









BQ25600, BQ25600D

SLUSCJ4B - JUNE 2017 - REVISED MARCH 2022

# BQ25600 and BQ25600D I<sup>2</sup>C Controlled 1-Cell 3.0-A Buck Battery Chargers for High-Input Voltage and NVDC Power Path Management

#### 1 Features

- High-efficiency, 1.5-MHz, synchronous switchmode buck charger
  - 92% charge efficiency at 2-A from 5-V input
  - Optimized for USB voltage input (5 V)
  - Selectable low power pulse frequency modulation (PFM) mode for light load operations
- Supports USB On-The-Go (OTG)
  - Boost converter with up to 1.2-A output
  - 92% boost efficiency at 1-A output
  - Accurate constant current (CC) limit
  - Soft-start up to 500-µF capacitive load
  - Output short circuit protection
  - Low power PFM mode for light load operations
- Single input to support USB input and high voltage adapters
  - Support 3.9-V to 13.5-V input voltage range with 22-V absolute maximum input voltage
  - Programmable input current limit (100 mA) to 3.2 A with 100-mA resolution) to support USB 2.0, USB 3.0 standards and high voltage adaptors (IINDPM)
  - Maximum power tracking by input voltage limit up to 5.4 V (VINDPM)
  - VINDPM threshold automatically tracks battery
  - Auto detect USB SDP, DCP and non-standard adaptors
- High battery discharge efficiency with 19.5-m $\Omega$ battery discharge MOSFET
- Narrow VDC (NVDC) power path management
  - Instant-on works with no battery or deeply discharged battery
  - Ideal diode operation in battery supplement mode
- BATFET control to support ship mode, wake up and full system reset
- Flexible autonomous and I<sup>2</sup>C mode for optimal system performance
- High integration includes all MOSFETs, current sensing and loop compensation

- 17-µA low battery leakage current
- High accuracy
  - ±0.5% charge voltage regulation
  - ±6% at 1.38-A charge current regulation
  - ±10% at 0.9-A Input current regulation
  - Remote battery sensing for fast charge

### 2 Applications

- **Smartphone**
- Mobile phone accessory
- Medical equipment

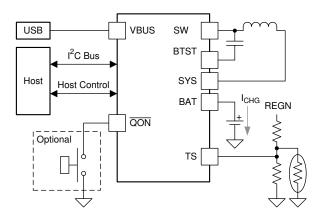
### 3 Description

The BQ25600 and BQ25600D are highly-integrated 3.0-A switch-mode battery charge management and system power path management devices for single cell Li-ion and Li-polymer batteries. The low impedance power path optimizes switch-mode operation efficiency, reduces battery charging time, and extends battery life during discharging phase. The I<sup>2</sup>C serial interface with charging and system settings makes the device a truly flexible solution.

#### **Device Information**

PART NUMBER	PACKAGE <sup>(1)</sup>	BODY SIZE (NOM)		
BQ25600	WCSP (30)	2.00 mm × 2.40 mm		
BQ25600D	WOOF (30)	2.00 111111 ^ 2.40 111111		

For all available packages, see the orderable addendum at the end of the data sheet.



Simplified Application



### **Table of Contents**

1 Features	1	8.5 Programming	31
2 Applications	1	8.6 Register Maps	
3 Description	1	9 Application and Implementation	46
4 Revision History		9.1 Application Information	
5 Description (continued)		9.2 Typical Application	
6 Pin Configuration and Functions	5	10 Power Supply Recommendations	
7 Specifications	8	11 Layout	54
7.1 Absolute Maximum Ratings	8	11.1 Layout Guidelines	54
7.2 ESD Ratings	8	11.2 Layout Example	54
7.3 Recommended Operating Conditions	8	12 Device and Documentation Support	55
7.4 Thermal Information	9	12.1 Device Support	55
7.5 Electrical Characteristics	9	12.2 Receiving Notification of Documentation Updates	55
7.6 Timing Requirements	14	12.3 Support Resources	55
7.7 Typical Characteristics		12.4 Trademarks	55
8 Detailed Description		12.5 Electrostatic Discharge Caution	55
8.1 Overview	17	12.6 Glossary	
8.2 Functional Block Diagram	18	13 Mechanical, Packaging, and Orderable	
8.3 Feature Description	19	Information	56
8.4 Device Functional Modes	27		

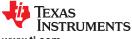
# **4 Revision History**

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

С	nanges from Revision A (August 2017) to Revision B (March 2022)	Page
•	Deleted WEBENCH throughout data sheet	1
•	Deleted V <sub>REGN</sub> MAX values in Electrical Characteristics table	9
•	Added last sentence to Section 8.3.3.5	<mark>21</mark>
•	Changed Figure 8-3	24
•	Changed Figure 8-4	24
•	Added Figure 8-5	
•	Changed Figure 8-6	
•	Added Section 8.4	
•	Changed Figure 8-7	
•	Changed description of exiting shipping mode from QON pin	
•	Added Section 8.5	
•	Changed BQ25600 010 to 011 in Description in Table 8-15	
•	Deleted PG pin in Figure 9-2	
	Added Table 9-1	48
•	Added Table 9-1	
_ C	nanges from Revision * ( June 2017) to Revision A (August 2017)	Page
<u>c</u>	nanges from Revision * (June 2017) to Revision A (August 2017)  Changed data sheet title	Page
<u>c</u>	nanges from Revision * (June 2017) to Revision A (August 2017)	Page1
•	Changed data sheet title	Page1
•	nanges from Revision * (June 2017) to Revision A (August 2017)  Changed data sheet title  Deleted 200 ns Fast Turn-Off in Section 1  Changed Simplified Application schematic.	Page1
•	Changed data sheet title	Page111
•	Changed Simplified Application schematic.  Deleted ACDRV pin references from Pin Functions table.  Changed VAC pin description in Pin Functions table.	Page111
•	Changed data sheet title	Page1
•	Changed data sheet title	Page1
•	Changed data sheet title  Deleted 200 ns Fast Turn-Off in Section 1  Changed Simplified Application schematic.  Deleted ACDRV pin references from Pin Functions table.  Changed VAC pin description in Pin Functions table.  Changed ACDRV pin references to "NC" in Section 6 section.  Deleted ACDRV pin references from Section 7.1 table.  Added Input supply current specification (I <sub>VACVBUS_HIZ</sub> ) in Electrical Characteristics table.  Changed Section 8.2	Page
•	Changed data sheet title  Deleted 200 ns Fast Turn-Off in Section 1  Changed Simplified Application schematic.  Deleted ACDRV pin references from Pin Functions table.  Changed VAC pin description in Pin Functions table.  Changed ACDRV pin references to "NC" in Section 6 section.  Deleted ACDRV pin references from Section 7.1 table.  Added Input supply current specification (I <sub>VACVBUS_HIZ</sub> ) in Electrical Characteristics table.  Changed Section 8.2	Page
••••••	Changed data sheet title Deleted 200 ns Fast Turn-Off in Section 1 Changed Simplified Application schematic. Deleted ACDRV pin references from Pin Functions table. Changed VAC pin description in Pin Functions table. Changed ACDRV pin references to "NC" in Section 6 section. Deleted ACDRV pin references from Section 7.1 table. Added Input supply current specification (I <sub>VACVBUS</sub> HIZ) in Electrical Characteristics table.	Page
••••••	Changed data sheet title  Deleted 200 ns Fast Turn-Off in Section 1  Changed Simplified Application schematic  Deleted ACDRV pin references from Pin Functions table  Changed VAC pin description in Pin Functions table  Changed ACDRV pin references to "NC" in Section 6 section  Deleted ACDRV pin references from Section 7.1 table  Added Input supply current specification (I <sub>VACVBUS_HIZ</sub> ) in Electrical Characteristics table  Changed Section 8.2  Changed Power Up from Input Source section  Deleted Power Up OVPFET section	Page
• • • • • • • • • • • • • • • • • • • •	Changed data sheet title  Deleted 200 ns Fast Turn-Off in Section 1  Changed Simplified Application schematic.  Deleted ACDRV pin references from Pin Functions table.  Changed VAC pin description in Pin Functions table.  Changed ACDRV pin references to "NC" in Section 6 section.  Deleted ACDRV pin references from Section 7.1 table.  Added Input supply current specification (I <sub>VACVBUS_HIZ</sub> ) in Electrical Characteristics table.  Changed Section 8.2  Changed Power Up from Input Source section.	Page



# **BQ25600, BQ25600D** SLUSCJ4B – JUNE 2017 – REVISED MARCH 2022



### www.ti.com

•	Changed Input Overvoltage (ACOV) section	26
	Changed Power Path Management Application schematic	
	Changed BQ25600D Applications Diagram schematic	



### 5 Description (continued)

The BQ25600 and BQ25600D feature fast charging with high input voltage support for a wide range of smartphones, tablets and portable devices. Its input voltage and current regulation and battery remote sensing deliver maximum charging power to the battery. It also integrates a bootstrap diode for the high-side gate drive for simplified system design. The I<sup>2</sup>C serial interface with charging and system settings makes the device a truly flexible solution.

The device supports a wide range of input sources, including standard USB host port, USB charging port, and USB compliant high voltage adapter. The device sets the default input current limit based on the built-in USB interface. To set the default input current limit, the device uses the built-in USB interface, or takes the result from the detection circuit in the system, such as USB PHY device. The device is compliant with the USB 2.0 and USB 3.0 power specs with input current and voltage regulation. The device also meets the USB On-the-Go (OTG) operation power rating specification by supplying 5.15 V on VBUS with a constant current limit up to 1.2 A.

The power path management regulates the system slightly above battery voltage but does not drop below the 3.5-V minimum system voltage (programmable). With this feature, the system maintains operation even when the battery is completely depleted or removed. When the input current limit or voltage limit is reached, the power path management automatically reduces the charge current to zero. As the system load continues to increase, the power path discharges the battery until the system power requirement is met. This Supplement mode prevents overloading the input source.

The device initiates and completes a charging cycle without software control. It senses battery voltage and charges the battery in three phases: pre-conditioning, constant current, and constant voltage. At the end of the charging cycle, the charger automatically terminates when the charge current is below a preset limit and the battery voltage is higher than the recharge threshold. If the fully charged battery falls below the recharge threshold, the charger automatically starts another charging cycle.

The charger provides various safety features for battery charging and system operations including: battery negative temperature coefficient thermistor monitoring, charging safety timer, and overvoltage and overcurrent protections. The thermal regulation reduces charge current when the junction temperature exceeds 110°C (programmable). The STAT output reports charging status and any fault conditions. Other safety features include battery temperature sensing for charge and boost mode, thermal regulation and thermal shutdown, and input UVLO and overvoltage protection. The VBUS\_GD bit indicates if a good power source is present. The INT output immediately notifies the host when a fault occurs.

The device also provides the  $\overline{\text{QON}}$  pin for BATFET enable and reset control to exit low power ship mode or the full system reset function.

The device family is available in a 30-ball, 2.0 mm × 2.4 mm WCSP package.



# **6 Pin Configuration and Functions**

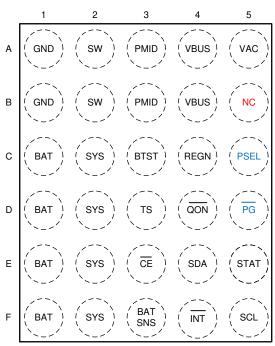


Figure 6-1. BQ25600 YFF Package 30-Pin WCSP Top View

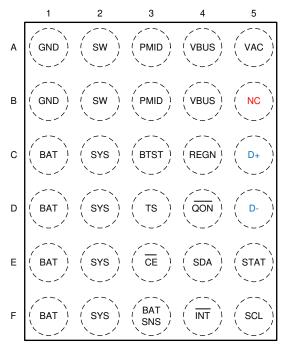


Figure 6-2. BQ25600D YFF Package 30-Pin WCSP Top View



### Table 6-1. Pin Functions

	PIN				
	BQ25600	BQ25600D	TYPE <sup>(1)</sup>	DESCRIPTION	
NAME	WCSP	WCSP			
	C1	C1			
D.4.T.	D1	D1	_	Battery connection point to the positive terminal of the battery pack. The internal	
BAT	E1	E1	P	current sensing resistor is connected between SYS and BAT. Connect a 10 $\mu$ F closely to the BAT pin.	
	F1	F1	-		
BATSNS	F3	F3	AIO	Battery voltage sensing pin for charge current regulation. in order to minimize the parasitic trace resistance during charging, BATSNS pin is connected to the actual battery pack as close as possible.	
BTST	С3	С3	Р	PWM high side driver positive supply. internally, the BTST is connected to the cathode of the boost-strap diode. Connect the $0.047$ - $\mu$ F bootstrap capacitor from SW to BTST.	
CE	E3	E3	DI	Charge enable pin. When this pin is driven low, battery charging is enabled.	
D+	_	C5	AIO	Positive line of the USB data line pair. D+/D- based USB host/charging port detection. The detection includes data contact detection (DCD), primary and secondary detection in BC1.2.	
D–	_	D5	AIO	Negative line of the USB data line pair. D+/D- based USB host/charging port detection. The detection includes data contact detection (DCD), primary and secondary detection BC1.2.	
GND	A1	A1	P	Ground	
OND	B1	B1		Ordand	
ĪNT	F4	F4	DO	Open-drain interrupt Output. Connect the INT to a logic rail through 10-k $\Omega$ resistor. TI INT pin sends active low, 256- $\mu$ s pulse to host to report charger device status and fau	
NC	B5	B5		No connection. This pin must be floating.	
PG	D5	_	DO	Open drain active low power good indicator. Connect to the pull up rail through 10 k $\Omega$	
	A3	A3		Connected to the drain of the reverse blocking MOSFET (RBFET) and the drain of	
PMID	В3	В3	DO  Connected to the drain of the reverse blocking MOSFET (RBFET) and the drain DO HSFET. Given the total input capacitance, put 1 µF on VBUS to GND, and the capacitance on PMID to GND.		
PSEL	C5	_	DI	Power source selection input. High indicates 500 mA input current limit. Low indicates 2.4A input current limit. Once the device gets into host mode, the host can program different input current limit to IINDPM register.	
QON	D4	D4	DI	BATFET enable/reset control input. When BATFET is in ship mode, a logic low of t <sub>SHIPMODE</sub> duration turns on BATFET to exit shipping mode. When VBUS is not plugged–in, a logic low of t <sub>QON_RST</sub> (minimum 8 s) duration resets SYS (system power) by turning BATFET off for t <sub>BATFET_RST</sub> (minimum 250 ms) and then re-enable BATFET to provide full system power reset. The pin contains an internal pull-up to maintain default high logic.	
REGN	C4	C4	Р	PWM low side driver positive supply output. internally, REGN is connected to the anode of the boost-strap diode. Connect a 4.7-µF (10-V rating) ceramic capacitor from REGN to analog GND. The capacitor should be placed close to the IC.	
SCL	F5	F5	DI	$I^2C$ interface clock. Connect SCL to the logic rail through a 10-k $\!\Omega$ resistor.	
SDA	E4	E4	DIO	$I^2C$ interface data. Connect SDA to the logic rail through a 10-k $\!\Omega$ resistor.	
STAT	E5	E5	DO	Open-drain interrupt output. Connect the STAT pin to a logic rail via 10-k $\Omega$ resistor. The STAT pin indicates charger status. Charge in progress: LOW Charge complete or charger in SLEEP mode: HIGH Charge suspend (fault response): Blink at 1Hz	
	A2	A2	_	Switching node connecting to output inductor. Internally SW is connected to the source	
SW	B2	B2	Р	of the n-channel HSFET and the drain of the n-channel LSFET. Connect the 0.047-μF bootstrap capacitor from SW to BTST.	
	C2	C2			
	D2	D2	-	Converter output connection point. The internal current sensing resistor is connected	
SYS	E2	E2	. Р	between SYS and BAT. Connect a 20 µF closely to the SYS pin.	
F2 F2		-			
Thermal Pad	_	_	P	Ground reference for the device that is also the thermal pad used to conduct heat from the device. This connection serves two purposes. The first purpose is to provide an electrical ground connection for the device. The second purpose is to provide a low thermal-impedance path from the device die to the PCB. This pad should be tied externally to a ground plane.	

Table 6-1. Pin Functions (continued)

	Table of Train Caronic (Continuous)						
	PIN						
NAME	BQ25600	BQ25600 BQ25600D		DESCRIPTION			
NAIVIE	WCSP WCSP						
TS	D3	D3	AI	Temperature qualification voltage input to support JEITA profile. Connect a negative temperature coefficient thermistor. Program temperature window with a resistor divider from REGN to TS to GND. Charge suspends when TS pin voltage is out of range. When TS pin is not used, connect a $10\text{-}k\Omega$ resistor from REGN to TS and a $10\text{-}k\Omega$ resistor from TS to GND. It is recommended to use a $103\text{AT-}2$ thermistor.			
VAC	A5	A5	Al	Input voltage sensing. This pin must be tied to VBUS.			
	A4	A4		Charger input voltage. The internal n-channel reverse block MOSFET (RBFET) is			
VBUS	B4	B4	Р	connected between VBUS and PMID with VBUS on source. Place a 1-uF ceramic capacitor from VBUS to GND and place it as close as possible to IC.			

<sup>(1)</sup> Al = Analog input, AO = Analog Output, AIO = Analog input Output, DI = Digital input, DO = Digital Output, DIO = Digital input Output, P = Power



### 7 Specifications

### 7.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted)(1)

	,	MIN	MAX	UNIT
Voltage Range (with respect to GND)	VAC	-2	22	V
Voltage Range (with respect to GND)	VBUS (converter not switching) <sup>(2)</sup>	-2	22	V
Voltage Range (with respect to GND)	BTST, PMID (converter not switching) <sup>(2)</sup>	-0.3	22	V
Voltage Range (with respect to GND)	SW	-2	16	V
Voltage Range (with respect to GND)	BTST to SW	-0.3	7	V
Voltage Range (with respect to GND)	PSEL	-0.3	7	V
Voltage Range (with respect to GND)	D+, D–	-0.3	7	V
Voltage Range (with respect to GND)	BATSNS (converter not switching)	-0.3	7	V
Voltage Range (with respect to GND)	REGN, TS, CE, PG, BAT, SYS (converter not switching)	-0.3	7	V
Output Sink Current	STAT		6	mA
Voltage Range (with respect to GND)	SDA, SCL, ĪNT, QON, STAT	-0.3	7	V
Voltage Range (with respect to GND)	PGND to GND (QFN package only)	-0.3	0.3	V
Output Sink Current	ĪNT		6	mA
Operating junction temperature,	T <sub>J</sub>	-40	150	°C
Storage temperature, T <sub>stg</sub>		-65	150	°C

<sup>(1)</sup> Stresses beyond those listed under Absolute maximum Ratings may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under Recommended Operating Conditions. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability. All voltage values are with respect to the network ground terminal unless otherwise noted.

#### 7.2 ESD Ratings

			VALUE	UNIT
		Human body model (HBM), per ANSI/ ESDA/JEDEC JS-001, all pins <sup>(1)</sup>	±2000	
V <sub>(ESD)</sub>	Electrostatic discharge	Charged device model (CDM), per JEDEC specification JESD22-C101, all pins <sup>(2)</sup>	±250	V

<sup>(1)</sup> JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

### 7.3 Recommended Operating Conditions

		MIN	NOM	MAX	UNIT
V <sub>BUS</sub>	Input voltage	3.9		13.5 <sup>(1)</sup>	V
I <sub>in</sub>	Input current (VBUS)			3.25	Α
I <sub>SWOP</sub>	Output current (SW)			3.25	Α

Submit Document Feedback

<sup>(2)</sup> VBUS is specified up to 22 V for a maximum of one hour at room temperature

<sup>(2)</sup> JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

7.3 Recommended Operating Conditions (continued)

		MIN	NOM	MAX	UNIT
V <sub>BATOP</sub>	Battery voltage			4.624	V
I <sub>BATOP</sub>	Fast charging current			3.0	Α
I <sub>BATOP</sub>	Discharging current (continuous)			6	Α
T <sub>A</sub>	Operating ambient temperature	-40		85	°C

<sup>(1)</sup> The inherent switching noise voltage spikes should not exceed the absolute maximum voltage rating on either the BTST or SW pins. A tight layout minimizes switching noise.

### 7.4 Thermal Information

		BQ25600(D)	
	THERMAL METRIC	YFF (DSBGA)	UNIT
		30 Balls	
$R_{\theta JA}$	Junction-to-ambient thermal resistance	58.8	°C/W
R <sub>θJC(top)</sub>	Junction-to-case (top) thermal resistance	0.2	°C/W
$R_{\theta JB}$	Junction-to-board thermal resistance	8.3	°C/W
$\Psi_{\text{JT}}$	Junction-to-top characterization parameter	1.4	°C/W
$\Psi_{JB}$	Junction-to-board characterization parameter	8.3	°C/W
$R_{\theta JC(bot)}$	Junction-to-case (bottom) thermal resistance	N/A	°C/W

### 7.5 Electrical Characteristics

 $V_{VAC\_UVLOZ} < V_{VAC\_OV}$  and  $V_{VAC\_OV}$  and  $V_{VAC} > V_{BAT} + V_{SLEEP}$ ,  $T_J = -40^{\circ}C$  to 125°C and  $T_J = 25^{\circ}C$  for typical values (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
QUIESCENT C	CURRENTS					
I <sub>ВАТ</sub>	Battery discharge current (BAT, SW, SYS) in buck mode	$V_{BAT}$ = 4.5 V, $V_{BUS}$ < $V_{AC\text{-}UVLOZ}$ , leakage between BAT and VBUS, $T_{J}$ < 85°C			5	μΑ
I <sub>ВАТ</sub>	Battery discharge current (BAT) in buck mode	V <sub>BAT</sub> = 4.5 V, HIZ Mode and OVPFET_DIS = 1 or No VBUS, I2C disabled, BATFET Disabled. T <sub>J</sub> < 85°C		17	33	μΑ
I <sub>BAT</sub>	Battery discharge current (BAT, SW, SYS)	V <sub>BAT</sub> = 4.5 V, HIZ Mode and OVPFET_DIS = 1 or No VBUS, I2C Disabled, BATFET Enabled. T <sub>J</sub> < 85°C		58	85	μΑ
I <sub>VAC_HIZ</sub>	Input supply current (VAC) in buck mode	V <sub>VAC</sub> = 5 V, HIZ Mode and OVPFET_DIS = 1, No battery		24	37	μΑ
		V <sub>VAC</sub> = 12 V, HIZ Mode and OVPFET_DIS = 1, No battery		41	61	μΑ
I <sub>VACVBUS_HIZ</sub>	Input supply current (VAC and VBUS short) in buck mode	V <sub>VAC</sub> = 5 V, HIZ Mode and OVPFET_DIS = 1, No battery		37	50	μΑ
		V <sub>VAC</sub> = 12 V, HIZ Mode and OVPFET_DIS = 1, No battery		68	90	μΑ
	lanut quank querent (VDLIC) in hugh	V <sub>VBUS</sub> = 12 V, V <sub>VBUS</sub> > V <sub>VBAT</sub> , converter not switching		1.5	3	mA
I <sub>VBUS</sub>	Input supply current (VBUS) in buck mode	V <sub>VBUS</sub> > VUVLO, V <sub>VBUS</sub> > V <sub>VBAT</sub> , converter switching, VBAT = 3.8V, ISYS = 0A		3		mA
I <sub>BOOST</sub>	Battery discharge current in boost mode	V <sub>BAT</sub> = 4.2 V, boost mode, I <sub>VBUS</sub> = 0 A, converter switching		3		mA
VBUS, VAC AI	ND BAT PIN POWER-UP	7., ostrono ownorming				



 $V_{VAC\_UVLOZ} < V_{VAC\_OV}$  and  $V_{VAC\_OV}$  and  $V_{VAC} > V_{BAT} + V_{SLEEP}$ ,  $T_J = -40^{\circ}C$  to 125°C and  $T_J = 25^{\circ}C$  for typical values (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
V <sub>BUS OP</sub>	VBUS operating range	V <sub>VBUS</sub> rising	3.9		13.5	V
V <sub>VAC_UVLOZ</sub>	VAC for active I <sup>2</sup> C, no battery Sense VAC pin voltage	V <sub>VAC</sub> rising		3.3	3.7	V
V <sub>VAC_UVLOZ_HYS</sub>	I <sup>2</sup> C active hysteresis	V <sub>AC</sub> falling from above V <sub>VAC_UVLOZ</sub>		300		mV
V <sub>VAC_PRESENT</sub>	REGN turn-on threshold	V <sub>VAC</sub> rising		3.65	3.9	V
VVAC_PRESENT_H YS		V <sub>VAC</sub> falling		500		mV
V <sub>SLEEP</sub>	Sleep mode falling threshold	$(V_{VAC}-V_{VBAT})$ , $V_{BUSMIN\_FALL} \le V_{BAT}$ $\le V_{REG}$ , VAC falling	15	60	131	mV
V <sub>SLEEPZ</sub>	Sleep mode rising threshold	$(V_{VAC}-V_{VBAT}), V_{BUSMIN\_FALL} \le V_{BAT}$ $\le V_{REG}, VAC rising$	115	220	340	mV
V <sub>VAC_OV_RISE</sub>	VAC 6.5-V Overvoltage rising threshold	VAC rising; OVP (REG06[7:6]) = '01'	6.1	6.42	6.75	V
V <sub>VAC_OV_RISE</sub>	VAC 10.5-V Overvoltage rising threshold	VAC rising, OVP (REG06[7:6]) = '10'	10.35	11	11.5	V
V <sub>VAC_OV_RISE</sub>	VAC 14-V Overvoltage rising threshold	VAC rising, OVP (REG06[7:6]) = '11'	13.5	14.2	15	V
V <sub>VAC_OV_HYS</sub>	VAC 6.5-V Overvoltage hysteresis	VAC falling, OVP (REG06[7:6]) = '01'		130		mV
V <sub>VAC_OV_HYS</sub>	VAC 10.5-V Overvoltage hysteresis	VAC falling, OVP (REG06[7:6]) = '10'		250		mV
V <sub>VAC_OV_HYS</sub>	VAC 14-V Overvoltage hysteresis	VAC falling, OVP (REG06[7:6]) = '11'		300		mV
$V_{BAT\_UVLOZ}$	BAT for active I <sup>2</sup> C, no adapter	V <sub>BAT</sub> rising	2.5			V
$V_{BAT\_DPL\_FALL}$	Battery Depletion Threshold	V <sub>BAT</sub> falling	2.18		2.62	V
$V_{BAT\_DPL\_RISE}$	Battery Depletion Threshold	V <sub>BAT</sub> rising	2.34		2.86	V
V <sub>BAT_DPL_HYST</sub>	Battery Depletion rising hysteresis	V <sub>BAT</sub> rising		180		mV
V <sub>BUSMIN_FALL</sub>	Bad adapter detection falling threshold	V <sub>BUS</sub> falling	3.68	3.8	3.9	V
V <sub>BUSMIN_HYST</sub>	Bad adapter detection hysteresis			180		mV
I <sub>BADSRC</sub>	Bad adapter detection current source	Sink current from VBUS to GND		30		mA
POWER-PATH						
V <sub>SYS_MIN</sub>	System regulation voltage	V <sub>VBAT</sub> < SYS_MIN[2:0] = 101, BATFET Disabled (REG07[5] = 1)	3.5	3.68		V
$V_{SYS}$	System Regulation Voltage	$I_{SYS}$ = 0 A, $V_{VBAT}$ > $V_{SYSMIN}$ , $V_{VBAT}$ = 4.400 V, BATFET disabled (REG07[5] = 1)		V <sub>BAT</sub> + 50 mV		V
V <sub>SYS_MAX</sub>	Maximum DC system voltage output	$I_{SYS} = 0 \text{ A}$ , Q4 off, $V_{VBAT} \le 4.400 \text{ V}$ , $V_{VBAT} > V_{SYSMIN} = 3.5 \text{V}$	4.4	4.45	4.48	V
R <sub>ON(RBFET)</sub>	Top reverse blocking MOSFET on-resistance between VBUS and PMID - Q1	-40°C≤ T <sub>A</sub> ≤ 125°C		35		mΩ
R <sub>ON(HSFET)</sub>	Top switching MOSFET on- resistance between PMID and SW - Q2	V <sub>REGN</sub> = 5 V , -40°C≤ T <sub>A</sub> ≤ 125°C		55		mΩ
R <sub>ON(LSFET)</sub>	Bottom switching MOSFET on- resistance between SW and GND - Q3	V <sub>REGN</sub> = 5 V , -40°C≤ T <sub>A</sub> ≤ 125°C		60		mΩ
V <sub>FWD</sub>	BATFET forward voltage in supplement mode			30		mV



 $V_{VAC\_UVLOZ} < V_{VAC} < V_{VAC\_OV}$  and  $V_{VAC} > V_{BAT} + V_{SLEEP}$ ,  $T_J = -40^{\circ}C$  to 125°C and  $T_J = 25^{\circ}C$  for typical values (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
R <sub>ON(BAT-SYS)</sub>	SYS-BAT MOSFET on-resistance	QFN package, Measured from BAT to SYS, V <sub>BAT</sub> = 4.2V, T <sub>J</sub> = -40 - 125°C		19.5		mΩ
BATTERY CHAR	RGER					
V <sub>BATREG_RANGE</sub>	Charge voltage program range		3.856		4.624	V
V <sub>BATREG_STEP</sub>	Charge voltage step			32		mV
$V_{BATREG}$	Charge voltage setting	VREG (REG04[7:3]) = 4.208 V (01011), V, -40 ≤ T <sub>J</sub> ≤ 85°C	4.187	4.208	4.229	V
* BAIREG	onargo voltago cottinig	VREG (REG04[7:3]) = 4.352 V (01111), V, -40 ≤ T <sub>J</sub> ≤ 85°C	4.330	4.352	4.374	V
V <sub>BATREG_ACC</sub>	Charge voltage setting accuracy	$V_{BAT} = 4.208 \text{ V or } V_{BAT} = 4.352 \text{ V},$ -40 \le T <sub>J</sub> \le 85°C	-0.5%		0.5%	
I <sub>CHG_REG_RANGE</sub>	Charge current regulation range		0		3000	mA
I <sub>CHG_REG_STEP</sub>	Charge current regulation step			60		mA
I <sub>CHG_REG</sub>	Charge current regulation setting	I <sub>CHG</sub> = 240 mA, V <sub>VBAT</sub> = 3.1V or V <sub>VBAT</sub> = 3.8 V	0.214	0.24	0.26	Α
I <sub>CHG_REG_ACC</sub>	Charge current regulation accuracy	$I_{CHG}$ = 240 mA, $V_{VBAT}$ = 3.1 V or $V_{VBAT}$ = 3.8 V	-11%		9%	
I <sub>CHG_REG</sub>	Charge current regulation setting	I <sub>CHG</sub> = 720 mA, V <sub>VBAT</sub> = 3.1 V or V <sub>VBAT</sub> = 3.8 V	0.68	0.720	0.76	Α
I <sub>CHG_REG</sub>	Charge current regulation accuracy	$I_{CHG\_REG}$ = 720 mA, $V_{BAT}$ = 3.1 V or $V_{BAT}$ = 3.8 V	-6%		6%	
I <sub>CHG_REG</sub>	Charge current regulation setting	I <sub>CHG</sub> = 1.38 A, V <sub>VBAT</sub> = 3.1 V or V <sub>VBAT</sub> = 3.8 V	1.30	1.380	1.45	Α
I <sub>CHG_REG_ACC</sub>	Charge current regulation accuracy	I <sub>CHG</sub> = 720 mA or I <sub>CHG</sub> = 1.38 A, V <sub>VBAT</sub> = 3.1 V or V <sub>VBAT</sub> = 3.8 V	-6%		6%	
V <sub>BATLOWV_FALL</sub>	Battery LOWV falling threshold	I <sub>CHG</sub> = 240 mA	2.7	2.8	2.9	V
V <sub>BATLOWV_RISE</sub>	Battery LOWV rising threshold	Pre-charge to fast charge	3	3.12	3.24	V
I <sub>PRECHG</sub>	Precharge current regulation	IPRECHG[3:0] = '0010' = 180 mA	150	170	190	mA
I <sub>PRECHG_ACC</sub>	Precharge current regulation accuracy	IPRECHG[3:0] = '0010' = 180 mA	-15		5	%
I <sub>TERM</sub>	Termination current regulation	I <sub>CHG</sub> > 780 mA, ITERM[3:0] = '0010' = 180 mA, V <sub>VBAT</sub> = 4.208 V	145	180	215	mA
I <sub>TERM_ACC</sub>	Termination current regulation accuracy	I <sub>CHG</sub> > 780 mA, , ITERM[3:0] = '0010' = 180 mA, V <sub>VBAT</sub> = 4.208 V	-20%		20%	
I <sub>TERM</sub>	Termination current regulation	I <sub>CHG</sub> ≤ 780 mA, , ITERM[3:0] = '0000' = 60 mA, V <sub>VBAT</sub> = 4.208 V	44	60	75	mA
I <sub>TERM_ACC</sub>	Termination current regulation accuracy	I <sub>CHG</sub> ≤ 780 mA, ,ITERM[3:0] = '0000' = 60 mA, V <sub>VBAT</sub> = 4.208 V	-27%		25%	
V <sub>SHORT</sub>	Battery short voltage	V <sub>VBAT</sub> falling	1.85	2	2.15	V
V <sub>SHORTZ</sub>	Battery short voltage	V <sub>VBAT</sub> rising	2.15	2.25	2.35	V
I <sub>SHORT</sub>	Battery short current	V <sub>VBAT</sub> < V <sub>SHORTZ</sub>	50	90	117	mA
V <sub>RECHG</sub>	Recharge Threshold below V <sub>BAT_REG</sub>	V <sub>BAT</sub> falling, REG04[0] = 0	90	120	150	mV
V <sub>RECHG</sub>	Recharge Threshold below V <sub>BAT_REG</sub>	V <sub>BAT</sub> falling, REG04[0] = 1	200	230	265	mV
I <sub>SYSLOAD</sub>	System discharge load current	V <sub>SYS</sub> = 4.2 V		30		mA
INPUT VOLTAGI	E AND CURRENT REGULATION	-	,		1	
$V_{\text{INDPM}}$	Input voltage regulation limit	V <sub>INDPM</sub> (REG06[3:0] = 0000) = 3.9 V	3.78	3.95	4.1	V



 $V_{VAC\_UVLOZ} < V_{VAC} < V_{VAC\_OV}$  and  $V_{VAC} > V_{BAT} + V_{SLEEP}$ ,  $T_J = -40^{\circ}C$  to 125°C and  $T_J = 25^{\circ}C$  for typical values (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
V <sub>INDPM_ACC</sub>	Input voltage regulation accuracy	V <sub>INDPM</sub> (REG06[3:0] = 0000) = 3.9 V	-4.5%		4%	
V <sub>INDPM</sub>	Input voltage regulation limit	V <sub>INDPM</sub> (REG06[3:0] = 0110) = 4.4 V	4.268	4.4	4.532	V
V <sub>INDPM_ACC</sub>	Input voltage regulation accuracy	V <sub>INDPM</sub> (REG06[3:0] = 0110) = 4.4 V	-3%		3%	
– V <sub>DPM_</sub> VBAT	Input voltage regulation limit tracking VBAT	VINDPM = 3.9V, VDPM_VBAT_TRACK = 300mV, VBAT = 4.0V	4.17	4.3	4.46	V
V <sub>DPM_VBAT_ACC</sub>	Input voltage regulation accuracy tracking VBAT	VINDPM = 3.9V, VDPM_VBAT_TRACK = 300mV, VBAT = 4.0V	-3%		4%	
		$V_{VBUS}$ = 5 V, current pulled from SW, $I_{INDPM}$ (REG[4:0] = 00100) = 500 mA, $-40 \le T_J \le 85^{\circ}$ C	450		500	mA
I <sub>INDPM</sub>	USB input current regulation limit	$V_{VBUS}$ = 5 V, current pulled from SW, IINDPM (REG[4:0] = 01000) = 900 mA, $-40 \le T_J \le 85^{\circ}C$	750		900	mA
		$V_{VBUS}$ = 5 V, current pulled from SW, IINDPM (REG[4:0] = 01110) = 1.5 A, -40 ≤ T <sub>J</sub> ≤ 85°C	1.28		1.5	Α
I <sub>IN_START</sub>	Input current limit during system start-up sequence			200		mA
BAT PIN OVERV	OLTAGE PROTECTION				•	
V <sub>BATOVP_RISE</sub>	Battery overvoltage threshold	V <sub>BAT</sub> rising, as percentage of V <sub>BAT_REG</sub>	103	104	105	%
V <sub>BATOVP_Fall_HYS</sub>	Battery overvoltage falling hysteresis	V <sub>BAT</sub> falling, as percentage of V <sub>BAT_REG</sub>		2		%
THERMAL REG	ULATION AND THERMAL SHUTDOV	VN				
T <sub>JUNCTION_REG</sub>	Junction Temperature Regulation Threshold	Temperature Increasing, TREG (REG05[1] = 1) = 110°C		110		°C
T <sub>JUNCTION_REG</sub>	Junction Temperature Regulation Threshold	Temperature Increasing, TREG (REG05[1] = 0) = 90°C		90		°C
T <sub>SHUT</sub>	Thermal Shutdown Rising Temperature	Temperature Increasing		160		°C
T <sub>SHUT_HYST</sub>	Thermal Shutdown Hysteresis			30		°C
JEITA THERMIS	TOR COMPARATOR (BUCK MODE)					
$V_{T1}$	T1 (0°C) threshold, Charge suspended T1 below this temperature.	Charger suspends charge. As Percentage to V <sub>REGN</sub>	72.4%	73.3%	74.2%	
V <sub>T1</sub>	Falling	As Percentage to V <sub>REGN</sub>	69%	71.5%	74%	
V <sub>T2</sub>	T2 (10°C) threshold, Charge back to I <sub>CHG</sub> /2 and 4.2 V below this temperature	As percentage of V <sub>REGN</sub>	67.2%	68%	69%	
V <sub>T2</sub>	Falling	As Percentage to V <sub>REGN</sub>	66%	66.8%	67.7%	
V <sub>T3</sub>	T3 (45°C) threshold, charge back to ICHG and 4.05V above this temperature.	Charger suspends charge. As Percentage to V <sub>REGN</sub>	43.8%	44.7%	45.8%	
	Falling	As Percentage to V <sub>REGN</sub>	45.1%	45.7%	46.2%	
V <sub>T3</sub>	i aiiiig					
V <sub>T3</sub>	T5 (60°C) threshold, charge suspended above this temperature.	As Percentage to V <sub>REGN</sub>	33.7%	34.2%	35.1%	

Submit Document Feedback

Copyright © 2022 Texas Instruments Incorporated



 $V_{VAC\_UVLOZ} < V_{VAC} < V_{VAC\_OV}$  and  $V_{VAC} > V_{BAT} + V_{SLEEP}$ ,  $T_J = -40^{\circ}C$  to 125°C and  $T_J = 25^{\circ}C$  for typical values (unless otherwise noted)

80% 80.59 79% 79.59 1.2% 32.29 4.4% 34.99 1500 168 1412 166 97% 5.126 5.28	6 6 6 A O KHZ O V 3 %
1.2% 32.29 4.4% 34.99 1500 168 1412 166 97%	6 A 0 kHz 0 kHz 0 V 3 %
1500 168 1412 166 97% 5.126 5.28	6 A 0 kHz 0 kHz 0 V 3 %
1500 168 1412 166 97% 5.126 5.28	A 0 kHz 0 kHz 0 V 3 %
1412 166 97% 5.126 5.28	0 kHz 0 kHz 0 V
1412 166 97% 5.126 5.28	0 kHz 0 kHz 0 V
1412 166 97% 5.126 5.28	0 kHz
1412 166 97% 5.126 5.28	0 kHz
97% 5.126 5.28	0 V
5.126 5.28	3 %
:	3 %
:	3 %
2.8 2.9	
	9 V
3.0 3.1	5 V
2.5 2.	6 V
2.8 2.	9 V
1.4 1.	6 A
0.7	3 A
5.8 6.1	5 V
100	mA
6	V
4.7	V
0.4	4 V
	V
	1 µA
0.4	4 V
	V
	1 µA
0.0	4 V
,	
1.3	5 V
	3.0 3.11 2.5 2.1 2.8 2.1 1.4 1.1 0.7 5.8 6.1 100 6 4.7



 $V_{VAC\_UVLOZ} < V_{VAC} < V_{VAC\_OV}$  and  $V_{VAC} > V_{BAT} + V_{SLEEP}$ ,  $T_J = -40^{\circ}\text{C}$  to 125°C and  $T_J = 25^{\circ}\text{C}$  for typical values (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
I <sub>D+_LKG</sub>	Leakage current into D+	HiZ	-1		1	μΑ
V <sub>D600MVSRC</sub>	Voltage source (600 mV)		500	600	700	mV
I <sub>D100UAISNK</sub>	D– current sink (100 μA)	V <sub>D</sub> _ = 500 mV,	50	100	150	μΑ
R <sub>D19K</sub>	D– resistor to ground (19 kΩ)	V <sub>D</sub> _ = 500 mV,	14.25		24.8	kΩ
V <sub>D0P325</sub>	D– comparator threshold for primary detection	D- pin Rising	250		400	mV
V <sub>D2P8</sub>	D– Threshold for non-standard adapter (combined V2P8_VTH_LO and V2P8_VTH_HI)		2.55		2.85	V
V <sub>D2P0</sub>	D- Comparator threshold for non- standard adapter (For non-standard – same as bq2589x)		1.85		2.15	V
V <sub>D1P2</sub>	D– Threshold for non-standard adapter (combined V1P2_VTH_LO and V1P2_VTH_HI)		1.05		1.35	V
I <sub>DLKG</sub>	Leakage current into D-	HiZ	-1		1	μΑ

<sup>(1)</sup> Specified by design. Not production tested.

# 7.6 Timing Requirements

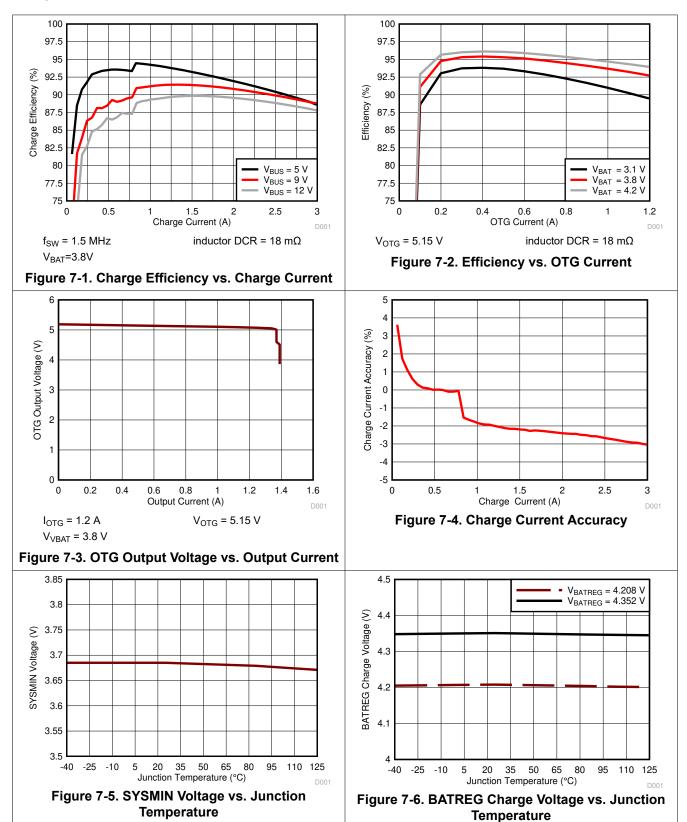
			MIN	NOM	MAX	UNIT
VBUS/BAT P	OWER UP					
t <sub>ACOV</sub>	VAC OVP reaction time	VAC rising above ACOV threshold to turn off Q2		200		ns
t <sub>BADSRC</sub>	Bad adapter detection duration			30		ms
BATTERY CH	IARGER					
t <sub>TERM_DGL</sub>	Deglitch time for charge termination			250		ms
t <sub>RECHG_DGL</sub>	Deglitch time for recharge			250		ms
t <sub>sysovld_dgl</sub>	System over-current deglitch time to turn off Q4			100		μs
t <sub>BATOVP</sub>	Battery over-voltage deglitch time to disable charge			1		μs
t <sub>SAFETY</sub>	Typical Charge Safety Timer Range	CHG_TIMER = 1	8	10	12	hr
t <sub>TOP_OFF</sub>	Typical Top-Off Timer Range	TOP_OFF_TIMER[1:0] = 10 (30 min)	24	30	36	min
QON TIMING						
t <sub>SHIPMODE</sub>	/QON low time to turn on BATFET and exit ship mode	-10°C ≤ T <sub>J</sub> ≤ 60°C	0.9		1.3	S
t <sub>QON_RST_2</sub>	QON low time to reset BATFET	-10°C ≤ T <sub>J</sub> ≤ 60°C	8		12	s
t <sub>BATFET_RST</sub>	BATFET off time during full system reset	-10°C ≤ T <sub>J</sub> ≤ 60°C	250		400	ms
t <sub>SM_DLY</sub>	Enter ship mode delay	-10°C ≤ T <sub>J</sub> ≤ 60°C	10		15	s
DIGITAL CLC	OCK AND WATCHDOG TIMER					
t <sub>WDT</sub>	REG05[4]=1	REGN LDO disabled		40		S
f <sub>LPDIG</sub>	Digital Low Power Clock	REGN LDO disabled		30		kHz
f <sub>DIG</sub>	Digital Clock	REGN LDO enabled		500		kHz
f <sub>SCL</sub>	SCL clock frequency				400	kHz

Submit Document Feedback

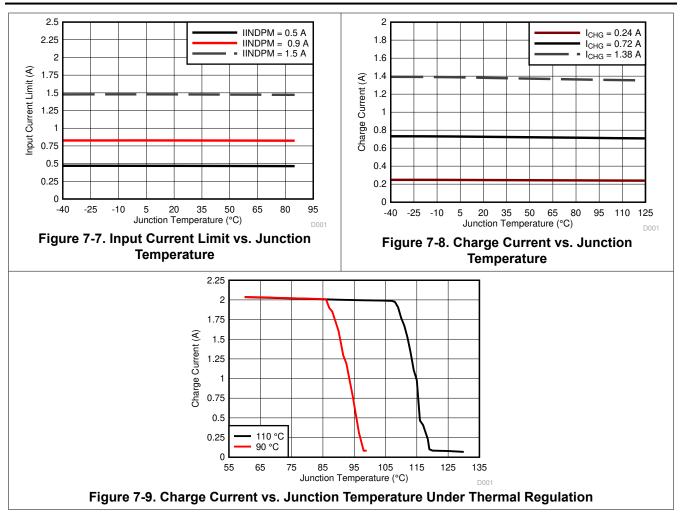
Copyright © 2022 Texas Instruments Incorporated



### 7.7 Typical Characteristics









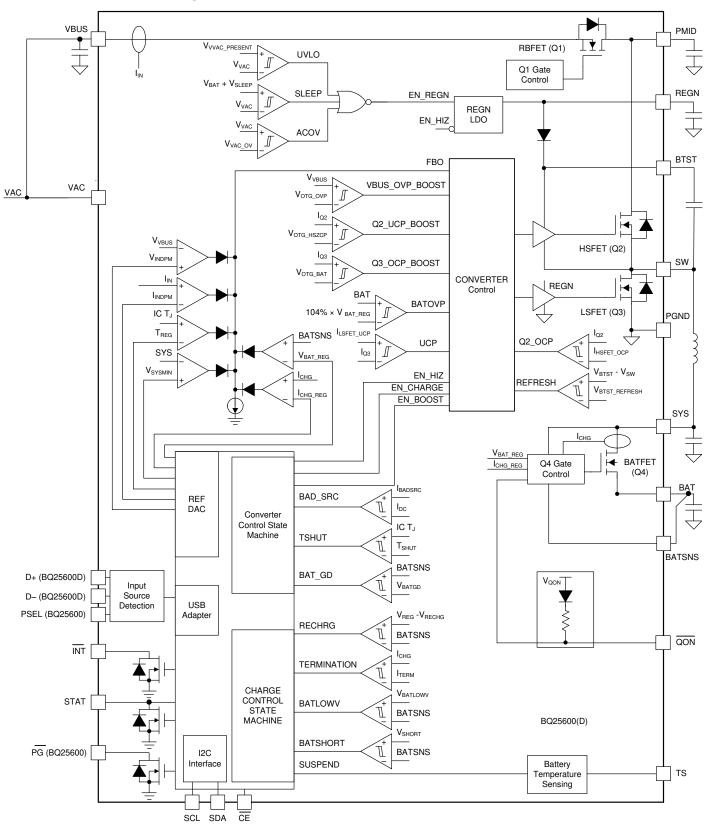
# **8 Detailed Description**

### 8.1 Overview

The BQ25600 and BQ25600D is a highly integrated 3.0-A switch-mode battery charger for single cell Li-ion and Li-polymer batteries. It includes an input reverse-blocking FET (RBFET, Q1), high-side switching FET (HSFET, Q2), low-side switching FET (LSFET, Q3), and battery FET (BATFET, Q4), and bootstrap diode for the high-side gate drive.



### 8.2 Functional Block Diagram





### 8.3 Feature Description

### 8.3.1 Power-On-Reset (POR)

The device powers internal bias circuits from the higher voltage of VBUS and BAT. When VBUS rises above  $V_{VBUS\_UVLOZ}$  or BAT rises above  $V_{BAT\_UVLOZ}$ , the sleep comparator, battery depletion comparator and BATFET driver are active. I<sup>2</sup>C interface is ready for communication and all the registers are reset to default value. The host can access all the registers after POR.

### 8.3.2 Device Power Up from Battery without Input Source

If only battery is present and the voltage is above depletion threshold (V<sub>BAT\_DPL\_RISE)</sub>, the BATFET turns on and connects battery to system. The REGN stays off to minimize the quiescent current. The low RDSON of BATFET and the low quiescent current on BAT minimize the conduction loss and maximize the battery run time.

The device always monitors the discharge current through BATFET (Supplement Mode). When the system is overloaded or shorted ( $I_{BAT} > I_{BATFET\_OCP}$ ), the device turns off BATFET immediately and set BATFET\_DIS bit to indicate BATFET is disabled until the input source plugs in again or one of the methods described in BATFET Enable (Exit Shipping Mode) is applied to re-enable BATFET.

### 8.3.3 Power Up from Input Source

When an input source is plugged in, the device checks the input source voltage to turn on REGN LDO and all the bias circuits. It detects and sets the input current limit before the buck converter is started. The power-up sequence from input source is as listed:

- 1. Power up REGN LDO
- 2. Poor source qualification
- 3. Input source type detection is based on D+/D- or PSEL to set default input current limit (IINDPM) register or input source type.
- 4. Input voltage limit threshold setting (VINDPM threshold)
- 5. Converter power up

#### 8.3.3.1 Power Up REGN Regulation

The REGN LDO supplies internal bias circuits as well as the HSFET and LSFET gate drive. The REGN also provides bias rail to TS external resistors. The pull-up rail of STAT can be connected to REGN as well. The REGN is enabled when all the below conditions are valid:

- V<sub>VAC</sub> above V<sub>VAC\_PRESENT</sub>
- V<sub>VAC</sub> above V<sub>BAT</sub> + V<sub>SI FEPZ</sub> in buck mode or VBUS below V<sub>BAT</sub> + V<sub>SI FEPZ</sub> in boost mode
- · After 220-ms delay is completed

If any one of the above conditions is not valid, the device is in high impedance mode (HIZ) with REGN LDO off. The device draws less than IVBUS\_HIZ from VBUS during HIZ state. The battery powers up the system when the device is in HIZ.

#### 8.3.3.2 Poor Source Qualification

After REGN LDO powers up, the device confirms the current capability of the input source. The input source must meet both of the following requirements in order to start the buck converter.

- VAC voltage below V<sub>VAC OV</sub>
- VBUS voltage above V<sub>VBUSMIN</sub> when pulling I<sub>BADSRC</sub> (typical 30 mA)

Once the input source passes all the conditions above, the status register bit VBUS\_GD is set high and the INT pin is pulsed to signal to the host. If the device fails the poor source detection, it repeats poor source qualification every 2 seconds.

#### 8.3.3.3 Input Source Type Detection

After the VBUS\_GD bit is set and REGN LDO is powered, the device runs input source detection through D+/D-lines or the PSEL pin. The BQ25600D follows the USB Battery Charging Specification 1.2 (BC1.2) to detect input

source (SDP/ DCP) and nonstandard adapter through USB D+/D- lines. The BQ25600 sets input current limit through PSEL pins.

After input source type detection is completed, an INT pulse is asserted to the host. in addition, the following registers and pin are changed:

- 1. Input Current Limit (IINDPM) register is changed to set current limit
- 2. PG STAT bit is set
- 3. VBUS\_STAT bit is updated to indicate USB or other input source

The host can overwrite IINDPM register to change the input current limit if needed. The charger input current is always limited by the IINDPM register.

### 8.3.3.3.1 D+/D- Detection Sets Input Current Limit in BQ25600D

The BQ25600D contains a D+/D- based input source detection to set the input current limit at VBUS plug-in. The D+/D- detection includes standard USB BC1.2 and nonstandard adapter. When input source is plugged in, the device starts standard USB BC1.2 detections. The USB BC1.2 is capable to identify Standard Downstream Port (SDP) and Dedicated Charging Port (DCP). When the Data Contact Detection (DCD) timer expires, the nonstandard adapter detection is applied to set the input current limit. The nonstandard detection is used to distinguish vendor specific adapters (Apple and Samsung) based on their unique dividers on the D+/D- pins. If an adapter is detected as DCP, the input current limit is set at 2.4 A. If an adapter is detected as unknown, the input current limit is set at 500 mA

**Table 8-1. Nonstandard Adapter Detection** 

NONSTANDARD ADAPTER	D+ THRESHOLD	D- THRESHOLD	INPUT CURRENT LIMIT (A)
Divider 1	V <sub>D+</sub> within V <sub>D+ _2p8</sub>	$V_{D-}$ within $V_{D-\_2p0}$	2.1
Divider 2	V <sub>D+</sub> within V <sub>D+ _1p2</sub>	V <sub>D</sub> _ within V <sub>D</sub> 1p2	2
Divider 3	V <sub>D+</sub> within V <sub>D+ _2p0</sub>	V <sub>D</sub> _ within V <sub>D</sub> 2p8	1
Divider 4	V <sub>D+</sub> within V <sub>D+ 2p8</sub>	V <sub>D</sub> within V <sub>D</sub> 2p8	2.4

Table 8-2. Input Current Limit Setting from D+/D- Detection

D+/D- DETECTION	INPUT CURRENT LIMIT (IINLIM)
USB SDP (USB500)	500 mA
USB DCP	2.4 A
Divider 3	1 A
Divider 1	2.1 A
Divider 4	2.4 A
Divider 2	2 A
Unknown 5-V adapter	500 mA

#### 8.3.3.3.2 PSEL Pins Sets Input Current Limit in BQ25600

The BQ25600 has PSEL pin for input current limit setting to interface with USB PHY. It directly takes the USB PHY device output to decide whether the input is USB host or charging port. When the device operates in host-control mode, the host needs to IINDET\_EN bit to read the PSEL value and update the IINDPM register. When the device is in default mode, PSEL value updates IINDPM in real time.

Table 8-3. Input Current Limit Setting from PSEL

INPUT DETECTION	PSEL PIN	INPUT CURRENT LIMIT (ILIM)	VBUS_STAT
USB SDP	High	500 mA	001
Adapter	Low	2.4A	011

Submit Document Feedback

### 8.3.3.4 Input Voltage Limit Threshold Setting (VINDPM Threshold)

The device supports wide range of input voltage limit (3.9 V to 5.4 V) for USB. The device VINDPM is set at 4.5 V. The device supports dynamic VINDPM trackingsettings which tracks the battery voltage. This function can be enabled via the VDPM\_BAT\_TRACK[1:0] register bits. When enabled, the actual input voltage limit will be the higher of the VINDPM register and VBAT + VDPM\_BAT\_TRACK offset.

#### 8.3.3.5 Converter Power Up

After the input current limit is set, the converter is enabled and the HSFET and LSFET start switching. If battery charging is disabled, BATFET turns off. Otherwise, BATFET stays on to charge the battery.

The device provides soft start when system rail is ramped up. When the system rail is below 2.2 V, the input current is limited to is to the lower of 200 mA or IINDPM register setting. After the system rises above 2.2 V, the device limits input current to the value set by IINDPM register.

As a battery charger, the device deploys a highly efficient 1.5 MHz step-down switching regulator. The fixed frequency oscillator keeps tight control of the switching frequency under all conditions of input voltage, battery voltage, charge current and temperature, simplifying output filter design.

The device switches to PFM control at light load or when battery is below minimum system voltage setting or charging is disabled. The PFM\_DIS bit can be used to prevent PFM operation in either buck or boost configuration. PFM mod is only enabled when IINDPM is set  $\geq 500$  mA. When IINDPM is set  $\leq 400$  mA, PFM mode is disabled.

#### 8.3.4 Boost Mode Operation From Battery

The device supports boost converter operation to deliver power from the battery to other portable devices through USB port. The boost mode output current rating meets the USB On-The-Go 500 mA output requirement. The maximum output current is up to 1.2 A. The boost operation can be enabled if the conditions are valid:

- 1. BAT above V<sub>OTG\_BAT</sub>
- 2. VBUS less than BAT+V<sub>SLEEP</sub> (in sleep mode)
- 3. Boost mode operation is enabled (OTG\_CONFIG bit = 1)
- 4. Voltage at TS (thermistor) pin as a percentage of  $V_{REGN}$  is within acceptable range ( $V_{BHOT} < V_{TS} < V_{BCOLD}$ )
- 5. After 30-ms delay from boost mode enable

During boost mode, the status register VBUS\_STAT bits is set to 111, the VBUS output is 5.15 V and the output current can reach up to 1.2 A , selected through  $I^2C$  (BOOST\_LIM bit). The boost output is maintained when BAT is above  $V_{OTG\ BAT}$  threshold.

When OTG is enabled, the device starts up with PFM and later transits to PWM to minimize the overshoot. The PFM\_DIS bit can be used to prevent PFM operation in either buck or boost configuration.

#### 8.3.5 Host Mode and Standalone Power Management

#### 8.3.5.1 Host Mode and Default Mode in BQ25600 and BQ25600D

The BQ25600 and BQ25600D is a host controlled charger, but it can operate in default mode without host management. in default mode, the device can be used as an autonomous charger with no host or while host is in sleep mode. When the charger is in default mode, WATCHDOG\_FAULT bit is HIGH. When the charger is in host mode, WATCHDOG\_FAULT bit is LOW.

After power-on-reset, the device starts in default mode with watchdog timer expired, or default mode. All the registers are in the default settings. During default mode, any change on PSEL pin will make real time IINDPM register changes.

In default mode, the device keeps charging the battery with default 10-hour fast charging safety timer. At the end of the 10-hour, the charging is stopped and the buck converter continues to operate to supply system load.

Writing a 1 to the WD\_RST bit transitions the charger from default mode to host mode. All the device parameters can be programmed by the host. To keep the device in host mode, the host has to reset the watchdog timer by writing 1 to WD\_RST bit before the watchdog timer expires (WATCHDOG\_FAULT bit is set), or disable watchdog timer by setting WATCHDOG bits = 00.

When the watchdog timer expires (WATCHDOG\_FAULT bit = 1), the device returns to default mode and all registers are reset to default values except IINDPM, VINDPM, BATFET\_RST\_EN, BATFET\_DLY, and BATFET DIS bits.

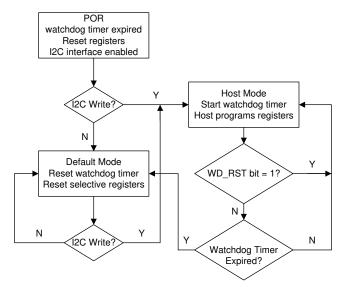


Figure 8-1. Watchdog Timer Flow Chart

#### 8.3.6 Power Path Management

The device accommodates a wide range of input sources from USB, wall adapter, to car charger. The device provides automatic power path selection to supply the system (SYS) from input source (VBUS), battery (BAT), or both.

#### 8.3.7 Battery Charging Management

The device charges 1-cell Li-lon battery with up to 3.0-A charge current for high capacity tablet battery. The  $19.5\text{-m}\Omega$  BATFET improves charging efficiency and minimize the voltage drop during discharging.

### 8.3.7.1 Autonomous Charging Cycle

With battery charging enabled (CHG\_CONFIG bit = 1 and  $\overline{\text{CE}}$  pin is LOW), the device autonomously completes a charging cycle without host involvement. The device default charging parameters are listed in Table 8-4. The host can always control the charging operations and optimize the charging parameters by writing to the corresponding registers through I<sup>2</sup>C.

**Table 8-4. Charging Parameter Default Setting** 

DEFAULT MODE	BQ25600 and BQ25600D
Charging voltage	4.208V
Charging current	2.048 A
Precharge current	180 mA
Termination current	180 mA
Temperature profile	JEITA
Safety timer	10 hours

A new charge cycle starts when the following conditions are valid:

- Converter starts
- Battery charging is enabled (CHG\_CONFIG bit = 1 and I<sub>CHG</sub> register is not 0 mA and CE is low)
- No thermistor fault on TS
- No safety timer fault
- BATFET is not forced to turn off (BATFET\_DIS bit = 0)

The charger device automatically terminates the charging cycle when the charging current is below termination threshold, battery voltage is above recharge threshold, and device not is in DPM mode or thermal regulation. When a fully charged battery is discharged below recharge threshold (selectable through VRECHG bit), the device automatically starts a new charging cycle. After the charge is done, toggle  $\overline{\text{CE}}$  pin or CHG\_CONFIG bit can initiate a new charging cycle.

The STAT output indicates the charging status: charging (LOW), charging complete or charge disable (HIGH) or charging fault (blinking). The STAT output can be disabled by setting EN\_ICHG\_MON bits = 11. in addition, the status register (CHRG\_STAT) indicates the different charging phases: 00-charging disable, 01-precharge, 10-fast charge (constant current) and constant voltage mode, 11-charging done. Once a charging cycle is completed, an INT is asserted to notify the host.

#### 8.3.7.2 Battery Charging Profile

The device charges the battery in five phases: battery short, preconditioning, constant current, constant voltage and top-off trickle charging (optional). At the beginning of a charging cycle, the device checks the battery voltage and regulates current and voltage accordingly.

Table 8-5. Char	ging	Current	Setting	
				ā

V <sub>BAT</sub>	CHARGING CURRENT	REGISTER DEFAULT SETTING	CHRG_STAT
< 2.2 V	I <sub>SHORT</sub>	100 mA	01
2.2 V to 3 V	I <sub>PRECHG</sub>	180 mA	01
> 3 V	I <sub>CHG</sub>	2.048 A	10

If the charger device is in DPM regulation or thermal regulation during charging, the actual charging current will be less than the programmed value. in this case, termination is temporarily disabled and the charging safety timer is counted at half the clock rate.

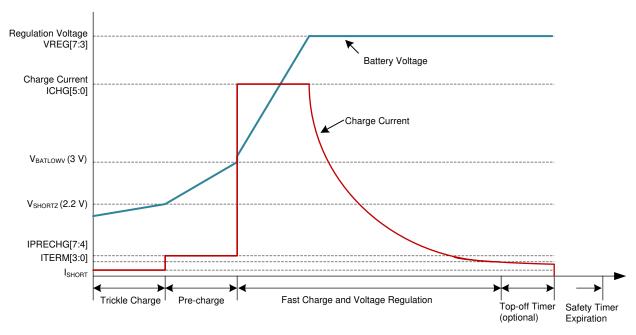


Figure 8-2. Battery Charging Profile

#### 8.3.7.3 Charging Termination

The device terminates a charge cycle when the battery voltage is above recharge threshold, and the current is below termination current. After the charging cycle is completed, the BATFET turns off. The converter keeps running to power the system, and BATFET can turn on again to engage Supplement Mode.

When termination occurs, the status register CHRG\_STAT is set to 11, and an INT pulse is asserted to the host. Termination is temporarily disabled when the charger device is in input current, voltage, or thermal regulation . Termination can be disabled by writing 0 to EN TERM bit prior to charge termination.

At low termination currents, due to the comparator offset, the actual termination current may be 10 mA-20 mA higher than the termination target. in order to compensate for comparator offset, a programmable top-off timer can be applied after termination is detected. The termination timer will follow safety timer constraints, such that if safety timer is suspended, so will the termination timer. Similarly, if safety timer is doubled, so will the termination timer. TOPOFF\_ACTIVE bit reports whether the top off timer is active or not. The host can read CHRG\_STAT and TOPOFF ACTIVE to find out the termination status.

Top off timer gets reset at one of the following conditions:

- 1. Charge disable to enable
- 2. Termination status low to high
- 3. REG\_RST register bit is set

The top-off timer settings are read in once termination is detected by the charger. Programming a top-off timer value after termination will have no effect unless a recharge cycle is initiated. An INT is asserted to the host when entering top-off timer segment as well as when top-off timer expires.

#### 8.3.7.4 Thermistor Qualification

The charger device provides a single thermistor input for battery temperature monitor.

### 8.3.7.5 JEITA Guideline Compliance During Charging Mode

To improve the safety of charging Li-ion batteries, JEITA guideline was released on April 20, 2007. The guideline emphasized the importance of avoiding a high charge current and high charge voltage at certain low and high temperature ranges.

To initiate a charge cycle, the voltage on TS pin must be within the VT1 to VT5 thresholds. If TS voltage exceeds the T1-T5 range, the controller suspends charging and waits until the battery temperature is within the T1 to T5 range.

At cool temperature (T1-T2), JEITA recommends the charge current to be reduced to half of the charge current or lower. At warm temperature (T3-T5), JEITA recommends charge voltage less than 4.1 V.

The charger provides flexible voltage/current settings beyond the JEITA requirement. The voltage setting at warm temperature (T3-T5) can be VREG or 4.1V (configured by JEITA\_VSET). The current setting at cool temperature (T1-T2) can be further reduced to 20% of fast charge current (JEITA\_ISET).

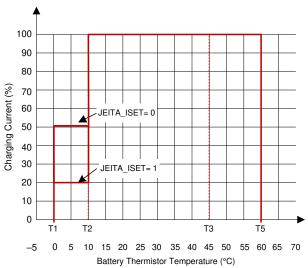


Figure 8-3. JEITA Profile: Charging Current

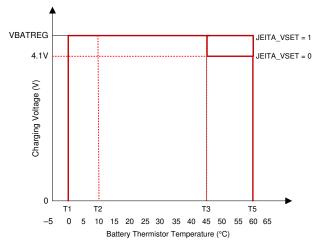


Figure 8-4. JEITA Profile: Charging Voltage

(2)



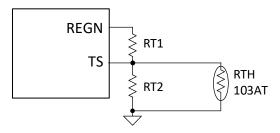


Figure 8-5. TS Resistor Network

Equation 1 through Equation 2 describe updates to the resistor bias network.

$$RT2 = \frac{V_{REGN} \times RTH_{COLD} \times RTH_{HOT} \times \left(\frac{1}{VT1} - \frac{1}{VT5}\right)}{RTH_{HOT} \times \left(\frac{V_{REGN}}{VT5} - 1\right) - RTH_{COLD} \times \left(\frac{V_{REGN}}{VT1} - 1\right)}$$

$$RT1 = \frac{\left(\left(\frac{V_{REGN}}{VT1}\right) - 1\right)}{\left(\frac{1}{VT1}\right) + \left(\frac{1}{VT1}\right)}$$
(1)

Select 0°C to 60°C range for Li-ion or Li-polymer battery:

- RTH<sub>COLD</sub> = 27.28 K $\Omega$
- RTH<sub>HOT</sub> =  $3.02 \text{ K}\Omega$
- RT1 = 5.23 KΩ
- RT2 = 30.9 KΩ

#### 8.3.7.6 Boost Mode Thermistor Monitor During Battery Discharge Mode

For battery protection during boost mode, the device monitors the battery temperature to be within the  $V_{BCOLD}$  to  $V_{BHOT}$  thresholds. When temperature is outside of the temperature thresholds, the boost mode is suspended. In additional, VBUS\_STAT bits are set to 000 and NTC\_FAULT is reported. Once temperature returns within thresholds, the boost mode is recovered and NTC\_FAULT is cleared.

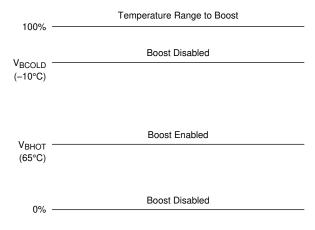


Figure 8-6. TS Pin Thermistor Sense Threshold in Boost Mode

#### 8.3.7.7 Charging Safety Timer

The device has built-in safety timer to prevent extended charging cycle due to abnormal battery conditions. The safety timer is two hours when the battery is below  $V_{BATLOWV}$  threshold and 10 hours when the battery is higher than  $V_{BATLOWV}$  threshold.

The user can program fast charge safety timer through I<sup>2</sup>C (CHG\_TIMER bits). When safety timer expires, the fault register CHRG\_FAULT bits are set to 11 and an INT is asserted to the host. The safety timer feature can be disabled through I<sup>2</sup>C by setting EN\_TIMER bit.

During input voltage, current, JEITA cool or thermal regulation, the safety timer counts at half clock rate as the actual charge current is likely to be below the register setting. For example, if the charger is in input current regulation (IDPM\_STAT = 1) throughout the whole charging cycle, and the safety time is set to five hours, the safety timer will expire in 10 hours. This half clock rate feature can be disabled by writing 0 to TMR2X EN bit.

During the fault, timer is suspended. Once the fault goes away, the timer resumes counting. If user stops the current charging cycle, and start again, timer gets reset (toggle CE pin or CHRG\_CONFIG bit).

#### 8.3.8 Protections

#### 8.3.8.1 Voltage and Current Monitoring in Converter Operation

The device closely monitors the input and system voltage, as well as internal FET currents for safe buck and boost mode operation.

### 8.3.8.1.1 Voltage and Current Monitoring in Buck Mode

#### 8.3.8.1.1.1 Input Overvoltage (ACOV)

If VBUS voltage exceeds V<sub>VAC OV</sub> (programmable via OVP[2:0] bits), the device stops switching immediately.

During input overvoltage event (ACOV), the fault register CHRG\_FAULT bits are set to 01. An INT pulse is asserted to the host. The device will automatically resume normal operation once the input voltage drops back below the OVP threshold.

#### 8.3.8.1.1.2 System Overvoltage Protection (SYSOVP)

The charger device clamps the system voltage during load transient so that the components connect to system would not be damaged due to high voltage. SYSOVP threshold is 350 mV above minimum system regulation voltage when the system is regulate at  $V_{SYS\_MIN}$ . Upon SYSOVP, converter stops switching immediately to clamp the overshoot. The charger provides  $\bar{3}0$ -mA discharge current ( $I_{SYSLOAD}$ ) to bring down the system voltage.

### 8.3.8.2 Voltage and Current Monitoring in Boost Mode

The device closely monitors the VBUS voltage, as well as RBFET and LSFET current to ensure safe boost mode operation.

### 8.3.8.2.1 VBUS Soft Start

When the boost function is enabled, the device soft-starts boost mode to avoid inrush current.

#### 8.3.8.2.2 VBUS Output Protection

The device monitors boost output voltage and other conditions to provide output short circuit and overvoltage protection. The boost build in accurate constant current regulation to allow OTG to adapt to various types of load. If a short circuit is detected on VBUS, boost turns off and retries 7 times. If retries are not successful, OTG is disabled with OTG\_CONFIG bit cleared. In addition, the BOOST\_FAULT bit is set and  $\overline{\text{INT}}$  pulse is generated. The BOOST\_FAULT bit can be cleared by host by reenabling boost mode

#### 8.3.8.2.3 Boost Mode Overvoltage Protection

When the VBUS voltage rises above regulation target and exceeds VOTG\_OVP, the device enters overvoltage protection which stops switching, clears OTG\_CONFIG bit and exits boost mode. At Boost overvoltage duration, the fault register bit (BOOST\_FAULT) is set high to indicate fault in boost operation. An INT is also asserted to the host.

### 8.3.8.3 Thermal Regulation and Thermal Shutdown

#### 8.3.8.3.1 Thermal Protection in Buck Mode

The BQ25600 and BQ25600D monitors the internal junction temperature  $T_J$  to avoid overheat of the chip and limits the IC surface temperature in buck mode. When the internal junction temperature exceeds thermal regulation limit (110°C), the device lowers down the charge current. During thermal regulation, the actual charging current is usually below the programmed battery charging current. Therefore, termination is disabled, the safety timer runs at half the clock rate, and the status register THERM\_STAT bit goes high.

Additionally, the device has thermal shutdown to turn off the converter and BATFET when IC surface temperature exceeds  $T_{SHUT}(160^{\circ}C)$ . The fault register CHRG\_FAULT is set to 1 and an  $\overline{INT}$  is asserted to the host. The BATFET and converter is enabled to recover when IC temperature is  $T_{SHUT\_HYS}$  (30°C) below  $T_{SHUT}(160^{\circ}C)$ .

#### 8.3.8.3.2 Thermal Protection in Boost Mode

The device monitors the internal junction temperature to provide thermal shutdown during boost mode. When IC junction temperature exceeds  $T_{SHUT}$  (160°C), the boost mode is disabled by setting OTG\_CONFIG bit low and BATFET is turned off. When IC junction temperature is below  $T_{SHUT}$ (160°C) -  $T_{SHUT\_HYS}$  (30°C), the BATFET is enabled automatically to allow system to restore and the host can re-enable OTG\_CONFIG bit to recover.

#### 8.3.8.4 Battery Protection

#### 8.3.8.4.1 Battery Overvoltage Protection (BATOVP)

The battery overvoltage limit is clamped at 4% above the battery regulation voltage. When battery over voltage occurs, the charger device immediately disables charging. The fault register BAT\_FAULT bit goes high and an INT is asserted to the host.

#### 8.3.8.4.2 Battery Overdischarge Protection

When battery is discharged below  $V_{BAT\_DPL\_FALL}$ , the BATFET is turned off to protect battery from overdischarge. To recover from overdischarge latch-off, an input source plug-in is required at VBUS. The battery is charged with  $I_{SHORT}$  (typically 100 mA) current when the  $V_{BAT} < V_{SHORT}$ , or precharge current as set in IPRECHG register when the battery voltage is between  $V_{SHORTZ}$  and  $V_{BAT\_LOWV}$ .

### 8.3.8.4.3 System Overcurrent Protection

When the system is shorted or significantly overloaded ( $I_{BAT} > I_{BATOP}$ ) and the current exceeds BATFET overcurrent limit, the BATFET latches off. Section BATFET Enable (Exit Shipping Mode) can reset the latch-off condition and turn on BATFET.

#### 8.4 Device Functional Modes

### 8.4.1 Narrow VDC Architecture

The device deploys Narrow VDC architecture (NVDC) with BATFET separating system from battery. The minimum system voltage is set by SYS\_MIN bits. Even with a fully depleted battery, the system is regulated above the minimum system voltage.

When the battery is below minimum system voltage setting, the BATFET operates in linear mode (LDO mode), and the system is typically 180 mV above the minimum system voltage setting. As the battery voltage rises above the minimum system voltage, BATFET is fully on and the voltage difference between the system and battery is the  $V_{\rm DS}$  of BATFET.

When the battery charging is disabled and above minimum system voltage setting or charging is terminated, the system is always regulated at typically 50 mV above battery voltage. The status register VSYS\_STAT bit goes high when the system is in minimum system voltage regulation.



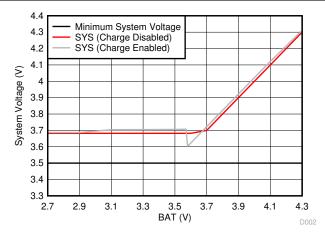


Figure 8-7. System Voltage vs Battery Voltage

### 8.4.2 Dynamic Power Management

To meet maximum current limit in USB spec and avoid over loading the adapter, the device features Dynamic Power management (DPM), which continuously monitors the input current and input voltage. When input source is over-loaded, either the current exceeds the input current limit (IINDPM) or the voltage falls below the input voltage limit (VINDPM). The device then reduces the charge current until the input current falls below the input current limit and the input voltage rises above the input voltage limit.

When the charge current is reduced to zero, but the input source is still overloaded, the system voltage starts to drop. Once the system voltage falls below the battery voltage, the device automatically enters the supplement mode where the BATFET turns on and battery starts discharging so that the system is supported from both the input source and battery.

During DPM mode, the status register bits VDPM\_STAT (VINDPM) or IDPM\_STAT (IINDPM) goes high. shows the DPM response with 9-V/1.2-A adapter, 3.2-V battery, charge current and 3.5-V minimum system voltage setting.

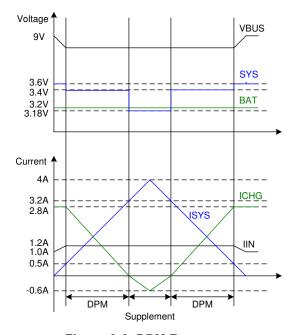


Figure 8-8. DPM Response

#### 8.4.3 Supplement Mode

When the system voltage falls 180 mV ( $V_{BAT} > V_{SYS\_MIN}$ ) or 45 mV ( $V_{BAT} < V_{SYS\_MIN}$ ) below the battery voltage, the BATFET turns on and the BATFET gate is regulated the gate drive of BATFET so that the minimum BATFET  $V_{DS}$  stays at 30 mV when the current is low. This prevents oscillation from entering and exiting the supplement mode.

As the discharge current increases, the BATFET gate is regulated with a higher voltage to reduce  $R_{DSON}$  until the BATFET is in full conduction. At this point onwards, the BATFET  $V_{DS}$  linearly increases with discharge current. Figure 8-9 shows the V-I curve of the BATFET gate regulation operation. BATFET turns off to exit supplement mode when the battery is below battery depletion threshold.

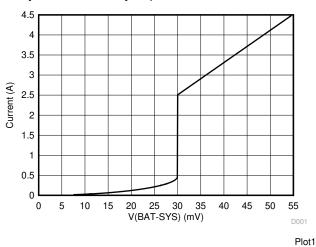


Figure 8-9. BAFET V-I Curve

### 8.4.4 Shipping Mode and QON Pin

### 8.4.4.1 BATFET Disable Mode (Shipping Mode)

To extend battery life and minimize power when system is powered off during system idle, shipping, or storage, the device can turn off BATFET so that the system voltage is zero to minimize the battery leakage current. When the host set BATFET\_DIS bit, the charger can turn off BATFET immediately or delay by  $t_{SM\_DLY}$  as configured by BATFET\_DLY bit.

### 8.4.4.2 BATFET Enable (Exit Shipping Mode)

When the BATFET is disabled (in shipping mode) and indicated by setting BATFET\_DIS, one of the following events can enable BATFET to restore system power:

- 1. Plug in adapter
- 2. Clear BATFET DIS bit
- 3. Set REG\_RST bit to reset all registers including BATFET\_DIS bit to default (0)
- 4. A logic high to low transition on  $\overline{\text{QON}}$  pin with  $t_{\text{SHIPMODE}}$  deglitch time to enable BATFET to exit shipping mode

#### 8.4.4.3 BATFET Full System Reset

The BATFET functions as a load switch between battery and system when input source is not plugged in. By changing the state of BATFET from on to off, systems connected to SYS can be effectively forced to have a power-on-reset. The  $\overline{\text{QON}}$  pin supports push-button interface to reset system power without host by changing the state of BATFET.

When the  $\overline{\text{QON}}$  pin is driven to logic low for  $t_{\text{QON\_RST}}$  while input source is not plugged in and BATFET is enabled (BATFET\_DIS = 0), the BATFET is turned off for  $t_{\text{BATFET\_RST}}$  and then it is re-enabled to reset system power. This function can be disabled by setting BATFET\_RST\_EN bit to 0.

#### 8.4.4.4 QON Pin Operations

The  $\overline{QON}$  pin incorporates two functions to control BATFET.  $\overline{QON}$  is pulled up to  $V_{QON}$  by an internal 200-k $\Omega$  pull-up resistor.

- BATFET Enable: A QON logic transition from high to low with longer than t<sub>SHIPMODE</sub> deglitch turns on BATFET to exit shipping mode. When exiting shipping mode, HIZ is enabled (EN\_HIZ = 1) as well. HIZ can be disabled (EN\_HIZ = 0) by the host after exiting shipping mode. OTG cannot be enabled (OTG\_CONFIG = 1) until HIZ is disabled.
- BATFET Reset: When QON is driven to logic low by at least t<sub>QON\_RST</sub> while adapter is not plugged in (and BATFET\_DIS = 0), the BATFET is turned off for t<sub>BATFET\_RST</sub>. The BATFET is re-enabled after t<sub>BATFET\_RST</sub> duration. This function allows systems connected to SYS to have power-on-reset. This function can be disabled by setting BATFET\_RST\_EN bit to 0.

Figure 8-10 shows the sample external configurations for each.

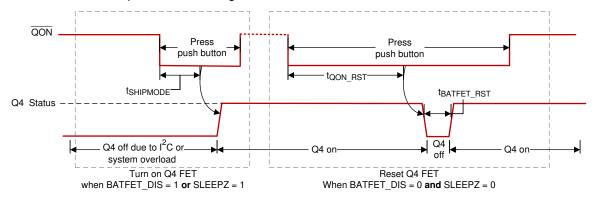


Figure 8-10. QON Timing

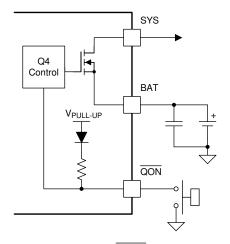


Figure 8-11. QON Circuit

#### 8.4.5 Status Outputs ( PG, STAT, INT)

## 8.4.5.1 Power Good Indicator ( PG Pin and PG\_STAT Bit)

The PG\_STAT bit goes HIGH and  $\overline{PG}$  pin goes LOW to indicate a good input source when:

- VBUS above V<sub>VBUS UVLO</sub>
- VBUS above battery (not in sleep)
- VBUS below V<sub>VAC OV</sub> threshold
- VBUS above V<sub>VBUSMin</sub> (typical 3.8 V) when I<sub>BADSRC</sub> (typical 30 mA) current is applied (not a poor source)
- · Completed input Source Type Detection



### 8.4.5.2 Charging Status Indicator (STAT)

The device indicates charging state on the open drain STAT pin. The STAT pin can drive LED. The STAT pin function can be disabled by setting the EN\_ICHG\_MON bits = 11.

Table 8-6. STAT Pin State

CHARGING STATE	STAT INDICATOR
Charging in progress (including recharge)	LOW
Charging complete	HIGH
Sleep mode, charge disable	HIGH
Charge suspend (input overvoltage, TS fault, timer fault or system overvoltage) Boost Mode suspend (due to TS fault)	Blinking at 1 Hz

### 8.4.5.3 Interrupt to Host ( INT)

In some applications, the host does not always monitor the charger operation. The INT pulse notifies the system on the device operation. The following events will generate 256-µs INT pulse.

- USB/adapter source identified (through PSEL pin or DPDM detection)
- · Good input source detected
  - VBUS above battery (not in sleep)
  - VBUS below V<sub>VAC</sub> OV threshold
  - VBUS above V<sub>VBUSMin</sub> (typical 3.8 V) when I<sub>BADSRC</sub> (typical 30 mA) current is applied (not a poor source)
- Input removed
- Charge complete
- Any FAULT event in REG09
- VINDPM / IINDPM event detected (maskable)

When a fault occurs, the charger device sends out INT and keeps the fault state in REG09 until the host reads the fault register. Before the host reads REG09 and all the faults are cleared, the charger device would not send any INT upon new faults. To read the current fault status, the host has to read REG09 two times consecutively. The first read reports the pre-existing fault register status and the second read reports the current fault register status.

### 8.5 Programming

#### 8.5.1 Serial Interface

The device uses I<sup>2</sup>C compatible interface for flexible charging parameter programming and instantaneous device status reporting. I<sup>2</sup>C is a bi-directional 2-wire serial interface developed by Philips Semiconductor (now NXP Semiconductors). Only two bus lines are required: a serial data line (SDA) and a serial clock line (SCL). Devices can be considered as masters or slaves when performing data transfers. A master is the device which initiates a data transfer on the bus and generates the clock signals to permit that transfer. At that time, any device addressed is considered a slave.

The device operates as a slave device with address 6BH, receiving control inputs from the master device like micro controller or a digital signal processor through REG00-REG0B. Register read beyond REG0B (0x0B) returns 0xFF. The I<sup>2</sup>C interface supports both standard mode (up to 100 kbits), and fast mode (up to 400 kbits). connecting to the positive supply voltage via a current source or pull-up resistor. When the bus is free, both lines are HIGH. The SDA and SCL pins are open drain.

### 8.5.1.1 Data Validity

The data on the SDA line must be stable during the HIGH period of the clock. The HIGH or LOW state of the data line can only change when the clock signal on the SCL line is LOW. One clock pulse is generated for each data bit transferred.

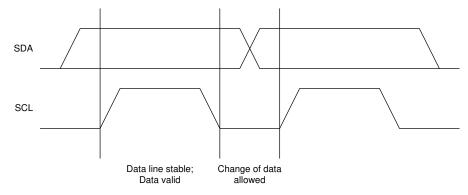


Figure 8-12. Bit Transfer on the I<sup>2</sup>C Bus

#### 8.5.1.2 START and STOP Conditions

All transactions begin with a START (S) and can be terminated by a STOP (P). A HIGH to LOW transition on the SDA line while SCI is HIGH defines a START condition. A LOW to HIGH transition on the SDA line when the SCL is HIGH defines a STOP condition. START and STOP conditions are always generated by the master. The bus is considered busy after the START condition, and free after the STOP condition.

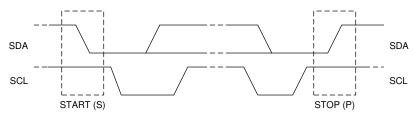


Figure 8-13. TS START and STOP conditions

#### 8.5.1.3 Byte Format

Every byte on the SDA line must be 8 bits long. The number of bytes to be transmitted per transfer is unrestricted. Each byte has to be followed by an Acknowledge bit. Data is transferred with the Most Significant Bit (MSB) first. If a slave cannot receive or transmit another complete byte of data until it has performed some other function, it can hold the clock line SCL low to force the master into a wait state (clock stretching). Data transfer then continues when the slave is ready for another byte of data and release the clock line SCL.

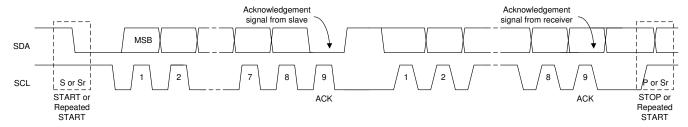


Figure 8-14. Data Transfer on the I<sup>2</sup>C Bus

#### 8.5.1.4 Acknowledge (ACK) and Not Acknowledge (NACK)

The acknowledge takes place after every byte. The acknowledge bit allows the receiver to signal the transmitter that the byte was successfully received and another byte may be sent. All clock pulses, including the acknowledge ninth clock pulse, are generated by the master. The transmitter releases the SDA line during the acknowledge clock pulse so the receiver can pull the SDA line LOW and it remains stable LOW during the HIGH period of this clock pulse.

When SDA remains HIGH during the ninth clock pulse, this is the Not Acknowledge signal. The master can then generate either a STOP to abort the transfer or a repeated START to start a new transfer.

#### 8.5.1.5 Slave Address and Data Direction Bit

After the START, a slave address is sent. This address is 7 bits long followed by the eighth bit as a data direction bit (bit R/W). A zero indicates a transmission (WRITE) and a one indicates a request for data (READ).

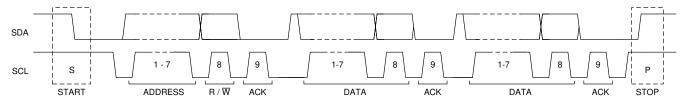


Figure 8-15. Complete Data Transfer

### 8.5.1.6 Single Read and Write

If the register address is not defined, the charger IC send back NACK and go back to the idle state.

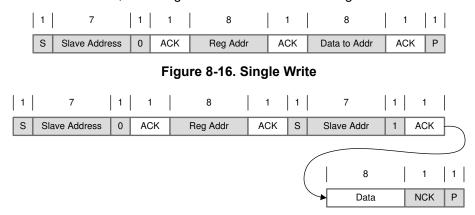


Figure 8-17. Single Read

#### 8.5.1.7 Multi-Read and Multi-Write

The charger device supports multi-read and multi-write on REG00 through REG0B.

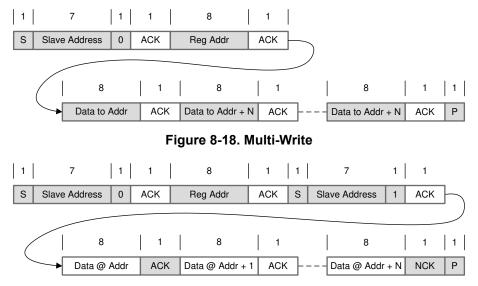


Figure 8-19. Multi-Read

REG09 is a fault register. It keeps all the fault information from last read until the host issues a new read. For example, if Charge Safety Timer Expiration fault occurs but recovers later, the fault register REG09 reports the fault when it is read the first time, but returns to normal when it is read the second time. in order to get the



fault information at present, the host has to read REG09 for the second time. The only exception is NTC\_FAULT which always reports the actual condition on the TS pin. in addition, REG09 does not support multi-read and multi-write.



# 8.6 Register Maps

I<sup>2</sup>C Slave Address: 6BH

### 8.6.1 REG00

### Table 8-7. REG00 Field Descriptions

Bit	Field	POR	Type	Reset	Description	Comment
7	EN_HIZ	0	R/W	by REG_RST by Watchdog	0 – Disable, 1 – Enable	Enable HIZ Mode 0 – Disable (default) 1 – Enable
6	EN_ICHG_MON[1]	0	R/W	by REG_RST	00 – Enable STAT pin function	
5	EN_ICHG_MON[0]	0	R/W	by REG_RST	(default) 01 – Reserved 10 – Reserved 11 – Disable STAT pin function (float pin)	
4	IINDPM[4]	1	R/W	by REG_RST	1600 mA	Input Current Limit Offset: 100 mA Range: 100 mA (000000) – 3.2 A (11111) Default: 2400 mA (10111), maximum input current limit, not typical. IINDPM bits are changed automatically after input source detection is completed BQ25600D USB SDP = 500 mA USB DCP = 2.4 A Unknown Adapter = 500 mA Non-Standard Adapter = 1 A, 2 A, 2.1 A, or 2.4 A BQ25600 PSEL = Hi = 500 mA PSEL = Lo = 2.4 A Host can over-write IINDPM register bits after input source detection is completed.
3	IINDPM[3]	0	R/W	by REG_RST	800 mA	
2	IINDPM[2]	1	R/W	by REG_RST	400 mA	
1	IINDPM[1]	1	R/W	by REG_RST	200 mA	
0	IINDPM[0]	1	R/W	by REG_RST	100 mA	

LEGEND: R/W = Read/Write; R = Read only



### 8.6.2 REG01

### Table 8-8. REG01 Field Descriptions

Bit	Field	POR	Type	Reset	Description	Comment
7	PFM_DIS	0	R/W	by REG_RST	0 – Enable PFM 1 – Disable PFM	Default: 0 - Enable
6	WD_RST	0	R/W	by REG_RST by Watchdog	I <sup>2</sup> C Watchdog Timer Reset 0 – Normal ; 1 – Reset	Default: Normal (0) Back to 0 after watchdog timer reset
5	OTG_CONFIG	0	R/W		0 – OTG Disable 1 – OTG Enable	Default: OTG disable (0) Note: 1. OTG_CONFIG would over- ride Charge Enable Function in CHG_CONFIG
4	CHG_CONFIG	1	R/W	by REG_RST by Watchdog	0 – Charge Disable 1 – Charge Enable	Default: Charge Battery (1) Note: 1. Charge is enabled when both CE pin is pulled low AND CHG_CONFIG bit is 1.
3	SYS_MIN[2]	1	R/W	by REG_RST	System Minimum Voltage	000: 2.6 V 001: 2.8 V 010: 3 V 011: 3.2 V 100: 3.4 V 101: 3.5 V 110: 3.6 V 111: 3.7 V Default: 3.5 V (101)
2	SYS_MIN[1]	0	R/W	by REG_RST		
1	SYS_MIN[0]	1	R/W	by REG_RST		
0	MIN_V <sub>BAT</sub> _SEL	0	R/W	by REG_RST	0 – 2.8 V BAT falling, 1 – 2.5 V BAT falling	Minimum battery voltage for OTG mode. Default falling 2.8 V (0); Rising threshold 3.0 V (0)

LEGEND: R/W = Read/Write; R = Read only



## 8.6.3 REG02

Table 8-9. REG02 Field Descriptions

Bit	Field	POR	Type	Reset	Description	Comment
7	BOOST_LIM	1	R/W	by REG_RST by Watchdog	0 – 0.5 A 1 – 1.2 A	Default: 1.2 A (1) Note: The current limit options listed are minimum current limit specs.
6	Q1_FULLON	0	R/W	by REG_RST	0 – Use higher Q1 RDSON when programmed IINDPM < 700mA (better accuracy) 1 – Use lower Q1 RDSON always (better efficiency)	In boost mode, full FET is always used and this bit has no effect
5	ICHG[5]	1	R/W	by REG_RST by Watchdog	1920 mA	
4	ICHG[4]	0	R/W	by REG_RST by Watchdog	960 mA	Fast Charge Current Default: 2040 mA (100010)
3	ICHG[3]	0	R/W	by REG_RST by Watchdog	480 mA	Range: 0 mA (0000000) – 3000 mA (110010) Note:
2	ICHG[2]	0	R/W	by REG_RST by Watchdog	240 mA	I <sub>CHG</sub> = 0 mA disables charge.
1	ICHG[1]	1	R/W	by REG_RST by Watchdog	120 mA	to register value 3000 mA (110010))
0	ICHG[0]	0	R/W	by REG_RST by Watchdog	60 mA	



## 8.6.4 REG03

## Table 8-10. REG03 Field Descriptions

Bit	Field	POR	Туре	Reset	Description	Comment		
7	IPRECHG[3]	0	R/W	by REG_RST by Watchdog	480 mA			
6	IPRECHG[2]	0	R/W	by REG_RST by Watchdog	240 mA	Precharge Current Default: 180 mA (0010) Offset: 60 mA		
5	IPRECHG[1]	1	R/W	by REG_RST by Watchdog	120 mA	Note: IPRECHG > 780 mA clamped to 780 mA (1100)		
4	IPRECHG[0]	0	R/W	by REG_RST by Watchdog	60 mA	(1.00)		
3	ITERM[3]	0	R/W	by REG_RST by Watchdog	480 mA			
2	ITERM[2]	0	R/W	by REG_RST by Watchdog	240 mA	Termination Current Default: 180 mA (0010) Offset: 60 mA		
1	ITERM[1]	1	R/W	by REG_RST by Watchdog	120 mA	Note: ITERM > 780 mA clamped to 780 mA(1100)		
0	ITERM[0]	0	R/W	by REG_RST by Watchdog	60 mA			



## 8.6.5 REG04

Table 8-11. REG04 Field Descriptions

Bit	Field	POR	Type	Reset	Description	Comment	
7	VREG[4]	0	R/W	by REG_RST by Watchdog	512 mV	Charge Voltage	
6	VREG[3]	1	R/W	by REG_RST by Watchdog	256 mV	Offset: 3.856 V Range: 3.856 V to 4.624 V (11000)	
5	VREG[2]	0	R/W	by REG_RST by Watchdog	128 mV	Default: 4.208 V (01011) Special Value:	
4	VREG[1]	1	R/W	by REG_RST by Watchdog	64 mV	(01111): 4.352 V Note: Value above 11000 (4.624 V)	
3	VREG[0]	1	R/W	by REG_RST by Watchdog	32 mV	is clamped to register value 11000 (4.624 V)	
2	TOPOFF_TIMER[1]	0	R/W	by REG_RST by Watchdog	00 – Disabled (Default) 01 – 15 minutes	The extended time following the termination condition is met. When	
1	TOPOFF_TIMER[0]	0	R/W	by REG_RST by Watchdog	10 – 30 minutes 11 – 45 minutes	disabled, charge terminated when termination conditions are met	
0	VRECHG	0	R/W	by REG_RST by Watchdog	0 – 100 mV 1 – 200 mV	Recharge threshold Default: 100 mV (0)	



## 8.6.6 REG05

Table 8-12. REG05 Field Descriptions

Bit	Field	POR	Type	Reset	Description	Comment	
7	EN_TERM	1	R/W	by REG_RST by Watchdog	0 – Disable 1 – Enable	Default: Enable termination (1)	
6	OVPFET_DIS	0	R/W	by REG_RST by Watchdog	0 – Enable OVPFET 1 – Disable OVPFET	Default: Enable OVPFET (0) Note: This bit only takes effect when EN_HIZ bit is active	
5	WATCHDOG[1]	0	R/W	by REG_RST by Watchdog	00 – Disable timer, 01 – 40 s, 10 –	Default: 40 s (01)	
4	WATCHDOG[0]	1	R/W	by REG_RST by Watchdog	80 s,11 – 160 s	Delault. 40 3 (01)	
3	EN_TIMER	1	R/W	by REG_RST by Watchdog	0 – Disable 1 – Enable both fast charge and precharge timer	Default: Enable (1)	
2	CHG_TIMER	1	R/W	by REG_RST by Watchdog	0 – 5 hrs 1 – 10 hrs	Default: 10 hours (1)	
1	TREG	1	R/W	by REG_RST by Watchdog	Thermal Regulation Threshold: 0 – 90°C 1 – 110°C	Default: 110°C (1)	
0	JEITA_ISET (0C-10C)	1	R/W	by REG_RST by Watchdog	0 – 50% of ICHG 1 – 20% of ICHG	Default: 20% (1)	



## 8.6.7 REG06

## Table 8-13. REG06 Field Descriptions

Bit	Field	POR	Type	Reset	Description	Comment	
7	OVP[1]	0	R/W	by REG_RST		VAC OVP threshold:	
6	OVP[0]	1	R/W	by REG_RST	Default: 6.5 V (01)	00 - 5.5 V 01 – 6.5 V (5-V input) 10 – 10.5 V (9-V input) 11 – 14 V (12-V input)	
5	BOOSTV[1]	1	R/W	by REG_RST		Boost Regulation Voltage:	
4	BOOSTV[0]	0	R/W	by REG_RST		00 – 4.85 V 01 – 5.00 V 10 – 5.15 V 11 – 5.30 V	
3	VINDPM[3]	0	R/W	by REG_RST	800 mV	Absolute VINDPM Threshold	
2	VINDPM[2]	1	R/W	by REG_RST	400 mV	Offset: 3.9 V	
1	VINDPM[1]	1	R/W	by REG_RST	200 mV	Range: 3.9 V (0000) – 5.4 V (1111)	
0	VINDPM[0]	0	R/W	by REG_RST	100 mV	Default: 4.5 V (0110)	



## 8.6.8 REG07

# Table 8-14. REG07 Field Descriptions

Bit	Field	POR	Type	Reset	Description	Comment	
7	IINDET_EN	0	R/W	by REG_RST by Watchdog	0 – Not in D+/D– detection (or PSEL detection); 1 – Force D+/D– detection	Default: Not in DPDM detection (0) Note: For PSEL part, reads PSEL pin value	
6	TMR2X_EN	1	R/W	by REG_RST by Watchdog	0 – Disable 1 – Safety timer slowed by 2X during input DPM (both V and I) or JEITA cool, or thermal regulation		
5	BATFET_DIS	0	R/W	by REG_RST	0 – Allow Q4 turn on, 1 – Turn off Q4 with t <sub>BATFET_DLY</sub> delay time (REG07[3])	Default: Allow Q4 turn on(0)	
4	JEITA_VSET (45C-60C)	0	R/W	by REG_RST by Watchdog	0 – Set Charge Voltage to 4.1V ( max), 1 – Set Charge Voltage to VREG		
3	BATFET_DLY	1	R/W	by REG_RST	0 – Turn off BATFET immediately when BATFET_DIS bit is set 1 – Turn off BATFET after t <sub>BATFET_DLY</sub> (typ. 10 s) when BATFET_DIS bit is set	Default: 1 Turn off BATFET after t <sub>BATFET_DLY</sub> (typ. 10 s) when BATFET_DIS bit is set	
2	BATFET_RST_EN	1	R/W	by REG_RST by Watchdog	0 – Disable BATFET reset function 1 – Enable BATFET reset function	Default: 1 Enable BATFET reset function	
1	VDPM_BAT_TRACK[1]	0	R/W	R/W by REG_RST 00 – Disable function (VINDPM set		Sets VINDPM to track BAT	
0	VDPM_BAT_TRACK[0]	0	R/W	by REG_RST	by register) 01 – VBAT + 200 mV 10 – VBAT + 250 mV 11 – VBAT + 300 mV	voltage. Actual VINDPM is higher of register value and VBAT + VDPM_BAT_TRACK	



## 8.6.9 REG08

# Table 8-15. REG08 Field Descriptions

Bit	Field	POR	Туре	Reset	Description			
7	VBUS_STAT[2]	х	R	NA	VBUS Status register			
6	VBUS_STAT[1]	Х	R	NA	BQ25600D 000: No input			
5	VBUS_STAT[0]	x	R	NA	001: USB Host SDP 010: USB CDP: (1.5A) 011: USB DCP (2.4 A) 101: Unknown Adapter (500 mA) 110: Non-Standard Adapter (1A/2A/2.1A/2.4A) 111: OTG BQ25600 000 – No input 001 – USB Host SDP (500 mA) → PSEL HIGH 011 – Adapter 2.4 A → PSEL LOW 111 – OTG Software current limit is reported in IINDPM register			
4	CHRG_STAT[1]	Х	R	NA	Charging status:			
3	CHRG_STAT[0]	х	R	NA	00 – Not Charging 01 – Pre-charge (< V <sub>BATLOWV</sub> ) 10 – Fast Charging 11 – Charge Termination			
2	PG_STAT	х	R	NA	Power Good status: 0 – Power Not Good 1 – Power Good			
1	THERM_STAT	х	R	NA	0 – Not in thermal regulation 1 – In thermal regulation			
0	VSYS_STAT	х	R	NA	0 – Not in V <sub>SYS_MIN</sub> regulation (BAT > V <sub>SYS_MIN</sub> ) 1 – In V <sub>SYS_MIN</sub> regulation (BAT < V <sub>SYS_MIN</sub> )			

LEGEND: R/W = Read/Write



## 8.6.10 REG09

## Table 8-16. REG09 Field Descriptions

Bit	Field	POR	Type	Reset	Description				
7	WATCHDOG_FAULT	х	R	NA	0 – Normal, 1- Watchdog timer expiration				
6	BOOST_FAULT	х	R	NA 0 – Normal, 1 – VBUS overloaded in OTG, or VBUS OVP, or battery too low (any conditions that cannot start boost function)					
5	CHRG_FAULT[1]	х	R	NA	00 - Normal, 01 - input fault (VAC OVP or VBAT < VBUS < 3.8 V), 10 -				
4	CHRG_FAULT[0]	х	R	NA	Thermal shutdown, 11 – Charge Safety Timer Expiration				
3	BAT_FAULT	х	R	NA	0 – Normal, 1 – BATOVP				
2	NTC_FAULT[2]	х	R	NA	JEITA				
1	NTC_FAULT[1]	х	R	NA	000 – Normal, 010 – Warm, 011 – Cool, 101 – Cold, 110 – Hot (Buck mode)				
0	NTC_FAULT[0]	х	R	NA	000 – Normal, 101 – Cold, 110 – Hot (Boost mode)				



## 8.6.11 REG0A

## Table 8-17. REG0A Field Descriptions

Bit	Field	POR	Туре	Reset	Description
7	VBUS_GD	х	R	NA	0 – Not VBUS attached, 1 – VBUS Attached
6	VINDPM_STAT	х	R	NA	0 – Not in VINDPM, 1 – in VINDPM
5	IINDPM_STAT	х	R	NA	0 – Not in IINDPM, 1 – in IINDPM
4	Reserved	х	R	NA	
3	TOPOFF_ACTIVE	х	R	NA	0 – Top off timer not counting. 1 – Top off timer counting
2	ACOV_STAT	x	R	NA	0 – Device is NOT in ACOV 1 – Device is in ACOV
1	VINDPM_INT_ MASK	0	R/W	by REG_RST	0 – Allow VINDPM INT pulse 1 – Mask VINDPM INT pulse
0	IINDPM_INT_ MASK	0	R/W	by REG_RST	0 – Allow IINDPM INT pulse 1 – Mask IINDPM INT pulse



#### 8.6.12 REG0B

Table 8-18. REG0B Field Descriptions

Bit	Field	POR	Туре	Reset	Description			
7	REG_RST	0	R/W	NA	Register reset  0 – Keep current register setting  1 – Reset to default register value and reset safety timer  Note: Bit resets to 0 after register reset is completed			
6	PN[3]	х	R	NA				
5	PN[2]	х	R	NA	BQ25600: 0000			
4	PN[1]	х	R	NA	BQ25600D: 0001			
3	PN[0]	х	R	NA				
2	Reserved	х	R	NA				
1	DEV_REV[1]	х	R	NA				
0	DEV_REV[0]	х	R	NA				

LEGEND: R/W = Read/Write; R = Read only

## 9 Application and Implementation

#### Note

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes, as well as validating and testing their design implementation to confirm system functionality.

## 9.1 Application Information

A typical application consists of the device configured as an I<sup>2</sup>C controlled power path management device and a single cell battery charger for Li-lon and Li-polymer batteries used in a wide range of Smartphone and other portable devices. It integrates an input reverse-block FET (RBFET, Q1), high-side switching FET (HSFET, Q2), low-side switching FET (LSFET, Q3), and battery FET (BATFET Q4) between the system and battery. The device also integrates a bootstrap diode for the high-side gate drive.

Submit Document Feedback

Copyright © 2022 Texas Instruments Incorporated



# 9.2 Typical Application

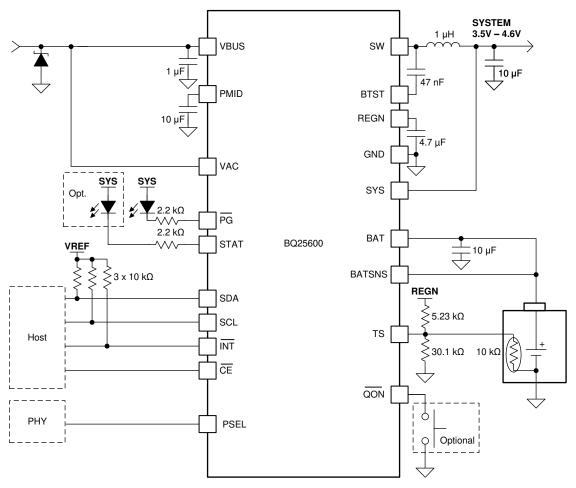


Figure 9-1. Power Path Management Application



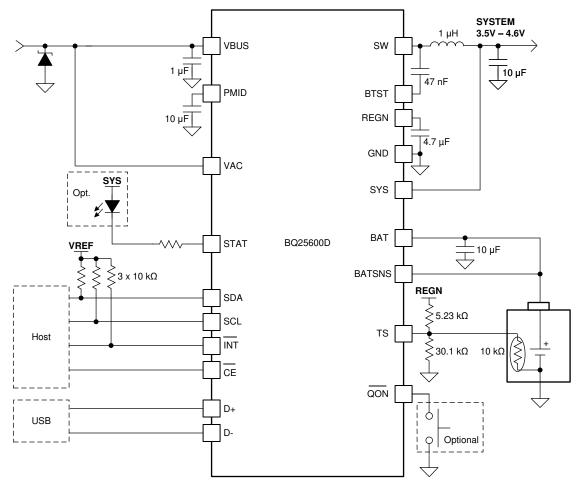


Figure 9-2. BQ25600D Applications Diagram

## 9.2.1 Design Requirements

Table 9-1. Design Parameters

PARAMETER	VALUE
VBUS voltage range	4 V to 13.5 V
Input current limit (REG00[4:0])	3.2 A
Fast charge current limit (REG02[5:0])	2.4 A
Minimum system voltage (REG01[3:1])	3.5 V
Battery regulation voltage (REG04[7:3])	4.2 V

## 9.2.2 Detailed Design Procedure

## 9.2.2.1 Inductor Selection

The 1.5-MHz switching frequency allows the use of small inductor and capacitor values to maintain an inductor saturation current higher than the charging current ( $I_{CHG}$ ) plus half the ripple current ( $I_{RIPPLE}$ ):

$$I_{SAT} \ge I_{CHG} + (1/2) I_{RIPPLE} \tag{3}$$

The inductor ripple current depends on the input voltage ( $V_{VBUS}$ ), the duty cycle (D =  $V_{BAT}/V_{VBUS}$ ), the switching frequency ( $f_S$ ) and the inductance (L).

$$I_{RIPPLE} = \frac{V_{IN} \times D \times (1 - D)}{fs \times L}$$
(4)

The maximum inductor ripple current occurs when the duty cycle (D) is 0.5 or approximately 0.5. Usually inductor ripple is designed in the range between 20% and 40% maximum charging current as a trade-off between inductor size and efficiency for a practical design.

#### 9.2.2.2 Input Capacitor

Design input capacitance to provide enough ripple current rating to absorb input switching ripple current. The worst case RMS ripple current is half of the charging current when duty cycle is 0.5. If the converter does not operate at 50% duty cycle, then the worst case capacitor RMS current  $I_{Cin}$  occurs where the duty cycle is closest to 50% and can be estimated using Equation 5.

$$I_{CIN} = I_{CHG} \times \sqrt{D \times (1 - D)}$$
(5)

Low ESR ceramic capacitor such as X7R or X5R is preferred for input decoupling capacitor and should be placed to the drain of the high-side MOSFET and source of the low-side MOSFET as close as possible. Voltage rating of the capacitor must be higher than normal input voltage level. A rating of 25 V or higher capacitor is preferred for 15-V input voltage. Capacitance of 22 µF is suggested for typical of 3-A charging current.

## 9.2.2.3 Output Capacitor

Ensure that the output capacitance has enough ripple current rating to absorb the output switching ripple current. Equation 6 shows the output capacitor RMS current  $I_{COUT}$  calculation.

$$I_{COUT} = \frac{I_{RIPPLE}}{2 \times \sqrt{3}} \approx 0.29 \times I_{RIPPLE}$$
(6)

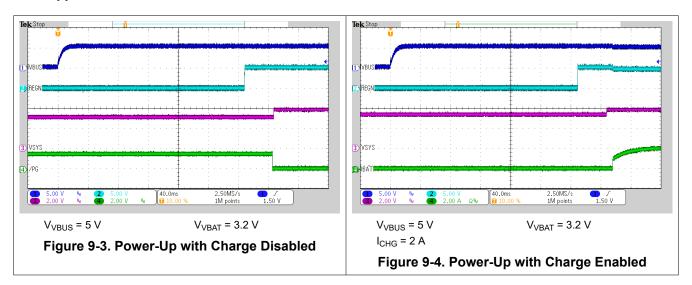
The output capacitor voltage ripple can be calculated as follows:

$$\Delta V_{O} = \frac{V_{OUT}}{8LCfs^{2}} \left( 1 - \frac{V_{OUT}}{V_{IN}} \right)$$
(7)

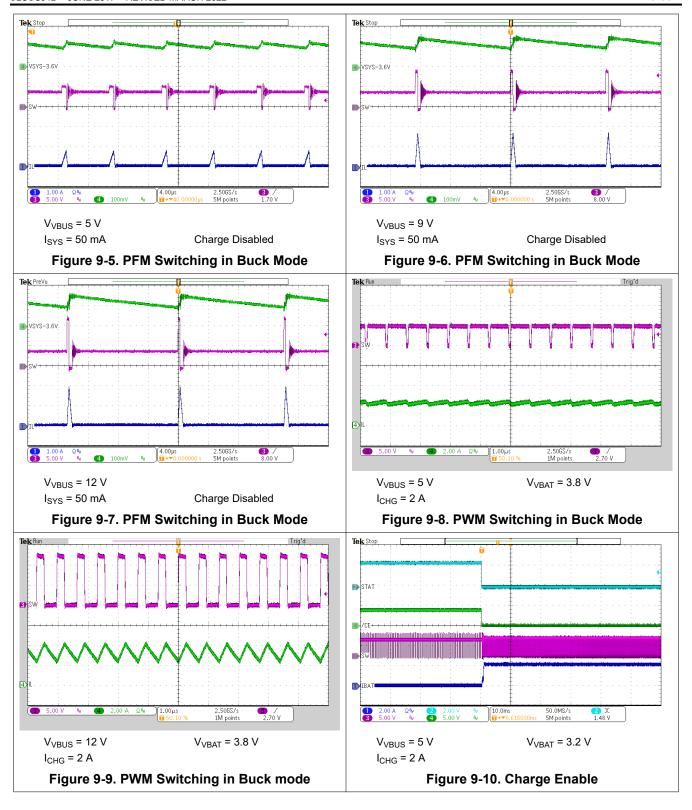
At certain input and output voltage and switching frequency, the voltage ripple can be reduced by increasing the output filter LC.

The charger device has internal loop compensation optimized for >20-µF ceramic output capacitance. The preferred ceramic capacitor is 10-V rating, X7R or X5R.

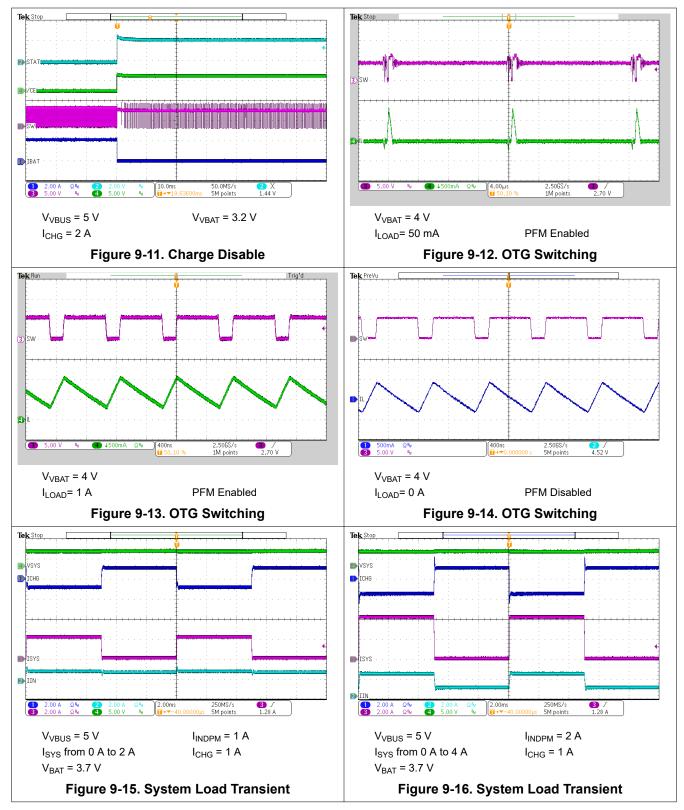
#### 9.2.3 Application Curves



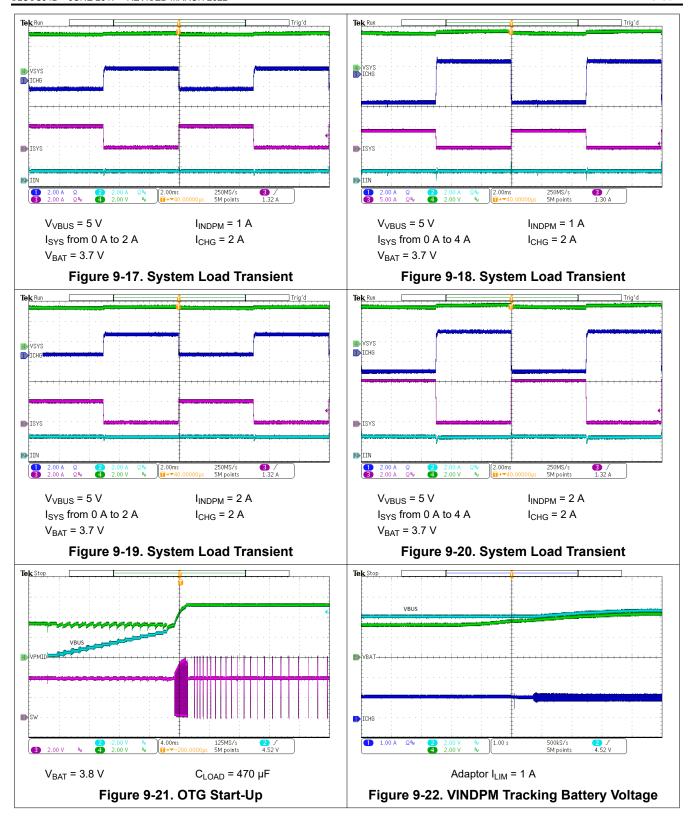














# 10 Power Supply Recommendations

In order to provide an output voltage on SYS, the BQ25600 and BQ25600D device requires a power supply between 3.9-V and 13.5-V input with at least 100-mA current rating connected to VBUS and a single-cell Li-lon battery with voltage > V<sub>BATUVLO</sub> connected to BAT. The source current rating needs to be at least 3 A in order for the buck converter of the charger to provide maximum output power to SYS.



## 11 Layout

## 11.1 Layout Guidelines

The switching node rise and fall times should be minimized for minimum switching loss. Proper layout of the components to minimize high frequency current path loop (see Figure 11-1) is important to prevent electrical and magnetic field radiation and high frequency resonant problems.

#### Note

It is essential to follow this specific layout PCB order.

- 1. Place input capacitor as close as possible to PMID pin and GND pin connections and use shortest copper trace connection or GND plane.
- 2. Put output capacitor near to the inductor and the IC.
- 3. Decoupling capacitors should be placed next to the IC pins and make trace connection as short as possible.
- 4. Place inductor input terminal to SW pin as close as possible. Minimize the copper area of this trace to lower electrical and magnetic field radiation but make the trace wide enough to carry the charging current. Do not use multiple layers in parallel for this connection. Minimize parasitic capacitance from this area to any other trace or plane.
- 5. It is OK to connect all grounds together to reduce PCB size and improve thermal dissipation.
- 6. Try to avoid ground planes in parallel with high frequency traces in other layers.

See the EVM design for the recommended component placement with trace and via locations.

## 11.2 Layout Example

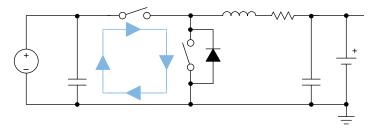


Figure 11-1. High Frequency Current Path



## 12 Device and Documentation Support

## 12.1 Device Support

## 12.1.1 Third-Party Products Disclaimer

TI'S PUBLICATION OF INFORMATION REGARDING THIRD-PARTY PRODUCTS OR SERVICES DOES NOT CONSTITUTE AN ENDORSEMENT REGARDING THE SUITABILITY OF SUCH PRODUCTS OR SERVICES OR A WARRANTY, REPRESENTATION OR ENDORSEMENT OF SUCH PRODUCTS OR SERVICES, EITHER ALONE OR IN COMBINATION WITH ANY TI PRODUCT OR SERVICE.

## 12.2 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on ti.com. Click on *Subscribe to updates* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

## 12.3 Support Resources

TI E2E<sup>™</sup> support forums are an engineer's go-to source for fast, verified answers and design help — straight from the experts. Search existing answers or ask your own question to get the quick design help you need.

Linked content is provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's Terms of Use.

#### 12.4 Trademarks

TI E2E™ is a trademark of Texas Instruments.

All trademarks are the property of their respective owners.

## 12.5 Electrostatic Discharge Caution



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

## 12.6 Glossary

TI Glossary

This glossary lists and explains terms, acronyms, and definitions.



# 13 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

www.ti.com 9-Nov-2025

#### PACKAGING INFORMATION

Orderable part number	Status	Material type	Package   Pins	Package qty   Carrier	RoHS	Lead finish/ Ball material	MSL rating/ Peak reflow	Op temp (°C)	Part marking
	(.,	(=)			(8)	(4)	(5)		(3)
BQ25600DYFFR	Active	Production	DSBGA (YFF)   30	3000   LARGE T&R	Yes	SNAGCU	Level-1-260C-UNLIM	-40 to 85	BQ25600D
BQ25600DYFFR.A	Active	Production	DSBGA (YFF)   30	3000   LARGE T&R	Yes	SNAGCU	Level-1-260C-UNLIM	-40 to 85	BQ25600D
BQ25600DYFFT	Active	Production	DSBGA (YFF)   30	250   SMALL T&R	Yes	SNAGCU	Level-1-260C-UNLIM	-40 to 85	BQ25600D
BQ25600DYFFT.A	Active	Production	DSBGA (YFF)   30	250   SMALL T&R	Yes	SNAGCU	Level-1-260C-UNLIM	-40 to 85	BQ25600D
BQ25600YFFR	Active	Production	DSBGA (YFF)   30	3000   LARGE T&R	Yes	SNAGCU	Level-1-260C-UNLIM	-40 to 85	BQ25600
BQ25600YFFR.A	Active	Production	DSBGA (YFF)   30	3000   LARGE T&R	Yes	SNAGCU	Level-1-260C-UNLIM	-40 to 85	BQ25600
BQ25600YFFR.B	Active	Production	DSBGA (YFF)   30	3000   LARGE T&R	Yes	SNAGCU	Level-1-260C-UNLIM	-40 to 85	BQ25600
BQ25600YFFT	Active	Production	DSBGA (YFF)   30	250   SMALL T&R	Yes	SNAGCU	Level-1-260C-UNLIM	-40 to 85	BQ25600
BQ25600YFFT.A	Active	Production	DSBGA (YFF)   30	250   SMALL T&R	Yes	SNAGCU	Level-1-260C-UNLIM	-40 to 85	BQ25600
BQ25600YFFT.B	Active	Production	DSBGA (YFF)   30	250   SMALL T&R	Yes	SNAGCU	Level-1-260C-UNLIM	-40 to 85	BQ25600

<sup>(1)</sup> Status: For more details on status, see our product life cycle.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

Important Information and Disclaimer: The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative

<sup>(2)</sup> Material type: When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

<sup>(3)</sup> RoHS values: Yes, No, RoHS Exempt. See the TI RoHS Statement for additional information and value definition.

<sup>(4)</sup> Lead finish/Ball material: Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

<sup>(5)</sup> **MSL rating/Peak reflow:** The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

<sup>(6)</sup> Part marking: There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.



# **PACKAGE OPTION ADDENDUM**

www.ti.com 9-Nov-2025

and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.



www.ti.com 30-May-2024

## TAPE AND REEL INFORMATION



# TAPE DIMENSIONS KO PI BO Cavity A0

	-
A0	Dimension designed to accommodate the component width
В0	Dimension designed to accommodate the component length
K0	Dimension designed to accommodate the component thickness
W	Overall width of the carrier tape
P1	Pitch between successive cavity centers

## QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



#### \*All dimensions are nominal

Device	Package Type	Package Drawing		SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
BQ25600DYFFR	DSBGA	YFF	30	3000	180.0	8.4	2.09	2.59	0.78	4.0	8.0	Q1
BQ25600DYFFT	DSBGA	YFF	30	250	180.0	8.4	2.09	2.59	0.78	4.0	8.0	Q1
BQ25600YFFR	DSBGA	YFF	30	3000	180.0	8.4	2.09	2.59	0.78	4.0	8.0	Q1
BQ25600YFFT	DSBGA	YFF	30	250	180.0	8.4	2.09	2.59	0.78	4.0	8.0	Q1



www.ti.com 30-May-2024

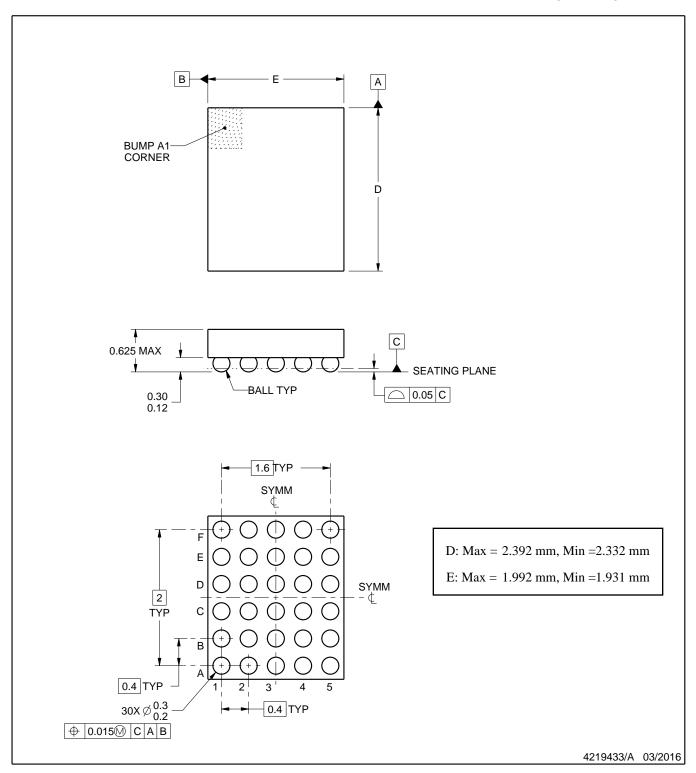


#### \*All dimensions are nominal

7 th difference are from that								
	Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
	BQ25600DYFFR	DSBGA	YFF	30	3000	182.0	182.0	20.0
	BQ25600DYFFT	DSBGA	YFF	30	250	182.0	182.0	20.0
	BQ25600YFFR	DSBGA	YFF	30	3000	182.0	182.0	20.0
	BQ25600YFFT	DSBGA	YFF	30	250	182.0	182.0	20.0



DIE SIZE BALL GRID ARRAY

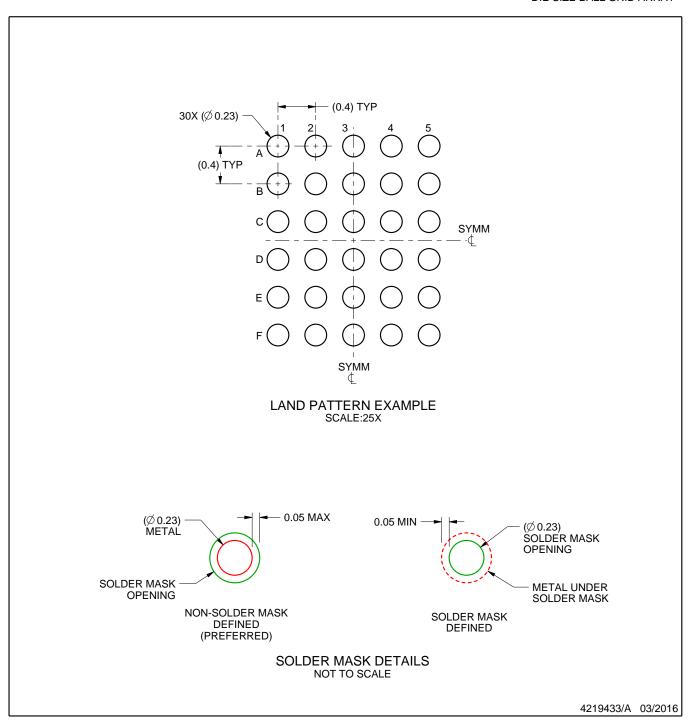


## NOTES:

- All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
- 2. This drawing is subject to change without notice.



DIE SIZE BALL GRID ARRAY

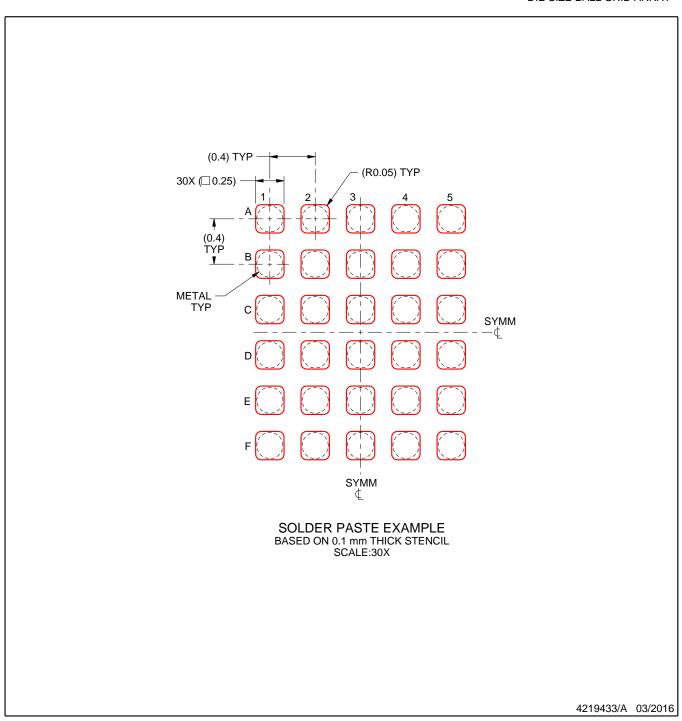


NOTES: (continued)

3. Final dimensions may vary due to manufacturing tolerance considerations and also routing constraints. For more information, see Texas Instruments literature number SNVA009 (www.ti.com/lit/snva009).



DIE SIZE BALL GRID ARRAY



NOTES: (continued)

4. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release.



## IMPORTANT NOTICE AND DISCLAIMER

TI PROVIDES TECHNICAL AND RELIABILITY DATA (INCLUDING DATASHEETS), DESIGN RESOURCES (INCLUDING REFERENCE DESIGNS), APPLICATION OR OTHER DESIGN ADVICE, WEB TOOLS, SAFETY INFORMATION, AND OTHER RESOURCES "AS IS" AND WITH ALL FAULTS, AND DISCLAIMS ALL WARRANTIES, EXPRESS AND IMPLIED, INCLUDING WITHOUT LIMITATION ANY IMPLIED WARRANTIES OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE OR NON-INFRINGEMENT OF THIRD PARTY INTELLECTUAL PROPERTY RIGHTS.

These resources are intended for skilled developers designing with TI products. You are solely responsible for (1) selecting the appropriate TI products for your application, (2) designing, validating and testing your application, and (3) ensuring your application meets applicable standards, and any other safety, security, regulatory or other requirements.

These resources are subject to change without notice. TI grants you permission to use these resources only for development of an application that uses the TI products described in the resource. Other reproduction and display of these resources is prohibited. No license is granted to any other TI intellectual property right or to any third party intellectual property right. TI disclaims responsibility for, and you fully indemnify TI and its representatives against any claims, damages, costs, losses, and liabilities arising out of your use of these resources.

TI's products are provided subject to TI's Terms of Sale, TI's General Quality Guidelines, or other applicable terms available either on ti.com or provided in conjunction with such TI products. TI's provision of these resources does not expand or otherwise alter TI's applicable warranties or warranty disclaimers for TI products. Unless TI explicitly designates a product as custom or customer-specified, TI products are standard, catalog, general purpose devices.

TI objects to and rejects any additional or different terms you may propose.

Copyright © 2025, Texas Instruments Incorporated

Last updated 10/2025