LMR10515 5.5-V_{IN}, 1.5-A Step-Down Voltage Regulator in SOT-23 and WSON Packages

1 Features

- Input Voltage Range of 3 V to 5.5 V
- Output Voltage Range of 0.6 V to 4.5 V
- Output Current up to 1.5 A
- 1.6-MHz (LMR10515X) and 3-MHz (LMR10515Y) Switching Frequencies
- Low Shutdown I_Q, 30 nA Typical
- Internal Soft-Start
- Internally Compensated
- Current-Mode PWM Operation
- Thermal Shutdown
- Tiny Overall Solution Reduces System Cost
- SOT-23 (2.92 × 2.84 × 1 mm) and WSON (3 × 3 × 0.8 mm) Packaging
- Create a custom design using the LMR10515 with the WEBENCH® Power Designer

2 Applications

- Point-of-Load Conversions from 3.3-V and 5-V Rails
- Space Constrained Applications
- Battery Powered Equipment
- Industrial Distributed Power Applications
- Power Meters
- Portable Hand-Held Instruments

3 Description

The LMR10515 regulator is a monolithic, high frequency, PWM step-down DC/DC converter in a 5-pin SOT-23 and a 6-pin WSON package. It provides all the active functions to provide local DC/DC conversion with fast transient response and accurate regulation in the smallest possible PCB area. With a minimum of external components, the LMR10515 is easy to use. The ability to drive 1.5-A loads with an internal 130-mΩ PMOS switch results in the best power density available. The world-class control circuitry allows on-times as low as 30ns, thus supporting exceptionally high frequency conversion over the entire 3-V to 5.5-V input operating range down to the minimum output voltage of 0.6 V. The LMR10515 is internally compensated, so it is simple to use and requires few external components. Switching frequency is internally set to 1.6 MHz, or 3 MHz, allowing the use of extremely small surface mount inductors and chip capacitors. Even though the operating frequency is high, efficiencies up to 93% are easy to achieve. External shutdown is included, featuring an ultra-low stand-by current of 30 nA. The LMR10515 utilizes current-mode control and internal compensation to provide high-performance regulation over a wide range of operating conditions. Additional features include internal soft-start circuitry to reduce inrush current, pulse-by-pulse current limit, thermal shutdown, and output over-voltage protection.

Device Information[1]

PART NUMBER	PACKAGE	BODY SIZE (NOM)
LMR10515	SOT-23 (5)	2.90 mm × 1.60 mm
	WSON (6)	3.00 mm × 3.00 mm

(1) For all available packages, see the orderable addendum at the end of the data sheet.

Simplified Application

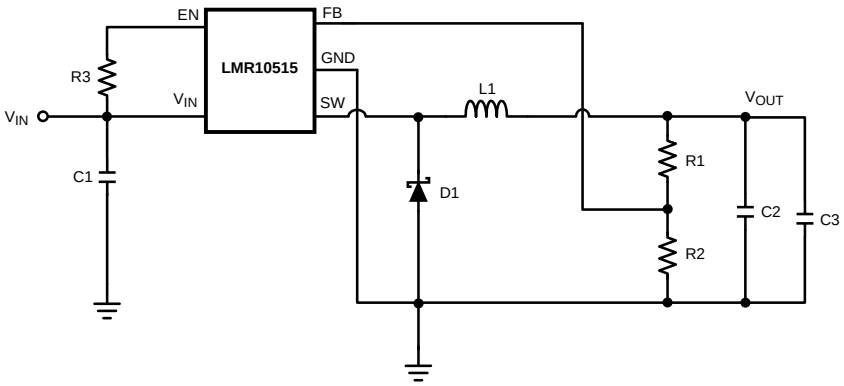


Table of Contents

4 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

Changes from Revision C (April 2013) to Revision D **Page**

- Editorial changes only; add WEBENCH links and top navigator icon for reference design ... 1

Changes from Revision B (April 2013) to Revision C **Page**

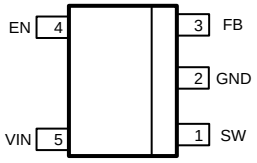
- Changed layout of National Semiconductor data sheet to TI format ... 1

5 Description, continued

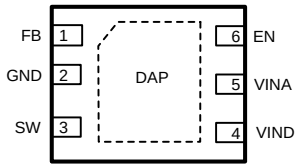
The LMR10515 is internally compensated, so it is simple to use and requires few external components. Switching frequency is internally set to 1.6 MHz, or 3 MHz, allowing the use of extremely small surface mount inductors and chip capacitors. Even though the operating frequency is high, efficiencies up to 93% are easy to achieve. External shutdown is included, featuring an ultra-low stand-by current of 30 nA. The LMR10515 utilizes current-mode control and internal compensation to provide high-performance regulation over a wide range of operating conditions. Additional features include internal soft-start circuitry to reduce inrush current, pulse-by-pulse current limit, thermal shutdown, and output overvoltage protection.

6 Pin Configuration and Functions

DBV Package
5-Pin SOT-23
Top View



NGG Package
6-Pin WSON
Top View



Pin Description: 5-Pin SOT-23

PIN		DESCRIPTION
NO.	NAME	
1	SW	Switch node. Connect to the inductor and catch diode.
2	GND	Signal and power ground pin. Place the bottom resistor of the feedback network as close as possible to this pin.
3	FB	Feedback pin. Connect to external resistor divider to set output voltage.
4	EN	Enable control input. Logic high enables operation. Do not allow this pin to float or be greater than V_{IN} + 0.3 V.
5	VIN	Input supply voltage.

Pin Descriptions 6-Pin WSON

PIN		DESCRIPTION
NO.	NAME	
1	FB	Feedback pin. Connect to external resistor divider to set output voltage.
2	GND	Signal and power ground pin. Place the bottom resistor of the feedback network as close as possible to this pin.
3	SW	Switch node. Connect to the inductor and catch diode.
4	VIND	Power Input supply.
5	VINA	Control circuitry supply voltage. Connect VINA to VIND on PC board.
6	EN	Enable control input. Logic high enables operation. Do not allow this pin to float or be greater than VINA + 0.3 V.
DAP	Die Attach Pad	Connect to system ground for low thermal impedance, but it cannot be used as a primary GND connection.

7 Specifications

7.1 Absolute Maximum Ratings(1)(2)

VIN	-0.5V to 7V
FB Voltage	-0.5V to 3V
EN Voltage	-0.5V to 7V
SW Voltage	-0.5V to 7V
ESD Susceptibility	2kV
Junction Temperature(3)	150°C
Storage Temperature	−65°C to +150°C
Soldering Information	
For soldering specifications: http://www.ti.com/lit/SNOA549C	

(1) Absolute maximum ratings indicate limits beyond which damage to the device may occur. Operating Range indicates conditions for which the device is intended to be functional, but does not ensure specfic performance limits. For ensured specifications and test conditions, see *Electrical Characteristics*.
(2) If Military/Aerospace specified devices are required, contact the Texas Instruments Sales Office/ Distributors for availability and specifications
(3) Thermal shutdown occurs if the junction temperature exceeds the maximum junction temperature of the device.

7.2 Recommended Operating Ratings

VIN	3V to 5.5V
Junction Temperature	−40°C to +125°C

7.3 Electrical Characteristics

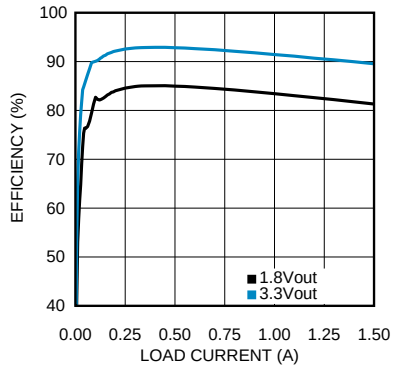
VIN = 5V unless otherwise indicated under the **conditions** column. Limits in standard type are for T_J = 25°C only; limits in **boldface type** apply over the junction temperature (T_J) range of -40°C to +125°C. Minimum and maximum limits are ensured through test, design, or statistical correlation. Typical values represent the most likely parametric norm at T_J = 25°C, and are provided for reference purposes only.(1)(2)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
V_{FB}	Feedback Voltage		**0.588**	0.600	**0.612**	V
$\Delta V_{FB}/V_{IN}$	Feedback Voltage Line Regulation	V_{IN} = 3V to 5V		0.02		%/V
I_B	Feedback Input Bias Current			0.1	**100**	nA
UVLO	Undervoltage Lockout	V_{IN} Rising		2.73	**2.90**	V
		V_{IN} Falling	**1.85**	2.3		
	UVLO Hysteresis			0.43		V
F_{SW}	Switching Frequency	LMR10515-X	**1.2**	1.6	**1.95**	MHz
		LMR10515-Y	**2.25**	3.0	**3.75**	
D_{MAX}	Maximum Duty Cycle	LMR10515-X	**86**	94		%
		LMR10515-Y	**82**	90		
D_{MIN}	Minimum Duty Cycle	LMR10515-X		5		%
		LMR10515-Y		7		
$R_{DS(ON)}$	Switch On Resistance	WSON Package		150		mΩ
		SOT-23 Package		130	**195**	
I_{CL}	Switch Current Limit	V_{IN} = 3.3V	**1.8**	2.5		A
V_{EN_TH}	Shutdown Threshold Voltage				**0.4**	V
	Enable Threshold Voltage		**1.8**			
I_{SW}	Switch Leakage			100		nA
I_{EN}	Enable Pin Current	Sink/Source		100		nA
I_Q	Quiescent Current (switching)	LMR10515X V_{FB} = 0.55		3.3	**5**	mA
		LMR10515Y V_{FB} = 0.55		4.3	**6.5**	
	Quiescent Current (shutdown)	All Options V_{EN} = 0V		30		nA
θ_{JA}	Junction to Ambient 0 LFPM Air Flow(3)	WSON Package		80		°C/W
		SOT-23 Package		118		
θ_{JC}	Junction to Case	WSON Package		18		°C/W
		SOT-23 Package		80		
T_{SD}	Thermal Shutdown Temperature			165		°C

(1) Min and Max limits are 100% production tested at 25°C. Limits over the operating temperature range are ensured through correlation using Statistical Quality Control (SQC) methods. Limits are used to calculate TI's Average Outgoing Quality Level (AOQL).
(2) Typical numbers are at 25°C and represent the most likely parametric norm.
(3) Applies for packages soldered directly onto a 3-inch x 3-inch PC board with 2 oz. copper on 4 layers in still air.

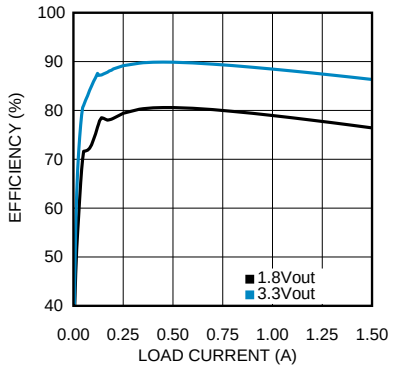
7.4 Typical Characteristics

Unless stated otherwise, all curves taken at V_{IN} = 5 V with configuration in typical application circuit shown in Figure 15. T_J = 25°C, unless otherwise specified.



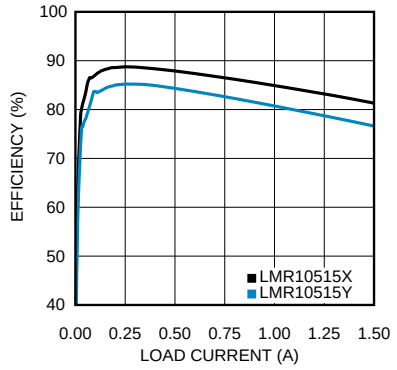
V_{IN} = 5 V V_{OUT} = 1.8 V and 3.3 V

Figure 1. Efficiency vs Load



V_{IN} = 5 V V_{OUT} = 1.8 V and 3.3 V

Figure 2. Efficiency vs Load "Y"



V_{IN} = 3.3 V V_{OUT} = 1.8 V

Figure 3. Efficiency vs Load "X and Y"

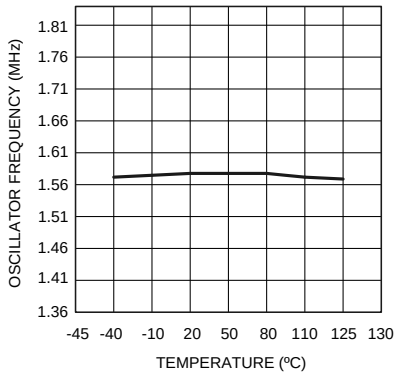


Figure 4. Oscillator Frequency vs Temperature - "X"

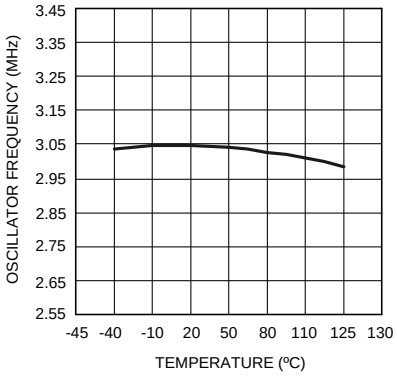
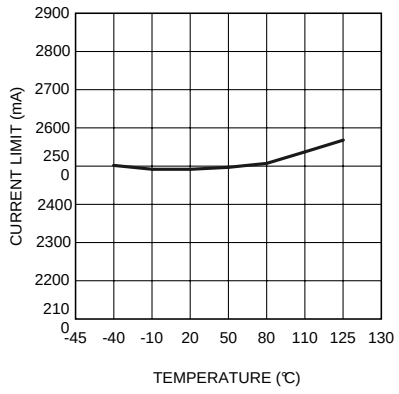


Figure 5. Oscillator Frequency vs Temperature - "Y"



V_{IN} = 3.3 V

Figure 6. Current Limit vs Temperature Vin = 3.3v

Typical Characteristics (continued)

Unless stated otherwise, all curves taken at V_{IN} = 5 V with configuration in typical application circuit shown in Figure 15. T_J = 25°C, unless otherwise specified.

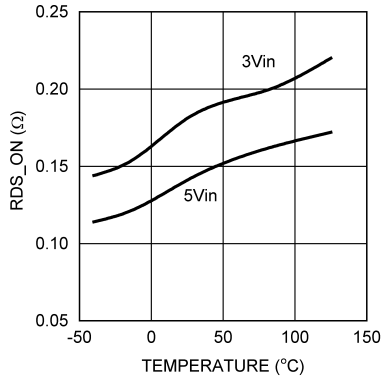


Figure 7. RD_{SON} vs Temperature (WSON Package)

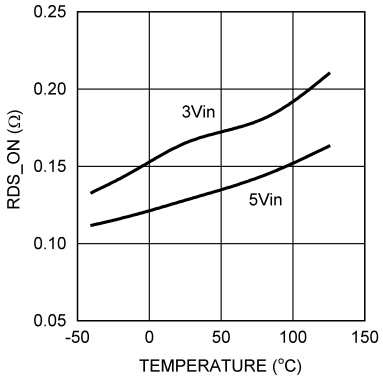


Figure 8. RD_{SON} vs Temperature (SOT-23 Package)

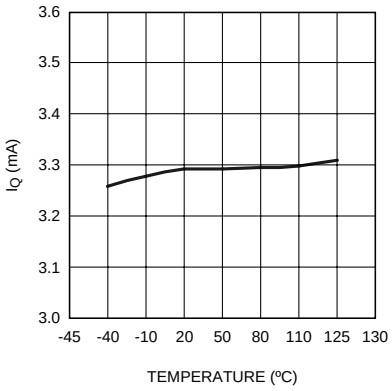


Figure 9. LMR10510X I_Q (Quiescent Current)

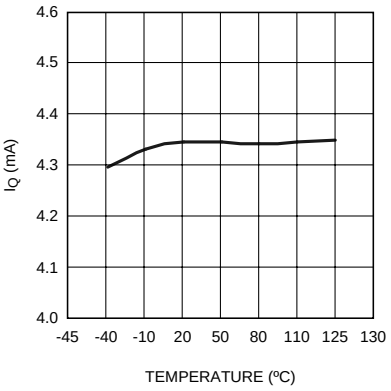


Figure 10. LMR10515Y I_Q (Quiescent Current)

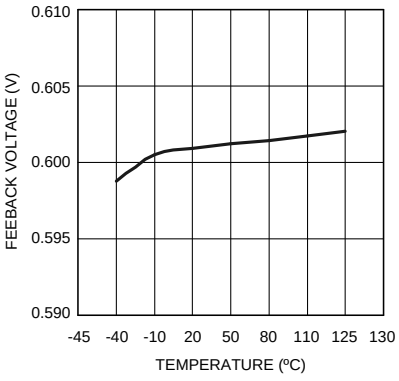
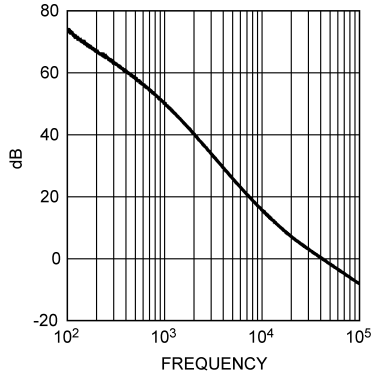


Figure 11. V_{FB} vs Temperature

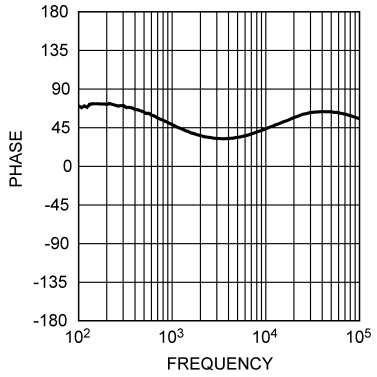


V_{IN} = 5 V V_{OUT} = 1.2 V at 1 A

Figure 12. Gain vs Frequency

Typical Characteristics (continued)

Unless stated otherwise, all curves taken at V_{IN} = 5 V with configuration in typical application circuit shown in Figure 15. T_J = 25°C, unless otherwise specified.



V_{IN} = 5 V V_{OUT} = 1.2 V at 1 A

Figure 13. Phase Plot vs Frequency

8 Detailed Description

8.1 Overview

The following operating description of the LMR10515 refers to *Functional Block Diagram* and to the waveforms in Figure 14. The LMR10515 supplies a regulated output voltage by switching the internal PMOS control switch at constant frequency and variable duty cycle. A switching cycle begins at the falling edge of the reset pulse generated by the internal oscillator. When this pulse goes low, the output control logic turns on the internal PMOS control switch. During this on-time, the SW pin voltage (V_{SW}) swings up to approximately V_{IN}, and the inductor current (I_L) increases with a linear slope. I_L is measured by the current sense amplifier, which generates an output proportional to the switch current. The sense signal is summed with the regulator's corrective ramp and compared to the error amplifier's output, which is proportional to the difference between the feedback voltage and V_{REF}. When the PWM comparator output goes high, the output switch turns off until the next switching cycle begins. During the switch off-time, inductor current discharges through the Schottky catch diode, which forces the SW pin to swing below ground by the forward voltage (V_D) of the Schottky catch diode. The regulator loop adjusts the duty cycle (D) to maintain a constant output voltage.

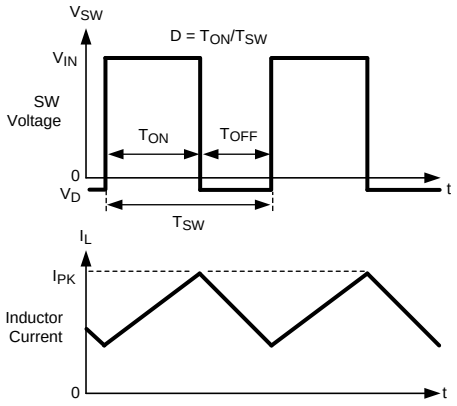
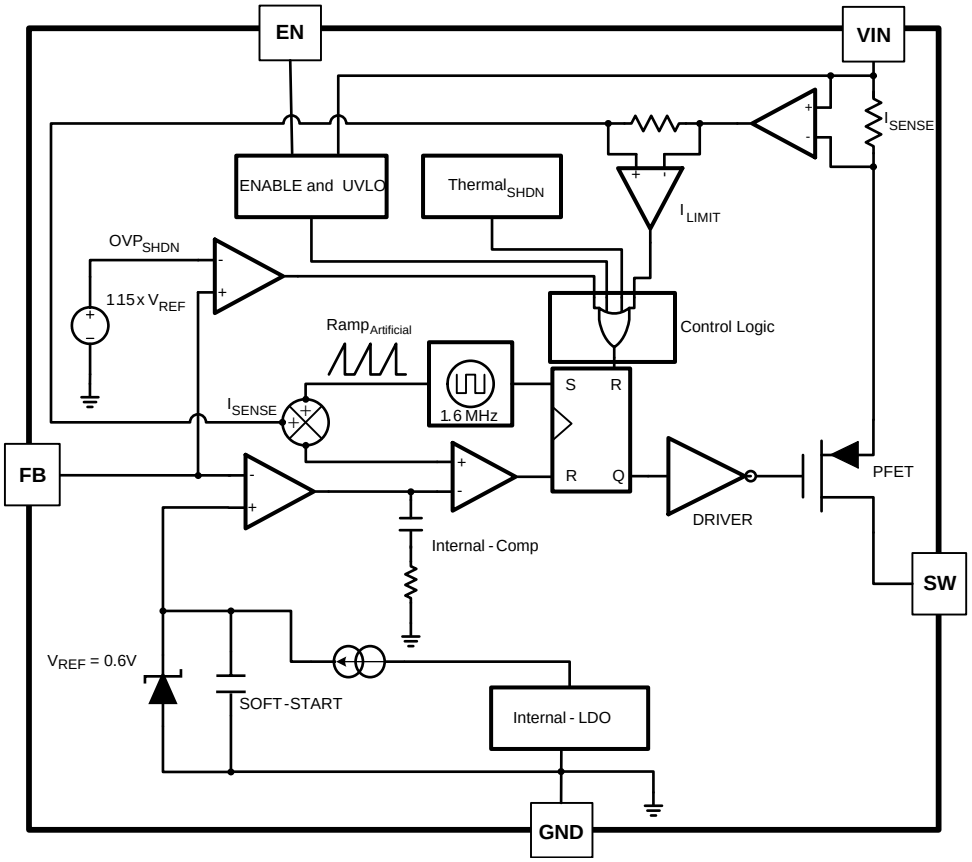


Figure 14. Typical Waveforms

8.2 Functional Block Diagram



8.3 Feature Description

8.3.1 Soft-Start

This function forces V_{OUT} to increase at a controlled rate during start up. During soft-start, the error amplifier's reference voltage ramps from 0 V to its nominal value of 0.6 V in approximately 600 µs. This forces the regulator output to ramp up in a controlled fashion, which helps reduce inrush current.

8.3.2 Output Overvoltage Protection

The over-voltage comparator compares the FB pin voltage to a voltage that is 15% higher than the internal reference V_{REF}. Once the FB pin voltage goes 15% above the internal reference, the internal PMOS control switch is turned off, which allows the output voltage to decrease toward regulation.

8.3.3 Undervoltage Lockout

Under-voltage lockout (UVLO) prevents the LMR10515 from operating until the input voltage exceeds 2.73 V (typical). The UVLO threshold has approximately 430 mV of hysteresis, so the part will operate until V_{IN} drops below 2.3 V (typical). Hysteresis prevents the part from turning off during power up if V_{IN} is non-monotonic.

8.3.4 Current Limit

The LMR10515 uses cycle-by-cycle current limiting to protect the output switch. During each switching cycle, a current limit comparator detects if the output switch current exceeds 2.5A (typical), and turns off the switch until the next switching cycle begins.

8.3.5 Thermal Shutdown

Thermal shutdown limits total power dissipation by turning off the output switch when the IC junction temperature exceeds 165°C. After thermal shutdown occurs, the output switch doesn't turn on until the junction temperature drops to approximately 150°C.

9 Application and Implementation

NOTE

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

9.1 Application Information

The LMR10515 is internally compensated, so it is simple to use and requires few external components. The regulator has a preset switching frequency of 1.6 MHz or 3 MHz. This high frequency allows the LMR10515 to operate with small surface mount capacitors and inductors, resulting in a DC/DC converter that requires a minimum amount of board space

9.2 Typical Application

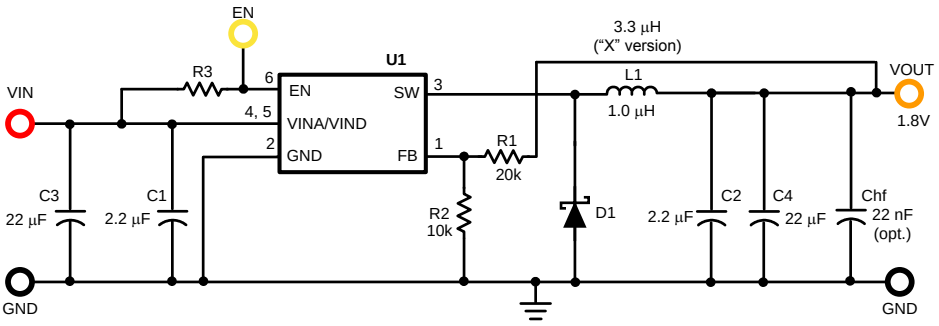


Figure 15. Typical Application Schematic

9.2.1 Detailed Design Procedure

9.2.1.1 Custom Design With WEBENCH® Tools

Click here to create a custom design using the LMR10515 device with the WEBENCH® Power Designer.

1. Start by entering the input voltage (V_{IN}), output voltage (V_{OUT}), and output current (I_{OUT}) requirements.
2. Optimize the design for key parameters such as efficiency, footprint, and cost using the optimizer dial.
3. Compare the generated design with other possible solutions from Texas Instruments.

The WEBENCH Power Designer provides a customized schematic along with a list of materials with real-time pricing and component availability.

In most cases, these actions are available:

- Run electrical simulations to see important waveforms and circuit performance
- Run thermal simulations to understand board thermal performance
- Export customized schematic and layout into popular CAD formats
- Print PDF reports for the design, and share the design with colleagues

Get more information about WEBENCH tools at www.ti.com/WEBENCH.

9.2.1.2 Inductor Selection

The Duty Cycle (D) can be approximated quickly using the ratio of output voltage (V_O) to input voltage (V_{IN}):

$$D = \frac{V_{OUT}}{V_{IN}}$$

The catch diode (D1) forward voltage drop and the voltage drop across the internal PMOS must be included to calculate a more accurate duty cycle. Calculate D by using the following formula:

Typical Application (continued)

$$D = \frac{V_{OUT} + V_D}{V_{IN} + V_D - V_{SW}}$$

V_{SW} can be approximated by:

$$V_{SW} = I_{OUT} \times R_{DSON}$$

The diode forward drop (V_D) can range from 0.3 V to 0.7 V depending on the quality of the diode. The lower the V_D, the higher the operating efficiency of the converter. The inductor value determines the output ripple current. Lower inductor values decrease the size of the inductor, but increase the output ripple current. An increase in the inductor value will decrease the output ripple current.

One must ensure that the minimum current limit (1.8A) is not exceeded, so the peak current in the inductor must be calculated. The peak current (I_{LPK}) in the inductor is calculated by:

$$I_{LPK} = I_{OUT} + \Delta i_L$$

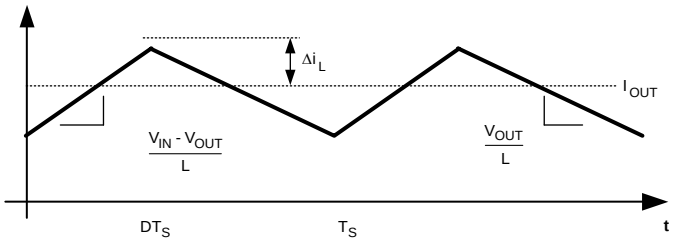


Figure 16. Inductor Current

$$\frac{V_{IN} - V_{OUT}}{L} = \frac{2\Delta i_L}{DT_S}$$

In general,

$$\Delta i_L = 0.1 \times (I_{OUT}) \rightarrow 0.2 \times (I_{OUT})$$

If Δi_L = 20% of 1.50A, the peak current in the inductor will be 1.8 A. The minimum specified current limit over all operating conditions is 1.8 A. One can either reduce Δi_L, or make the engineering judgment that zero margin will be safe enough. The typical current limit is 2.5 A.

The LMR10515 operates at frequencies allowing the use of ceramic output capacitors without compromising transient response. Ceramic capacitors allow higher inductor ripple without significantly increasing output ripple. See the Output Capacitor section for more details on calculating output voltage ripple. Now that the ripple current is determined, the inductance is calculated by:

$$L = \left(\frac{DT_S}{2\Delta i_L}\right) \times (V_{IN} - V_{OUT})$$

where

- $T_S = \frac{1}{f_S}$

When selecting an inductor, make sure that it is capable of supporting the peak output current without saturating. Inductor saturation will result in a sudden reduction in inductance and prevent the regulator from operating correctly. Because of the speed of the internal current limit, the peak current of the inductor need only be specified for the required maximum output current. For example, if the designed maximum output current is 1 A, and the peak current is 1.25 A, then the inductor should be specified with a saturation current limit of > 1.25 A. There is no need to specify the saturation or peak current of the inductor at the 2.5-A typical switch current limit. The difference in inductor size is a factor of 5. Because of the operating frequency of the LMR10515, ferrite based inductors are preferred to minimize core losses. This presents little restriction since the variety of ferrite-based inductors is huge. Lastly, inductors with lower series resistance (R_{DCR}) will provide better operating efficiency. For recommended inductors see Example Circuits.

Typical Application (continued)

9.2.1.3 Input Capacitor

An input capacitor is necessary to ensure that V_{IN} does not drop excessively during switching transients. The primary specifications of the input capacitor are capacitance, voltage, RMS current rating, and equivalent series inductance (ESL). The recommended input capacitance is 22 µF.The input voltage rating is specifically stated by the capacitor manufacturer. Make sure to check any recommended deratings and also verify if there is any significant change in capacitance at the operating input voltage and the operating temperature. The input capacitor maximum RMS input current rating (I_{RMS-IN}) must be greater than:

$$I_{RMS\_IN} \sqrt{D\left[I_{OUT}^2 (1\text{-}D) + \frac{\Delta i^2}{3}\right]}$$

Neglecting inductor ripple simplifies t to:

$$I_{RMS\_IN} = I_{OUT} \times \sqrt{D(1 - D)}$$

It can be shown from the above equation that maximum RMS capacitor current occurs when D = 0.5. Always calculate the RMS at the point where the duty cycle D is closest to 0.5. The ESL of an input capacitor is usually determined by the effective cross sectional area of the current path. A large leaded capacitor will have high ESL and a 0805 ceramic chip capacitor will have very low ESL. At the operating frequencies of the LMR10515, leaded capacitors may have an ESL so large that the resulting impedance ($2\pi fL$) will be higher than that required to provide stable operation. As a result, surface mount capacitors are strongly recommended.

Sanyo POSCAP, Tantalum or Niobium, Panasonic SP, and multilayer ceramic capacitors (MLCC) are all good choices for both input and output capacitors and have very low ESL. For MLCCs it is recommended to use X7R or X5R type capacitors due to their tolerance and temperature characteristics. Consult capacitor manufacturer datasheets to see how rated capacitance varies over operating conditions.

9.2.1.4 Output Capacitor

The output capacitor is selected based upon the desired output ripple and transient response. The initial current of a load transient is provided mainly by the output capacitor. The output ripple of the converter is:

$$\Delta V_{OUT} = \Delta I_L \left(R_{ESR} + \frac{1}{8 \times F_{SW} \times C_{OUT}}\right)$$

When using MLCCs, the ESR is typically so low that the capacitive ripple may dominate. When this occurs, the output ripple will be approximately sinusoidal and 90° phase shifted from the switching action. Given the availability and quality of MLCCs and the expected output voltage of designs using the LMR10515, there is really no need to review any other capacitor technologies. Another benefit of ceramic capacitors is their ability to bypass high frequency noise. A certain amount of switching edge noise will couple through parasitic capacitances in the inductor to the output. A ceramic capacitor will bypass this noise while a tantalum will not. Since the output capacitor is one of the two external components that control the stability of the regulator control loop, most applications will require a minimum of 22 µF of output capacitance. Capacitance often, but not always, can be increased significantly with little detriment to the regulator stability. Like the input capacitor, recommended multilayer ceramic capacitors are X7R or X5R types.

9.2.1.5 Catch Diode

The catch diode (D1) conducts during the switch off-time. A Schottky diode is recommended for its fast switching times and low forward voltage drop. The catch diode should be chosen so that its current rating is greater than:

$$I_{D1} = I_{OUT} \times (1\text{-}D)$$

The reverse breakdown rating of the diode must be at least the maximum input voltage plus appropriate margin. To improve efficiency, choose a Schottky diode with a low forward voltage drop.

Typical Application (continued)

9.2.1.6 Output Voltage

The output voltage is set using the following equation where R2 is connected between the FB pin and GND, and R1 is connected between V_O and the FB pin. A good value for R2 is 10 k. When designing a unity gain converter (V_{OUT} = 0.6 V), R1 should be between 0 Ω and 100 Ω, and R2 must be equal or greater than 1 0kΩ.

$$R1 = \left(\frac{V_{OUT}}{V_{REF}} - 1\right) \times R2$$

$$V_{REF} = 0.60V$$

9.2.1.7 Calculating Efficiency, And Junction Temperature

The complete LMR10515 DC/DC converter efficiency can be calculated in the following manner.

$$\eta = \frac{P_{OUT}}{P_{IN}}$$

Or

$$\eta = \frac{P_{OUT}}{P_{OUT} + P_{LOSS}}$$

Calculations for determining the most significant power losses are shown below. Other losses totaling less than 2% are not discussed.

Power loss (P_{LOSS}) is the sum of two basic types of losses in the converter: switching and conduction. Conduction losses usually dominate at higher output loads, whereas switching losses remain relatively fixed and dominate at lower output loads. The first step in determining the losses is to calculate the duty cycle (D):

$$D = \frac{V_{OUT} + V_D}{V_{IN} + V_D - V_{SW}}$$

V_{SW} is the voltage drop across the internal PFET when it is on, and is equal to:

$$V_{SW} = I_{OUT} \times R_{DSON}$$

V_D is the forward voltage drop across the Schottky catch diode. It can be obtained from the diode manufactures Electrical Characteristics section. If the voltage drop across the inductor (V_{DCR}) is accounted for, the equation becomes:

$$D = \frac{V_{OUT} + V_D + V_{DCR}}{V_{IN} + V_D + V_{DCR} - V_{SW}}$$

The conduction losses in the free-wheeling Schottky diode are calculated as follows:

$$P_{DIODE} = V_D \times I_{OUT} \times (1-D)$$

Often this is the single most significant power loss in the circuit. Care should be taken to choose a Schottky diode that has a low forward voltage drop.

Another significant external power loss is the conduction loss in the output inductor. The equation can be simplified to:

$$P_{IND} = I_{OUT}^2 \times R_{DCR}$$

The LMR10515 conduction loss is mainly associated with the internal PFET:

$$P_{COND} = (I_{OUT}^2 \times D)\left(1 + \frac{1}{3} \times \left(\frac{\Delta i_L}{I_{OUT}}\right)^2\right) R_{DSON}$$

If the inductor ripple current is fairly small, the conduction losses can be simplified to:

$$P_{COND} = I_{OUT}^2 \times R_{DSON} \times D$$

Typical Application (continued)

Switching losses are also associated with the internal PFET. They occur during the switch on and off transition periods, where voltages and currents overlap resulting in power loss. The simplest means to determine this loss is to empirically measuring the rise and fall times (10% to 90%) of the switch at the switch node.

Switching Power Loss is calculated as follows:

$P_{SWR} = 1/2(V_{IN} \times I_{OUT} \times F_{SW} \times T_{RISE})$

$P_{SWF} = 1/2(V_{IN} \times I_{OUT} \times F_{SW} \times T_{FALL})$

$P_{SW} = P_{SWR} + P_{SWF}$

Another loss is the power required for operation of the internal circuitry:

$P_Q = I_Q \times V_{IN}$

I_Q is the quiescent operating current, and is typically around 3.3 mA for the 1.6 MHz frequency option.

Typical Application power losses are:

Table 1. Power Loss Tabulation

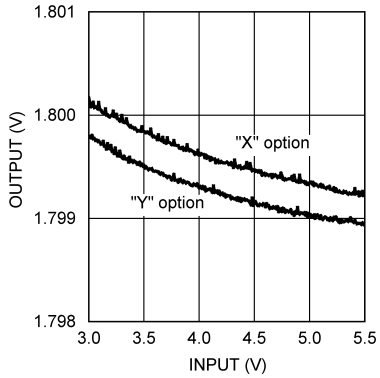
V_{IN}	5 V		
V_{OUT}	3.3 V	P_{OUT}	4.125 W
I_{OUT}	1.25 A		
V_D	0.45 V	P_{DIODE}	188 mW
F_{SW}	1.6 MHz		
I_Q	3.3 mA	P_Q	16.5 mW
T_{RISE}	4 ns	P_{SWR}	20 mW
T_{FALL}	4 ns	P_{SWF}	20 mW
$R_{DS(ON)}$	150 mΩ	P_{COND}	156 mW
IND_{DCR}	70 mΩ	P_{IND}	110 mW
D	0.667	P_{LOSS}	511 mW
η	88%	$P_{INTERNAL}$	213 mW

$\Sigma P_{COND} + P_{SW} + P_{DIODE} + P_{IND} + P_Q = P_{LOSS}$

$\Sigma P_{COND} + P_{SWF} + P_{SWR} + P_Q = P_{INTERNAL}$

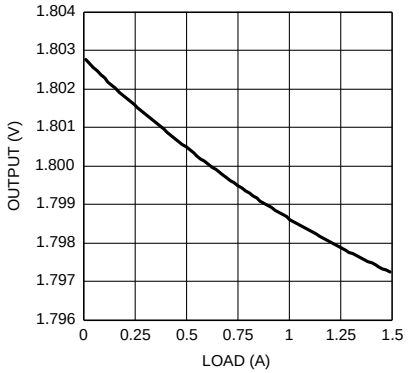
$P_{INTERNAL} = 213$ mW

9.2.2 Application Curves



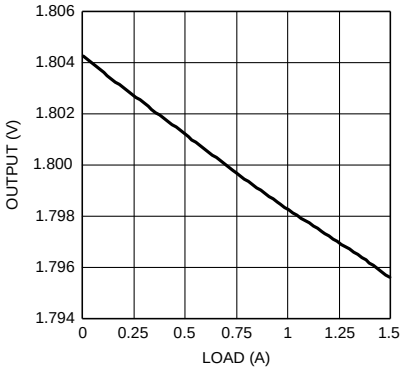
V_{OUT} = 1.8 V I_{OUT} = 500 mA

Figure 17. Line Regulation



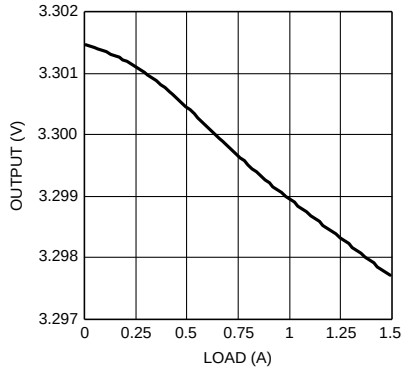
V_{IN} = 3.3 V V_{OUT} = 1.8 V (All Options)

Figure 18. Load Regulation



V_{IN} = 5 V V_{OUT} = 1.8 V (All Options)

Figure 19. Load Regulation



V_{IN} = 5 V V_{OUT} = 3.3 V (All Options)

Figure 20. Load Regulation

9.2.3 Other System Examples

9.2.3.1 LMR10510x Design Example 1

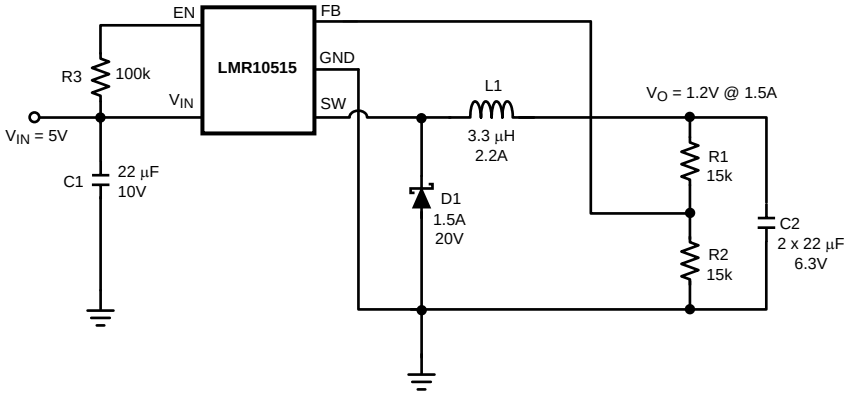


Figure 21. Lmr10515x (1.6mhz): Vin = 5v, Vo = 1.2v @ 1.5a

Figure 22. LMR10510X (1.6 MHz): V_{IN} = 5 V, V_{OUT} = 1.2 V at 1 A

9.2.3.2 Lmr10510X Design Example 2

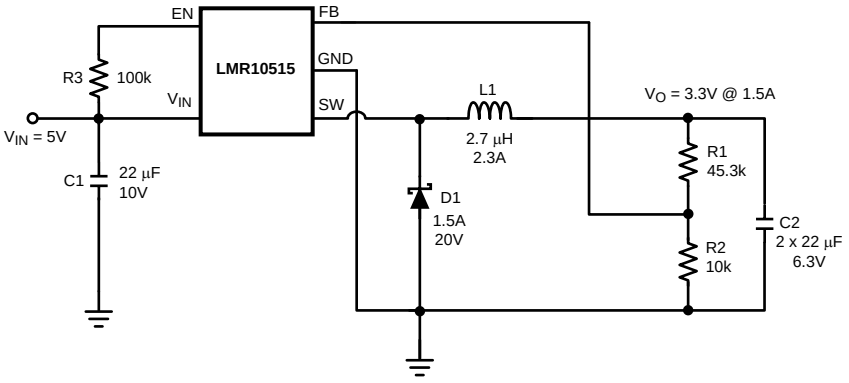


Figure 23. LMR10510X (1.6 MHz): V_{IN} = 5 V, V_{OUT} = 3.3 V at 1 A

9.2.3.3 LMR10510Y Design Example 3

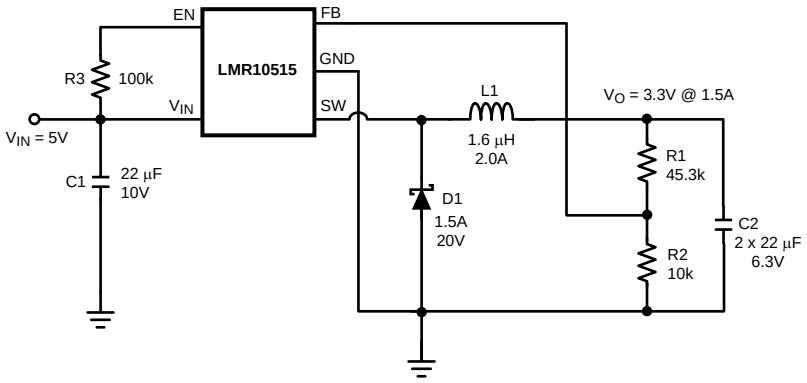


Figure 24. LMR10510Y (3 MHz): V_{IN} = 5 V, V_{OUT} = 3.3 V at 1 A

9.2.3.4 LMR10510Y Design Example 4

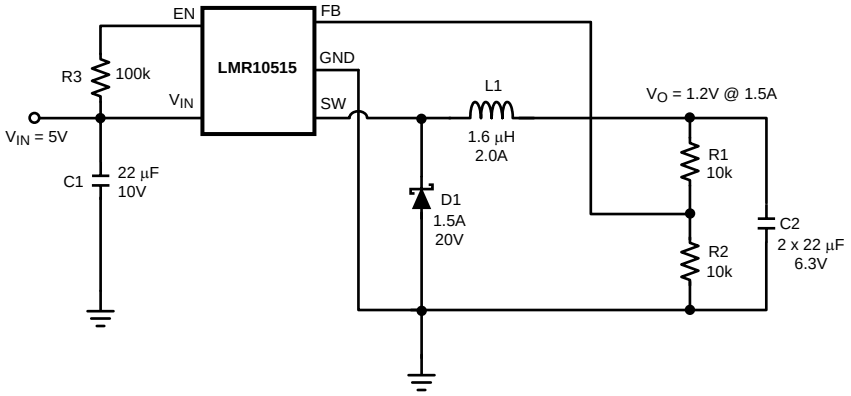


Figure 25. LMR10510Y (3 MHz): V_{IN} = 5 V, V_{OUT} = 1.2 V at 1 A

10 Layout

10.1 Layout Guidelines

When planning layout there are a few things to consider when trying to achieve a clean, regulated output. The most important consideration is the close coupling of the GND connections of the input capacitor and the catch diode D1. These ground ends should be close to one another and be connected to the GND plane with at least two through-holes. Place these components as close to the IC as possible. Next in importance is the location of the GND connection of the output capacitor, which should be near the GND connections of CIN and D1. There should be a continuous ground plane on the bottom layer of a two-layer board except under the switching node island. The FB pin is a high impedance node and care should be taken to make the FB trace short to avoid noise pickup and inaccurate regulation. The feedback resistors should be placed as close as possible to the IC, with the GND of R1 placed as close as possible to the GND of the IC. The V_{OUT} trace to R2 should be routed away from the inductor and any other traces that are switching. High AC currents flow through the V_{IN}, SW and V_{OUT} traces, so they should be as short and wide as possible. However, making the traces wide increases radiated noise, so the designer must make this trade-off. Radiated noise can be decreased by choosing a shielded inductor. The remaining components should also be placed as close as possible to the IC. Please see Application Note AN-1229 for further considerations and the LMR10515 demo board as an example of a good layout.

10.2 Layout Example

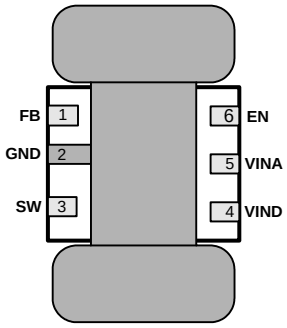


Figure 26. 6-Lead WSON PCB Dog Bone Layout

10.3 Thermal Definitions

T_J = Chip junction temperature

T_A = Ambient temperature

$R_{\theta JC}$ = Thermal resistance from chip junction to device case

$R_{\theta JA}$ = Thermal resistance from chip junction to ambient air

Heat in the LMR10515 due to internal power dissipation is removed through conduction and/or convection.

Conduction: Heat transfer occurs through cross sectional areas of material. Depending on the material, the transfer of heat can be considered to have poor to good thermal conductivity properties (insulator vs. conductor).

Heat Transfer goes as:

Silicon → package → lead frame → PCB

Convection: Heat transfer is by means of airflow. This could be from a fan or natural convection. Natural convection occurs when air currents rise from the hot device to cooler air.

Thermal impedance is defined as:

$$R_\theta = \frac{\Delta T}{\text{Power}}$$

Thermal impedance from the silicon junction to the ambient air is defined as:

Thermal Definitions (continued)

$$R_{\theta JA} = \frac{T_J - T_A}{Power}$$

The PCB size, weight of copper used to route traces and ground plane, and number of layers within the PCB can greatly effect $R_{\theta JA}$. The type and number of thermal vias can also make a large difference in the thermal impedance. Thermal vias are necessary in most applications. They conduct heat from the surface of the PCB to the ground plane. Four to six thermal vias should be placed under the exposed pad to the ground plane if the WSON package is used.

Thermal impedance also depends on the thermal properties of the application operating conditions (Vin, Vo, Io etc), and the surrounding circuitry.

Silicon Junction Temperature Determination Method 1:

To accurately measure the silicon temperature for a given application, two methods can be used. The first method requires the user to know the thermal impedance of the silicon junction to case temperature.

$R_{\theta JC}$ is approximately 18°C/Watt for the 6-pin WSON package with the exposed pad. Knowing the internal dissipation from the efficiency calculation given previously, and the case temperature, which can be empirically measured on the bench we have:

$$R_{\theta JC} = \frac{T_J - T_C}{Power}$$

where T_C is the temperature of the exposed pad and can be measured on the bottom side of the PCB.

Therefore:

$$T_j = (R_{\theta JC} \times P_{LOSS}) + T_C$$

From the previous example:

$$T_j = (R_{\theta JC} \times P_{INTERNAL}) + T_C$$
$$T_j = 18°C/W \times 0.213W + T_C$$

The second method can give a very accurate silicon junction temperature.

The first step is to determine $R_{\theta JA}$ of the application. The LMR10515 has over-temperature protection circuitry. When the silicon temperature reaches 165°C, the device stops switching. The protection circuitry has a hysteresis of about 15°C. Once the silicon temperature has decreased to approximately 150°C, the device will start to switch again. Knowing this, the $R_{\theta JA}$ for any application can be characterized during the early stages of the design one may calculate the $R_{\theta JA}$ by placing the PCB circuit into a thermal chamber. Raise the ambient temperature in the given working application until the circuit enters thermal shutdown. If the SW-pin is monitored, it will be obvious when the internal PFET stops switching, indicating a junction temperature of 165°C. Knowing the internal power dissipation from the above methods, the junction temperature, and the ambient temperature $R_{\theta JA}$ can be determined.

$$R_{\theta JA} = \frac{165° - Ta}{P_{INTERNAL}}$$

Once this is determined, the maximum ambient temperature allowed for a desired junction temperature can be found.

An example of calculating $R_{\theta JA}$ for an application using the LMR10515 is shown below.

A sample PCB is placed in an oven with no forced airflow. The ambient temperature was raised to 140°C, and at that temperature, the device went into thermal shutdown.

From the previous example:

$$P_{INTERNAL} = 213 \text{ mW}$$

Thermal Definitions (continued)

$$R_{\theta JA} = \frac{165℃ - 140℃}{213\ mW} = 117℃/W$$

Since the junction temperature must be kept below 125°C, then the maximum ambient temperature can be calculated as:

$T_j - (R_{\theta JA} \times P_{LOSS}) = T_A$

125°C – (117°C/W x 213 mW) = 100°C

10.4 WSON Package

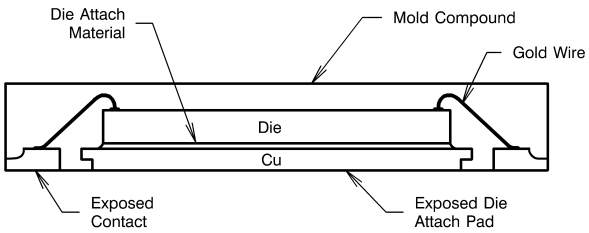


Figure 27. Internal WSON Connection

For certain high power applications, the PCB land may be modified to a "dog bone" shape (see). By increasing the size of ground plane, and adding thermal vias, the $R_{\theta JA}$ for the application can be reduced.

11 Device and Documentation Support

11.1 Device Support

11.1.1 Development Support

11.1.1.1 Custom Design With WEBENCH® Tools

Click here to create a custom design using the LMR10515 device with the WEBENCH® Power Designer.

1. Start by entering the input voltage (V_{IN}), output voltage (V_{OUT}), and output current (I_{OUT}) requirements.
2. Optimize the design for key parameters such as efficiency, footprint, and cost using the optimizer dial.
3. Compare the generated design with other possible solutions from Texas Instruments.

The WEBENCH Power Designer provides a customized schematic along with a list of materials with real-time pricing and component availability.

In most cases, these actions are available:

- Run electrical simulations to see important waveforms and circuit performance
- Run thermal simulations to understand board thermal performance
- Export customized schematic and layout into popular CAD formats
- Print PDF reports for the design, and share the design with colleagues

Get more information about WEBENCH tools at www.ti.com/WEBENCH.

11.2 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on ti.com. In the upper right corner, click on *Alert me* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

11.3 Community Resources

The following links connect to TI community resources. Linked contents are provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's Terms of Use.

TI E2E™ Online Community ***TI's Engineer-to-Engineer (E2E) Community.*** Created to foster collaboration among engineers. At e2e.ti.com, you can ask questions, share knowledge, explore ideas and help solve problems with fellow engineers.

Design Support ***TI's Design Support*** Quickly find helpful E2E forums along with design support tools and contact information for technical support.

11.4 Trademarks

E2E is a trademark of Texas Instruments.
WEBENCH is a registered trademark of Texas Instruments.
All other trademarks are the property of their respective owners.

11.5 Electrostatic Discharge Caution

This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

11.6 Glossary

SLYZ022 — *TI Glossary*.

This glossary lists and explains terms, acronyms, and definitions.

12 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

PACKAGING INFORMATION

Orderable part number	Status (1)	Material type (2)	Package | Pins	Package qty | Carrier	RoHS (3)	Lead finish/ Ball material (4)	MSL rating/ Peak reflow (5)	Op temp (°C)	Part marking (6)
LMR10515XMF/NOPB	Active	Production	SOT-23 (DBV) | 5	1000 | SMALL T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 125	SH6B
LMR10515XMF/NOPB.A	Active	Production	SOT-23 (DBV) | 5	1000 | SMALL T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 125	SH6B
LMR10515XMFE/NOPB	Active	Production	SOT-23 (DBV) | 5	250 | SMALL T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 125	SH6B
LMR10515XMFE/NOPB.A	Active	Production	SOT-23 (DBV) | 5	250 | SMALL T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 125	SH6B
LMR10515XMFE/NOPB.B	Active	Production	SOT-23 (DBV) | 5	250 | SMALL T&R	-	Call TI	Call TI	-40 to 125	
LMR10515XMFX/NOPB	Active	Production	SOT-23 (DBV) | 5	3000 | LARGE T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 125	SH6B
LMR10515XMFX/NOPB.A	Active	Production	SOT-23 (DBV) | 5	3000 | LARGE T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 125	SH6B
LMR10515XMFX/NOPB.B	Active	Production	SOT-23 (DBV) | 5	3000 | LARGE T&R	-	Call TI	Call TI	-40 to 125	
LMR10515XSD/NOPB	Active	Production	WSON (NGG) | 6	1000 | SMALL T&R	Yes	SN	Level-3-260C-168 HR	-40 to 125	L265B
LMR10515XSD/NOPB.A	Active	Production	WSON (NGG) | 6	1000 | SMALL T&R	Yes	SN	Level-3-260C-168 HR	-40 to 125	L265B
LMR10515XSDE/NOPB	Active	Production	WSON (NGG) | 6	250 | SMALL T&R	Yes	SN	Level-3-260C-168 HR	-40 to 125	L265B
LMR10515XSDE/NOPB.A	Active	Production	WSON (NGG) | 6	250 | SMALL T&R	Yes	SN	Level-3-260C-168 HR	-40 to 125	L265B
LMR10515XSDE/NOPB.B	Active	Production	WSON (NGG) | 6	250 | SMALL T&R	-	Call TI	Call TI	-40 to 125	
LMR10515YMF/NOPB	Active	Production	SOT-23 (DBV) | 5	1000 | SMALL T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 125	SJ1B
LMR10515YMF/NOPB.A	Active	Production	SOT-23 (DBV) | 5	1000 | SMALL T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 125	SJ1B
LMR10515YMFE/NOPB	Active	Production	SOT-23 (DBV) | 5	250 | SMALL T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 125	SJ1B
LMR10515YMFE/NOPB.A	Active	Production	SOT-23 (DBV) | 5	250 | SMALL T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 125	SJ1B
LMR10515YMFE/NOPB.B	Active	Production	SOT-23 (DBV) | 5	250 | SMALL T&R	-	Call TI	Call TI	-40 to 125	
LMR10515YMFX/NOPB	Active	Production	SOT-23 (DBV) | 5	3000 | LARGE T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 125	SJ1B
LMR10515YMFX/NOPB.A	Active	Production	SOT-23 (DBV) | 5	3000 | LARGE T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 125	SJ1B
LMR10515YSD/NOPB	Active	Production	WSON (NGG) | 6	1000 | SMALL T&R	Yes	SN	Level-3-260C-168 HR	-40 to 125	L269B
LMR10515YSD/NOPB.A	Active	Production	WSON (NGG) | 6	1000 | SMALL T&R	Yes	SN	Level-3-260C-168 HR	-40 to 125	L269B
LMR10515YSDE/NOPB	Active	Production	WSON (NGG) | 6	250 | SMALL T&R	Yes	SN	Level-3-260C-168 HR	-40 to 125	L269B
LMR10515YSDE/NOPB.A	Active	Production	WSON (NGG) | 6	250 | SMALL T&R	Yes	SN	Level-3-260C-168 HR	-40 to 125	L269B
LMR10515YSDE/NOPB.B	Active	Production	WSON (NGG) | 6	250 | SMALL T&R	-	Call TI	Call TI	-40 to 125	
LMR10515YSDX/NOPB	Active	Production	WSON (NGG) | 6	4500 | LARGE T&R	Yes	SN	Level-3-260C-168 HR	-40 to 125	L269B
LMR10515YSDX/NOPB.A	Active	Production	WSON (NGG) | 6	4500 | LARGE T&R	Yes	SN	Level-3-260C-168 HR	-40 to 125	L269B
LMR10515YSDX/NOPB.B	Active	Production	WSON (NGG) | 6	4500 | LARGE T&R	-	Call TI	Call TI	-40 to 125	

(1) **Status:** For more details on status, see our product life cycle.

(2) **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

(3) **RoHS values:** Yes, No, RoHS Exempt. See the TI RoHS Statement for additional information and value definition.

(4) **Lead finish/Ball material:** Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

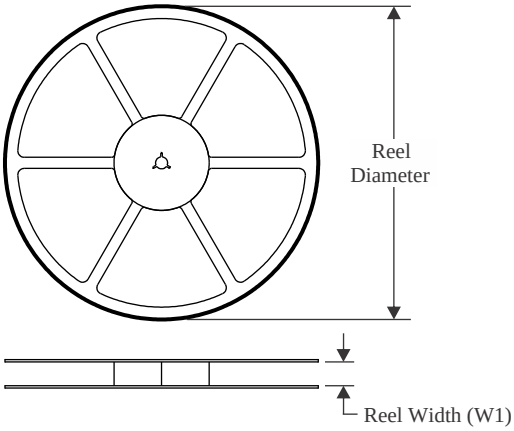
(5) **MSL rating/Peak reflow:** The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

(6) **Part marking:** There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

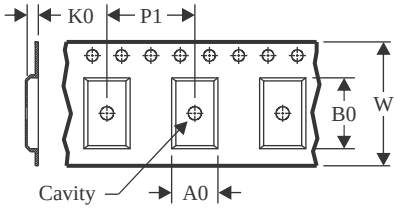
Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

TAPE AND REEL INFORMATION

REEL DIMENSIONS

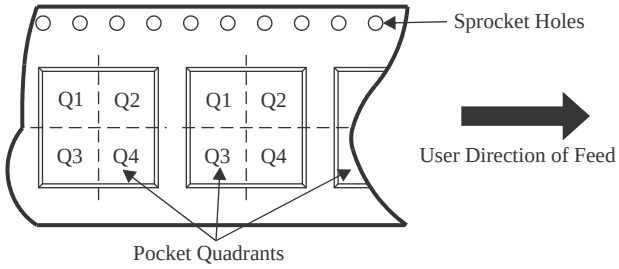


TAPE DIMENSIONS



A0	Dimension designed to accommodate the component width
B0	Dimension designed to accommodate the component length
K0	Dimension designed to accommodate the component thickness
W	Overall width of the carrier tape
P1	Pitch between successive cavity centers

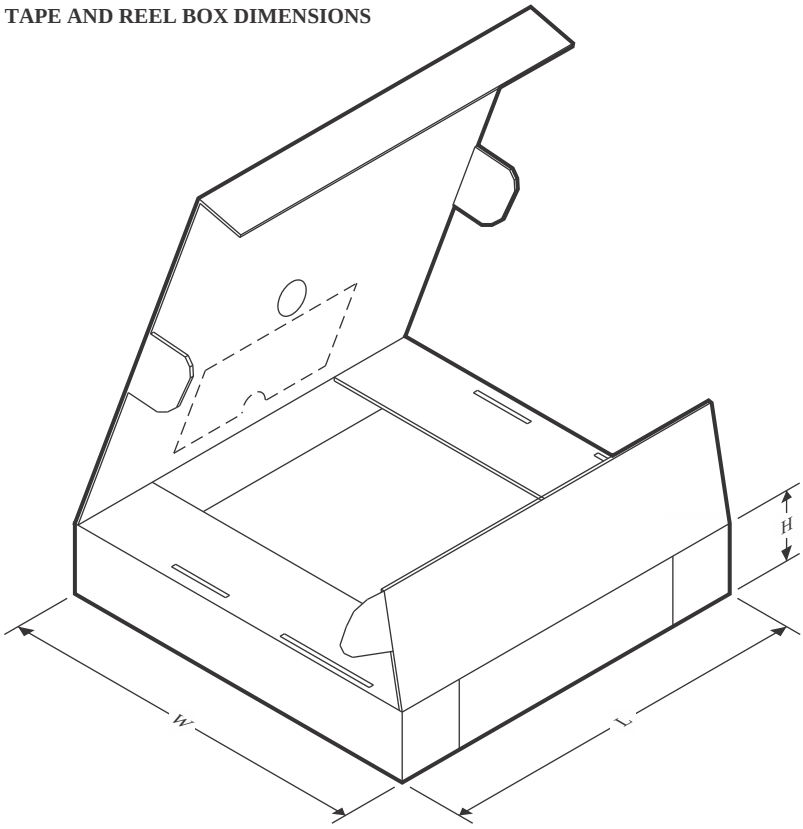
QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
LMR10515XMF/NOPB	SOT-23	DBV	5	1000	178.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
LMR10515XMFE/NOPB	SOT-23	DBV	5	250	178.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
LMR10515XMFX/NOPB	SOT-23	DBV	5	3000	178.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
LMR10515XSD/NOPB	WSON	NGG	6	1000	177.8	12.4	3.3	3.3	1.0	8.0	12.0	Q1
LMR10515XSDE/NOPB	WSON	NGG	6	250	177.8	12.4	3.3	3.3	1.0	8.0	12.0	Q1
LMR10515YMF/NOPB	SOT-23	DBV	5	1000	178.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
LMR10515YMFE/NOPB	SOT-23	DBV	5	250	178.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
LMR10515YMFX/NOPB	SOT-23	DBV	5	3000	178.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
LMR10515YSD/NOPB	WSON	NGG	6	1000	177.8	12.4	3.3	3.3	1.0	8.0	12.0	Q1
LMR10515YSDE/NOPB	WSON	NGG	6	250	177.8	12.4	3.3	3.3	1.0	8.0	12.0	Q1
LMR10515YSDX/NOPB	WSON	NGG	6	4500	330.0	12.4	3.3	3.3	1.0	8.0	12.0	Q1

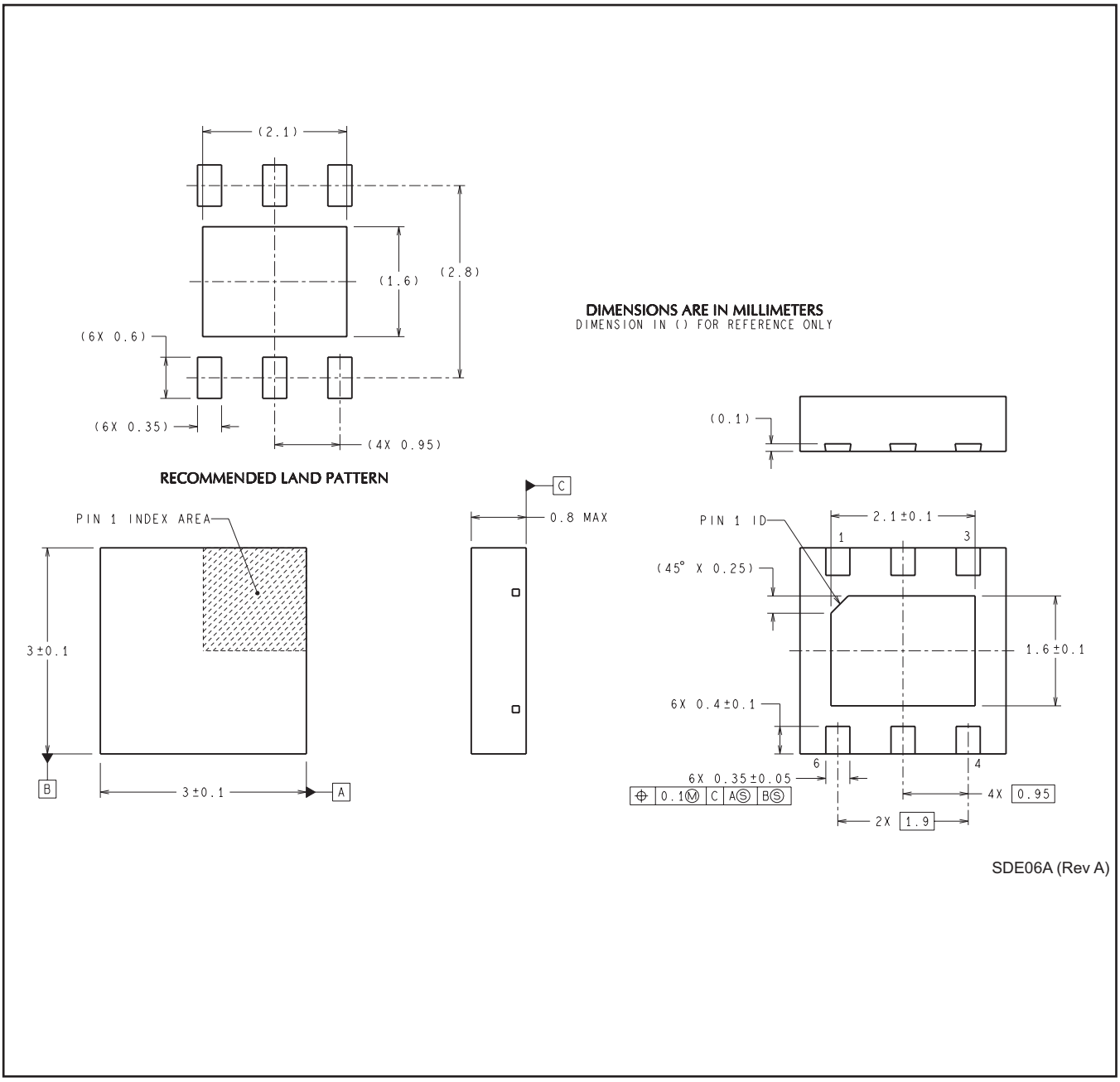
TAPE AND REEL BOX DIMENSIONS



*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
LMR10515XMF/NOPB	SOT-23	DBV	5	1000	208.0	191.0	35.0
LMR10515XMFE/NOPB	SOT-23	DBV	5	250	208.0	191.0	35.0
LMR10515XMFX/NOPB	SOT-23	DBV	5	3000	208.0	191.0	35.0
LMR10515XSD/NOPB	WSON	NGG	6	1000	208.0	191.0	35.0
LMR10515XSDE/NOPB	WSON	NGG	6	250	208.0	191.0	35.0
LMR10515YMF/NOPB	SOT-23	DBV	5	1000	208.0	191.0	35.0
LMR10515YMFE/NOPB	SOT-23	DBV	5	250	208.0	191.0	35.0
LMR10515YMFX/NOPB	SOT-23	DBV	5	3000	208.0	191.0	35.0
LMR10515YSD/NOPB	WSON	NGG	6	1000	208.0	191.0	35.0
LMR10515YSDE/NOPB	WSON	NGG	6	250	208.0	191.0	35.0
LMR10515YSDX/NOPB	WSON	NGG	6	4500	356.0	356.0	36.0

NGG0006A



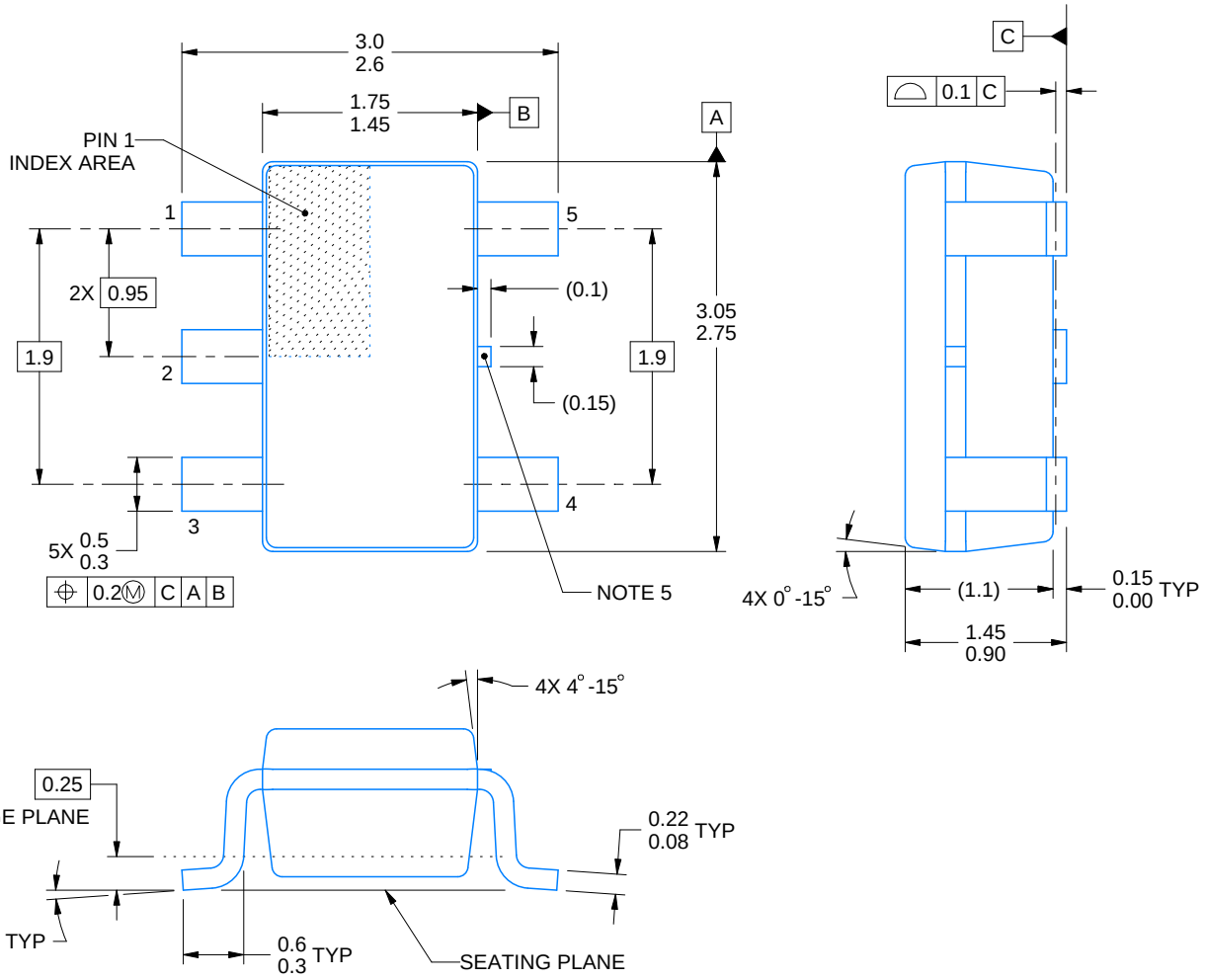
SDE06A (Rev A)

PACKAGE OUTLINE

DBV0005A

SOT-23 - 1.45 mm max height

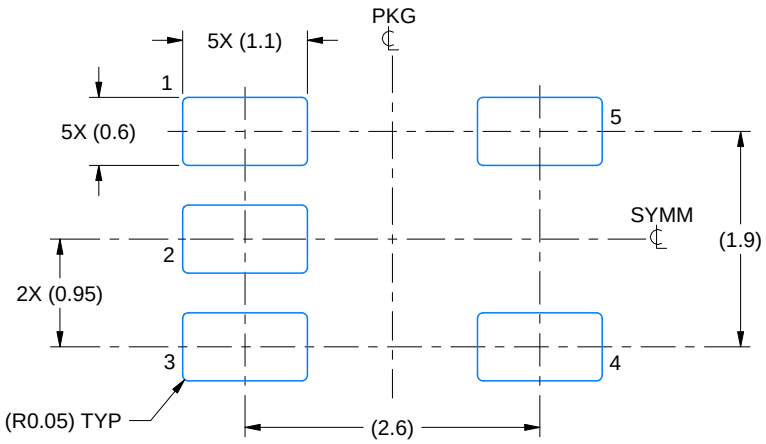
SMALL OUTLINE TRANSISTOR



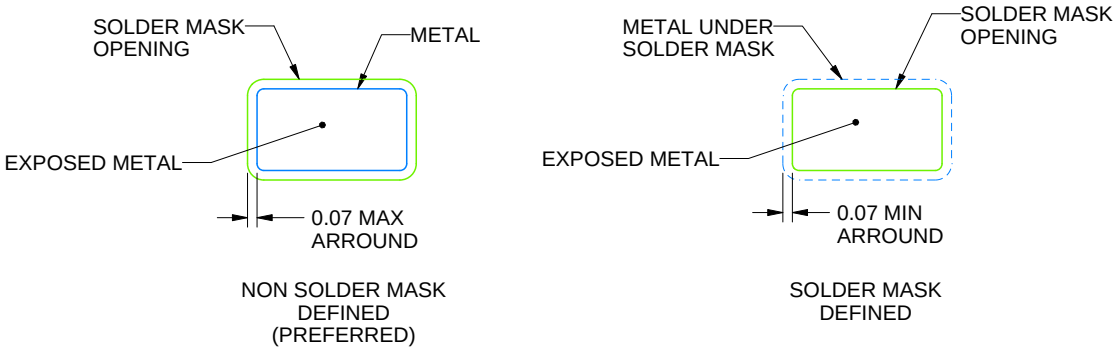
4214839/K 08/2024

NOTES:

1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. Refernce JEDEC MO-178.
4. Body dimensions do not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.25 mm per side.
5. Support pin may differ or may not be present.



LAND PATTERN EXAMPLE
EXPOSED METAL SHOWN
SCALE:15X

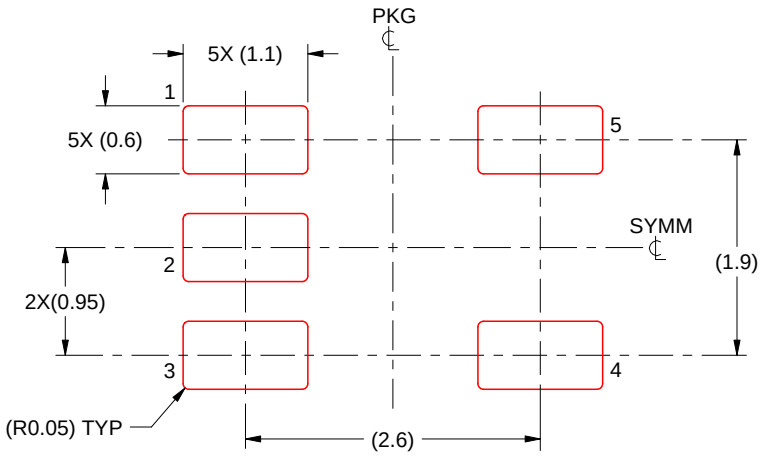


SOLDER MASK DETAILS

4214839/K 08/2024

NOTES: (continued)

6. Publication IPC-7351 may have alternate designs.
7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.



SOLDER PASTE EXAMPLE
BASED ON 0.125 mm THICK STENCIL
SCALE:15X

4214839/K 08/2024

NOTES: (continued)

8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
9. Board assembly site may have different recommendations for stencil design.

IMPORTANT NOTICE AND DISCLAIMER

TI PROVIDES TECHNICAL AND RELIABILITY DATA (INCLUDING DATASHEETS), DESIGN RESOURCES (INCLUDING REFERENCE DESIGNS), APPLICATION OR OTHER DESIGN ADVICE, WEB TOOLS, SAFETY INFORMATION, AND OTHER RESOURCES “AS IS” AND WITH ALL FAULTS, AND DISCLAIMS ALL WARRANTIES, EXPRESS AND IMPLIED, INCLUDING WITHOUT LIMITATION ANY IMPLIED WARRANTIES OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE OR NON-INFRINGEMENT OF THIRD PARTY INTELLECTUAL PROPERTY RIGHTS.

These resources are intended for skilled developers designing with TI products. You are solely responsible for (1) selecting the appropriate TI products for your application, (2) designing, validating and testing your application, and (3) ensuring your application meets applicable standards, and any other safety, security, regulatory or other requirements.

These resources are subject to change without notice. TI grants you permission to use these resources only for development of an application that uses the TI products described in the resource. Other reproduction and display of these resources is prohibited. No license is granted to any other TI intellectual property right or to any third party intellectual property right. TI disclaims responsibility for, and you fully indemnify TI and its representatives against any claims, damages, costs, losses, and liabilities arising out of your use of these resources.

TI’s products are provided subject to TI’s Terms of Sale, TI’s General Quality Guidelines, or other applicable terms available either on ti.com or provided in conjunction with such TI products. TI’s provision of these resources does not expand or otherwise alter TI’s applicable warranties or warranty disclaimers for TI products. Unless TI explicitly designates a product as custom or customer-specified, TI products are standard, catalog, general purpose devices.

TI objects to and rejects any additional or different terms you may propose.

Last updated 10/2025