







SN65HVD1785, SN65HVD1786, SN65HVD1787 SN65HVD1791, SN65HVD1792, SN65HVD1793

# SLLS872J - JANUARY 2008 - REVISED MARCH 2023

## SN65HVD17xx Fault-Protected RS-485 Transceivers With Extended Common-Mode Range

#### 1 Features

- Bus-Pin Fault Protection to:
  - > ±70 V ('HVD1785, 86, 91, 92)
  - > ±30 V ('HVD1787, 93)
- Common-Mode Voltage Range (-20 V to 25 V) More Than Doubles TIA/EIA 485 Requirement
- Bus I/O Protection
  - ±16 kV JEDEC HBM Protection
- Reduced Unit Load for Up to 256 Nodes
- Failsafe Receiver for Open-Circuit, Short-Circuit and Idle-Bus Conditions
- Low Power Consumption
  - Low Standby Supply Current, 1 μA Typical
  - I<sub>CC</sub> 5 mA Quiescent During Operation
- Power-Up, Power-Down Glitch-Free Operation

## 2 Applications

Designed for RS-485 and RS-422 Networks

## 3 Description

These devices are designed to survive overvoltage faults such as direct shorts to power supplies, miswiring faults, connector failures, cable crushes, and tool mis-applications. They are also robust to ESD events, with high levels of protection to human-body model specifications.

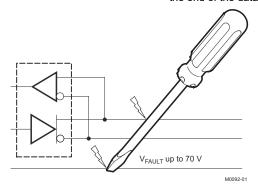
These devices combine a differential driver and a differential receiver, which operate from a single power supply. In the 'HVD1785, 'HVD1786, and 'HVD1787, the driver differential outputs and the receiver differential inputs are connected internally to form a bus port suitable for half-duplex (two-wire bus) communication. In the 'HVD1793, the driver differential outputs and the receiver differential inputs are separate pins, to form a bus port suitable for fullduplex (four-wire bus) communication. These ports feature a wide common-mode voltage range, making the devices suitable for multipoint applications over long cable runs. These devices are characterized from -40°C to 105°C.

For similar features with 3.3-V supply operation, see the SN65HVD1781 (SLLS877).

#### **Device Information**

-		••
PART NUMBER	PACKAGE <sup>(1)</sup>	BODY SIZE (NOM)
SN65HVD1785,	SOIC (8)	4.90 mm × 3.91 mm
SN65HVD1786, SN65HVD1787	PDIP (8)	9.81 mm × 6.35 mm
SN65HVD1791, SN65HVD1792, SN65HVD1793	SOIC (14)	8.65 mm × 3.91 mm

For all available packages, see the orderable addendum at the end of the datasheet.



**Example of Bus Short to Power Supply** 



## **Table of Contents**

1 Features	•	
2 Applications		
3 Description		on19
4 Revision History		
5 Product Selection Guide		
6 Pin Configuration and Functions		
7 Specifications		
7.1 Absolute Maximum Ratings <sup>(1)</sup>		
7.2 ESD Ratings		
7.3 Recommended Operating Conditions		
7.4 Thermal Information		
7.5 Electrical Characteristics		
7.6 Thermal Considerations	• • • • • • • • • • • • • • • • • • •	
7.7 Switching Characteristics		
7.8 Typical Characteristics		
8 Parameter Measurement Information		
9 Detailed Description	15 14 Mechanical, Packaging, and C	
9.1 Overview9.2 Functional Block Diagram		24
<b>4 Revision History</b> NOTE: Page numbers for previous revisions may	v differ from page numbers in the current v	version.
Changes from Revision I (August 2015) to Rev	·	Page
<ul> <li>Updated the numbering format for tables, figurence</li> </ul>		
<ul> <li>Changes from Revision H (February 2010) to Part Added Pin Configuration and Functions section Functional Modes, Application and Implement section, Device and Documentation Support section</li> </ul>	on, ESD Ratings table, Feature Description tation section, Power Supply Recomment section, and Mechanical, Packaging, and	lations section, Layout Orderable Information
Changes from Revision G (April 2009) to Revi		
Deleted 70-V from the data sheet title		1
<ul> <li>Changed first Features Bullet From: Bus-Pin I ±70 V ('HVD1785, 86,91,92), &gt; ±30 V ('HVD1</li> </ul>		
Changed Voltage range at A and B inputs in the different devices	he ABS MAX RATINGS table, adding sep	erate conditions for
Changed From: Voltage input range, transient		
through 100 Ω per TIA-485		
U II OUUII TUU 14 DOL TIA-700		
		6
Added the 70-V Fault-Protection section		6
Added the 70-V Fault-Protection section  Changes from Revision F (November 2008) to	o Revision G (April 2009)	6 16
Added the 70-V Fault-Protection section	o Revision G (April 2009)	6 16
Added the 70-V Fault-Protection section  Changes from Revision F (November 2008) to	o Revision G (April 2009) o the Receiver high-level output voltage	6 Page
<ul> <li>Added the 70-V Fault-Protection section</li> <li>Changes from Revision F (November 2008) to</li> <li>Added I<sub>OH</sub> = -400 μA conditions and values to</li> </ul>	o Revision G (April 2009) o the Receiver high-level output voltage	6 16 7
<ul> <li>Added the 70-V Fault-Protection section</li> <li>Changes from Revision F (November 2008) to</li> <li>Added I<sub>OH</sub> = -400 μA conditions and values to</li> <li>Added Receiver enabled V<sub>CM</sub> &gt; V<sub>CC</sub></li> <li>Added Receiver Failsafe information</li> </ul>	o Revision G (April 2009) o the Receiver high-level output voltage	
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•	Added Receiver enabled $V_{CM} > V_{CC}$ condition and values to the Driver enabled time	
C	hanges from Revision D (June 2008) to Revision E (July 2008)	Page
•	Changed - Removed Product Preview label	
•	Changed SN65HVD1792 Removed Product Preview label	
•	Changed SN65HVD1793 Removed Product Preview label	4
C	hanges from Revision C (March 2008) to Revision D (June 2008)	Page
•	Added Features Bullet: Power-Up, Power-Down Glitch-Free Operation	1
•	Changed (Preview) to part number SN65HVD1791 in the Product Selection Guide	
•	Added section - APPLICATION INFORMATION	
•	Changed Receiver disabled by default - Enable from X to OPEN. Output from OPEN to Z	18
C	hanges from Revision B (March 2008) to Revision C (March 2008)	Page
•	Changed Rec Op Table. Signaling rate, HVD1787, HVD1793 From: 20 Mbps max to 10 Mbps max	6
C	hanges from Revision A (March 2008) to Revision B (March 2008)	Page
•	Added $T_A \le 85^{\circ}C$ and $T_A \le 105^{\circ}C$ conditions and values to the Receiver low-level output voltage	
C	hanges from Revision * (January 2008) to Revision A (March 2008)	Page
•	Changed Features Bullet From: Low Standby Supply Current, 2 μA Max To: Low Standby Supply Currer μΑ Typ	
•	Deleted columns to the PRODUCT SELECTION GUIDE for Package Options and Status	4
•	Added text: For similar features with 3.3 V supply operation	
•	Changed the Product Selection Guide Signaling Rate for SN65HVD1787 From 20 Mbps To: 10 Mbps	
•	Changed the Product Selection Guide Signaling Rate for SN65HVD1793 From 20 Mbps To: 10 Mbps	
•	Deleted The Competitive Comparison table	
•	Added $ V_{OD} $ RS-485 with common-mode load $T_A \le 85^{\circ}$ C and $T_A \le 105^{\circ}$ C	<mark>7</mark>
•	Changed $\Delta V_{OC}$ From min = -0.2 mV and max 0.2 mV To: min = -100 mV and max 100 mV	
•	Changed HVD1785/1791 Driver differential output rise/fall time max value From 2.5 µs To: 2.6 µs	
•	Changed HVD1787/1793 Driver differential output rise/fall time max value From 1.5 ns To: 30 ns	
•	Changed Receiver propagation delay max value From 50 ns To: 70 ns	
•	Changed t <sub>PLZ</sub> , t <sub>PHZ</sub> Receiver disable time From 3000 ns To 100 ns  Deleted graph DIFFERENTIAL OUTPUT VOLTAGE vs DIFFERENTIAL LOAD CURRENT	



## **5 Product Selection Guide**

PART NUMBER	DUPLEX	SIGNALING RATE	NODES	CABLE LENGTH
SN65HVD1785	Half	115 kbps	Up to 256	1500 m
SN65HVD1786	Half	1 Mbps	Up to 256	150 m
SN65HVD1787	Half	10 Mbps	Up to 64	50 m
SN65HVD1791	Full	115 kbps	Up to 256	1500 m
SN65HVD1792	Full	1 Mbps	Up to 256	150 m
SN65HVD1793	Full	10 Mbps	Up to 64	50 m

## **6 Pin Configuration and Functions**

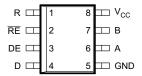
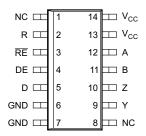


Figure 6-1. D or P Package 8-Pin SOIC or PDIP SN65HVD1785, 1786, 1787 (Top View)

## **Pin Functions (SN65HVD1785, SN65HVD1786, SN65HVD1787)**

	Thir discions (Sitestive 1766, Sitestive 1767)						
F	PIN	TYPE	DESCRIPTION				
NAME	NO.	111-	DESCRIPTION				
А	6	Bus input/ output	Driver output or receiver input (complementary to B)				
В	7	Bus input/ output	Driver output or receiver input (complementary to A)				
D	4	Digital input	Driver data input				
DE	3	Digital input	Driver enable, active high				
GND	5	Reference potential	Local device ground				
R	1	Digital output	Receive data output				
RE	2	Digital input	Receiver enable, active low				
V <sub>CC</sub>	8	Supply	4.5-V-to-5.5-V supply				





NC - No internal connection

Pins 6 and 7 are connected together internally.

Pins 13 and 14 are connected together internally.

## Figure 6-2. D Package 14-Pin SOIC SN65VD1791, 1792, 1793 (Top View)

#### **Pin Functions (SN65HVD1791, SN65HVD1792, SN65HVD1793)**

P	IN	TYPE	DESCRIPTION	
NAME	NO.	ITPE	DESCRIPTION	
A	12	Bus input	Receiver input (complementary to B)	
В	11	Bus input	Receiver input (complementary to A)	
Υ	9	Bus output	Driver output (complementary to Z)	
Z	10	Bus output	Driver output (complementary to Y)	
D	5	Digital input	Driver data input	
DE	4	Digital input	Driver enable, active high	
GND	6, 7	Reference potential	Local device ground	
R	2	Digital output	Receive data output	
RE	3	Digital input	Receiver enable, active low	
V <sub>CC</sub>	13, 14	Supply	/ to 5.5-V supply	
NC	1, 8	No connect	No connect; should be left floating	



## 7 Specifications

## 7.1 Absolute Maximum Ratings<sup>(1)</sup>

				MIN	MAX	UNIT
V <sub>CC</sub>	Supply voltage			-0.5	7	V
	'HVD1785, 86, 91, 92, 93		A, B pins	-70	70	V
	Voltage at bus pins	'HVD1787	A, B pins	-70	30	V
		'HVD1793	Y, Z pins	-70	30	V
	Input voltage at any logic pir	1		-0.3	V <sub>CC</sub> + 0.3	V
	Transient overvoltage pulse	through 100 Ω per TIA-485		-100	100	V
	Receiver output current			-24	24	mA
TJ	Junction temperature			170	°C	
T <sub>stg</sub>	Storage temperature				160	°C

<sup>(1)</sup> Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. These are stress ratings only and functional operation of the device at these or any other conditions beyond those indicated under Recommended Operating Conditions is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

## 7.2 ESD Ratings

				VALUE	UNIT
		Human body model (HBM), per ANSI/ESDA/JEDEC JS-001 <sup>(1)</sup> ,	Bus terminals and GND	±16000	
		JEDEC Standard 22, Test Method A114	All pins	±4000	
V <sub>(ESD)</sub>	Electrostatic discharge	Charged-device model (CDM), per JEDEC specification JESD22-C101 <sup>(2)</sup> , JEDEC Standard 22, Test Method C101			V
		Machine Model, JEDEC Standard 22, Test Method A115			
		IEC 60749-26 ESD (human-body model)	Bus terminals and GND	±16000	

<sup>(1)</sup> JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

## 7.3 Recommended Operating Conditions

			MIN	NOM	MAX	UNIT
V <sub>CC</sub>	Supply voltage	Supply voltage		5	5.5	V
VI	Input voltage at	any bus terminal (separately or common mode) <sup>(1)</sup>	-20		25	V
V <sub>IH</sub>	High-level input	t voltage (driver, driver enable, and receiver enable inputs)	2		V <sub>CC</sub>	V
V <sub>IL</sub>	Low-level input	voltage (driver, driver enable, and receiver enable inputs)	0		8.0	V
V <sub>ID</sub>	Differential inpu	ıt voltage	-25		25	V
	Output current, driver		-60		60	mA
I <sub>O</sub>	Output current, receiver		-8		8	mA
$R_L$	Differential load	I resistance	54	60		Ω
C <sub>L</sub>	Differential load	I capacitance		50		pF
		HVD1785, HVD1791			115	kbps
1/t <sub>UI</sub>	Signaling rate	HVD1786, HVD1792			1	Mhna
		HVD1787, HVD1793			10	Mbps
T <sub>A</sub>	Operating free-air temperature (see application section for thermal information)		-40		105	°C
TJ	Junction tempe	rature	-40		150	°C

<sup>(1)</sup> By convention, the least positive (most negative) limit is designated as minimum in this data sheet.

<sup>(2)</sup> JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.



#### 7.4 Thermal Information

THERMAL METRIC <sup>(1)</sup>		· ·	, SN65HVD1786, IVD1787	SN65HVD1791, SN65HVD1792, SN65HVD1793	UNIT
		D (SOIC)	P (PDIP)	D (SOIC)	
		8 PINS	8 PINS	14 PINS	
$R_{\theta JA}$	Junction-to-ambient thermal resistance	138	59	95	°C/W
R <sub>θJA (low-K)</sub>	Junction-to-case (top) thermal resistance	242	128	168	°C/W
R <sub>0</sub> JC(top)	Junction-to-board thermal resistance	61	61	44	°C/W
R <sub>0JB</sub>	Junction-to-top characterization parameter	62	39	40	°C/W
ΨЈТ	Junction-to-board characterization parameter	3.4	17.6	8.2	°C/W
ΨЈВ	Junction-to-case (bottom) thermal resistance	33.4	28.3	25	°C/W

<sup>(1)</sup> For more information about traditional and new thermal metrics, see the Semiconductor and IC Package Thermal Metrics application report, SPRA953.

#### 7.5 Electrical Characteristics

over recommended operating conditions (unless otherwise noted)

$ V_{OD}  \  \   \text{Driver differential output voltage magnitude} \  \   \begin{array}{llllllllllllllllllllllllllllllllll$	PARAMETER		TEST CONDITIONS		MIN	TYP	MAX	UNIT	
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	V <sub>OD</sub>	Driver differential output voltage magnitude	mode load, V <sub>CC</sub> > 4.75 V,						V
$ \Delta  V_{OD}                                     $			$R_L = 54 \Omega, 4.75 V \le V_0$	<sub>CC</sub> ≤ 5.25	V	1.5	2		
$V_{OC(SS)} \begin{tabular}{l l l l l l l l l l l l l l l l l l l $			R <sub>L</sub> = 100 Ω, 4.75 V ≤ \	/ <sub>CC</sub> ≤ 5.25	5 V	2	2.5		
	$\Delta  V_{OD} $		R <sub>L</sub> = 54 Ω			-0.2	0	0.2	V
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	V <sub>OC(SS)</sub>	Steady-state common-mode output voltage				1	V <sub>CC</sub> /2	3	V
$V_{\text{CC}(\text{PP})} \text{ voltage } \\ V_{\text{CD}} \text{ Differential output capacitance} \\ V_{\text{IT+}} \text{ Positive-going receiver differential input voltage threshold} \\ V_{\text{IT-}} \text{ Negative-going receiver differential input voltage threshold} \\ V_{\text{HY}} \text{ Receiver differential input voltage threshold hysteresis (V_{\text{IT+}} - V_{\text{IT-}})} \\ V_{\text{OH}} \text{ Receiver high-level output voltage} \\ V_{\text{OL}} \text{ Receiver low-level output voltage} \\ I_{\text{I}} \text{ Driver input, driver enable, and receiver enable input current} \\ I_{\text{OS}} \text{ Driver short-circuit output current} \\ I_{\text{I}} \text{ Bus input current (disabled driver)} \\ V_{\text{CC}} = 4.5 \text{ to } 5.5 \text{ V or } \\ V_{\text{CC}} = 0 \text{ V, DE at 0 V} \\ V_{\text{I}} = 12 \text{ V} \\ V_{\text{I}} = 12 \text{ V} \\ V_{\text{I}} = 12 \text{ V} \\ V_{\text{I}} = 20 \text{ V} \\ V_{\text{I}} = 20 \text{ V} \\ V_{\text{CC}} = 4.5 \text{ to } 5.5 \text{ V or } \\ V_{\text{CC}} = 0 \text{ V, DE at 0 V} \\ V_{\text{I}} = 12 \text{ V} \\ V_{\text{I}} = 12 \text{ V} \\ V_{\text{I}} = 20 \text{ Driver} \\ V_{\text{I}} = 20 \text{ V or 0 V} \\ V_{\text{CC}} = 4.5 \text{ to } 5.5 \text{ V or } \\ V_{\text{CC}} = 0 \text{ V, DE at 0 V} \\ V_{\text{I}} = 12 \text{ V} \\ V_{\text{I}} = 27 \text{ V} \\ V_{\text{I}} = 20 \text{ Driver} \\ V_{\text{I}} = 20 \text{ V or 0 V} \\ V_{\text{I}} = 20 \text{ V or 0 V} \\ V_{\text{CC}} = 4.5 \text{ to } 5.5 \text{ V or } \\ V_{\text{CC}} = 4.5 \text{ to } 5.5 \text{ V or } \\ V_{\text{CC}} = 0 \text{ V, DE at 0 V} \\ V_{\text{I}} = 12 \text{ V} \\ V_{\text{I}} = 12 \text{ V} \\ V_{\text{I}} = 20 \text{ Driver} \\ V_{\text{I}} = 20 \text{ Driver} \\ V_{\text{I}} = 20 \text{ Driver} \\ V_{\text{CD}} = 20 \text{ V or 0 V} \\ V_{\text{I}} = 20 \text{ V or 0 V} \\ V_{\text{I}} = 20 \text{ V or 0 V} \\ V_{\text{I}} = 20 \text{ V or 0 V} \\ V_{\text{I}} = 20 \text{ V or 0 V} \\ V_{\text{I}} = 20 \text{ V or 0 V} \\ V_{\text{I}} = 20 \text{ V or 0 V} \\ V_{\text{I}} = 20 \text{ V or 0 V} \\ V_{\text{I}} = 20 \text{ V or 0 V} \\ V_{\text{I}} = 20 \text{ V or 0 V} \\ V_{\text{I}} = 20 \text{ V or 0 V} \\ V_{\text{I}} = 20 \text{ V or 0 V} \\ V_{\text{I}} = 20 \text{ Driver or 0 V} \\ V_{\text{I}} = 20 \text{ Driver or 0 V} \\ V_{\text{I}} = 20 \text{ Driver or 0 V} \\ V_{\text{I}} = 20 \text{ Driver or 0 V} \\ V_{\text{I}} = 20 \text{ Driver or 0 V} \\ V_{\text{I}} = 20 \text{ Driver or 0 V} \\ V_{\text{I}} = 20 \text{ Driver or 0 V} \\ V_{\text{I}} = 20 \text{ Driver or 0 V} \\ V_{\text{I}} =$	ΔV <sub>OC</sub>					-100	0	100	mV
$V_{IT+}  \begin{array}{c} \text{Positive-going receiver differential input voltage} \\ V_{IT-}  \begin{array}{c} \text{Negative-going receiver differential input voltage} \\ \text{threshold} \\ \end{array}$ $V_{IT-}  \begin{array}{c} \text{Negative-going receiver differential input voltage} \\ \text{threshold} \\ \end{array}$ $V_{CM} = -20 \text{ V to } 25 \text{ V} \\ \end{aligned}$ $V_{CM} = -20 \text{ V to } 25 \text{ V} \\ \end{aligned}$ $V_{CM} = -20 \text{ V to } 25 \text{ V} \\ \end{aligned}$ $V_{CM} = -20 \text{ V to } 25 \text{ V} \\ \end{aligned}$ $V_{CM} = -20 \text{ V to } 25 \text{ V} \\ \end{aligned}$ $V_{CM} = -20 \text{ V to } 25 \text{ V} \\ \end{aligned}$ $V_{CM} = -20 \text{ V to } 25 \text{ V} \\ \end{aligned}$ $V_{CM} = -20 \text{ V to } 25 \text{ V} \\ \end{aligned}$ $V_{CM} = -20 \text{ V to } 25 \text{ V} \\ \end{aligned}$ $V_{CM} = -20 \text{ V to } 25 \text{ V} \\ \end{aligned}$ $V_{CM} = -20 \text{ V to } 25 \text{ V} \\ \end{aligned}$ $V_{CM} = -20 \text{ V to } 25 \text{ V} \\ \end{aligned}$ $V_{CM} = -20 \text{ V to } 25 \text{ V} \\ \end{aligned}$ $V_{CM} = -20 \text{ V to } 25 \text{ V} \\ \end{aligned}$ $V_{CM} = -20 \text{ V to } 25 \text{ V} \\ \end{aligned}$ $V_{CM} = -20 \text{ V to } 25 \text{ V} \\ \end{aligned}$ $V_{CM} = -20 \text{ V to } 25 \text{ V} \\ \end{aligned}$ $V_{CM} = -20 \text{ V to } 25 \text{ V} \\ \end{aligned}$ $V_{CM} = -20 \text{ V to } 25 \text{ V to } 25 \text{ V} \\ \end{aligned}$ $V_{CM} = -20 \text{ V to } 25 \text{ V to } 25$	V <sub>OC(PP)</sub>	·		ıd resistor	rs,		500		mV
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	C <sub>OD</sub>	Differential output capacitance					23		pF
$\begin{array}{c} \text{ViT-} & \text{threshold} \\ \text{V}_{\text{HYS}} & \text{Receiver differential input voltage threshold} \\ \text{V}_{\text{HYS}} & \text{Receiver differential input voltage} \\ \text{V}_{\text{OH}} & \text{Receiver high-level output voltage} \\ \end{array} \begin{array}{c} I_{\text{OH}} = -8 \text{ mA} \\ I_{\text{OH}} = -400  \mu\text{A} \\ \end{array} \begin{array}{c} 2.4 & \frac{\text{V}_{\text{CC}} - }{0.3} \\ \text{V}_{\text{O}} \\ \end{array} \begin{array}{c} \text{V}_{\text{CC}} = 100 \\ \text{V}_{\text{O}} = 100 \\ \end{array} \begin{array}{c} \text{MV}_{\text{CC}} = 100 \\ \text{MV}_{\text{CC}} = 100 \\ \end{array} \begin{array}{c} \text{MV}_{\text{CC}} = 100 \\ \text{MV}_{\text{CC}} = 100 \\ \end{array} \begin{array}{c} \text{MV}_{\text{CC}} = 100 \\ \text{MV}_{\text{CC}} = 100 \\ \end{array} \begin{array}{c} \text{MV}_{\text{CC}} = 100 \\ \text{MV}_{\text{CC}} = 100 \\ \text{MV}_{\text{CC}} = 100 \\ \end{array} \begin{array}{c} \text{MV}_{\text{CC}} = 100 \\ \text{MV}_{\text{CC}} = 100 \\ \text{MV}_{\text{CC}} = 100 \\ \end{array} \begin{array}{c} \text{MV}_{\text{CC}} = 100 \\ M$	V <sub>IT+</sub>						-100	-10	mV
$V_{OH}  \text{Receiver high-level output voltage} \qquad \begin{array}{ c c c c c c c c } \hline V_{OH}  \text{Receiver high-level output voltage} & \hline & I_{OH} = -8 \text{ mA} & 2.4 & \frac{V_{CC} -}{0.3} & V \\ \hline & I_{OH} = -400  \mu\text{A} & 4 & & & & \\ \hline & I_{OH} = -400  \mu\text{A} & 4 & & & & \\ \hline & I_{OH} = -400  \mu\text{A} & 4 & & & & \\ \hline & V_{OL}  \text{Receiver low-level output voltage} & I_{OL} = 8 \text{ mA} & \frac{T_A \le 85^{\circ}\text{C}}{T_A \le 105^{\circ}\text{C}} & 0.2 & 0.4 & V \\ \hline & I_{I}  \text{Driver input, driver enable, and receiver enable input current} & & -100 & 100 & \mu\text{A} \\ \hline & I_{OZ}  \text{Receiver output high-impedance current} & V_O = 0 \text{ V or } V_{CC}, \overline{\text{RE at }} V_{CC} & -1 & 1 & \mu\text{A} \\ \hline & I_{OS}  \text{Driver short-circuit output current} & & & -250 & 250 & \text{mA} \\ \hline & I_{I}  \text{Bus input current (disabled driver)} & & V_{CC} = 4.5 \text{ to } 5.5 \text{ V or } V_{CC} = 0 \text{ V, DE at 0 V} & V_{I} = -7 \text{ V} & -100 & -40 & \mu\text{A} \\ \hline & V_{I} = -7 \text{ V} & -100 & -40 & 0 & 0 \\ \hline & V_{I} = -7 \text{ V} & -100 & -40 & 0 & 0 \\ \hline & V_{I} = 12 \text{ V} & 0.500 & 0.500 & 0.500 \\ \hline & V_{I} = 12 \text{ V} & 0.500 & 0.500 \\ \hline & V_{I} = 12 \text{ V} & 0.500 & 0.500 \\ \hline & V_{I} = 12 \text{ V} & 0.500 & 0.500 \\ \hline & V_{I} = 12 \text{ V} & 0.500 & 0.500 \\ \hline & V_{I} = 12 \text{ V} & 0.500 & 0.500 \\ \hline & V_{I} = 12 \text{ V} & 0.500 & 0.500 \\ \hline & V_{I} = 0.500 & 0.500 & 0.500 \\ \hline & V_{I} = 0.500 & 0.500 & 0.500 & 0.500 \\ \hline & V_{I} = 0.500 & 0.500 & 0.500 & 0.500 \\ \hline & V_{I} = 0.500 & 0.500 & 0.500 & 0.500 \\ \hline & V_{I} = 0.500 & 0.500 & 0.500 & 0.500 \\ \hline & V_{I} = 0.500 & 0.500 & 0.500 & 0.500 \\ \hline & V_{I} = 0.500 & 0.500 & 0.500 & 0.500 \\ \hline & V_{I} = 0.500 & 0.500 & 0.500 & 0.500 \\ \hline & V_{I} = 0.500 & 0.500 & 0.500 \\ \hline & V_{I} = 0.500 & 0.500 & 0.500 \\ \hline & V_{I} = 0.500 & 0.500 & 0.500 \\ \hline & V_{I} = 0.500 & 0.500 & 0.500 \\ \hline & V_{I} = 0.500 & 0.500 & 0.500 \\ \hline & V_{I} = 0.500 & 0.500 & 0.500 \\ \hline & V_{I} = 0.500 & 0.500 & 0.500 \\ \hline & V_{I} = 0.500 & 0.500 & 0.500 \\ \hline & V_{I} = 0.500 & 0.500 & 0.500 \\ \hline & V_{I} = 0.500 & 0.500 & 0.500 \\ \hline & V_{I} = 0.500 & 0.500 & 0.500 \\ \hline & V_{I} = 0.500 & 0.500 & 0.500 \\ \hline $	V <sub>IT-</sub>		V <sub>CM</sub> = -20 V to 25 V			-200	-150		mV
$V_{OH}  \text{Receiver high-level output voltage}  \begin{array}{c ccccccccccccccccccccccccccccccccccc$	$V_{HYS}$					30	50		mV
$V_{OL}  \text{Receiver low-level output voltage} \qquad I_{OL} = 8 \text{ mA} \qquad \frac{T_{A} \leq 85^{\circ}\text{C}}{T_{A} \leq 105^{\circ}\text{C}} \qquad 0.2  0.4}{T_{A} \leq 105^{\circ}\text{C}} \qquad 0.2  0.5}  V$ $I_{I}  \text{Driver input, driver enable, and receiver enable input current} \qquad -100 \qquad 100  \mu A$ $I_{OZ}  \text{Receiver output high-impedance current} \qquad V_{O} = 0 \text{ V or } V_{CC}, \ \overline{\text{RE}} \text{ at } V_{CC} \qquad -1 \qquad 1  \mu A$ $I_{OS}  \text{Driver short-circuit output current} \qquad -250 \qquad 250  \text{mA}$ $I_{I}  \text{Bus input current (disabled driver)} \qquad V_{CC} = 4.5 \text{ to } 5.5 \text{ V or } V_{CC} = 4.5 \text{ to } 5.5 \text{ V or } V_{CC} = 0 \text{ V, DE at } 0 \text{ V} \qquad 0.2  0.4  V_{CC} = 0.2  0.5  V_{CC} = 0.2  0.$	$V_{OH}$	Receiver high-level output voltage	I <sub>OH</sub> = -8 mA			2.4	V <sub>CC</sub> – 0.3		V
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$			I <sub>OH</sub> = -400 μA			4			
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	Voi	Receiver low-level output voltage	lo = 8 mA	T <sub>A</sub> ≤ 85°	C		0.2	0.4	V
input current $V_{O}=0\ V\ or\ V_{CC}$ , $\overline{RE}$ at $V_{CC}$ $V_{I}=12\ V_{I}=7\ V_{I}=12\ V_{I}$	VOL	- Noserver level earput voltage	IOL OTHER	T <sub>A</sub> ≤ 105	5°C		0.2	0.5	•
	l <sub>i</sub>				-100		100	μΑ	
$V_{CC} = 4.5 \text{ to } 5.5 \text{ V or} \\ V_{CC} = 0 \text{ V, DE at } 0 \text{ V} \\ V_{CC} = 0 \text{ V, DE at } 0 \text{ V} \\ 0 \text{ A} = 0 \text{ V} \\ 0 \text{ A} = 0 \text{ A} $	l <sub>OZ</sub>	Receiver output high-impedance current	$V_O = 0 \text{ V or } V_{CC}, \overline{RE} \text{ at } V_{CC}$		-1		1	μΑ	
$V_{CC} = 4.5 \text{ to } 5.5 \text{ V or } V_{CC} = 0 \text{ V, DE at } 0 \text{ V}$ Bus input current (disabled driver) $V_{CC} = 0 \text{ V, DE at } 0 \text{ V}$ $V_{I} = -7 \text{ V}$ $V_{I} = -7 \text{ V}$ $V_{I} = 12 \text{ V}$	I <sub>OS</sub>	Driver short-circuit output current			-250		250	mA	
I <sub>I</sub> Bus input current (disabled driver) $ \begin{array}{c ccccccccccccccccccccccccccccccccccc$				85, 86,	V <sub>I</sub> = 12 V		75	125	
$V_{CC} = 0 \text{ V, DE at } 0 \text{ V}$	ı.	Rus input current (disabled driver)	$V_{CC} = 4.5 to 3.5 V or V_{CC} = 0 V, DE at 0 V$		V <sub>I</sub> = -7 V	-100	<del>-4</del> 0		пΔ
$V_1 = -7 V \qquad -400$	11	Bus input current (disabled univer)			V <sub>I</sub> = 12 V			500	μΛ
				01, 33	V <sub>I</sub> = -7 V	-400			



## 7.5 Electrical Characteristics (continued)

over recommended operating conditions (unless otherwise noted)

	PARAMETER	TEST CO	NDITIONS	MIN	TYP	MAX	UNIT
		Driver and receiver enabled	DE = V <sub>CC</sub> , RE = GND, no load		4	6	
		Driver enabled, receiver disabled	$\begin{aligned} &DE = V_{CC}, \\ &RE = V_{CC}, \\ &no \; load \end{aligned}$		3	5	mA
Icc	Supply current (quiescent)	Driver disabled, receiver enabled	DE = GND, RE = GND, no load		2	4	
		Driver and receiver disabled	DE = GND, D = open RE = V <sub>CC</sub> , no load		0.5	5	μА
	Supply current (dynamic)	See Section 7.8	- 1				

## 7.6 Thermal Considerations

	PARAMET	ER	TEST CONDITIONS	VALUE	UNIT
		85, 91	$V_{CC}$ = 5.5 V, $T_J$ = 150°C, $R_L$ = 300 $\Omega$ , $C_L$ = 50 pF (driver), $C_L$ = 15 pF (receiver) 5-V supply, unterminated <sup>(1)</sup>		
		85, 91			mW
		86	$V_{CC} = 5.5 \text{ V}$ , $T_{J} = 150^{\circ}\text{C}$ , $R_{L} = 100 \Omega$ , $C_{L} = 50 \text{ pF (driver)}$ , $C_{L} = 15 \text{ pF (receiver)}$ 5-V supply, RS-422 load <sup>(1)</sup>	320	
P <sub>D</sub>	Power dissipation	87	-   -   -   -   -   -   -   -   -   -		
		85, 91			
		86	$V_{CC} = 5.5 \text{ V, } T_{J} = 150^{\circ}\text{C, } R_{L} = 54 \Omega, C_{L} = 50 \text{ pF (driver),}$ $C_{L} = 15 \text{ pF (receiver) } 5-\text{V supply, } RS-485 \text{ load}^{(1)}$	400	
		87	le pr (reserver) e v eappry, rice ree read		
T <sub>SD</sub>	T <sub>SD</sub> Thermal-shutdown junction temperature			170	°C

<sup>(1)</sup> Driver and receiver enabled, 50% duty cycle square-wave signal at signaling rate: HVD1785, 1791 at 115 kbps, HVD1786 at 1 Mbps, HVD1787 at 10 Mbps)



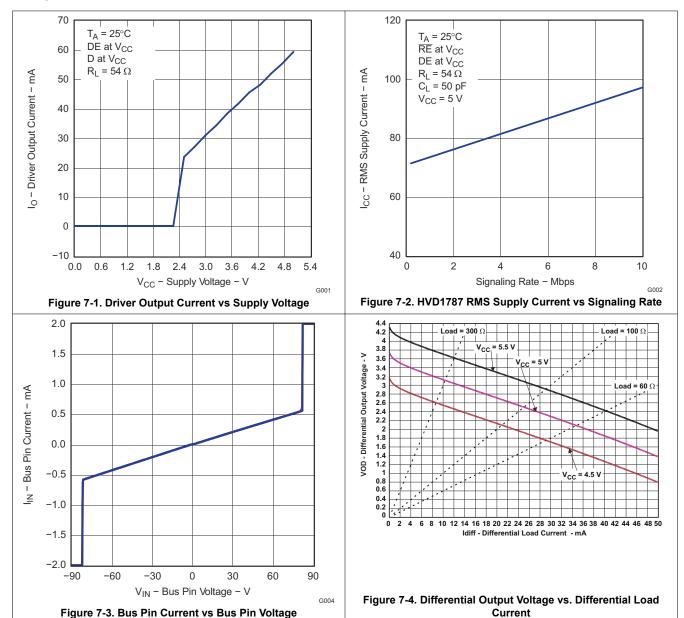
## 7.7 Switching Characteristics

over recommended operating conditions (unless otherwise noted)

	PARAMETER	TEST CO	TEST CONDITIONS				UNIT	
DRIVER (HVD	)1785 AND HVD1791)			•		•		
t <sub>r</sub> , t <sub>f</sub>	Driver differential output rise/fall time			0.4	1.7	2.6	μs	
t <sub>PHL</sub> , t <sub>PLH</sub>	Driver propagation delay	$R_L = 54 \Omega, C_L = 50$	pF,		0.8	2	μs	
t <sub>SK(P)</sub>	Driver differential output pulse skew,  t <sub>PHL</sub> – t <sub>PLH</sub>	see Figure 8-3			20	250	ns	
t <sub>PHZ</sub> , t <sub>PLZ</sub>	Driver disable time				0.1	5	μs	
	Duit can are able times	Receiver enabled	See Figure 8-4 and Figure 8-5		0.2	3		
t <sub>PZH</sub> , t <sub>PZL</sub>	Driver enable time	Receiver disabled	and rigare of c		3	12	μs	
DRIVER (HVD	01786 AND HVD1792)			1		1		
t <sub>r</sub> , t <sub>f</sub>	Driver differential output rise/fall time			50		300	ns	
t <sub>PHL</sub> , t <sub>PLH</sub>	Driver propagation delay	$R_L = 54 \Omega, C_L = 50$	pF,			200	ns	
t <sub>SK(P)</sub>	Driver differential output pulse skew,  t <sub>PHL</sub> – t <sub>PLH</sub>	see Figure 8-3				25	ns	
t <sub>PHZ</sub> , t <sub>PLZ</sub>	Driver disable time					3	μs	
		Receiver enabled	See Figure 8-4 and Figure 8-5			300	ns	
t <sub>PZH</sub> , t <sub>PZL</sub>	Driver enable time	Receiver disabled	and riguic 0-3			10	μs	
		Receiver enabled	V <sub>CM</sub> > V <sub>CC</sub>		500		ns	
DRIVER (HVD	01787 AND HVD1793)	1	1	•		,		
t <sub>r</sub> , t <sub>f</sub>	Driver differential output rise/fall time			3		30	ns	
t <sub>PHL</sub> , t <sub>PLH</sub>	Driver propagation delay	$R_L = 54 \Omega, C_L = 50$	pF,			50	ns	
t <sub>SK(P)</sub>	Driver differential output pulse skew,  t <sub>PHL</sub> - t <sub>PLH</sub>	see Figure 8-3				10	ns	
t <sub>PHZ</sub> , t <sub>PLZ</sub>	Driver disable time					3	μs	
		Receiver enabled	See Figure 8-4 and Figure 8-5			300	ns	
t <sub>PZH</sub> , t <sub>PZL</sub>	Driver enable time	Receiver disabled	and rigure of o			9	μs	
		Receiver enabled	V <sub>CM</sub> > V <sub>CC</sub>		500		ns	
RECEIVER (A	LL DEVICES UNLESS OTHERWISE NOT	ED)		•		'		
t <sub>r</sub> , t <sub>f</sub>	Receiver output rise/fall time				4	15	ns	
	Desciver propagation delevitims		85, 86, 91, 92		100	200		
t <sub>PHL</sub> , t <sub>PLH</sub>	Receiver propagation delay time	$C_L = 15 \text{ pF},$ see Figure 8-6	87, 93			70	70 ns	
	Receiver output pulse skew,	500 Figure 0-0	85, 86, 91, 92		6	20		
t <sub>SK(P)</sub>	t <sub>PHL</sub> - t <sub>PLH</sub>		87, 93			5	ns	
t <sub>PLZ</sub> , t <sub>PHZ</sub>	Receiver disable time	Driver enabled, see	Figure 8-7		15	100	ns	
t <sub>PZL(1)</sub> , t <sub>PZH(1)</sub>	Desciver enable tim-	Driver enabled, see	Driver enabled, see Figure 8-7			300	ns	
$t_{PZL(2)}, t_{PZH(2)}$	Receiver enable time	Driver disabled, see	Driver disabled, see Figure 8-8			9	μs	



#### 7.8 Typical Characteristics





#### **8 Parameter Measurement Information**

Input generator rate is 100 kbps, 50% duty cycle, rise and fall times less than 6 nsec, output impedance 50  $\Omega$ .

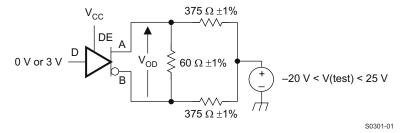


Figure 8-1. Measurement of Driver Differential Output Voltage With Common-Mode Load

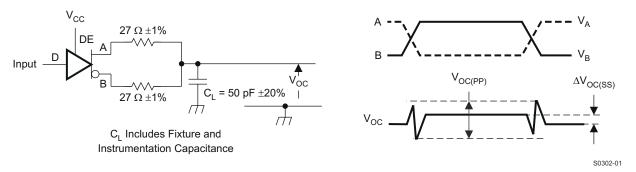


Figure 8-2. Measurement of Driver Differential and Common-Mode Output With RS-485 Load

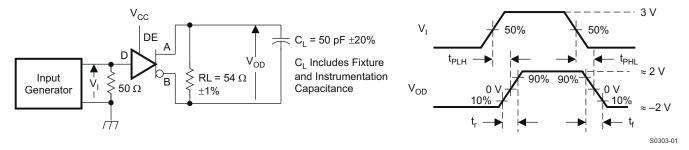
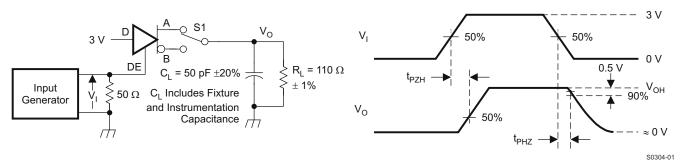


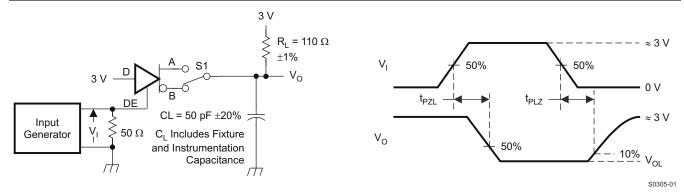
Figure 8-3. Measurement of Driver Differential Output Rise and Fall Times and Propagation Delays



D at 3 V to test non-inverting output, D at 0 V to test inverting output.

Figure 8-4. Measurement of Driver Enable and Disable Times With Active High Output and Pulldown Load





D at 0 V to test non-inverting output, D at 3 V to test inverting output.

Figure 8-5. Measurement of Driver Enable and Disable Times With Active-Low Output and Pullup Load

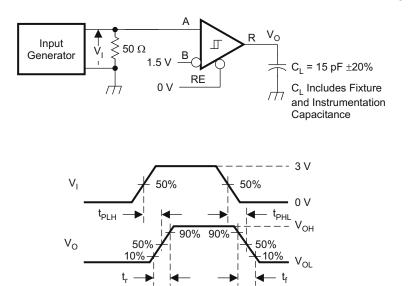


Figure 8-6. Measurement of Receiver Output Rise and Fall Times and Propagation Delays



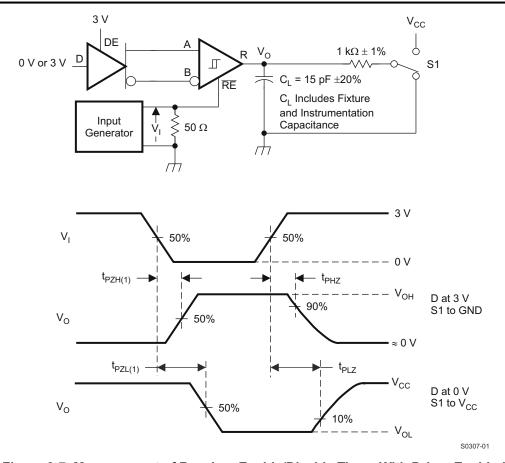


Figure 8-7. Measurement of Receiver Enable/Disable Times With Driver Enabled



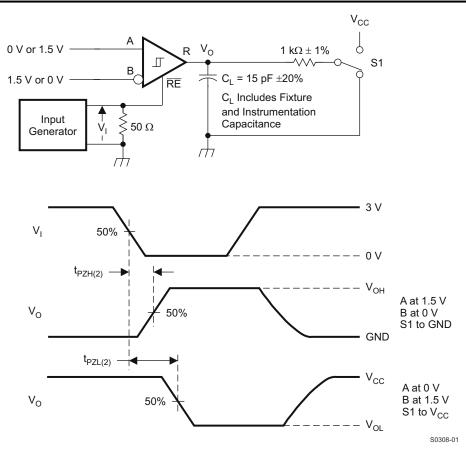


Figure 8-8. Measurement of Receiver Enable Times With Driver Disabled



## 9 Detailed Description

#### 9.1 Overview

The SN65HVD17xx family of RS-485 transceivers are designed to operate up to 115 kbps (HVD1785 and HVD1791), 1 Mbps (HVD1786 and HVD1792), or 10 Mbps (HVD1787 or HVD1793) and to withstand DC overvoltage faults on the bus interface pins. This helps to protect the devices against damages resulting from direct shorts to power supplies, cable mis-wirings, connector failures, or other common faults.

The SN65HVD178x devices are half-duplex, and thus have the transmitter and receiver bus interfaces connected together internally. The SN65HVD179x family leaves these two interfaces separate, allowing for full-duplex communication. The low receiver loading allows for up to 256 nodes to share a common RS-485 bus. The devices feature a wide common-mode range as well as fail-safe receivers, which ensure a stable logic-level output during bus open, short, or idle conditions.

#### 9.2 Functional Block Diagram

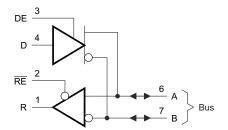


Figure 9-1. Half-Duplex Transceiver

Logic Diagram (Positive Logic)

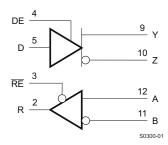


Figure 9-2. Full Duplex Transceiver

#### 9.3 Feature Description

#### 9.3.1 Hot-Plugging

These devices are designed to operate in hot swap or hot pluggable applications. Key features for hot-pluggable applications are power-up, power-down glitch free operation, default disabled input/output pins, and receiver failsafe. As shown in Figure 7-1, an internal Power-On Reset circuit keeps the driver outputs in a high-impedance state until the supply voltage has reached a level at which the device will reliably operate. This ensures that no spurious transitions (glitches) will occur on the bus pin outputs as the power supply turns on or turns off.

As shown in Section 9.4, the ENABLE inputs have the feature of default disable on both the driver enable and receiver enable. This ensures that the device will neither drive the bus nor report data on the R pin until the associated controller actively drives the enable pins.



#### 9.3.2 Receiver Failsafe

The differential receiver is failsafe to invalid bus states caused by:

- open bus conditions such as a disconnected connector,
- shorted bus conditions such as cable damage shorting the twisted-pair together,
- or idle bus conditions that occur when no driver on the bus is actively driving.

In any of these cases, the differential receiver outputs a failsafe logic High state, so that the output of the receiver is not indeterminate.

In the HVD17xx family of RS-485 devices, receiver failsafe is accomplished by offsetting the receiver thresholds so that the "input indeterminate" range does not include zero volts differential. In order to comply with the RS-422 and RS-485 standards, the receiver output must output a High when the differential input  $V_{ID}$  is more positive than 200 mV, and must output a Low when the  $V_{ID}$  is more negative than -200 mV. The HVD17xx receiver parameters which determine the failsafe performance are  $V_{IT+}$  and  $V_{IT-}$  and  $V_{HYS-}$ . In the *Electrical Characteristics* table,  $V_{IT-}$  has a typical value of -150 mV and a minimum (most negative) value of -200 mV, so differential signals more negative than -200 mV will always cause a Low receiver output. Similarly, differential signals more positive than 200 mV will always cause a High receiver output, because the typical value of  $V_{IT+}$  is -100mV, and  $V_{IT+}$  is never more positive than -10 mV under any conditions of temperature, supply voltage, or common-mode offset.

When the differential input signal is close to zero, it will still be above the  $V_{IT+}$  threshold, and the receiver output will be High. Only when the differential input is more negative than  $V_{IT-}$  will the receiver output transition to a Low state. So, the noise immunity of the receiver inputs during a bus fault condition includes the receiver hysteresis value  $V_{HYS}$  (the separation between  $V_{IT+}$  and  $V_{IT-}$ ) as well as the value of  $V_{IT+}$ .

For the HVD17xx devices, the typical noise immunity is typically about 150 mV, which is the negative noise level needed to exceed the  $V_{IT-}$  threshold ( $V_{IT-}$  TYP = -150 mV). In the worst case, the failsafe noise immunity is never less than 40 mV, which is set by the maximum positive threshold ( $V_{IT+}$  MAX = -10 mV) plus the minimum hysteresis voltage ( $V_{HYS}$  MIN = 30 mV).

#### 9.3.3 70-V Fault-Protection

The SN65HVD17xx family of RS-485 devices is designed to survive bus pin faults up to ±70V. The devices designed for fast signaling rate (10 Mbps) will not survive a bus pin fault with a direct short to voltages above 30V when:

- 1. the device is powered on AND
- 2a. the driver is enabled (DE=HIGH) AND D=HIGH AND the bus fault is applied to the A pin OR
- 2b. the driver is enabled (DE=HIGH) AND D=LOW AND the bus fault is applied to the B pin

Under other conditions, the device will survive shorts to bus pin faults up to 70V. Table 9-1 summarizes the conditions under which the device may be damaged, and the conditions under which the device will not be damaged.



			_	
Iania	u_1	Device	$C \cap D$	anoitir

POWER	DE	D	A	В	RESULTS
OFF	Х	Х	-70V < V <sub>A</sub> < 70V	$-70V < V_B < 70V$	Device survives
ON	LO	Х	-70V < V <sub>A</sub> < 70V	$-70V < V_B < 70V$	Device survives
ON	HI	L	-70V < V <sub>A</sub> < 70V	-70V < V <sub>B</sub> < 30V	Device survives
ON	HI	L	-70V < V <sub>A</sub> < 70V	30V < V <sub>B</sub>	Damage may occur
ON	HI	Н	-70V < V <sub>A</sub> < 30V	-70V < V <sub>B</sub> < 30V	Device survives
ON	HI	Н	30V < V <sub>A</sub>	-70V < V <sub>B</sub> < 30V	Damage may occur

### 9.3.4 Additional Options

The SN65HVD17xx family also has options for J1708 applications, for always-enabled full-duplex versions (industry-standard SN65LBC179 footprint) and for inverting-polarity versions, which allow users to correct a reversal of the bus wires without re-wiring. Contact your local Texas Instruments representative for information on these options.

Table 9-2. SN65HVD17xx Options for J1708 Applications

PART NUMBER		SN65HVD17xx					
FOOTPRINT/FUNCTION	SLOW	MEDIUM	FAST				
Half-duplex (176 pinout)	85	86	87				
Full-duplex no enables (179 pinout)	88	89	90				
Full-duplex with enables (180 pinout)	91	92	93				
Half-duplex with cable invert	94	95	96				
Full-duplex with cable invert and enables	97	98	99				
J1708	08	09	10				

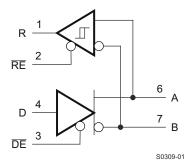


Figure 9-3. SN65HVD1708E Transceiver for J1708 Applications

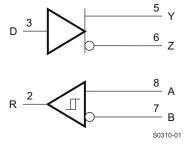
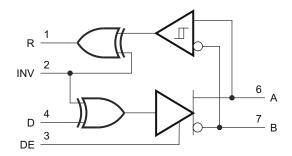


Figure 9-4. SN65HVD17xx Always-Enabled Driver Receiver





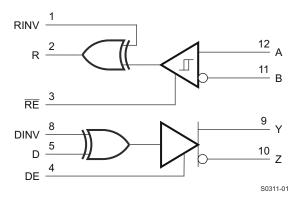


Figure 9-5. SN65HVD17xx Options With Inverting Feature to Correct for Miswired Cables

## 9.4 Device Functional Modes

**Table 9-3. Driver Function Table** 

INPUT	ENABLE	OUTP	UTS	
D	DE	A B		
Н	Н	Н	L	Actively drive bus high
L	Н	L	Н	Actively drive bus low
Х	L	Z	Z	Driver disabled
Х	OPEN	Z	Z	Driver disabled by default
OPEN	Н	Н	L	Actively drive bus high by default

**Table 9-4. Receiver Function Table** 

DIFFERENTIAL INPUT	ENABLE	OUTPUT	
$V_{ID} = V_A - V_B$	RE	R	
$V_{IT+} < V_{ID}$	L	Н	Receive valid bus high
$V_{IT-} < V_{ID} < V_{IT+}$	L	?	Indeterminate bus state
V <sub>ID</sub> < V <sub>IT</sub>	L	L	Receive valid bus low
Х	Н	Z	Receiver disabled
Х	OPEN	Z	Receiver disabled by default
Open-circuit bus	L	Н	Fail-safe high output
Short-circuit bus	L	Н	Fail-safe high output
Idle (terminated) bus	L	Н	Fail-safe high output



## 10 Application and Implementation

#### Note

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

#### **10.1 Application Information**

The SN65HVD17xx family consists of both half-duplex and full-duplex transceivers that can be used for asynchronous data communication. Half-duplex implementations require one signaling pair (two wires), while full-duplex implementations require two signaling pairs (four wires). The driver and receiver enable pins of the SN65HVD17xx family allow for control over the direction of data flow. Since it is common for multiple transceivers to share a common communications bus, care should be taken at the system level to ensure that only one driver is enabled at a time. This avoids bus contention, a fault condition in which multiple drivers attempt to send data at the same time.

### 10.2 Typical Application

An RS-485 bus consists of multiple transceivers connecting in parallel to a bus cable. To eliminate line reflections, each cable end is terminated with a termination resistor,  $R_T$ , whose value matches the characteristic impedance,  $Z_0$ , of the cable. This method, known as parallel termination, allows for higher data rates over longer cable length.

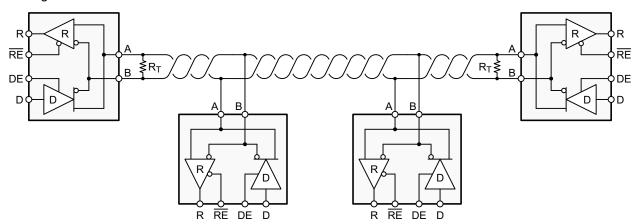


Figure 10-1. Typical RS-485 Network With Half-duplex Transceivers

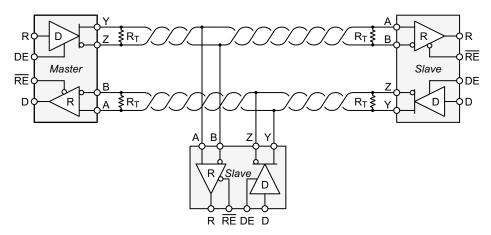


Figure 10-2. Typical RS-485 Network With Full-duplex Transceivers

#### 10.2.1 Design Requirements

RS-485 is a robust electrical standard suitable for long-distance networking that may be used in a wide range of applications with varying requirements, such as distance, data rate, and number of nodes.

#### 10.2.1.1 Data Rate and Bus Length

There is an inverse relationship between data rate and cable length, which means the higher the data rate, the short the cable length; and conversely, the lower the data rate, the longer the cable length. While most RS-485 systems use data rates between 10 kbps and 100 kbps, some applications require data rates up to 250 kbps at distances of 4000 feet and longer. Longer distances are possible by allowing for small signal jitter of up to 5 or 10%.

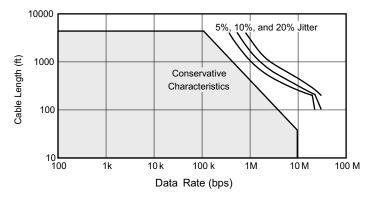


Figure 10-3. Cable Length vs Data Rate Characteristic

Even higher data rates are achievable (for example, 10 Mbps for the SN65HVD1787 and SN65HVD1793) in cases where the interconnect is short enough (or has suitably low attenuation at signal frequencies) to not degrade the data.

#### 10.2.1.2 Stub Length

When connecting a node to the bus, the distance between the transceiver inputs and the cable trunk, known as the stub, should be as short as possible. Stubs present a non-terminated piece of bus line which can introduce reflections as the length of the stub increases. As a general guideline, the electrical length, or round-trip delay, of a stub should be less than one-tenth of the rise time of the driver, thus giving a maximum physical stub length as shown in Equation 1.

$$L_{\text{stub}} \le 0.1 \times t_{\text{r}} \times v \times c \tag{1}$$

#### where

- t<sub>r</sub> is the 10/90 rise time of the driver
- c is the speed of light (3 × 10<sup>8</sup> m/s)
- v is the signal velocity of the cable or trace as a factor of c

#### 10.2.1.3 Receiver Failsafe

The differential receiver of the SN75HVD17xx family is failsafe to invalid bus states caused by:

- · Open bus conditions, such as a disconnected connector
- Shorted bus conditions, such as cable damage shorting the twisted-pair together
- Idle bus conditions that occur when no driver on the bus is actively driving

n any of these cases, the differential receiver will output a failsafe logic high state so that the output of the receiver is not indeterminate.

Receiver failsafe is accomplished by offsetting the receiver thresholds such that the "input indeterminate" range does not include zero volts differential. In order to comply with the RS-422 and RS-485 standards, the receiver output must output a high when the differential input  $V_{\rm ID}$  is more positive than +200 mV, and must output a low



when VID is more negative than -200 mV. The receiver parameters which determine the failsafe performance are  $V_{IT(+)}$  and  $V_{IT(-)}$ . As shown in the Electrical Characteristics table, differential signals more negative than -200 mV will always cause a low receiver output, and differential signals more positive than +200 mV will always cause a high receiver output.

When the differential input signal is close to zero, it is still above the maximum  $V_{IT(+)}$  threshold of -10 mV, and the receiver output will be high.

#### 10.2.2 Detailed Design Procedure

Although the SN65HVD17xx family is internally protected against human-body-model ESD strikes up to 16 kV, additional protection against higher-energy transients can be provided at the application level by implementing external protection devices.

#### 10.2.3 Application Curve

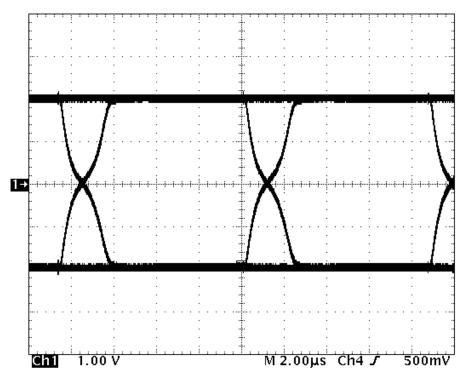


Figure 10-4. SN65HVD1785 Differential Output at 115 kbps

## 11 Power Supply Recommendations

To ensure reliable operation at all data rates and supply voltages, each supply should be decoupled with a 100-nF ceramic capacitor located as close to the supply pins as possible. This helps to reduce supply voltage ripple present on the outputs of switched-mode power supplies and also helps to compensate for the resistance and inductance of the PCB power planes.



## 12 Layout

## 12.1 Layout Guidelines

To ensure reliable operation at all data rates and supply voltages, each supply should be decoupled with a 100-nF ceramic capacitor located as close to the supply pins as possible. This helps to reduce supply voltage ripple present on the outputs of switched-mode power supplies and also helps to compensate for the resistance and inductance of the PCB power planes.

- 1. Place the protection circuitry close to the bus connector to prevent noise transients from entering the board.
- 2. Use V<sub>CC</sub> and ground planes to provide low-inductance power distribution. Note that high-frequency currents tend to follow the path of least inductance and not the path of least resistance.
- 3. Design the protection components into the direction of the signal path. Do not force the transient currents to divert from the signal path to reach the protection device.
- Apply 100-nF-to-220-nF bypass capacitors as close as possible to the V<sub>CC</sub> pins of transceiver, UART, or controller ICs on the board.
- 5. Use at least two vias for V<sub>CC</sub> and ground connections of bypass capacitors and protection devices to minimize effective via-inductance.
- 6. Use  $1-k\Omega$ -to- $10-k\Omega$  pullup and pulldown resistors for enable lines to limit noise currents in these lines during transient events.
- 7. Insert series pulse-proof resistors into the A and B bus lines if the TVS clamping voltage is higher than the specified maximum voltage of the transceiver bus terminals. These resistors limit the residual clamping current into the transceiver and prevent it from latching up.
- 8. While pure TVS protection is sufficient for surge transients up to 1 kV, higher transients require metal-oxide varistors (MOVs) which reduce the transients to a few hundred volts of clamping voltage, and transient blocking units (TBUs) that limit transient current to less than 1 mA.

#### 12.2 Layout Example

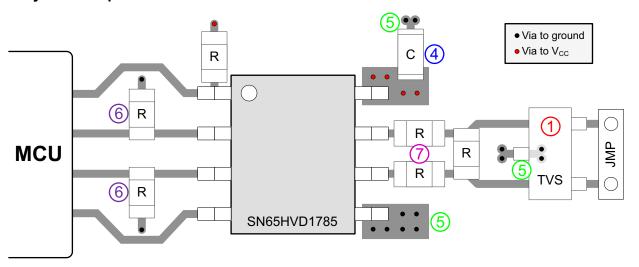


Figure 12-1. Layout Example (Half-Duplex Transceiver)



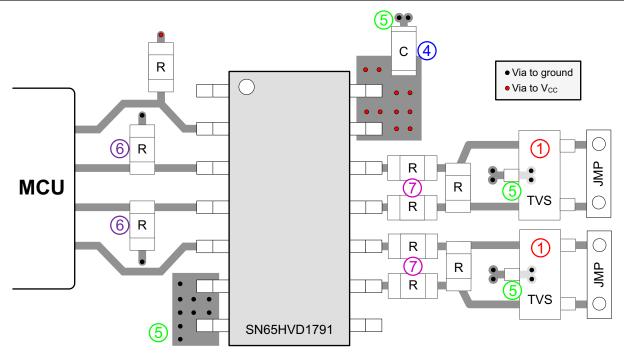


Figure 12-2. Layout Example (Full-Duplex Transceiver)



## 13 Device and Documentation Support

## 13.1 Documentation Support

For related documentation see the following:

SN65HVD1781, Fault-Protected RS-485 Transceivers With 3.3-V to 5-V Operation, (SLLS877)

#### 13.2 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on ti.com. Click on *Subscribe to updates* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

#### 13.3 Support Resources

TI E2E<sup>™</sup> support forums are an engineer's go-to source for fast, verified answers and design help — straight from the experts. Search existing answers or ask your own question to get the quick design help you need.

Linked content is provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's Terms of Use.

#### 13.4 Trademarks

TI E2E<sup>™</sup> is a trademark of Texas Instruments.

All trademarks are the property of their respective owners.

#### 13.5 Electrostatic Discharge Caution



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

#### 13.6 Glossary

TI Glossary

This glossary lists and explains terms, acronyms, and definitions.

## 14 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

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9-Nov-2025

## **PACKAGING INFORMATION**

Orderable part number	Status (1)	Material type	Package   Pins	Package qty   Carrier	<b>RoHS</b> (3)	Lead finish/ Ball material	MSL rating/ Peak reflow	Op temp (°C)	Part marking (6)
SN65HVD1785D	Active	Production	SOIC (D)   8	75   TUBE	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 105	VP1785
SN65HVD1785D.A	Active	Production	SOIC (D)   8	75   TUBE	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 105	VP1785
SN65HVD1785D.B	Active	Production	SOIC (D)   8	75   TUBE	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 105	VP1785
SN65HVD1785DG4	Active	Production	SOIC (D)   8	75   TUBE	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 105	VP1785
SN65HVD1785DR	Active	Production	SOIC (D)   8	2500   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 105	VP1785
SN65HVD1785DR.A	Active	Production	SOIC (D)   8	2500   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 105	VP1785
SN65HVD1785DR.B	Active	Production	SOIC (D)   8	2500   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 105	VP1785
SN65HVD1785DRG4	Active	Production	SOIC (D)   8	2500   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 105	VP1785
SN65HVD1785P	Active	Production	PDIP (P)   8	50   TUBE	Yes	NIPDAU	N/A for Pkg Type	-40 to 105	65HVD1785
SN65HVD1785P.A	Active	Production	PDIP (P)   8	50   TUBE	Yes	NIPDAU	N/A for Pkg Type	-40 to 105	65HVD1785
SN65HVD1785P.B	Active	Production	PDIP (P)   8	50   TUBE	Yes	NIPDAU	N/A for Pkg Type	-40 to 105	65HVD1785
SN65HVD1786D	Active	Production	SOIC (D)   8	75   TUBE	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 105	VP1786
SN65HVD1786D.A	Active	Production	SOIC (D)   8	75   TUBE	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 105	VP1786
SN65HVD1786D.B	Active	Production	SOIC (D)   8	75   TUBE	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 105	VP1786
SN65HVD1786DR	Active	Production	SOIC (D)   8	2500   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 105	VP1786
SN65HVD1786DR.A	Active	Production	SOIC (D)   8	2500   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 105	VP1786
SN65HVD1786DR.B	Active	Production	SOIC (D)   8	2500   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 105	VP1786
SN65HVD1786DRG4	Active	Production	SOIC (D)   8	2500   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 105	VP1786
SN65HVD1786P	Active	Production	PDIP (P)   8	50   TUBE	Yes	NIPDAU	N/A for Pkg Type	-40 to 105	65HVD1786
SN65HVD1786P.A	Active	Production	PDIP (P)   8	50   TUBE	Yes	NIPDAU	N/A for Pkg Type	-40 to 105	65HVD1786
SN65HVD1786P.B	Active	Production	PDIP (P)   8	50   TUBE	Yes	NIPDAU	N/A for Pkg Type	-40 to 105	65HVD1786
SN65HVD1787D	Active	Production	SOIC (D)   8	75   TUBE	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 105	VP1787
SN65HVD1787D.A	Active	Production	SOIC (D)   8	75   TUBE	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 105	VP1787
SN65HVD1787DR	Active	Production	SOIC (D)   8	2500   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 105	VP1787
SN65HVD1787DR.A	Active	Production	SOIC (D)   8	2500   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 105	VP1787
SN65HVD1787DRG4	Active	Production	SOIC (D)   8	2500   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 105	VP1787
SN65HVD1787DRG4.A	Active	Production	SOIC (D)   8	2500   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 105	VP1787
SN65HVD1791D	Active	Production	SOIC (D)   14	50   TUBE	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 105	VP1791
SN65HVD1791D.A	Active	Production	SOIC (D)   14	50   TUBE	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 105	VP1791





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Orderable part number	Status	Material type	Package   Pins	Package qty   Carrier	RoHS	Lead finish/ Ball material	MSL rating/ Peak reflow	Op temp (°C)	Part marking
						(4)	(5)		
SN65HVD1791DG4	Active	Production	SOIC (D)   14	50   TUBE	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 105	VP1791
SN65HVD1791DR	Active	Production	SOIC (D)   14	2500   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 105	VP1791
SN65HVD1791DR.A	Active	Production	SOIC (D)   14	2500   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 105	VP1791
SN65HVD1791DRG4	Active	Production	SOIC (D)   14	2500   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 105	VP1791
SN65HVD1791DRG4.A	Active	Production	SOIC (D)   14	2500   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 105	VP1791
SN65HVD1792D	Active	Production	SOIC (D)   14	50   TUBE	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 105	VP1792
SN65HVD1792D.A	Active	Production	SOIC (D)   14	50   TUBE	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 105	VP1792
SN65HVD1792DR	Active	Production	SOIC (D)   14	2500   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 105	VP1792
SN65HVD1792DR.A	Active	Production	SOIC (D)   14	2500   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 105	VP1792
SN65HVD1792DRG4	Active	Production	SOIC (D)   14	2500   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 105	VP1792
SN65HVD1792DRG4.A	Active	Production	SOIC (D)   14	2500   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 105	VP1792
SN65HVD1793D	Active	Production	SOIC (D)   14	50   TUBE	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 105	VP1793
SN65HVD1793D.A	Active	Production	SOIC (D)   14	50   TUBE	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 105	VP1793
SN65HVD1793DG4	Active	Production	SOIC (D)   14	50   TUBE	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 105	VP1793
SN65HVD1793DG4.A	Active	Production	SOIC (D)   14	50   TUBE	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 105	VP1793
SN65HVD1793DR	Active	Production	SOIC (D)   14	2500   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 105	VP1793
SN65HVD1793DR.A	Active	Production	SOIC (D)   14	2500   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 105	VP1793

<sup>(1)</sup> Status: For more details on status, see our product life cycle.

<sup>(2)</sup> Material type: When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

<sup>(3)</sup> RoHS values: Yes, No, RoHS Exempt. See the TI RoHS Statement for additional information and value definition.

<sup>(4)</sup> Lead finish/Ball material: Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

<sup>(5)</sup> MSL rating/Peak reflow: The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

## **PACKAGE OPTION ADDENDUM**

www.ti.com 9-Nov-2025

(6) Part marking: There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

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In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

#### OTHER QUALIFIED VERSIONS OF SN65HVD1792:

Enhanced Product: SN65HVD1792-EP

NOTE: Qualified Version Definitions:

• Enhanced Product - Supports Defense, Aerospace and Medical Applications



www.ti.com 24-Jul-2025

## TAPE AND REEL INFORMATION



## 

A0	Dimension designed to accommodate the component width
В0	Dimension designed to accommodate the component length
K0	Dimension designed to accommodate the component thickness
W	Overall width of the carrier tape
P1	Pitch between successive cavity centers

#### QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



#### \*All dimensions are nominal

Device	Package Type	Package Drawing		SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
SN65HVD1785DR	SOIC	D	8	2500	330.0	12.4	6.4	5.2	2.1	8.0	12.0	Q1
SN65HVD1787DR	SOIC	D	8	2500	330.0	12.4	6.4	5.2	2.1	8.0	12.0	Q1
SN65HVD1787DRG4	SOIC	D	8	2500	330.0	12.4	6.4	5.2	2.1	8.0	12.0	Q1
SN65HVD1791DR	SOIC	D	14	2500	330.0	16.4	6.5	9.0	2.1	8.0	16.0	Q1
SN65HVD1791DRG4	SOIC	D	14	2500	330.0	16.4	6.5	9.0	2.1	8.0	16.0	Q1
SN65HVD1792DR	SOIC	D	14	2500	330.0	16.4	6.5	9.0	2.1	8.0	16.0	Q1
SN65HVD1792DRG4	SOIC	D	14	2500	330.0	16.4	6.5	9.0	2.1	8.0	16.0	Q1
SN65HVD1793DR	SOIC	D	14	2500	330.0	16.4	6.5	9.0	2.1	8.0	16.0	Q1



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\*All dimensions are nominal

		<b>.</b>	<u> </u>	222		140 to ( )	
Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
SN65HVD1785DR	SOIC	D	8	2500	353.0	353.0	32.0
SN65HVD1787DR	SOIC	D	8	2500	353.0	353.0	32.0
SN65HVD1787DRG4	SOIC	D	8	2500	353.0	353.0	32.0
SN65HVD1791DR	SOIC	D	14	2500	353.0	353.0	32.0
SN65HVD1791DRG4	SOIC	D	14	2500	353.0	353.0	32.0
SN65HVD1792DR	SOIC	D	14	2500	353.0	353.0	32.0
SN65HVD1792DRG4	SOIC	D	14	2500	353.0	353.0	32.0
SN65HVD1793DR	SOIC	D	14	2500	353.0	353.0	32.0



www.ti.com 24-Jul-2025

## **TUBE**



#### \*All dimensions are nominal

Device	Package Name	Package Type	Pins	SPQ	L (mm)	W (mm)	T (µm)	B (mm)
SN65HVD1785D	D	SOIC	8	75	506.6	8	3940	4.32
SN65HVD1785D.A	D	SOIC	8	75	506.6	8	3940	4.32
SN65HVD1785D.B	D	SOIC	8	75	506.6	8	3940	4.32
SN65HVD1785DG4	D	SOIC	8	75	506.6	8	3940	4.32
SN65HVD1785P	Р	PDIP	8	50	506	13.97	11230	4.32
SN65HVD1785P.A	Р	PDIP	8	50	506	13.97	11230	4.32
SN65HVD1785P.B	Р	PDIP	8	50	506	13.97	11230	4.32
SN65HVD1786D	D	SOIC	8	75	506.6	8	3940	4.32
SN65HVD1786D.A	D	SOIC	8	75	506.6	8	3940	4.32
SN65HVD1786D.B	D	SOIC	8	75	506.6	8	3940	4.32
SN65HVD1786P	Р	PDIP	8	50	506	13.97	11230	4.32
SN65HVD1786P.A	Р	PDIP	8	50	506	13.97	11230	4.32
SN65HVD1786P.B	Р	PDIP	8	50	506	13.97	11230	4.32
SN65HVD1787D	D	SOIC	8	75	506.6	8	3940	4.32
SN65HVD1787D.A	D	SOIC	8	75	506.6	8	3940	4.32
SN65HVD1791D	D	SOIC	14	50	506.6	8	3940	4.32
SN65HVD1791D.A	D	SOIC	14	50	506.6	8	3940	4.32
SN65HVD1791DG4	D	SOIC	14	50	506.6	8	3940	4.32
SN65HVD1792D	D	SOIC	14	50	506.6	8	3940	4.32
SN65HVD1792D.A	D	SOIC	14	50	506.6	8	3940	4.32
SN65HVD1793D	D	SOIC	14	50	506.6	8	3940	4.32
SN65HVD1793D.A	D	SOIC	14	50	506.6	8	3940	4.32
SN65HVD1793DG4	D	SOIC	14	50	506.6	8	3940	4.32
SN65HVD1793DG4.A	D	SOIC	14	50	506.6	8	3940	4.32





### NOTES:

- 1. Linear dimensions are in inches [millimeters]. Dimensions in parenthesis are for reference only. Controlling dimensions are in inches. Dimensioning and tolerancing per ASME Y14.5M.
- 2. This drawing is subject to change without notice.
- 3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed .006 [0.15] per side.
- 4. This dimension does not include interlead flash.
- 5. Reference JEDEC registration MS-012, variation AA.





NOTES: (continued)

6. Publication IPC-7351 may have alternate designs.

7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.





NOTES: (continued)

- 8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
- 9. Board assembly site may have different recommendations for stencil design.



## P (R-PDIP-T8)

## PLASTIC DUAL-IN-LINE PACKAGE



NOTES:

- A. All linear dimensions are in inches (millimeters).
- B. This drawing is subject to change without notice.
- C. Falls within JEDEC MS-001 variation BA.







#### NOTES:

- 1. All linear dimensions are in millimeters. Dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.

  2. This drawing is subject to change without notice.

  3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not
- exceed 0.15 mm, per side.
- 4. This dimension does not include interlead flash. Interlead flash shall not exceed 0.43 mm, per side.
- 5. Reference JEDEC registration MS-012, variation AB.





NOTES: (continued)

6. Publication IPC-7351 may have alternate designs.

7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.





NOTES: (continued)

- 8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
- 9. Board assembly site may have different recommendations for stencil design.



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