher than the peak current limit and the temperature rise current is higher than the maximum expected rms output current. For the minimum effective inductance to ensure good performance at maximum peak output current over the operating temperature range refer to [Electrical Characteristics](#). DC resistance of the inductor must be less than $0.05\ \Omega$ for good efficiency at high-current condition. The inductor AC loss also affects conversion efficiency. Higher Q factor at switching frequency usually gives better efficiency at light load to middle load. Shielded inductors are preferred as they radiate less noise.

Typical Application (continued)

Table 8. Recommended Inductors

MANUFACTURER	PART NUMBER	VALUE	DIMENSIONS L × W × H (mm)	RATED DC CURRENT I _{SAT} maximum (typical) / I _{TEMP} maximum (typical) (A)	DCR typical / maximum (mΩ)
Murata	DFE252012PD-R47M	0.47 μH (20%)	2.5 × 2 × 1.2	5.2 (–) / 4 (–) ⁽¹⁾	— / 27
Tayo Yuden	MDMK2020TR47M MV	0.47 μH (20%)	2 × 2 × 1.2	4.2 (4.8) / 2.3 (2.45)	40 / 46

(1) Operating temperature range is up to 125°C including self temperature rise.

8.2.1.2 Buck Input Capacitor Selection

The input capacitors C_{IN_BUCK0} and C_{IN_BUCK1} are shown in the [Typical Application](#). A ceramic input bypass capacitor of 10 μF is required for each phase of the regulator. Place the input capacitor as close as possible to the VIN_Bx pin and PGND_Bx pin of the device. A larger value or higher voltage rating improves the input voltage filtering. Use X7R type of capacitors, not Y5V or F. Also the DC bias characteristics capacitors must be considered. Minimum effective input capacitance to ensure good performance is 1.9 μF per buck input at maximum input voltage including tolerances, ambient temperature range and aging. This is assuming that there are at least 22 μF of additional capacitance common for all the power input pins on the system power rail. See [Table 9](#).

The input filter capacitor supplies current to the high-side FET switch in the first half of each cycle and reduces voltage ripple imposed on the input power source. A ceramic capacitor's low ESR provides the best noise filtering of the input voltage spikes due to this rapidly changing current. Select an input filter capacitor with sufficient ripple current rating. In addition ferrite can be used in front of the input capacitor to reduce the EMI.

Table 9. Recommended Buck Input Capacitor (X7R Dielectric)

MANUFACTURER	PART NUMBER	VALUE	CASE SIZE	DIMENSIONS L × W × H (mm)	VOLTAGE RATING
Murata	GCM21BR71A106KE22	10 μF (10%)	0805	2 × 1.25 × 1.25	10 V

8.2.1.3 Buck Output Capacitor Selection

The output capacitor C_{OUT_BUCK0} and C_{OUT_BUCK1} are shown in [Typical Application](#). A ceramic local output capacitor of 22 μF is required per buck. Use ceramic capacitors, X7R type; do not use Y5V or F. DC bias voltage characteristics of ceramic capacitors must be considered. The output filter capacitor smooths out current flow from the inductor to the load, helps maintain a steady output voltage during transient load changes and reduces output voltage ripple. These capacitors must be selected with sufficient capacitance and sufficiently low ESR and ESL to perform these functions. Minimum effective output capacitance to ensure good performance is 10 μF per buck including the DC voltage rolloff, tolerances, aging, and temperature effects.

The output voltage ripple is caused by the charging and discharging of the output capacitor and also due to its R_{ESR}. The R_{ESR} is frequency dependent (as well as temperature dependent); make sure the value used for selection process is at the switching frequency of the part. See [Table 10](#).

POL capacitors can be used to improve load transient performance and to decrease the ripple voltage. A higher output capacitance improves the load step behavior and reduces the output voltage ripple as well as decreases the PFM switching frequency. However, output capacitance higher than 100 μF per buck is not necessarily of any benefit. Note that the output capacitor may be the limiting factor in the output voltage ramp, see [Specifications](#) for maximum output capacitance for different slew-rate settings. For large output capacitors, the output voltage might be slower than the programmed ramp rate at voltage transitions, because of the higher energy stored on the output capacitance. Also at start-up, the time required to charge the output capacitor to target value might be longer. At shutdown the output voltage is discharged to 0.6 V level using forced-PWM operation. This can increase the input voltage if the load current is small and the output capacitor is large compared to input capacitor. Below 0.6 V level the output capacitor is discharged by the internal discharge resistor and with large capacitor more time is required to settle V_{OUT} down as a consequence of the increased time constant.

Table 10. Recommended Buck Output Capacitors (X7R Dielectric)

MANUFACTURER	PART NUMBER	VALUE	CASE SIZE	DIMENSIONS L × W × H (mm)	VOLTAGE RATING
Murata	GCM31CR71A226KE02	22 μ F (10%)	1206	3.2 × 1.6 × 1.6	10 V

8.2.2 Detailed Design Procedure

The performance of the TPS65653-Q1 device depends greatly on the care taken in designing the printed circuit board (PCB). The use of low-inductance and low serial-resistance ceramic capacitors is strongly recommended, while proper grounding is crucial. Attention must be given to decoupling the power supplies. Decoupling capacitors must be connected close to the device and between the power and ground pins to support high peak currents being drawn from system power rail during turnon of the switching MOSFETs. Keep input and output traces as short as possible, because trace inductance, resistance, and capacitance can easily become the performance limiting items. The separate buck regulator power pins VIN_Bx are not connected together internally. Connect the VIN_Bx power connections together outside the package using power plane construction.

8.2.3 Application Curves

Measurements are done using typical application set up with connections shown in Figure 22. Graphs may not reflect the OTP default settings. Unless otherwise specified: $V_{(VIN_BX)} = V_{(VANA)} = 3.7\text{ V}$, $V_{OUT_BX} = 1\text{ V}$, $T_A = 25^\circ\text{C}$, $L = 0.47\text{ }\mu\text{H}$ (Murata DFE252012PD-R47M), $C_{OUT_BUCK} = 22\text{ }\mu\text{F}$, and $C_{POL_BUCK} = 22\text{ }\mu\text{F}$.

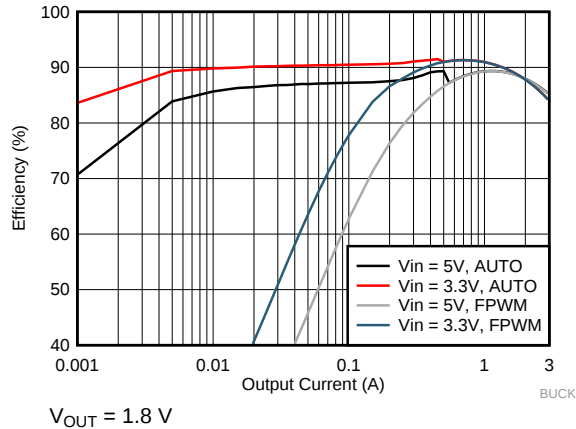


Figure 23. Buck Efficiency in PFM/PWM and Forced PWM Mode

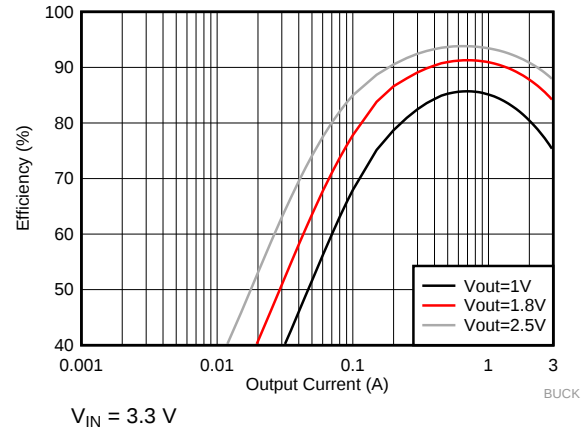


Figure 24. Buck Efficiency in Forced PWM Mode

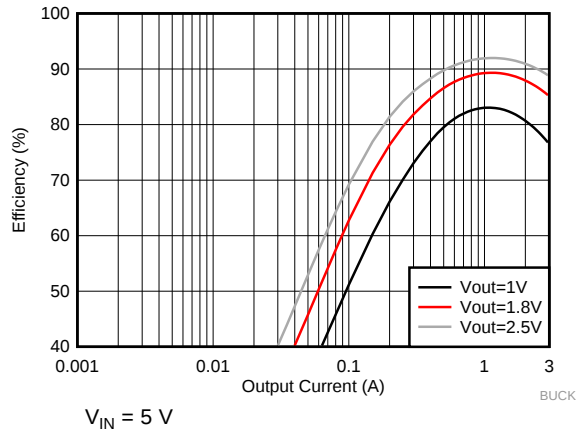


Figure 25. Buck Efficiency in Forced PWM Mode

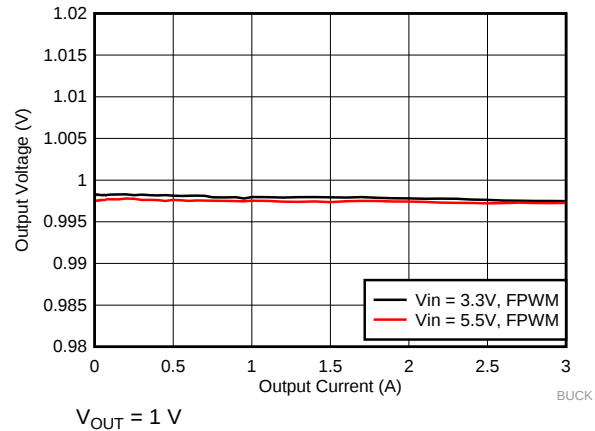


Figure 26. Buck Output Voltage vs Load Current in Forced PWM Mode

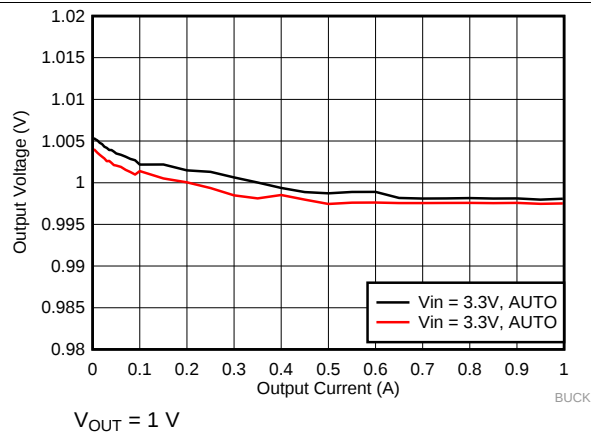


Figure 27. Buck Output Voltage vs Load Current in PFM/PWM Mode

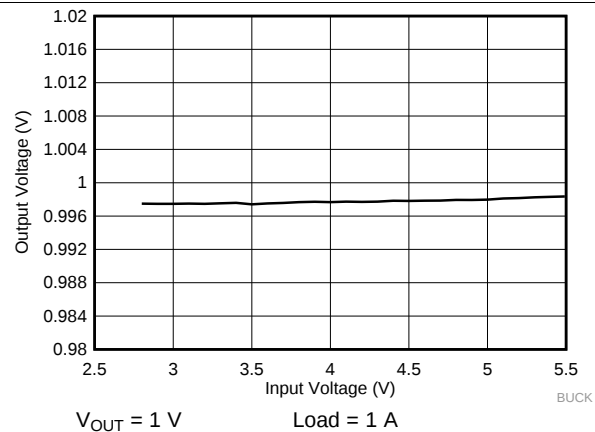
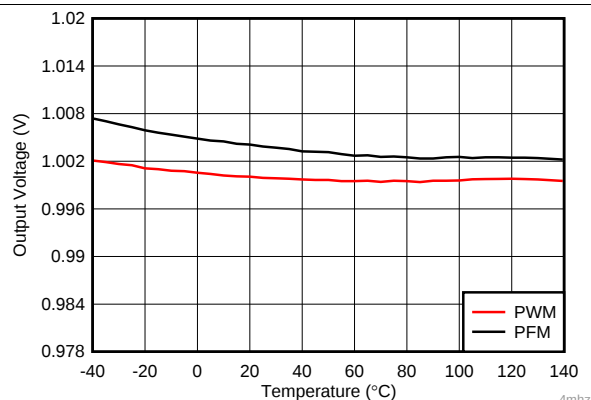
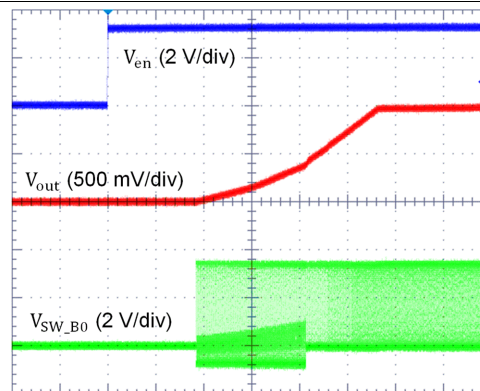


Figure 28. Buck Output Voltage vs Input Voltage in PWM Mode



Load = 1 A (PWM) and 0.1 A (PFM)

Figure 29. Buck Output Voltage vs Temperature

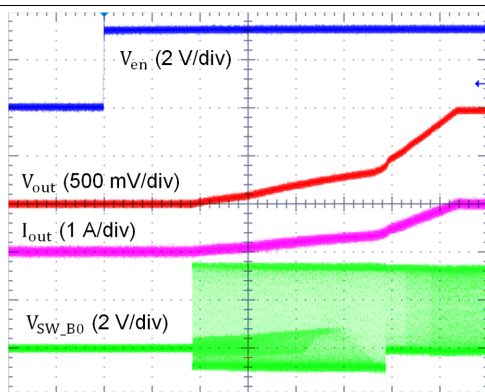


Slew-rate = 10 mV/μs

$I_{LOAD} = 0$ A

$V_{OUT} = 1$ V

Figure 30. Buck Start-Up With EN1, Forced PWM Mode

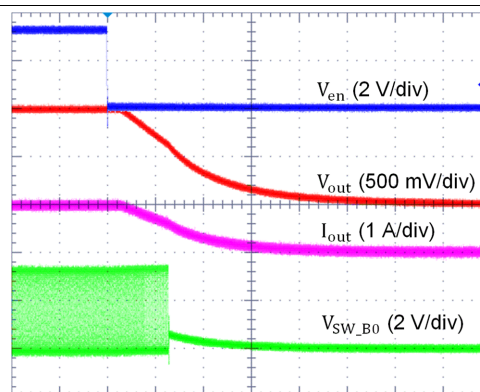


Slew-rate = 10 mV/μs

$R_{LOAD} = 1$ Ω

$V_{OUT} = 1$ V

Figure 31. Buck Start-Up with EN1, Forced PWM Mode

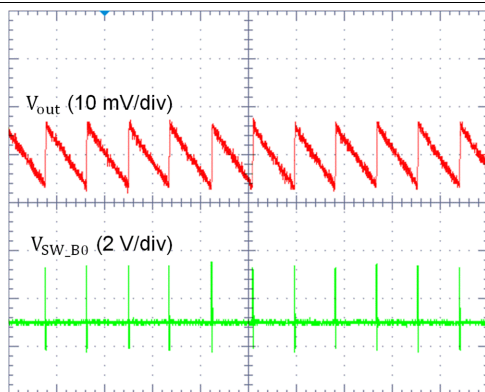


Slew-rate = 10 mV/μs

$R_{LOAD} = 1$ Ω

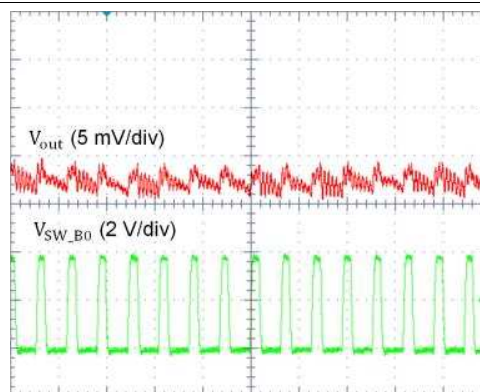
$V_{OUT} = 1$ V

Figure 32. Buck Shutdown With EN1, Forced PWM Mode



$I_{OUT} = 10$ mA

Figure 33. Buck Output Voltage Ripple, PFM Mode



$I_{OUT} = 500$ mA

Figure 34. Buck Output Voltage Ripple, Forced PWM Mode

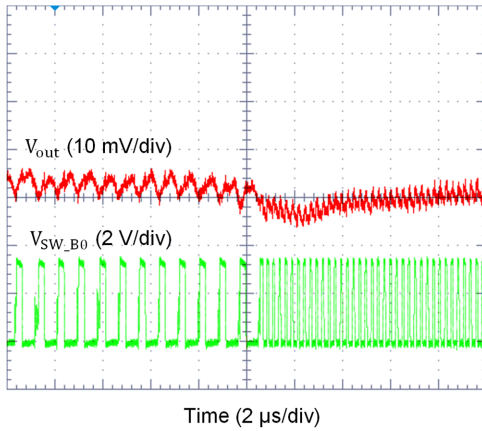


Figure 35. Buck Transient From PFM-to-PWM Mode

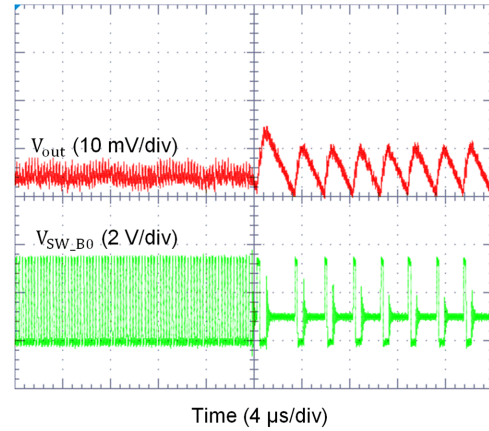
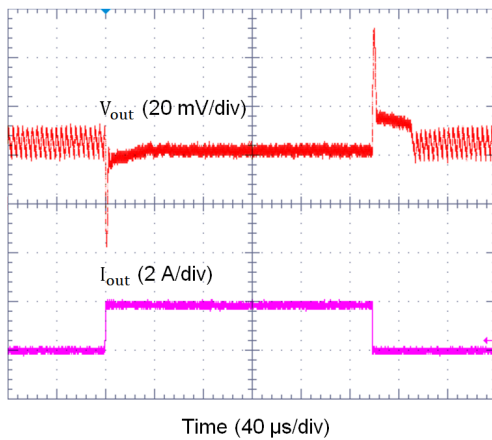
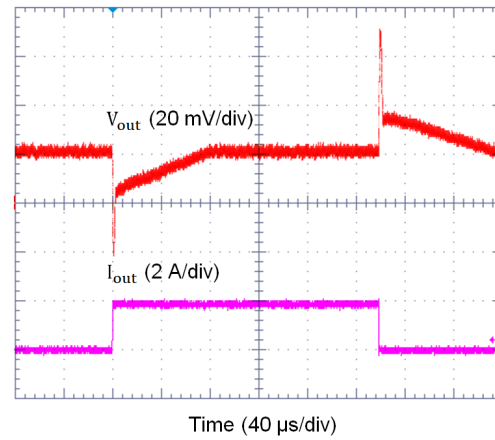


Figure 36. Buck Transient From PWM-to-PFM Mode



$I_{OUT} = 0.1 \text{ A} \rightarrow 2 \text{ A} \rightarrow 0.1 \text{ A}$ $T_R = T_F = 400 \text{ ns}$

Figure 37. Buck Transient Load Step Response, AUTO Mode



$I_{OUT} = 0.1 \text{ A} \rightarrow 2 \text{ A} \rightarrow 0.1 \text{ A}$ $T_R = T_F = 400 \text{ ns}$

Figure 38. Buck Transient Load Step Response, Forced PWM Mode

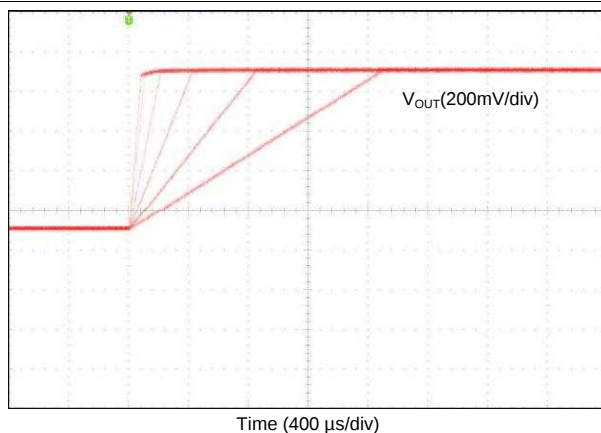


Figure 39. Buck V_{OUT} Transition from 0.6 V to 1.4 V With Different Slew Rate Settings

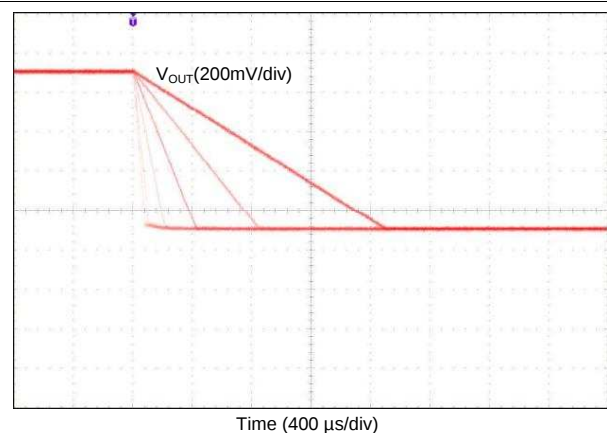


Figure 40. Buck V_{OUT} Transition from 1.4 V to 0.6 V With Different Slew Rate Settings

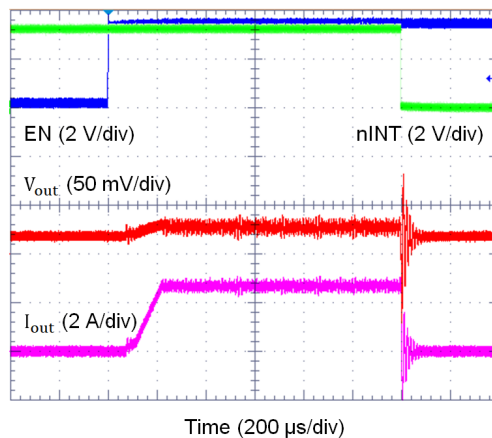


Figure 41. Buck Start-up With Short on Output

9 Power Supply Recommendations

The device is designed to operate from an input voltage supply range between 2.8 V and 5.5 V. The VANA input and VIN_Bx buck inputs must be connected together, and they must use the same input supply. This input supply must be well regulated and able to withstand maximum input current and maintain stable voltage without voltage drop even at load transition condition. The resistance of the input supply rail must be low enough that the input current transient does not cause too high a drop in the TPS65653-Q1 supply voltage that can cause false UVLO fault triggering. If the input supply is located more than a few inches from the TPS65653-Q1 additional bulk capacitance may be required in addition to the ceramic bypass capacitors.

10 Layout

10.1 Layout Guidelines

The high frequency and large switching currents of the TPS65653-Q1 make the choice of layout important. Good power supply results only occur when care is given to proper design and layout. Layout affects noise pickup and generation and can cause a good design to perform with less-than-expected results. With a range of output currents from milliamps to several amps, good power supply layout is much more difficult than most general PCB design. Use the following steps as a reference to ensure the device is stable and maintains proper voltage and current regulation across its intended operating voltage and current range.

1. Place C_{IN} as close as possible to the VIN_Bx pin and the PGND_Bx pin. Route the V_{IN} trace wide and thick to avoid IR drops. The trace between the positive node of the input capacitor and the VIN_Bx pin(s) of TPS65653-Q1, as well as the trace between the negative node of the input capacitor and power PGND_Bx pin(s), must be kept as short as possible. The input capacitance provides a low-impedance voltage source for the switching converter. The inductance of the connection is the most important parameter of a local decoupling capacitor — parasitic inductance on these traces must be kept as small as possible for proper device operation. The parasitic inductance can be reduced by using a ground plane as close as possible to top layer by using thin dielectric layer between top layer and ground plane.
2. The output filter, consisting of L and COUT, converts the switching signal at SW_Bx to the noiseless output voltage. It must be placed as close as possible to the device keeping the switch node small, for best EMI behavior. Route the traces between the output capacitors of the TPS65653-Q1 and the input capacitors of the load direct and wide to avoid losses due to the IR drop.
3. Input for analog blocks (VANA and AGND) must be isolated from noisy signals. Connect VANA directly to a quiet system voltage node and AGND to a quiet ground point where no IR drop occurs. Place the decoupling capacitor as close as possible to the VANA pin.
4. If remote voltage sensing can be used for the load, connect the TPS65653-Q1 feedback pins FB_Bx to the respective sense pins on the load capacitor. The sense lines are susceptible to noise. They must be kept away from noisy signals such as PGND_Bx, VIN_Bx, and SW_Bx, as well as high bandwidth signals such as

the I²C. Avoid both capacitive and inductive coupling by keeping the sense lines short and direct, and close to each other. Run the lines in a quiet layer. Isolate them from noisy signals by a voltage or ground plane if possible. If series resistors are used for load current measurement, place them after connection of the voltage feedback.

- Due to the small package of this converter and the overall small solution size, the thermal performance of the PCB layout is important. Many system-dependent issues such as thermal coupling, airflow, added heat sinks and convection surfaces, and the presence of other heat-generating components affect the power dissipation limits of a given component. Proper PCB layout, focusing on thermal performance, results in lower die temperatures. Wide power traces come with the ability to sink dissipated heat. This can be improved further on multi-layer PCB designs with vias to different planes. This results in reduced junction-to-ambient ($R_{\theta JA}$) and junction-to-board ($R_{\theta JB}$) thermal resistances, thereby reducing the device junction temperature, T_J . TI strongly recommends performance of a careful system-level 2D or full 3D dynamic thermal analysis at the beginning product design process by using a thermal modeling analysis software.

PRODUCT PREVIEW

11 Device and Documentation Support

11.1 Device Support

11.1.1 Third-Party Products Disclaimer

TI'S PUBLICATION OF INFORMATION REGARDING THIRD-PARTY PRODUCTS OR SERVICES DOES NOT CONSTITUTE AN ENDORSEMENT REGARDING THE SUITABILITY OF SUCH PRODUCTS OR SERVICES OR A WARRANTY, REPRESENTATION OR ENDORSEMENT OF SUCH PRODUCTS OR SERVICES, EITHER ALONE OR IN COMBINATION WITH ANY TI PRODUCT OR SERVICE.

11.2 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on ti.com. In the upper right corner, click on *Alert me* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

11.3 Community Resources

The following links connect to TI community resources. Linked contents are provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's [Terms of Use](#).

TI E2E™ Online Community *TI's Engineer-to-Engineer (E2E) Community*. Created to foster collaboration among engineers. At e2e.ti.com, you can ask questions, share knowledge, explore ideas and help solve problems with fellow engineers.

Design Support *TI's Design Support* Quickly find helpful E2E forums along with design support tools and contact information for technical support.

11.4 Trademarks

E2E is a trademark of Texas Instruments.
All other trademarks are the property of their respective owners.

11.5 Electrostatic Discharge Caution



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

11.6 Glossary

SLYZ022 — *TI Glossary*.

This glossary lists and explains terms, acronyms, and definitions.

PACKAGING INFORMATION

Orderable part number	Status (1)	Material type (2)	Package Pins	Package qty Carrier	RoHS (3)	Lead finish/ Ball material (4)	MSL rating/ Peak reflow (5)	Op temp (°C)	Part marking (6)
TPS6565342RHDRQ1	Active	Production	VQFN (RHD) 28	3000 LARGE T&R	Yes	NIPDAU SN	Level-2-260C-1 YEAR	-40 to 125	TPS6565 342-Q1
TPS6565342RHDRQ1.A	Active	Production	VQFN (RHD) 28	3000 LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	TPS6565 342-Q1
TPS6565342RHDTQ1	Active	Production	VQFN (RHD) 28	250 SMALL T&R	Yes	NIPDAU SN	Level-2-260C-1 YEAR	-40 to 125	TPS6565 342-Q1
TPS6565342RHDTQ1.A	Active	Production	VQFN (RHD) 28	250 SMALL T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	TPS6565 342-Q1

⁽¹⁾ **Status:** For more details on status, see our [product life cycle](#).

⁽²⁾ **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

⁽³⁾ **RoHS values:** Yes, No, RoHS Exempt. See the [TI RoHS Statement](#) for additional information and value definition.

⁽⁴⁾ **Lead finish/Ball material:** Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

⁽⁵⁾ **MSL rating/Peak reflow:** The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

⁽⁶⁾ **Part marking:** There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "-" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

Important Information and Disclaimer: The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

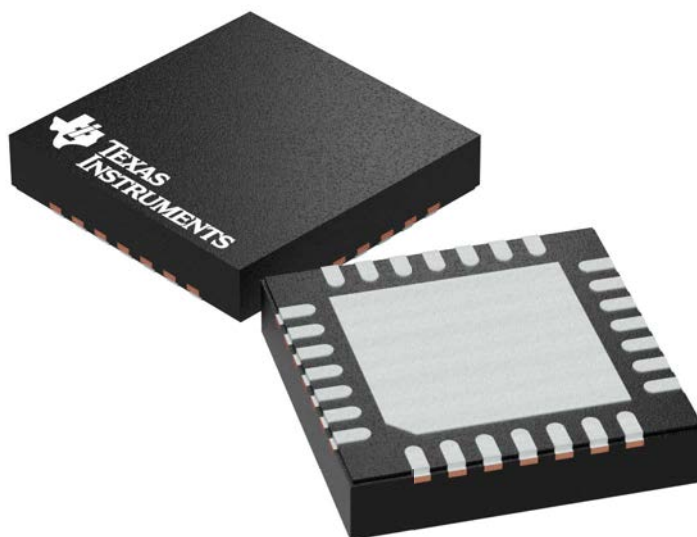
GENERIC PACKAGE VIEW

RHD 28

VQFN - 1 mm max height

5 x 5 mm, 0.5 mm pitch

PLASTIC QUAD FLATPACK - NO LEAD



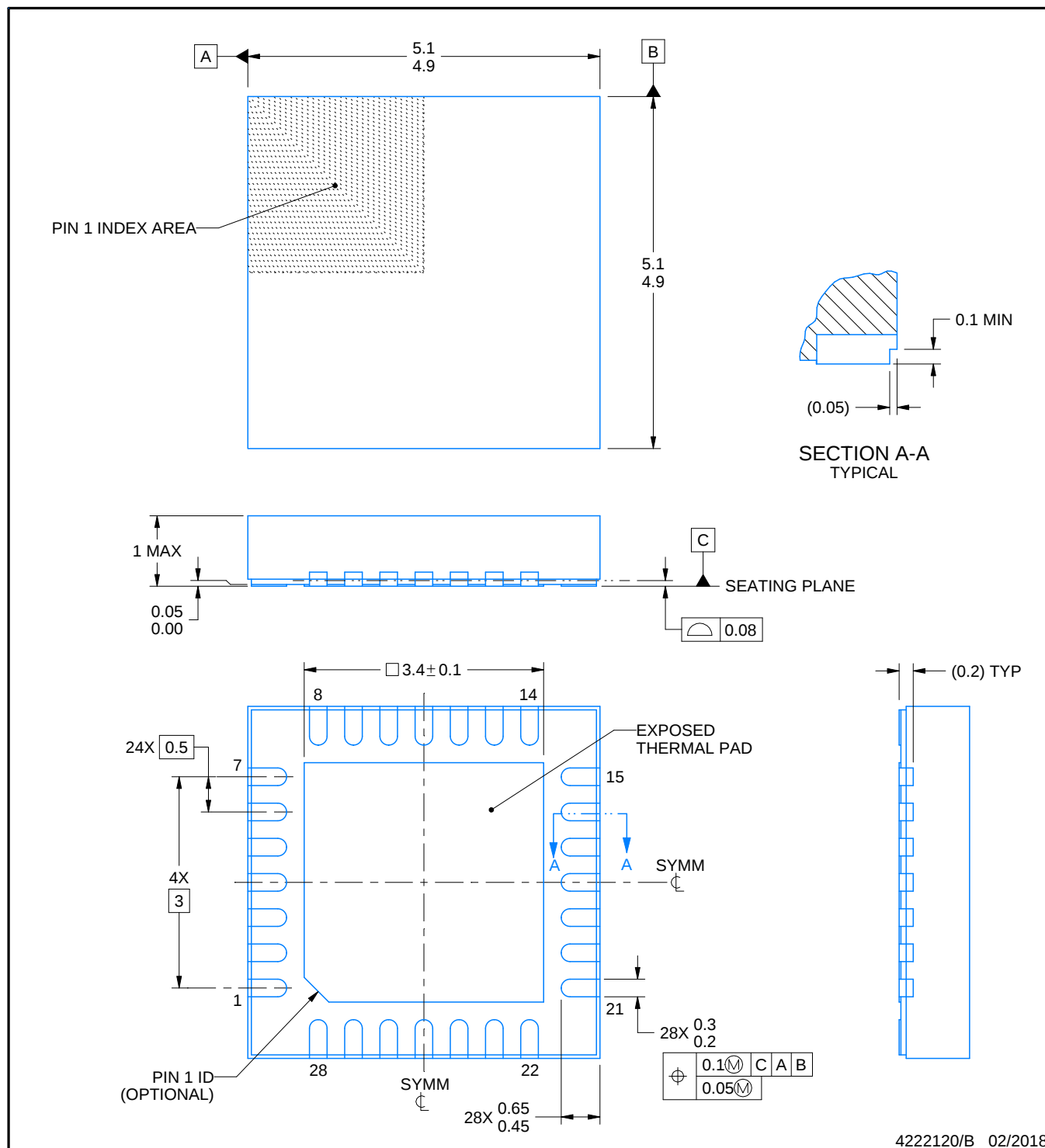
Images above are just a representation of the package family, actual package may vary.
Refer to the product data sheet for package details.

4204400/G



VQFN - 1 mm max height

PLASTIC QUAD FLATPACK - NO LEAD



NOTES:

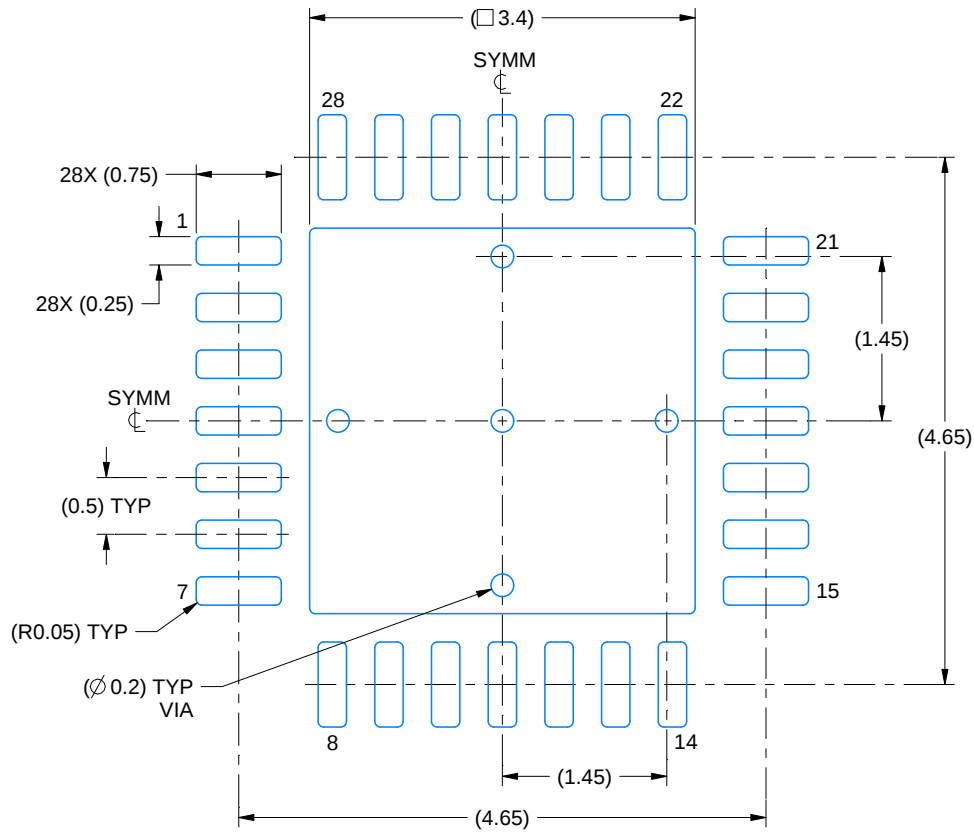
1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. The package thermal pad must be soldered to the printed circuit board for thermal and mechanical performance.

EXAMPLE BOARD LAYOUT

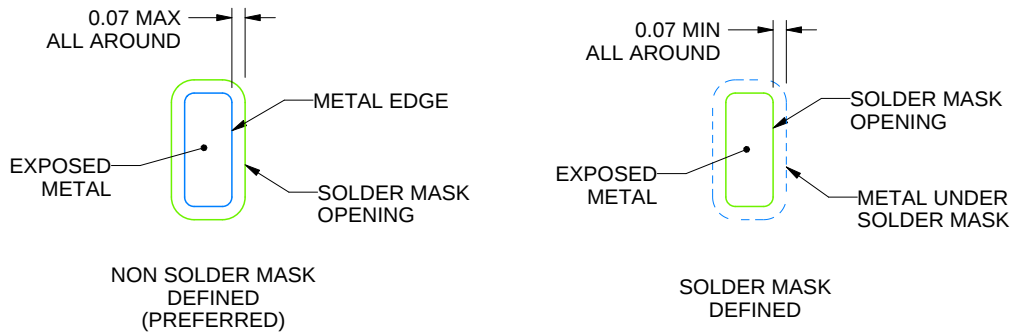
RHD0028W

VQFN - 1 mm max height

PLASTIC QUAD FLATPACK - NO LEAD



LAND PATTERN EXAMPLE
EXPOSED METAL SHOWN
SCALE:15X



SOLDER MASK DETAILS

4222120/B 02/2018

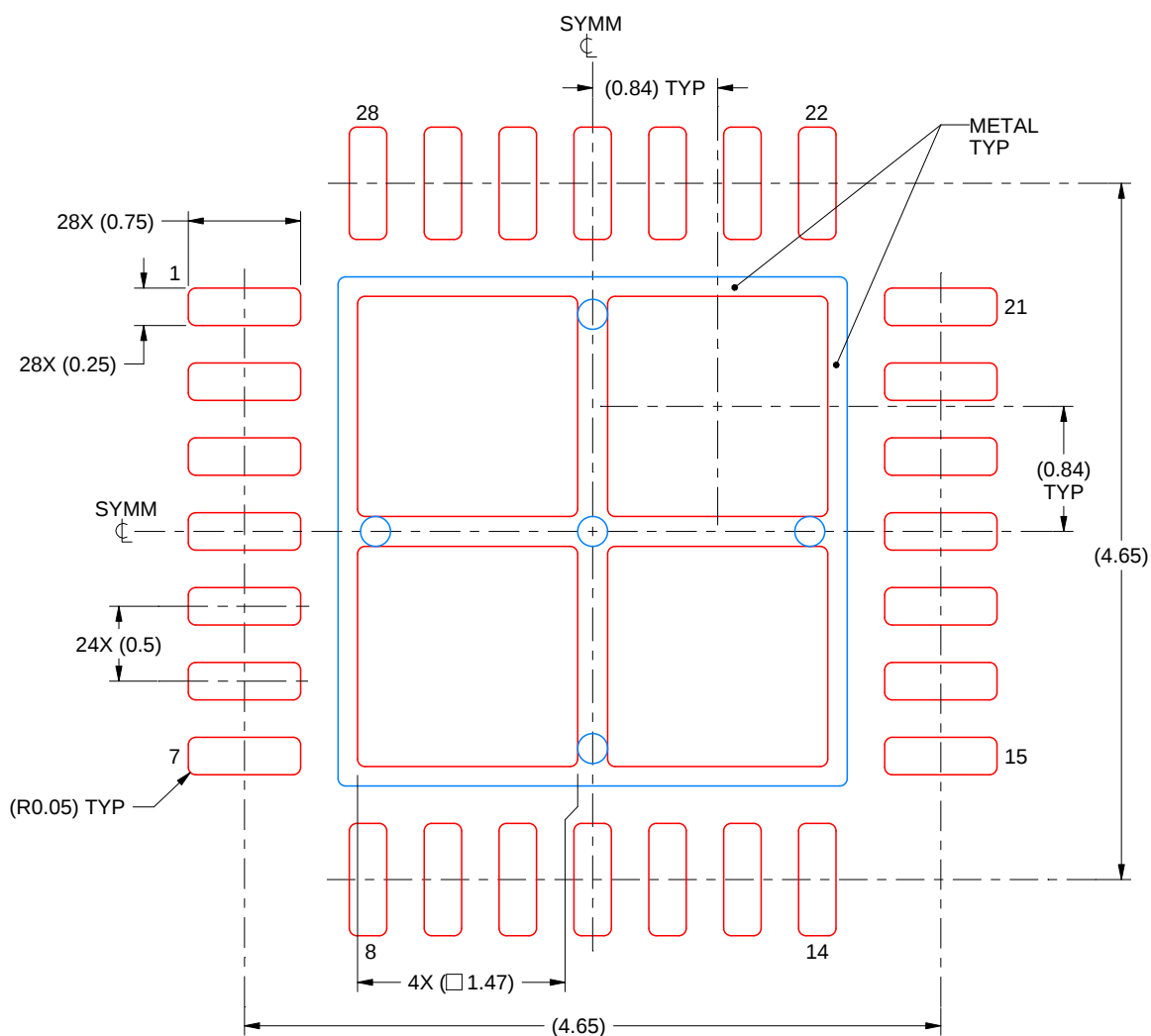
NOTES: (continued)

- This package is designed to be soldered to a thermal pad on the board. For more information, see Texas Instruments literature number SLUA271 (www.ti.com/lit/sluea271).

RHD0028W

VQFN - 1 mm max height

PLASTIC QUAD FLATPACK - NO LEAD



SOLDER PASTE EXAMPLE BASED ON 0.125 mm THICK STENCIL

EXPOSED PAD
75% PRINTED SOLDER COVERAGE BY AREA
SCALE:20X

4222120/B 02/2018

NOTES: (continued)

5. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.

IMPORTANT NOTICE AND DISCLAIMER

TI PROVIDES TECHNICAL AND RELIABILITY DATA (INCLUDING DATA SHEETS), DESIGN RESOURCES (INCLUDING REFERENCE DESIGNS), APPLICATION OR OTHER DESIGN ADVICE, WEB TOOLS, SAFETY INFORMATION, AND OTHER RESOURCES "AS IS" AND WITH ALL FAULTS, AND DISCLAIMS ALL WARRANTIES, EXPRESS AND IMPLIED, INCLUDING WITHOUT LIMITATION ANY IMPLIED WARRANTIES OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE OR NON-INFRINGEMENT OF THIRD PARTY INTELLECTUAL PROPERTY RIGHTS.

These resources are intended for skilled developers designing with TI products. You are solely responsible for (1) selecting the appropriate TI products for your application, (2) designing, validating and testing your application, and (3) ensuring your application meets applicable standards, and any other safety, security, regulatory or other requirements.

These resources are subject to change without notice. TI grants you permission to use these resources only for development of an application that uses the TI products described in the resource. Other reproduction and display of these resources is prohibited. No license is granted to any other TI intellectual property right or to any third party intellectual property right. TI disclaims responsibility for, and you will fully indemnify TI and its representatives against, any claims, damages, costs, losses, and liabilities arising out of your use of these resources.

TI's products are provided subject to [TI's Terms of Sale](#) or other applicable terms available either on [ti.com](https://www.ti.com) or provided in conjunction with such TI products. TI's provision of these resources does not expand or otherwise alter TI's applicable warranties or warranty disclaimers for TI products.

TI objects to and rejects any additional or different terms you may have proposed.

Mailing Address: Texas Instruments, Post Office Box 655303, Dallas, Texas 75265
Copyright © 2025, Texas Instruments Incorporated