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# Small Size, Low-Power, Unidirectional, CURRENT SHUNT MONITOR Zerø-Drift Series

Check for Samples: INA216

#### **FEATURES**

- CHIP-SCALE PACKAGE
- COMMON-MODE RANGE: +1.8V to +5.5V
- OFFSET VOLTAGE: ±30µV
- GAIN ERROR: ±0.2% MAX
- CHOICE OF GAINS:
  - INA216A1: 25V/V
  - INA216A2: 50V/V
  - INA216A3: 100V/V
  - INA216A4: 200V/V
- QUIESCENT CURRENT: 13µA
- BUFFERED VOLTAGE OUTPUT: No Additional Op Amp Needed

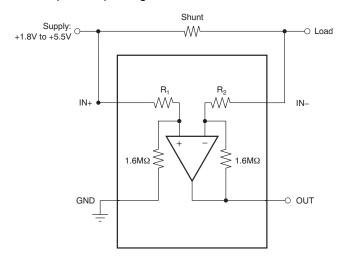
#### **APPLICATIONS**

- NOTEBOOK COMPUTERS
- CELL PHONES
- TELECOM EQUIPMENT
- POWER MANAGEMENT
- BATTERY CHARGERS

#### DESCRIPTION

The INA216 is a high-side voltage output current shunt monitor that can sense drops across shunts at common-mode voltages from +1.8V to +5.5V. Four fixed gains are available: 25V/V, 50V/V, 100V/V, and 200V/V. The low offset of the Zerø-Drift architecture enables current sensing with maximum drops across the shunt as low as 10mV full-scale, or with wide dynamic ranges of over 1000:1.

These devices operate from a single +1.8V to +5.5V power supply, drawing a maximum of 25µA of supply current. The INA216 series are specified over the temperature range of -40°C to +125°C, and offered in a chip-scale package.



PRODUCT	GAIN	<b>R</b> <sub>1</sub> = <b>R</b> <sub>2</sub>
INA216A1	25	64kΩ
INA216A2	50	32kΩ
INA216A3	100	16kΩ
INA216A4	200	8kΩ

ATA.

Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.





This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

# PACKAGE INFORMATION(1)

PRODUCT	GAIN	PACKAGE-LEAD	PACKAGE DESIGNATOR	PACKAGE MARKING
INA216A1	25\/\/	WCSP-4	YFF	OW
INAZ IOA I	25V/V	ThinQFN-10	RSW	SNJ
111404040	50///	WCSP-4	YFF	OX
INA216A2	50V/V	ThinQFN-10	RSW	SOJ
INIAGAGAG	100\/\/	WCSP-4	YFF	OY
INA216A3	100V/V	ThinQFN-10	RSW	SPJ
INA216A4	2001/1/	WCSP-4	YFF	OZ
	200V/V	ThinQFN-10	RSW	SQJ

<sup>(1)</sup> For the most current package and ordering information see the Package Option Addendum at the end of this document, or visit the device product folder at www.ti.com.

## ABSOLUTE MAXIMUM RATINGS(1)

Over operating free-air temperature range, unless otherwise noted.

		INA216	UNIT
Supply Voltage		+7	V
Analog Inputs,	Differential (V <sub>IN+</sub> )–(V <sub>IN</sub> –)	-5.5 to +5.5	V
$V_{IN+}, V_{IN-}^{(2)}$	Common-Mode <sup>(3)</sup>	GND-0.3V to +5.5	V
Output <sup>(3)</sup>		GND-0.3V to (V+)+0.3	V
Input Current into Any Pin (3)		5	mA
Operating Temp	erature	-55 to +150	°C
Storage Temper	ature	-65 to +150	°C
Junction Temper	rature	+150	°C
	Human Body Model	2.5	kV
ESD Ratings:	Charged Device Model	1	kV
-	Machine Model	200	V

<sup>(1)</sup> Stresses above these ratings may cause permanent damage. Exposure to absolute maximum conditions for extended periods may degrade device reliability. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those specified is not implied.

(2)  $V_{IN+}$  and  $V_{IN-}$  are the voltages at the IN+ and IN- pins, respectively.

<sup>(3)</sup> Input voltage at any pin may exceed the voltage shown if the current at that pin is limited to 5mA.



#### THERMAL INFORMATION

	THERMAL METRIC <sup>(1)</sup>	INA216A1YFF, INA216A2YFF INA216A3YFF, INA216A4YFF	UNITS
$\theta_{JA}$	Junction-to-ambient thermal resistance	<b>4 PINS</b> 160	
$\theta_{\text{JC(top)}}$	Junction-to-case(top) thermal resistance	75	
$\theta_{JB}$	Junction-to-board thermal resistance	76	0000
ΨЈТ	Junction-to-top characterization parameter	3	°C/W
ΨЈВ	Junction-to-board characterization parameter	74	
θ <sub>JC(bottom)</sub>	Junction-to-case(bottom) thermal resistance	n/a	

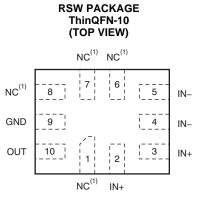
<sup>(1)</sup> For more information about traditional and new thermal metrics, see the IC Package Thermal Metrics application report, SPRA953.

#### THERMAL INFORMATION

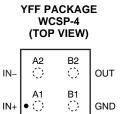
	THERMAL METRIC <sup>(1)</sup>	INA216A1RSW, INA216A2RSW INA216A3RSW, INA216A4RSW	UNITS
		RSW	
		10 PINS	
$\theta_{JA}$	Junction-to-ambient thermal resistance	114.9	
$\theta_{JC(top)}$	Junction-to-case(top) thermal resistance	66.3	
$\theta_{JB}$	Junction-to-board thermal resistance	21.4	°C ///
ΨЈТ	Junction-to-top characterization parameter	1.9	°C/W
ΨЈВ	Junction-to-board characterization parameter	21.4	
θ <sub>JC(bottom)</sub>	Junction-to-case(bottom) thermal resistance	N/A	

<sup>(1)</sup> For more information about traditional and new thermal metrics, see the IC Package Thermal Metrics application report, SPRA953.

# **PIN CONFIGURATIONS**



(1) No internal connection.



- (2) Bump side down. Drawing not to scale.
- (3) Power supply is derived from shunt (minimum common-mode range = 1.8V)



# **ELECTRICAL CHARACTERISTICS**

**Boldface** limits apply over the specified temperature range,  $T_A = -40^{\circ}C$  to +125°C. At  $T_A = +25^{\circ}C$  and  $V_{CM} = V_{IN+} = 4.2V$ , unless otherwise noted.

				INA216		
PARAMETER		CONDITIONS	MIN	TYP	MAX	UNIT
INPUT						
Offset Voltage, RTI <sup>(1)</sup>	Vos					
INA216A1				±30	±100	μV
vs Temperature	dV <sub>os</sub> /dT			0.06	0.2	μ <b>V/°C</b>
INA216A2				±20	±75	μV
vs Temperature	dV <sub>os</sub> /dT			0.05	0.25	μ <b>V/°C</b>
INA216A3				±20	±75	μV
vs Temperature	dV <sub>os</sub> /dT			0.03	0.25	μ <b>V/°C</b>
INA216A4				±20	±75	μV
vs Temperature	dV <sub>OS</sub> /dT			0.1	0.3	μ <b>۷/°C</b>
Common-Mode Input Range	V <sub>CM</sub>		1.8		5.5	V
Common-Mode Rejection (2)	CMRR	$V_{IN+} = +1.8V \text{ to } +5.5V$	90	108		dB
Power-Supply Rejection	PSRR		90	108		dB
Input Bias Current	I <sub>IN</sub> _			3		μΑ
OUTPUT	<u> </u>					
Gain	G					
INA216A1				25		V/V
INA216A2				50		V/V
INA216A3				100		V/V
INA216A4				200		V/V
Gain Error						
INA216A1		$V_{OUT} = 0.2V$ to $V_{OUT} = 2.5V$		±0.01	±0.2	%
vs Temperature		V <sub>OUT</sub> = 0.2V to V <sub>OUT</sub> = 2.5V		0.01	0.025	m%/°C
INA216A2				0.05	±0.2	%
vs Temperature				0.017	0.1	m%/°C
INA216A3				0.06	±0.2	%
vs Temperature				0.023	0.1	m%/°C
INA216A4				0.03	±0.2	%
vs Temperature				0.076	0.3	m%/°C
Nonlinearity Error				±0.01		%
Maximum Capacitive Load		No sustained oscillation		750		pF
VOLTAGE OUTPUT <sup>(3)</sup>		$R_L = 10k\Omega$ to GND				
Swing to V+ Power-Supply Rail				(V+) -0.1	(V+) -0.3	٧
Swing to GND <sup>(3)</sup>				(V <sub>GND</sub> ) +0.001	(V <sub>GND</sub> ) +0.002	٧
Output Impedance				42		Ω
FREQUENCY RESPONSE						
Bandwidth	BW	C <sub>LOAD</sub> = 10pF				
INA216A1		·		20		kHz
INA216A2				10		kHz
INA216A3				5		kHz
INA216A4				2.5		kHz

 <sup>(1)</sup> RTI: Referred-to-input.
 (2) CMRR and PSRR are the same because V<sub>CM</sub> is the supply voltage.
 (3) See Typical Characteristics graph, *Output Swing to Rail* (Figure 9).



# **ELECTRICAL CHARACTERISTICS (continued)**

**Boldface** limits apply over the specified temperature range,  $T_A = -40^{\circ}C$  to +125°C. At  $T_A = +25^{\circ}C$  and  $V_{CM} = V_{IN+} = 4.2V$ , unless otherwise noted.

PARAMETER		CONDITIONS	MIN	N TYP MAX		UNIT	
FREQUENCY RESPONSE, cont	inued						
Slew Rate	SR			0.03		V/µs	
NOISE, RTI <sup>(4)</sup>							
Voltage Noise Density				60		nV/√ <del>Hz</del>	
POWER SUPPLY							
Specified Range	V <sub>IN+</sub>		+1.8		+5.5	V	
Quiescent Current	IQ			13	25	μA	
Over Temperature					30	μ <b>Α</b>	
TURN-ON TIME		$V_{IN+} = 0 \text{ to } +2.5 \text{V}; V_{SENSE} = 10 \text{mV}; V_{OUT} \pm 0.5\%$		200		μs	
TEMPERATURE RANGE						•	
Specified Temperature Range			-40		+125	°C	

<sup>(4)</sup> RTI: Referred-to-input.



#### TYPICAL CHARACTERISTICS

The INA216A1 is used for typical characteristic measurements at  $T_A = +25$ °C,  $V_S = +4.2$ V, unless otherwise noted.

#### INPUT OFFSET VOLTAGE PRODUCTION DISTRIBUTION

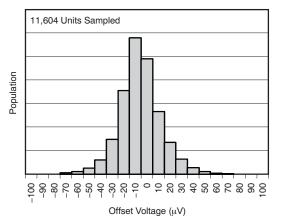


Figure 1.

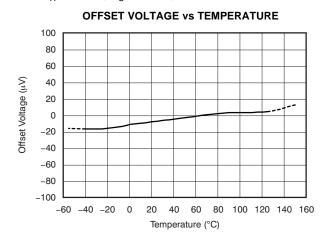


Figure 2.

#### **COMMON-MODE REJECTION RATIO vs TEMPERATURE**

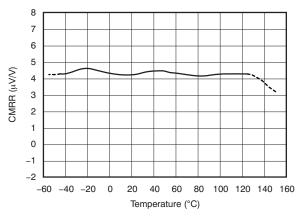


Figure 3.

#### **GAIN ERROR vs TEMPERATURE**

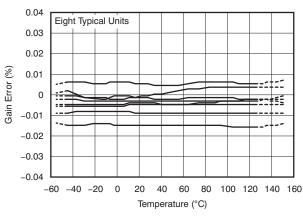


Figure 4.

#### QUIESCENT CURRENT AND NEGATIVE INPUT BIAS CURRENT vs TEMPERATURE

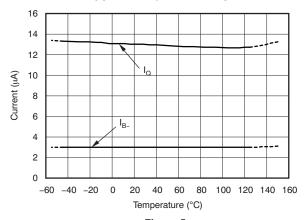


Figure 5.

#### **GAIN vs FREQUENCY**

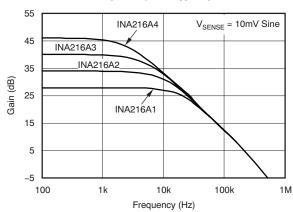


Figure 6.

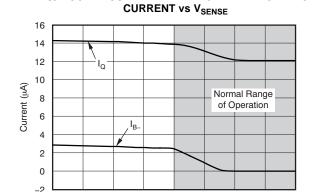


#### **TYPICAL CHARACTERISTICS (continued)**

The INA216A1 is used for typical characteristic measurements at  $T_A = +25$ °C,  $V_S = +4.2$ V, unless otherwise noted.

# COMMON-MODE REJECTION RATIO vs FREQUENCY 140 120 100 60 40 20 0 1 10 100 1k 10k 100k

Frequency (Hz) **Figure 7.** 



QUIESCENT CURRENT AND NEGATIVE INPUT BIAS

V<sub>SENSE</sub> (mV) **Figure 8.** 

0

0.1

0.2

0.3

0.4

-0.3

-0.4

-0.2

0.1

#### **OUTPUT VOLTAGE SWING vs OUTPUT CURRENT**

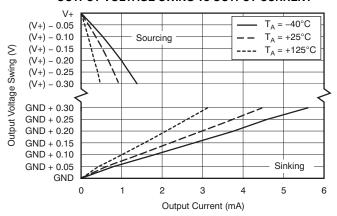


Figure 9.

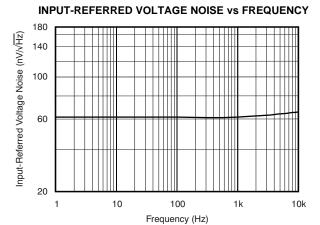


Figure 10.

# 0.1Hz to 10Hz VOLTAGE NOISE, RTI

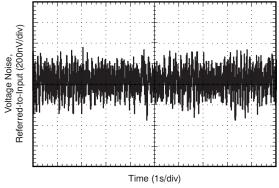


Figure 11.

# STEP RESPONSE (80mV<sub>PP</sub> Input Step)

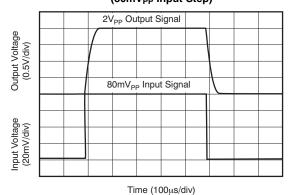


Figure 12.



# TYPICAL CHARACTERISTICS (continued)

The INA216A1 is used for typical characteristic measurements at  $T_A = +25$ °C,  $V_S = +4.2$ V, unless otherwise noted.

#### **COMMON-MODE VOLTAGE TRANSIENT RESPONSE**

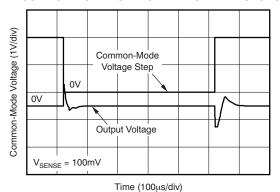
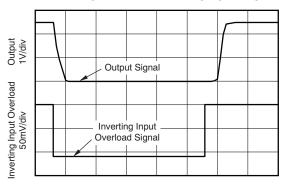


Figure 13.

#### **INVERTING DIFFERENTIAL INPUT OVERLOAD**



Time (100μs/div) Figure 14.

NONINVERTING DIFFERENTIAL INPUT OVERLOAD

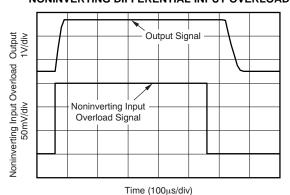
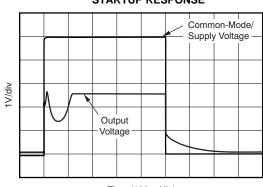


Figure 15.

#### STARTUP RESPONSE



Time (100μs/div)

Figure 16.

BROWNOUT RECOVERY

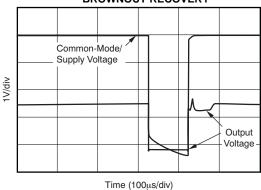


Figure 17.



#### **APPLICATION INFORMATION**

#### **Basic Connections**

Figure 18 shows the basic connections of the INA216. The input pins, IN+ and IN-, should be connected as closely as possible to the shunt resistor to minimize any resistance in series with the shunt resistance.

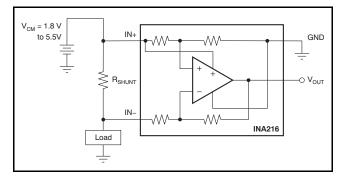


Figure 18. Typical Application

Figure 19 illustrates the INA216 connected to a shunt resistor with additional trace resistance in series with the shunt placed between where the current shunt monitors the input pins. With the typically low shunt resistor values commonly used in these applications, even small amounts of additional impedance in series with the shunt resistor can significantly affect the differential voltage present at the INA216 input pins.

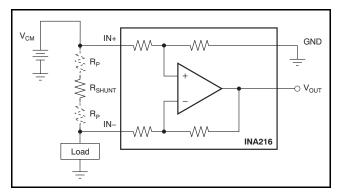


Figure 19. Shunt Resistance Measurement Including Trace Resistance, R<sub>P</sub>

Figure 20 shows a proper Kelvin, or four-wire, connection of the shunt resistor to the INA216 input pins. This connection helps ensure that the only impedance between the current monitor input pins is the shunt resistor.

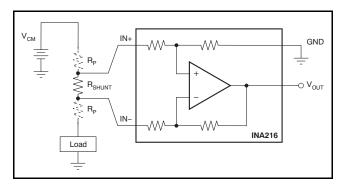


Figure 20. Shunt Resistance Measurement Using a Kelvin Connection

# **Power Supply**

The INA216 does not have a dedicated power-supply pin. Instead, an internal connection to the IN+ pin serves as the power supply for this device. Because the INA216 is powered from the IN+ pin, the common-mode input range is limited on the low end to 1.8V. Therefore, the INA216 cannot be used as a low-side current shunt monitor.

#### Selecting R<sub>s</sub>

The selection of the value of the shunt resistor (R<sub>S</sub>) to use with the INA216 is based on the specific operating conditions and requirements of the application. The starting point for selecting the resistor is to first determine the desired full-scale output from the INA216. The INA216 is available in four gain options: 25, 50, 100, and 200. By dividing the desired full-scale output by each of the gain options, there are then four available differential input voltages that can achieve the desired full-scale output voltage, given that the appropriate gain device is used. With four values for the total voltage that is to be dropped across the shunt, the decision on how much of a drop is allowed in the application must be made. Most applications have a maximum drop allowed to ensure that the load receives the required voltage necessary to operate. Assuming that there are now multiple shunt voltages that are acceptable (based on the design criteria), the choice of what value shunt resistor to use can be made based on accuracy. As a result of the INA216 auto-zero architecture, the input offset voltage is extremely low. However, even the 100µV maximum input offset voltage specification plays a role in the decision of which shunt resistor value to choose. With a larger shunt voltage present at the current shunt monitor input, less error is introduced by the input offset voltage.



These comments have framed the decision on what the shunt resistor value should be, based on the full-scale value; but many applications require accurate measurements at levels as low as 10% of the full-scale value. At this level, the input offset voltage of the current shunt monitor becomes a larger percentage of the shunt voltage, and thus contributes a larger error to the output. The percentage of error created by the input offset voltage relative to the shunt voltage is shown in Equation 1.

$$Error_{V_{OS}} = \frac{V_{OS}}{V_{SENSE}} \cdot 100$$
 (1)

Ideally, the differential input voltage at 10% would be increased to minimize the effects of the input offset voltage; however, we are bound by the full-scale value. The full-scale output voltage on the INA216 is limited to 200mV below the supply voltage (IN+). Selecting a shunt resistor to increase the shunt voltage at the low operating range of the load current could easily saturate the output of the current shunt monitor at the full-scale load current. For applications where accuracy over a larger range is needed, a lower gain option (and therefore, a larger differential input voltage) is selected. For applications where a minimal voltage drop on the line that powers the load is required, a higher gain option (and so, a smaller differential input voltage) is selected.

For example, consider a design that requires a full-scale output voltage of 4V, a maximum load current of 10A, and a maximum voltage drop on the common-mode line of 25mV. The 25mV maximum voltage drop requirement and a 4V full-scale output limits the gain option to the 200V/V device. A 100V/V setting would require a maximum voltage drop of 40mV with the other two lower gain versions creating larger voltage drops. Based on the gain of 200 on a 4V full-scale output, the maximum differential input voltage would be 20mV. The shunt resistor needed to create a 20mV drop with a 10A load current is  $2m\Omega$ .

When choosing the proper shunt resistor, it is also important to consider that at higher currents, the power dissipation in the shunt resistor becomes greater. Therefore, it is important to evaluate the drift of the sense resistor as a result of power dissipation, and choose an appropriate resistor based on its power wattage rating.

#### **Calculating Total Error**

The electrical specifications for the INA216 include the typical individual errors terms such as gain error, offset error, and nonlinearity error. Total error including all of these individual error components is not specified in the *Electrical Characteristics* table. To accurately calculate the error that can be expected from the device, we must first know the operating conditions to which the device is subjected. Some current shunt monitors specify a total error in the product data sheet. However, this total error term is accurate under only one particular set of operating conditions. Specifying the total error at this one point has little practical value, though, because any deviation from these specific operating conditions no longer yields the same total error value. This section discusses the individual error sources. information on how to apply them in order to calculate the total error value for the device under normal operating conditions.

The typical error sources that have the largest impact on the total error of the device are input offset voltage, common-mode voltage rejection, gain error, and nonlinearity error.

The nonlinearity error of the INA216 is relatively low compared to the gain error specification, which results in a gain error that can be expected to be relatively constant throughout the linear input range of the device. While the gain error remains constant across the linear input range of the device, the error associated with the input offset voltage does not. As the differential input voltage developed across a shunt resistor at the input of the INA216 decreases, the inherent input offset voltage of the device becomes a larger percentage of the measured input signal, resulting in an increase in measurement error. This varying error is present among all current shunt monitors, given the input offset voltage ratio to the voltage being sensed by the device. The low input offset voltages present in the INA216 devices, however, limit the amount of contribution the offset voltage has on the total error term.

Two examples are provided that detail how different operating conditions can affect the total error calculations. Typical and maximum calculations are shown as well to provide the user more information on how much error variance could be present from device to device.



# Example 1

Conditions: INA216A3;  $V_{CM} = V_S = 3.3V$ ;  $V_{SENSE} = 20mV$ 

Table 1. Example 1

TERM	LABEL	EQUATION	TYPICAL	MAXIMUM
Maximum initial input offset voltage	VIO	_	20μV	75μV
Added input offset voltage as result of common-mode voltage	VIO_CM	$\frac{1}{10^{\left(\frac{\text{CMRR dB}}{20}\right)}} \bullet  4.2\text{V} - \text{V}_{\text{CM}} $	3.6µV	28μV
Total input offset voltage	VIO_Total	$\sqrt{\left(\text{VIO}\right)^2 + \left(\text{VIO\_CM}\right)^2}$	20μV	80μV
Error because of input offset voltage	Error_VIO	VIO_Total V <sub>SENSE</sub> ◆100	0.1%	0.4%
Gain error	Error_Gain	_	0.06%	0.2%
Nonlinearity error	Error_Lin	_	0.01%	0.01%
Total error		$\sqrt{\left(\text{Error\_VIO}\right)^2 + \left(\text{Error\_Gain}\right)^2 + \left(\text{Error\_Lin}\right)^2}$	0.12%	0.45%

# Example 2

Conditions: INA216A1;  $V_{CM} = V_S = 5V$ ;  $V_{SENSE} = 160 mV$ 

Table 2. Example 2

		rabio II Inampio I		
TERM	LABEL	EQUATION	TYPICAL	MAXIMUM
Maximum initial input offset voltage	VIO	_	30μV	100μV
Added input offset voltage as result of common-mode voltage		$\frac{1}{10^{\left(\frac{\text{CMRR}_dB}{20}\right)}} \cdot  4.2\text{V} - \text{V}_{\text{CM}} $	3.1μV	25.2μV
Total input offset voltage	VIO_Total	$\sqrt{\left(\text{VIO}\right)^2 + \left(\text{VIO\_CM}\right)^2}$	30μV	100μV
Error because of input offset voltage	Error_VIO	VIO_Total V <sub>SENSE</sub> • 100	0.02%	0.06%
Gain error	Error_Gain	_	0.01%	0.2%
Nonlinearity error	Error_Lin	_	0.01%	0.01%
Total error		$\sqrt{(\text{Error_VIO})^2 + (\text{Error_Gain})^2 + (\text{Error_Lin})^2}$	0.025%	0.21%



#### Input Filtering

An ideal location where filtering is implemented is at the inputs for a device. Placing an input filter in front of the INA216, though, is not recommended but can be implemented if it is determined to be necessary. This location is not recommended for filtering because adding input filters induces an additional gain error to the device that can easily exceed the device maximum gain error specification of 0.2%. In the INA216, the nominal current into the IN+ pin is in the range of 13µA while the bias current into the INpin is in the range of approximately 3µA. The current flowing into the IN+ pin includes both the input bias current as well as the quiescent current. Where the issue of input filtering begins to become more of an issue is that as the guiescent current of the INA216 also flows through the IN+ pin, when the output begins to drive current, this additional current also flows through the IN+ pin, creating an even larger error.

Placing a typical common-mode filter of  $10\Omega$  in series with each input and a  $0.1\mu F$  capacitor across the input pins, as shown in Figure 21, introduces an additional gain error into the system. For example, consider an application using the INA216A3 with a full-scale output of 4V, assuming that the device is not driving any output current. The shunt voltage needed to create the 4V output with a gain of 100 is 40mV. With  $10\Omega$  filter resistors on each input, there is a difference voltage created that subtracts from the 40mV full-scale differential current. The error can be calculated using Equation 2.

Error\_
$$R_{FILTER} = \frac{(I_{IN+} - I_{IN-}) \cdot R_{FILTER}}{V_{SHUNT}} \cdot 100$$
 (2)

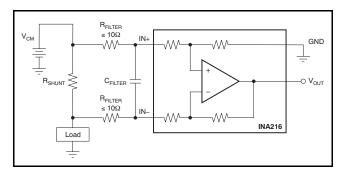


Figure 21. Input Filter

As mentioned previously, the current flowing into the IN+ pin increases once the output begins to drive current because of the quiescent current also flowing into the IN+ pin. The previous example resulted in an additional gain error of 0.3% as a result of the  $10\Omega$  filter resistors (assuming the output stage was not

driving any current). Connecting a  $100k\Omega$  load to the 4V output now increases the current by an additional  $40\mu A$ . This increase in current flowing through the IN+ pin would change the additional gain error from 0.3% to 1.3%.

If filtering is required for the application and the gain error introduced by the input filter resistors exceeds the available error budget for this circuit, a filter can be implemented following the INA216. Placing a filter at the output of the current shunt monitor is not typically the ideal location because the benefit of the low impedance output of the amplifier is lost. Applications that require the low impedance output require an additional buffer amplifier that follows the post current shunt monitor filter.

#### Using the INA216 With Transients Above 5.5V

With a small amount of additional circuitry, INA216 can be used in circuits subject to transients higher than 5.5V. Use only zener diode or zener-type transient absorbers, which are sometimes referred to as Transzorbs. Any other type of transient absorber has an unacceptable time delay. To use these protection devices, resistors are required in series with the INA216 inputs, as shown in Figure 22. These resistors serve as a working impedance for the zener. It is desirable to keep these resistors as small as possible because of the error described in the Input Filtering section. These protection resistors are most often around  $10\Omega$ . Larger values can be used with a greater impact to the total gain error. Because this circuit limits only short-term transients, many applications are satisfied with a 10Ω resistor along with conventional zener diodes of the lowest power rating that can be found. This combination uses the least amount of board space. These diodes can be found in packages as small as SOT-523 or SOD-523. The use of these protection components may allow the INA216 to survive from being damaged in environments where large transients are common.

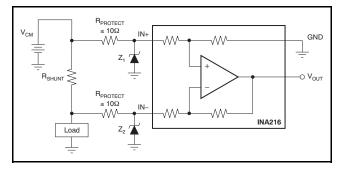


Figure 22. Transient Protection Using Dual Zener Diodes



# **REVISION HISTORY**

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

CI	hanges from Revision B (June 2010) to Revision C	Page
•	Changed product status from Mixed Status to Production Data	1
•	Updated Package Information table to include RSW package information	<mark>2</mark>
•	Added Thermal Information table for RSW package	3
<u>.</u>	Added RSW package pinout drawing	3
CI	hanges from Revision A (June, 2010) to Revision B	Page
•	Removed product preview status of INA216A2, INA216A3, and INA216A4 devices	2
•	Added offset voltage specifications for INA216A2, INA216A3, and INA216A4	4
•	Added gain and gain error specifications for INA216A2, INA216A3, and INA216A4	4
•	Added bandwidth specifications for INA216A2, INA216A3, and INA216A4	4
•	Updated graph grid for Figure 2 through Figure 5	6
•	Revised Table 1 and Table 2	
•	Changed description of nominal current into IN+ pin to 13µA and bias current into IN- pin to 3µA	12

Product Folder Link(s): INA216

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7-Oct-2025

# **PACKAGING INFORMATION**

Orderable part number	Status (1)	Material type	Package   Pins	Package qty   Carrier	<b>RoHS</b> (3)	Lead finish/ Ball material	MSL rating/ Peak reflow	Op temp (°C)	Part marking (6)
INA216A1RSWR	Active	Production	UQFN (RSW)   10	3000   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	SNJ
INA216A1RSWR.A	Active	Production	UQFN (RSW)   10	3000   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	SNJ
INA216A1RSWT	Obsolete	Production	UQFN (RSW)   10	-	-	Call TI	Call TI	-40 to 125	SNJ
INA216A1YFFR	Active	Production	DSBGA (YFF)   4	3000   LARGE T&R	Yes	SNAGCU	Level-1-260C-UNLIM	-40 to 125	OW
INA216A1YFFR.A	Active	Production	DSBGA (YFF)   4	3000   LARGE T&R	Yes	SNAGCU	Level-1-260C-UNLIM	-40 to 125	OW
INA216A2RSWR	Active	Production	UQFN (RSW)   10	3000   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	SOJ
INA216A2RSWR.A	Active	Production	UQFN (RSW)   10	3000   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	SOJ
INA216A2RSWRG4	Active	Production	UQFN (RSW)   10	3000   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	SOJ
INA216A2RSWRG4.A	Active	Production	UQFN (RSW)   10	3000   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	SOJ
INA216A2RSWT	Active	Production	UQFN (RSW)   10	250   SMALL T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	SOJ
INA216A2RSWT.A	Active	Production	UQFN (RSW)   10	250   SMALL T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	SOJ
INA216A2YFFR	Active	Production	DSBGA (YFF)   4	3000   LARGE T&R	Yes	SNAGCU	Level-1-260C-UNLIM	-40 to 125	OX
INA216A2YFFR.A	Active	Production	DSBGA (YFF)   4	3000   LARGE T&R	Yes	SNAGCU	Level-1-260C-UNLIM	-40 to 125	OX
INA216A2YFFR.B	Active	Production	DSBGA (YFF)   4	3000   LARGE T&R	Yes	SNAGCU	Level-1-260C-UNLIM	-40 to 125	OX
INA216A2YFFT	Last Time Buy	Production	DSBGA (YFF)   4	250   SMALL T&R	Yes	SNAGCU	Level-1-260C-UNLIM	-40 to 125	OX
INA216A3RSWR	Active	Production	UQFN (RSW)   10	3000   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	SPJ
INA216A3RSWR.A	Active	Production	UQFN (RSW)   10	3000   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	SPJ
INA216A3RSWRG4	Active	Production	UQFN (RSW)   10	3000   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	SPJ
INA216A3RSWRG4.A	Active	Production	UQFN (RSW)   10	3000   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	SPJ
INA216A3RSWT	Obsolete	Production	UQFN (RSW)   10	-	-	Call TI	Call TI	-40 to 125	SPJ
INA216A3YFFR	Active	Production	DSBGA (YFF)   4	3000   LARGE T&R	Yes	SNAGCU	Level-1-260C-UNLIM	-40 to 125	OY
INA216A3YFFR.A	Active	Production	DSBGA (YFF)   4	3000   LARGE T&R	Yes	SNAGCU	Level-1-260C-UNLIM	-40 to 125	OY
INA216A3YFFR.B	Active	Production	DSBGA (YFF)   4	3000   LARGE T&R	Yes	SNAGCU	Level-1-260C-UNLIM	-40 to 125	OY
INA216A4RSWR	Active	Production	UQFN (RSW)   10	3000   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	SQJ
INA216A4RSWR.A	Active	Production	UQFN (RSW)   10	3000   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	SQJ
INA216A4RSWRG4	Active	Production	UQFN (RSW)   10	3000   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	SQJ
INA216A4RSWRG4.A	Active	Production	UQFN (RSW)   10	3000   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	SQJ
INA216A4YFFR	Active	Production	DSBGA (YFF)   4	3000   LARGE T&R	Yes	SNAGCU	Level-1-260C-UNLIM	-40 to 125	OZ



7-Oct-2025



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Orderable part number	Status	Material type	Package   Pins	Package qty   Carrier	RoHS	Lead finish/ Ball material	MSL rating/ Peak reflow	Op temp (°C)	Part marking
						(4)	(5)		
INA216A4YFFR.A	Active	Production	DSBGA (YFF)   4	3000   LARGE T&R	Yes	SNAGCU	Level-1-260C-UNLIM	-40 to 125	OZ
INA216A4YFFR.B	Active	Production	DSBGA (YFF)   4	3000   LARGE T&R	Yes	SNAGCU	Level-1-260C-UNLIM	-40 to 125	OZ
INA216A4YFFT	Last Time Buy	Production	DSBGA (YFF)   4	250   SMALL T&R	Yes	SNAGCU	Level-1-260C-UNLIM	-40 to 125	OZ
INA216A4YFFT.B	NRND	Production	DSBGA (YFF)   4	250   SMALL T&R	Yes	SNAGCU	Level-1-260C-UNLIM	-40 to 125	OZ

(3) RoHS values: Yes, No, RoHS Exempt. See the TI RoHS Statement for additional information and value definition.

- (4) Lead finish/Ball material: Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.
- (5) MSL rating/Peak reflow: The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.
- (6) Part marking: There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

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# TAPE AND REEL INFORMATION





A0	Dimension designed to accommodate the component width
В0	Dimension designed to accommodate the component length
K0	Dimension designed to accommodate the component thickness
W	Overall width of the carrier tape
P1	Pitch between successive cavity centers

#### QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



#### \*All dimensions are nominal

Device	Package Type	Package Drawing		SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
INA216A1RSWR	UQFN	RSW	10	3000	180.0	8.4	1.7	2.1	0.7	4.0	8.0	Q1
INA216A1YFFR	DSBGA	YFF	4	3000	180.0	8.4	0.85	0.85	0.64	4.0	8.0	Q1
INA216A2RSWR	UQFN	RSW	10	3000	180.0	8.4	1.7	2.1	0.7	4.0	8.0	Q1
INA216A2RSWRG4	UQFN	RSW	10	3000	179.0	8.4	1.7	2.1	0.7	4.0	8.0	Q1
INA216A2RSWT	UQFN	RSW	10	250	180.0	8.4	1.7	2.1	0.7	4.0	8.0	Q1
INA216A2YFFR	DSBGA	YFF	4	3000	180.0	8.4	0.85	0.85	0.64	4.0	8.0	Q1
INA216A2YFFT	DSBGA	YFF	4	250	180.0	8.4	0.85	0.85	0.64	4.0	8.0	Q1
INA216A3RSWR	UQFN	RSW	10	3000	180.0	8.4	1.7	2.1	0.7	4.0	8.0	Q1
INA216A3RSWRG4	UQFN	RSW	10	3000	179.0	8.4	1.7	2.1	0.7	4.0	8.0	Q1
INA216A3YFFR	DSBGA	YFF	4	3000	180.0	8.4	0.85	0.85	0.64	4.0	8.0	Q1
INA216A4RSWR	UQFN	RSW	10	3000	180.0	8.4	1.7	2.1	0.7	4.0	8.0	Q1
INA216A4RSWRG4	UQFN	RSW	10	3000	179.0	8.4	1.7	2.1	0.7	4.0	8.0	Q1
INA216A4YFFR	DSBGA	YFF	4	3000	180.0	8.4	0.85	0.85	0.64	4.0	8.0	Q1
INA216A4YFFT	DSBGA	YFF	4	250	180.0	8.4	0.85	0.85	0.64	4.0	8.0	Q1



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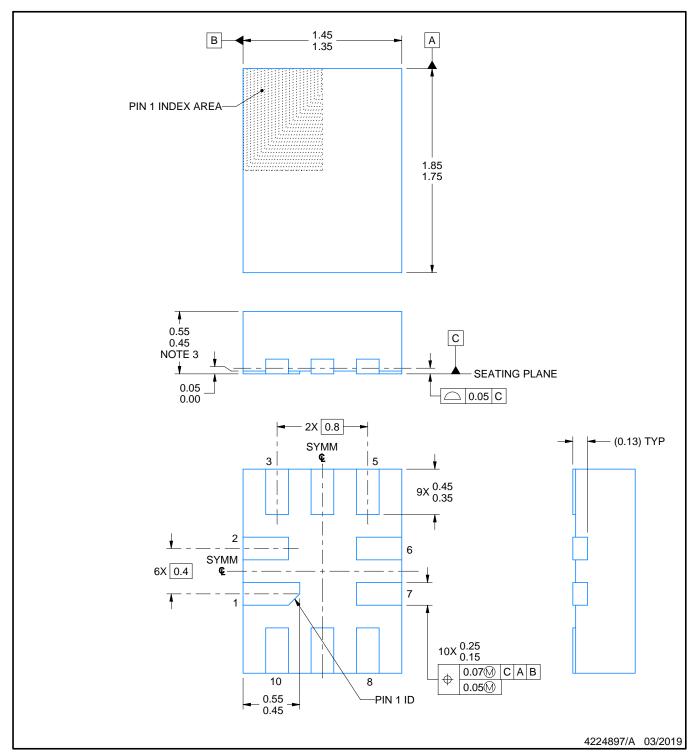


\*All dimensions are nominal

Device	Device Package Type		Pins	SPQ	Length (mm)	Width (mm)	Height (mm)	
INA216A1RSWR	UQFN	RSW	10	3000	210.0	185.0	35.0	
INA216A1YFFR	DSBGA	YFF	4	3000	182.0	182.0	20.0	
INA216A2RSWR	UQFN	RSW	10	3000	210.0	185.0	35.0	
INA216A2RSWRG4	UQFN	RSW	10	3000	200.0	183.0	25.0	
INA216A2RSWT	UQFN	RSW	10	250	210.0	185.0	35.0	
INA216A2YFFR	DSBGA	YFF	4	3000	182.0	182.0	20.0	
INA216A2YFFT	DSBGA	YFF	4	250	182.0	182.0	20.0	
INA216A3RSWR	UQFN	RSW	10	3000	210.0	185.0	35.0	
INA216A3RSWRG4	UQFN	RSW	10	3000	200.0	183.0	25.0	
INA216A3YFFR	DSBGA	YFF	4	3000	182.0	182.0	20.0	
INA216A4RSWR	UQFN	RSW	10	3000	210.0	185.0	35.0	
INA216A4RSWRG4	UQFN	RSW	10	3000	200.0	183.0	25.0	
INA216A4YFFR	DSBGA	YFF	4	3000	182.0	182.0	20.0	
INA216A4YFFT	DSBGA	YFF	4	250	182.0	182.0	20.0	



PLASTIC QUAD FLATPACK - NO LEAD



#### NOTES:

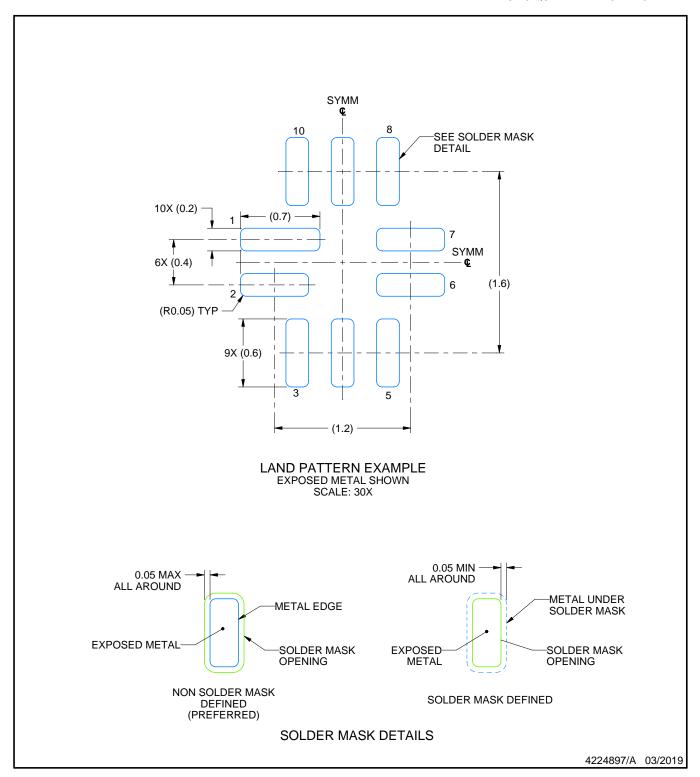
- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.

  2. This drawing is subject to change without notice.

  3. This package complies to JEDEC MO-288 variation UDEE, except minimum package height.



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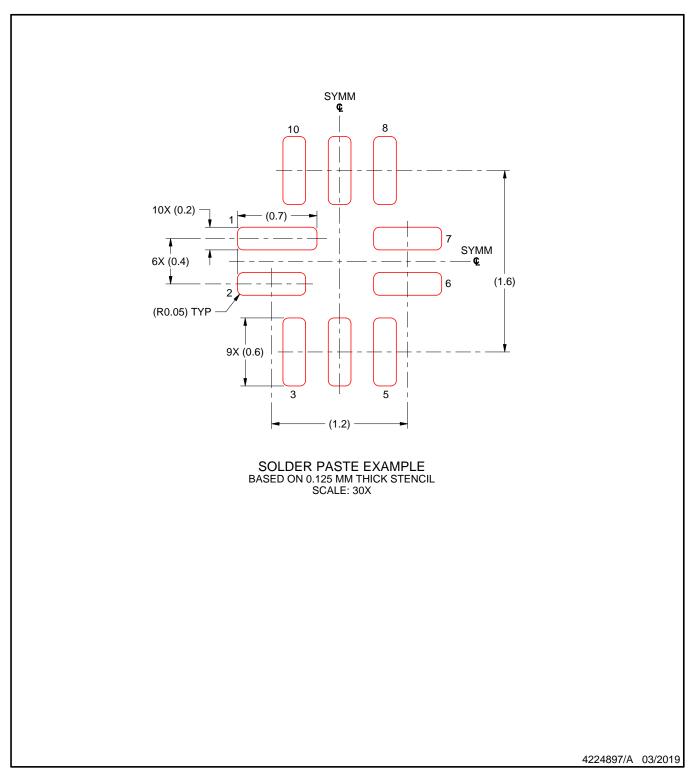


NOTES: (continued)

- 4. This package is designed to be soldered to a thermal pad on the board. For more information, see Texas Instruments literature number SLUA271 (www.ti.com/lit/slua271).
- 5. Vias are optional depending on application, refer to device data sheet. If any vias are implemented, refer to their locations shown on this view. It is recommended that vias under paste be filled, plugged or tented.



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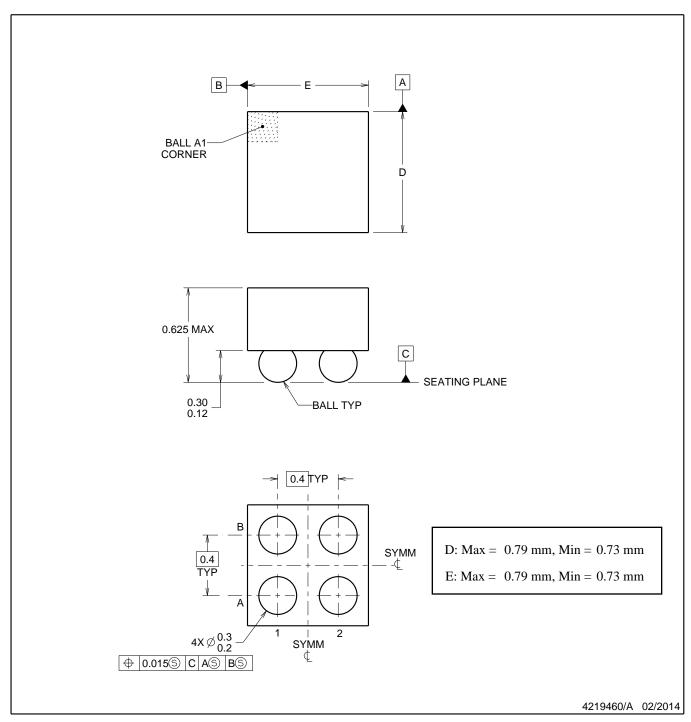
NOTES: (continued)

6. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.





DIE SIZE BALL GRID ARRAY



#### NOTES:

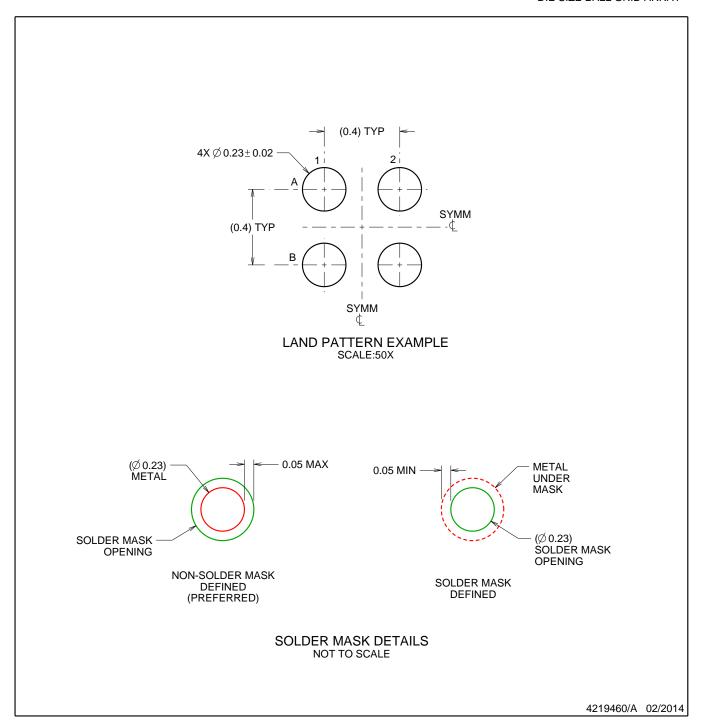
NanoFree Is a trademark of Texas Instruments.

- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.

  2. This drawing is subject to change without notice.
- 3. NanoFree<sup>™</sup> package configuration.



DIE SIZE BALL GRID ARRAY

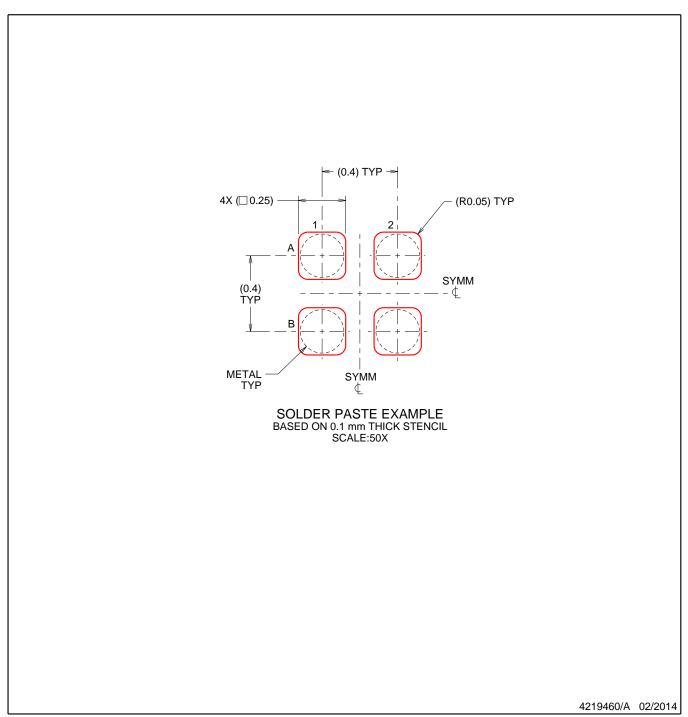


NOTES: (continued)

4. Final dimensions may vary due to manufacturing tolerance considerations and also routing constraints. For more information, see Texas Instruments literature number SBVA017 (www.ti.com/lit/sbva017).



DIE SIZE BALL GRID ARRAY



NOTES: (continued)

5. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release.



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