

OCTAL SIMULTANEOUS-SAMPLING 24-BIT ANALOG-TO-DIGITAL CONVERTER

Check for Samples: ADS1278-HT

FEATURES

- Simultaneously Measure Eight Channels
- Up to 128-kSPS Data Rate
- AC Performance:
 62-kHz Bandwidth
 111-dB SNR (High-Resolution Mode)
 -108-dB THD
- DC Accuracy: 0.8-µV/°C Offset Drift 1.3-ppm/°C Gain Drift
- Selectable Operating Modes:
 High-Speed: 128 kSPS, 106 dB SNR
 High-Resolution: 52 kSPS, 111 dB SNR
 Low-Power: 52 kSPS, 31 mW/ch
 Low-Speed: 10 kSPS, 7 mW/ch
- Linear Phase Digital Filter
- SPI™ or Frame-Sync Serial Interface
- Low Sampling Aperture Error
- Modulator Output Option (digital filter bypass)
- Analog Supply: 5 VDigital Core: 1.8 V
- I/O Supply: 1.8 V to 3.3 V
- Currently Available in an HTQFP-64
 PowerPAD™ package, an 84-Pin HFQ Package and a KGD Chiptray Option

SUPPORTS EXTREME TEMPERATURE APPLICATIONS

- Controlled Baseline
- One Assembly/Test Site
- One Fabrication Site
- Available in Extreme (-55°C/210°C)
 Temperature Range (1)
- Extended Product Life Cycle
- Extended Product-Change Notification
- Product Traceability
- Texas Instruments High Temperature Products
 Utilize Highly Optimized Silicon (Die) Solutions
 With Dsign and Process Enhancements to
 Maximize Performance Over Extended
 Temperatures
- (1) Custom temperature ranges available

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APPLICATIONS

- Down-Hole Drilling
- High Temperature Environments
- Vibration/Modal Analysis
- Multi-Channel Data Acquisition
- Acoustics/Dynamic Strain Gauges
- Pressure Sensors

DESCRIPTION

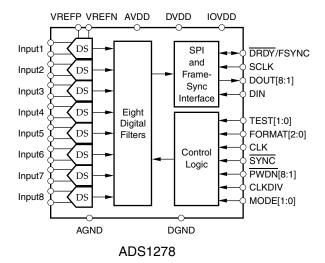
Based on the single-channel ADS1271, the ADS1278 (octal) is a 24-bit, delta-sigma ($\Delta\Sigma$) analog-to-digital converter (ADC) with data rates up to 128 k samples per second (SPS), allowing simultaneous sampling of eight channels.

Traditionally, industrial delta-sigma ADCs offering good drift performance use digital filters with large passband droop. As a result, they have limited signal bandwidth and are mostly suited for dc measurements. High-resolution ADCs in audio applications offer larger usable bandwidths, but the offset and drift specifications are significantly weaker than respective industrial counterparts. The ADS1278 combines these types of converters, allowing high-precision industrial measurement with excellent dc and ac specifications.

The high-order, chopper-stabilized modulator achieves very low drift with low in-band noise. The onboard decimation filter suppresses modulator and signal out-of-band noise. These ADCs provide a usable signal bandwidth up to 90% of the Nyquist rate with less than 0.005 dB of ripple.

Four operating modes allow for optimization of speed, resolution, and power. All operations are controlled directly by pins; there are no registers to program. The device is fully specified over the extended industrial range (–55°C to 210°C) and is available in an HTQFP-64 PowerPAD package (-55°C to 175°C), an 84-pin HFQ package and a KGD chiptray option.







This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

Table 1. ORDERING INFORMATION⁽¹⁾

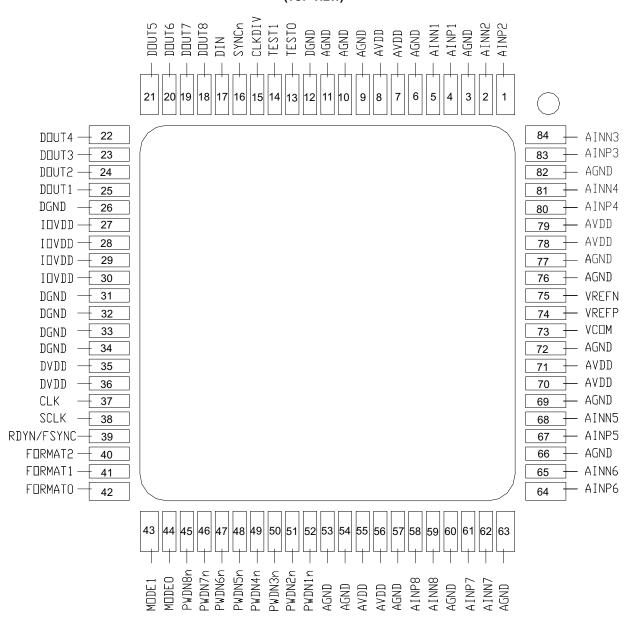
T _A	PACKAGE	ORDERABLE PART NUMBER
–55°C to 175°C	PAP	ADS1278HPAP
	HFQ	ADS1278SHFQ
-55°C to 210°C	HKP	ADS1278SHKP
	CHIPTRAY (bare die)	ADS1278SKGDA

⁽¹⁾ For the most current package and ordering information, see the Package Option Addendum at the end of this document, or see the TI Web site at www.ti.com.



PIN OUTS

HFQ OR HKP PACKAGE (TOP VIEW)





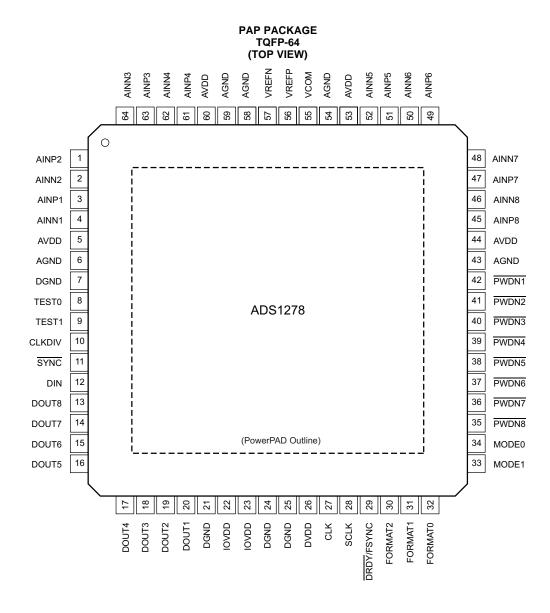




Table 2. HFQ or HKP PIN DESCRIPTIONS

PIN NAME	FUNCTION	DESCRIPTION					
AGND	Analog ground	Analog ground; connect to DGND using a single plane.					
AINP1	Analog input						
AINP2	Analog input						
AINP3	Analog input						
AINP4	Analog input	AINIDIO 41 Decitive engles input about all of through 4					
AINP5	Analog input	AINP[8:1] Positive analog input, channels 8 through 1.					
AINP6	Analog input						
AINP7	Analog input						
AINP8	Analog input						
AINN1	Analog input						
AINN2	Analog input						
AINN3	Analog input						
AINN4	Analog input	AININIO 41 No mativo caralla minarata ab anno la O abraviata 4					
AINN5	Analog input	AINN[8:1] Negative analog input, channels 8 through 1.					
AINN6	Analog input						
AINN7	Analog input						
AINN8	Analog input						
AVDD	Analog power supply	Analog power supply (4.75V to 5.25V).					
VCOM	Analog output	AVDD/2 Unbuffered voltage output.					
VREFN	Analog input	Negative reference input.					
VREFP	Analog input	Positive reference input.					
CLK	Digital input	Master clock input.					
CLKDIV	Digital input	CLK input divider control: 1 = 32.768MHz (High-Speed mode only) / 27MHz 0 = 13.5MHz (low-power) / 5.4MHz (low-speed)					
DGND	Digital ground	Digital ground power supply.					
DIN	Digital input	Daisy-chain data input.					
DOUT1	Digital output	DOUT1 is TDM data output (TDM mode).					
DOUT2	Digital output						
DOUT3	Digital output						
DOUT4	Digital output						
DOUT5	Digital output	DOUT[8:1] Data output for channels 8 through 1.					
DOUT6	Digital output						
DOUT7	Digital output						
DOUT8	Digital output						
DRDY/ FSYNC	Digital input/output	Frame-Sync protocol: frame clock input; SPI protocol: data ready output.					
DVDD	Digital power supply	Digital core power supply (+1.65V to +1.95V).					
FORMAT0	Digital input	FORMATION Calcute France Come/CDI and and TDM/Fee 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1					
FORMAT1	Digital input	FORMAT[2:0] Selects Frame-Sync/SPI protocol, TDM/discrete data outputs, fixed/dynamic position TDM data, and modulator mode/normal operating mode.					
FORMAT2	Digital input	, and a special specia					
IOVDD	Digital power supply	I/O power supply (+1.65V to +3.6V).					
MODE0	Digital input	MODE[1:0] Selects High-Speed, High-Resolution, Low-Power, or Low-Speed mode operation.					
MODE1	Digital input	mobel 1.01 Solecto Fight Operation, Low-Flower, or Low-Operation.					

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Table 2. HFQ or HKP PIN DESCRIPTIONS (continued)

PIN NAME	FUNCTION	DESCRIPTION						
PWDN1	Digital input							
PWDN2	Digital input							
PWDN3	Digital input							
PWDN4	Digital input	PWDN[8:1] Power-down control for channels 8 through 1.						
PWDN5	Digital input							
PWDN6	Digital input							
PWDN7	Digital input							
PWDN8	Digital input							
SCLK	Digital input/output	Serial clock input, Modulator clock	ck output.					
SYNC	Digital input	Synchronize input (all channels).						
TEST0	Digital input	TEST[1:0] Test mode select:	00 = Normal operation	01 = Do not use				
TEST1	Digital input		11 = Test mode 10 = Do not use			' 40 Daniel	10 = Do not use	

Table 3. PAP PIN DESCRIPTIONS

	PIN		5. FAF FIN DESCRIFTIONS			
NAME	NO.	FUNCTION	DESCRIPTION			
AGND	6, 43, 54, 58, 59	Analog ground	Analog ground; connect to DGND using a single plane.			
AINP1	3	Analog input				
AINP2	1	Analog input				
AINP3	63	Analog input				
AINP4	61	Analog input	AINP[8:1] Positive analog input, channels 8 through 1.			
AINP5	51	Analog input				
AINP6	49	Analog input				
AINP7	47	Analog input				
AINP8	45	Analog input				
AINN1	4	Analog input				
AINN2	2	Analog input				
AINN3	64	Analog input				
AINN4	62	Analog input	AINN[8:1] Negative analog input, channels 8 through 1.			
AINN5	52	Analog input				
AINN6	50	Analog input				
AINN7	48	Analog input				
AINN8	46	Analog input				
AVDD	5, 44, 53, 60	Analog power supply	Analog power supply (4.75V to 5.25V).			
VCOM	55	Analog output	AVDD/2 Unbuffered voltage output.			
VREFN	57	Analog input	Negative reference input.			
VREFP	56	Analog input	Positive reference input.			
CLK	27	Digital input	Master clock input (f _{CLK}).			
CLKDIV	10	Digital input	CLK input divider control: 1 = 37MHz (High-Speed mode)/otherwise 27MHz 0 = 13.5MHz (low-power)/5.4MHz (low-speed)			
DGND	7, 21, 24, 25	Digital ground	Digital ground power supply.			
DIN	12	Digital input	Daisy-chain data input.			
DOUT1	20	Digital output	DOUT1 is TDM data output (TDM mode).			
DOUT2	19	Digital output				
DOUT3	18	Digital output				
DOUT4	17	Digital output	DOUT[8:1] Data output for channels 8 through 1.			

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Table 3. PAP PIN DESCRIPTIONS (continued)

I	PIN						
NAME	NO.	FUNCTION	DESCRIPTION				
DOUT5	16	Digital output					
DOUT6	15	Digital output					
DOUT7	14	Digital output					
DOUT8	13	Digital output					
DRDY/ FSYNC	29	Digital input/output	Frame-Sync protocol: frame clock input; SPI protocol: data ready output.				
DVDD	26	Digital power supply	Digital core power supply.				
FORMAT0	32	Digital input					
FORMAT1	31	Digital input	l input				
FORMAT2	30	Digital input	Tixed/dynamic position 15 w data, and modulator mode/normal operating mode.				
IOVDD	22, 23	Digital power supply	I/O power supply (+1.65V to +3.6V).				
MODE0	34	Digital input	MODE[1:0] Selects High-Speed, High-Resolution, Low-Power, or Low-Speed				
MODE1	33	Digital input	mode operation.				
PWDN1	42	Digital input					
PWDN2	41	Digital input					
PWDN3	40	Digital input					
PWDN4	39	Digital input	PWDN[8:1] Power-down control for channels 8 through 1.				
PWDN5	38	Digital input					
PWDN6	37	Digital input					
PWDN7	36	Digital input					
PWDN8	35	Digital input					
SCLK	28	Digital input/output	utput Serial clock input, Modulator clock output.				
SYNC	11	Digital input	Synchronize input (all channels).				
TEST0	8	Digital input	TEST[1:0] Test mode select: 00 = Normal operation 01 = Do not use				
TEST1	9	Digital input	11 = Test mode 10 = Do not use				



BARE DIE INFORMATION

DIE THICKNESS	BACKSIDE FINISH	BACKSIDE POTENTIAL	BOND PAD METALLIZATION COMPOSITION
15 mils	Silicon with backgrind	GND	AlCu

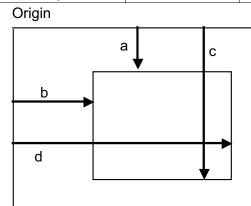


Table 4. Bond Pad Coordinates in Microns - Rev A⁽¹⁾

DISCRIPTION	PAD NUMBER	а	b	С	d
Do not connect	1	5.00	4455.65	70.00	4520.65
AINP2	2	5.00	4355.65	70.00	4420.65
AINN2	3	5.00	4255.65	70.00	4320.65
Do not connect	4	5.00	4155.65	70.00	4220.65
Do not connect	5	5.00	4038.30	70.00	4103.30
AINP1	6	5.00	3938.30	70.00	4003.30
AINN1	7	5.00	3838.30	70.00	3903.30
Do not connect	8	5.00	3738.30	70.00	3803.30
AVDD	9	5.00	3373.30	70.00	3678.30
AGND	10	5.00	3033.30	70.00	3338.30
Do not connect	11	5.00	2853.30	70.00	2998.30
DGND	12	5.00	1911.65	70.00	1976.65
TEST0	13	5.00	1760.45	70.00	1825.45
Do not connect	14	5.00	1648.95	70.00	1713.95
TEST1	15	5.00	1536.60	70.00	1601.60
CLKDIV	16	5.00	1385.40	70.00	1450.40
SYNC	17	5.00	1234.20	70.00	1299.20
DIN	18	5.00	1083.00	70.00	1148.00
DOUT8	19	5.00	780.60	70.00	845.60
DOUT7	20	5.00	629.40	70.00	694.40
DOUT6	21	5.00	478.20	70.00	543.20
DOUT5	22	5.00	275.80	70.00	340.80
DOUT4	23	275.80	5.00	340.80	70.00
DOUT3	24	745.40	5.00	810.40	70.00
DOUT2	25	1099.30	5.00	1164.30	70.00
DOUT1	26	1250.50	5.00	1315.50	70.00
DGND	27	1525.25	5.00	1590.25	70.00
IOVDD	28	1691.00	5.00	1756.00	70.00
IOVDD	29	1842.20	5.00	1907.20	70.00

Product Folder Links: ADS1278-HT

For signal descriptions see the Pin Descriptions table.



Table 4. Bond Pad Coordinates in Microns - Rev A⁽¹⁾ (continued)

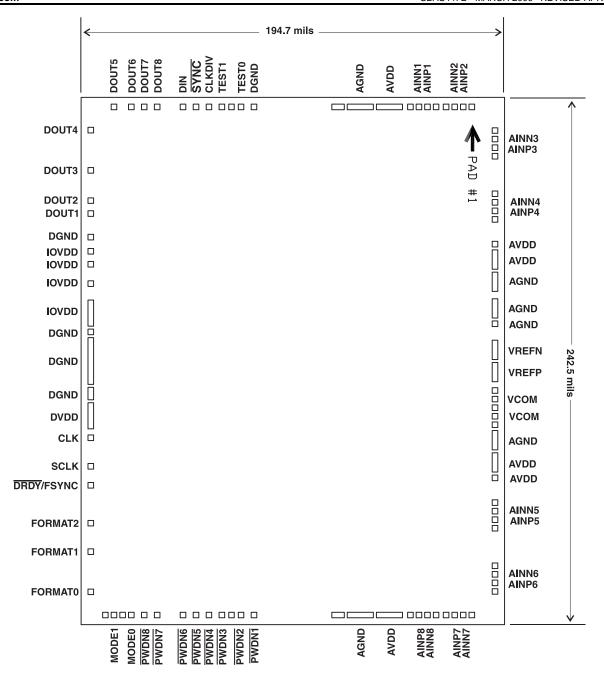
DISCRIPTION	PAD NUMBER	а	b	С	d
IOVDD	30	2068.10	5.00	2133.10	70.00
IOVDD	31	2292.45	5.00	2597.45	70.00
DGND	32	2632.45	5.00	2697.45	70.00
DGND	33	2732.45	5.00	3277.45	70.00
DGND	34	3312.45	5.00	3457.45	70.00
DVDD	35	3492.45	5.00	3797.45	70.00
CLK	36	3869.40	5.00	3934.40	70.00
SCLK	37	4201.90	5.00	4266.90	70.00
DRDY/FSYNC	38	4423.90	5.00	4488.90	70.00
FORMAT2	39	4866.90	5.00	4931.90	70.00
FORMAT1	40	5199.40	5.00	5264.40	70.00
FORMAT0	41	5669.00	5.00	5734.00	70.00
MODE1	42	5939.80	275.80	6004.80	340.80
MODE0	43	5939.80	478.20	6004.80	543.20
PWDN8	44	5939.80	629.40	6004.80	694.40
PWDN7	45	5939.80	780.60	6004.80	845.60
PWDN6	46	5939.80	1083.00	6004.80	1148.00
PWDN5	47	5939.80	1234.20	6004.80	1299.20
PWDN4	48	5939.80	1385.40	6004.80	1450.40
PWDN3	49	5939.80	1536.60	6004.80	1601.60
Do not connect	50	5939.80	1648.95	6004.80	1713.95
PWDN2	51	5939.80	1760.45	6004.80	1825.45
PWDN1	52	5939.80	1911.65	6004.80	1976.65
Do not connect	53	5939.80	2853.30	6004.80	2998.30
AGND	54	5939.80	3033.30	6004.80	3338.30
AVDD	55	5939.80	3373.30	6004.80	3678.30
Do not connect	56	5939.80	3738.30	6004.80	3803.30
AINP8	57	5939.80	3838.30	6004.80	3903.30
AINN8	58	5939.80	3938.30	6004.80	4003.30
Do not connect	59	5939.80	4038.30	6004.80	4103.30
Do not connect	60	5939.80	4155.65	6004.80	4220.65
AINP7	61	5939.80	4255.65	6004.80	4320.65
AINN7	62	5939.80	4355.65	6004.80	4420.65
Do not connect	63	5939.80	4455.65	6004.80	4520.65
Do not connect	64	5664.20	4726.45	5729.20	4791.45
AINP6	65	5564.20	4726.45	5629.20	4791.45
AINN6	66	5464.20	4726.45	5529.20	4791.45
Do not connect	67	5364.20	4726.45	5429.20	4791.45
Do not connect	68	4925.95	4726.45	4990.95	4791.45
AINP5	69	4825.95	4726.45	4890.95	4791.45
AINN5	70	4725.95	4726.45	4790.95	4791.45
Do not connect	71	4625.95	4726.45	4690.95	4791.45
AVDD	72	4337.40	4726.45	4402.40	4791.45
AVDD	73	4077.40	4726.45	4302.40	4791.45
AGND	74	3817.40	4726.45	4042.40	4791.45
Do not connect	75	3717.40	4726.45	3782.40	4791.45
VCOM	76	3617.40	4726.45	3682.40	4791.45



Table 4. Bond Pad Coordinates in Microns - Rev A⁽¹⁾ (continued)

DISCRIPTION	PAD NUMBER	а	b	С	d
Do not connect	77	3517.40	4726.45	3582.40	4791.45
VCOM	78	3417.40	4726.45	3482.40	4791.45
Do not connect	79	3317.40	4726.45	3382.40	4791.45
VREFP	80	3022.40	4726.45	3247.40	4791.45
VREFN	81	2762.40	4726.45	2987.40	4791.45
AGND	82	2537.40	4726.45	2602.40	4791.45
AGND	83	2277.40	4726.45	2502.40	4791.45
AGND	84	1967.40	4726.45	2192.40	4791.45
AVDD	85	1707.40	4726.45	1932.40	4791.45
AVDD	86	1607.40	4726.45	1672.40	4791.45
Do not connect	87	1318.85	4726.45	1383.85	4791.45
AINP4	88	1218.85	4726.45	1283.85	4791.45
AINN4	89	1118.85	4726.45	1183.85	4791.45
Do not connect	90	1018.85	4726.45	1083.85	4791.45
Do not connect	91	580.60	4726.45	645.60	4791.45
AINP3	92	480.60	4726.45	545.60	4791.45
AINN3	93	380.60	4726.45	445.60	4791.45
Do not connect	94	280.60	4726.45	345.60	4791.45
Do not connect	95	5939.80	377.00	6004.80	442.00
Do not connect	96	5939.80	175.80	6004.80	240.80







ABSOLUTE MAXIMUM RATINGS

Over operating free-air temperature range, unless otherwise noted(1)

			UNIT		
AVDD to AGND		-0.3 to 6.0	V		
DVDD, IOVDD to DGND		-0.3 to 3.6	V		
AGND to DGND		-0.3 to 0.3	V		
Input current	Momentary	100	mA		
	Continuous	10	mA		
Analog input to AGND		-0.3 to AVDD + 0.3	V		
Digital input or output to DGND		-0.3 to DVDD + 0.3	V		
<u> </u>	HFQ and HKP Packages	-55 to 217	°C		
	D Package	–55 to 175			

⁽¹⁾ Stresses above these ratings may cause permanent damage. Exposure to absolute maximum conditions for extended periods may degrade device reliability. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those specified is not implied.

THERMAL INFORMATION

		ADS	1278	
	THERMAL METRIC(1)	PAP	HFQ/HKP	UNITS
		64 PINS	84 PINS	
θ_{JA}	Junction-to-ambient thermal resistance (2)	33.1	21.813	
θ_{JCtop}	Junction-to-case (top) thermal resistance (3)	6.2	0.849	
θ_{JB}	Junction-to-board thermal resistance ⁽⁴⁾	7.9	N/A	0000
ΨЈТ	Junction-to-top characterization parameter ⁽⁵⁾	0.2	N/A	°C/W
Ψ_{JB}	Junction-to-board characterization parameter ⁽⁶⁾	7.8	N/A	
θ_{JCbot}	Junction-to-case (bottom) thermal resistance (7)	0.2	N/A	

- (1) For more information about traditional and new thermal metrics, see the IC Package Thermal Metrics application report, SPRA953.
- (2) The junction-to-ambient thermal resistance under natural convection is obtained in a simulation on a JEDEC-standard, high-K board, as specified in JESD51-7, in an environment described in JESD51-2a.
- (3) The junction-to-case (top) thermal resistance is obtained by simulating a cold plate test on the package top. No specific JEDEC-standard test exists, but a close description can be found in the ANSI SEMI standard G30-88.
- (4) The junction-to-board thermal resistance is obtained by simulating in an environment with a ring cold plate fixture to control the PCB temperature, as described in JESD51-8.
- (5) The junction-to-top characterization parameter, ψ_{JT} , estimates the junction temperature of a device in a real system and is extracted from the simulation data for obtaining θ_{JA} , using a procedure described in JESD51-2a (sections 6 and 7).
- (6) The junction-to-board characterization parameter, ψ_{JB}, estimates the junction temperature of a device in a real system and is extracted from the simulation data for obtaining θ_{JA}, using a procedure described in JESD51-2a (sections 6 and 7).
- (7) The junction-to-case (bottom) thermal resistance is obtained by simulating a cold plate test on the exposed (power) pad. No specific JEDEC standard test exists, but a close description can be found in the ANSI SEMI standard G30-88.



ELECTRICAL CHARACTERISTICS

All specifications at $T_A = T_J = -55^{\circ}\text{C}$ to 210°C, AVDD = 5 V, DVDD = 1.8 V, IOVDD = 3.3 V, $f_{CLK} = 27$ MHz, VREFP = 2.5 V, VREFN = 0 V, and all channels active, unless otherwise noted.

			T _A = -	55°C to 125	5°C	T _A	= 210°C ⁽¹⁾		
PA	RAMETER	TEST CONDITIONS	MIN	TYP	MAX	MIN	TYP	MAX	UNIT
Analog Inputs		+							
Full-scale input vol	tage (FSR ⁽²⁾)	$V_{IN} = (AINP - AINN)$		±V _{REF}			±V _{REF}		V
Common-mode input voltage (FSR (2)) Absolute input voltage Common-mode input voltage (V _{CM}) High-Speed mode Low-Power mode Low-Speed mode Resolution High-Speed mode		AINP or AINN to AGND	AGND - 0.1		AVDD + 0.1	AGND – 0.1		AVDD + 0.1	٧
Common-mode inp	out voltage (V _{CM})	V _{CM} = (AINP + AINN)/2		2.5			2.5		V
Differential input mpedance High-Result Low-Pov Low-Spe	High-Speed mode			14			14		kΩ
Differential input	High-Resolution mode			14			14		kΩ
impedance	Low-Power mode			28			28		kΩ
Differential input impedance High-Resolution Low-Power mode Low-Speed mode Resolution High-Speed mode Low-Power mode Low-Power mode Low-Power mode Low-Power mode Low-Speed mode Low-Speed mode Low-Speed mode Low-Speed mode Resolution High-Resolution Low-Speed mode Low-Power mode Low-Power mode Low-Power mode Low-Power mode Low-Power mode Low-Power mode Low-Speed mode	Low-Speed mode			140			140		kΩ
DC Performance					<u> </u>				
Resolution No missing codes		24						Bits	
		f _{CLK} = 32.768MHz ⁽³⁾		128,000			128,000		SPS
	High-Speed mode	f _{CLK} = 27MHz		105,469			105,469		SPS ⁽⁴⁾
Data rate (f _{DATA})	High-Resolution mode			52,734			52,734	69 34 34	SPS
	Low-Power mode			52,734			52,734		SPS
	Low-Speed mode			10,547			10,547		SPS
Integral nonlinearit	y (INL) ⁽⁵⁾	Differential input, V _{CM} = 2.5V		±0.0003	±0.0012			±0.0014	% FSR ⁽²⁾
Offset error				0.25	2			2	mV
Offset drift				0.8					μV/°C
Offset drift Gain error				0.1	0.5			0.5	% FSR
Gain drift				1.3					ppm/°C
	High-Speed mode	Shorted input		8.5	21			21	μV, rms
	High-Resolution mode	Shorted input		5.5	13			0.5	μV, rms
Noise	Low-Power mode	Shorted input		8.5	21			21	μV, rms
	Low-Speed mode	Shorted input		8.0	21		TYP MAX ±V _{REF} AVDD + 0.1 2.5 14 14 28 140 128,000 105,469 52,734 52,734 10,547 ±0.0014 2 0.5 21 13 21	μV, rms	
Common-mode rej	ection	f _{CM} = 60Hz	90	108		90			dB
	AVDD			80			80		dB
Power-supply	DVDD	$f_{PS} = 60Hz$		85			85		dB
rejection	IOVDD			105			102		dB
V _{COM} output voltage	ie	No load		AVDD/2			AVDD/2		V
AC Performance		1	l .		1				
Crosstalk		f = 1kHz, -0.5dBFS ⁽⁶⁾		-107					dB
	High-Speed mode	,	98	106		96			dB
0		V _{REF} = 2.5V	101	110		101			dB
Signal-to-noise ratio (SNR) ⁽⁷⁾	High-Resolution mode	V _{REF} = 3V	-	111					dB
(unweighted)	Low-Power mode	1361	98	106		97			dB
	Low-Speed mode		98	107		98			dB
Total harmonic dis		V _{IN} = 1kHz, -0.5dBFS		-108	-96			-96	dB
Spurious-free dyna		, , , , , , , , , , , , , , , , , , , ,		109					dB
Passband ripple				±0.005					dB

⁽¹⁾ Minimum and maximum parameters are characterized for operation at T_A = 175°C but may not be production tested at that temperature. Production test limits with statistical guardbands are used to ensure high temperature performance.

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⁽²⁾ $FSR = full-scale range = 2V_{REF}$.

⁽³⁾ $f_{CLK} = 32.768MHz$ max for High-Speed mode, and 27MHz max for all other modes. When $f_{CLK} > 27MHz$, operation is limited to Frame-Sync mode and $V_{REF} \le 2.6V$.

⁽⁴⁾ SPS = samples per second.

⁽⁵⁾ Best fit method.

⁽⁶⁾ Worst-case channel crosstalk between one or more channels.

⁽⁷⁾ Minimum SNR is ensured by the limit of the *DC noise* specification.

⁽⁸⁾ THD includes the first nine harmonics of the input signal; Low-Speed mode includes the first five harmonics.



All specifications at $T_A = T_J = -55^{\circ}\text{C}$ to 210°C, AVDD = 5 V, DVDD = 1.8 V, IOVDD = 3.3 V, $f_{CLK} = 27$ MHz, VREFP = 2.5 V, VREFN = 0 V, and all channels active, unless otherwise noted.

			T _A = -	-55°C to 12	5°C	$T_A = 210^{\circ}C^{(1)}$			
P	ARAMETER	TEST CONDITIONS	MIN	TYP	MAX	MIN	TYP	MAX	UNIT
Passband				0.453 f _{DATA}					Hz
-3dB Bandwidth				0.49 f _{DATA}					Hz
Stop band	High-Resolution mode		95	DATA					dB
attenuation	All other modes		100						
			0.547		127.453				11-
Stop band	High-Resolution mode		f _{DATA}		f_{DATA}				Hz
Otop band	All other modes		0.547 f _{DATA}		63.453 f _{DATA}				Hz
Group delay	High-Resolution mode			39/f _{DATA}					s
Group delay	All other modes			$38/f_{DATA}$					s
Settling time	High-Resolution mode	Complete settling		78/f _{DATA}					S
(latency)	All other modes	Complete settling		76/f _{DATA}					s
Voltage Reference	ce Inputs								
Reference input v	roltage (V _{REF})	f _{CLK} = 27MHz	0.5	2.5	3.1	0.5	2.5	3.1	V
(V _{REF} = VREFP -	VREFN)	f _{CLK} = 32.768MHz ⁽³⁾	0.5	2.5	2.6	0.5	2.5	2.6	V
Negative reference	e input (VREFN)		AGND - 0.1		AGND + 0.1	AGND – 0.1		AGND + 0.1	V
Positive reference	e input (VREFP)		VREFN + 0.5		AVDD + 0.1	VREFN + 0.5		AVDD + 0.1	V
Reference Input impedance	High-Speed mode			0.65			0.65		kΩ
	High-Resolution mode			0.65			0.65		kΩ
	Low-Power mode			1.3			1.3		kΩ
	Low-Speed mode			6.5			6.5		kΩ
Digital Input/Out 3.6V)	put (IOVDD = 1.8V to							·	
V _{IH}			0.7 IOVDD		IOVDD	0.7 IOVDD		IOVDD	V
V _{IL}			DGND		0.3 IOVDD	DGND		0.3 IOVDD	V
V _{OH}		I _{OH} = 4mA	0.8 IOVDD		IOVDD	0.8 IOVDD		IOVDD	V
V _{OL}		I _{OL} = 4mA	DGND		0.2 IOVDD	DGND		0.2 IOVDD	V
Input leakage		0 < V _{IN DIGITAL} < IOVDD			±10				μΑ
Master clock rate	(f)	High-Speed mode (9)	0.1		32.768	0.1		32.768	MHz
	(iCLK)	Other modes	0.1		27	0.1		27	MHz
Power Supply									
AVDD			4.75	5	5.25	4.75	5	5.25	V
DVDD			1.65	1.8	1.95	1.65	1.8	1.95	V
IOVDD	T		1.65		3.6	1.65		3.6	V
	AVDD			1	10		65		μΑ
Power-down current	DVDD			1	50		200		μΑ
	IOVDD			1	11		25		μΑ
	High-Speed mode			97	145		135	185	mA
AVDD current	High-Resolution mode			97	145		135	185	mA
AVDD Callell	Low-Power mode			44	64		60	84	mA
	Low-Speed mode			9	14		12	22	mA

⁽⁹⁾ $f_{CLK} = 32.768MHz$ max for High-Speed mode, and 27MHz max for all other modes. When $f_{CLK} > 27MHz$, operation is limited to Frame-Sync mode and $V_{REF} \le 2.6V$.

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All specifications at $T_A = T_J = -55^{\circ}\text{C}$ to 210°C, AVDD = 5 V, DVDD = 1.8 V, IOVDD = 3.3 V, $f_{CLK} = 27$ MHz, VREFP = 2.5 V, VREFN = 0 V, and all channels active, unless otherwise noted.

			T _A = -55	5°C to 125°	C	T _A =	: 210°C ⁽¹⁾		
PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	MIN	TYP	MAX	UNIT
	High-Speed mode			23	30		24	31	mA
DVDD current	High-Resolution mode			16	20		17	20	mA
DVDD current	Low-Power mode			12	17		13	17	mA
	Low-Speed mode			2.5	4.5		3	5	mA
	High-Speed mode			0.25	1		0.3	1.15	mA
IOVDD current	High-Resolution mode			0.125	0.6		0.2	0.75	mA
IOVDD current	Low-Power mode			0.125	0.6		0.2	0.75	mA
	Low-Speed mode			0.035	0.3		0.1	0.45	mA
	High-Speed mode			530	785			985	mW
	High-Resolution mode			515	765			985	mW
Power dissipation	Low-Power mode			245	355			455	mW
	Low-Speed mode			50	80			120	mW

Product Folder Links: ADS1278-HT



ELECTRICAL CHARACTERISTICS

All specifications at $T_A = -55^{\circ}\text{C}$ to 175°C , AVDD = 5 V, DVDD = 1.8 V, IOVDD = 3.3 V, $f_{CLK} = 27$ MHz, VREFP = 2.5 V, VREFN = 0 V, and all channels active, unless otherwise noted.

			$T_A = -55$ °C to 175°C (PAP Package)		ackage)	
PARAMETER		TEST CONDITIONS	MIN TYP MAX			UNIT
Analog Inputs			-			
Full-scale input voltage ((FSR ⁽¹⁾)	V _{IN} = (AINP – AINN)		±V _{REF}		V
Absolute input voltage		AINP or AINN to AGND	AGND – 0.1		AVDD + 0.1	V
Common-mode input vol	Itage (V _{CM})	$V_{CM} = (AINP + AINN)/2$		2.5		V
	High-Speed mode			14		kΩ
Differential input	High-Resolution mode			14		kΩ
impedance .	Low-Power mode			28		kΩ
	Low-Speed mode			140		kΩ
DC Performance						
Resolution		No missing codes	24			Bits
	High Conned and	f _{CLK} = 32.768MHz ⁽²⁾		128,000		SPS
	High-Speed mode	f _{CLK} = 27MHz		105,469		SPS ⁽³⁾
Data rate (f _{DATA})	High-Resolution mode			52,734		SPS
	Low-Power mode			52,734		SPS
	Low-Speed mode			10,547		SPS
Integral nonlinearity (INL) ⁽⁴⁾	Differential input, V _{CM} = 2.5V		±0.0003	±0.0015	% FSR ⁽¹⁾
Offset error	•			0.25	3	mV
Offset drift				0.8		μV/°C
Gain error				0.1	0.5	% FSR
Gain drift				1.3		ppm/°C
	High-Speed mode	Shorted input		8.5	68	μV, rms
	High-Resolution mode	Shorted input		5.5	13	μV, rms
Noise	Low-Power mode	Shorted input		8.5	21	μV, rms
	Low-Speed mode	Shorted input		8.0	21	μV, rms
Common-mode rejection	· 1	f _{CM} = 60Hz	90	108		dB
	AVDD			80		dB
Power-supply rejection	DVDD	f _{PS} = 60Hz		85		dB
,	IOVDD			105		dB
V _{COM} output voltage		No load		AVDD/2		V
AC Performance		1	L			
Crosstalk		$f = 1kHz, -0.5dBFS^{(5)}$		-107		dB
	High-Speed mode	· ·	88	106		dB
		V _{REF} = 2.5V	101	110		dB
Signal-to-noise ratio	High-Resolution mode	$V_{REF} = 3V$		111		dB
(SNR) ⁽⁶⁾ (unweighted)	Low-Power mode	1121	98	106		dB
	Low-Speed mode		98	107		dB
Total harmonic distortion	·	V _{IN} = 1kHz, -0.5dBFS		-108	-96	dB
Spurious-free dynamic ra		, , , , , , , , , , , , , , , , , , , ,		109		dB
Passband ripple	<u> </u>			±0.005		dB
Passband				0.453 f _{DATA}		Hz
-3dB Bandwidth				0.49 f _{DATA}		Hz

- (1) FSR = full-scale range = 2V_{REF}.
 (2) f_{CLK} = 32.768MHz max for High-Speed mode, and 27MHz max for all other modes. When f_{CLK} > 27MHz, operation is limited to Frame-Sync mode and V_{REF} ≤ 2.6V.
- SPS = samples per second.
- Best fit method.
- (5) Worst-case channel crosstalk between one or more channels.
- Minimum SNR is ensured by the limit of the DC noise specification.
- THD includes the first nine harmonics of the input signal; Low-Speed mode includes the first five harmonics. (7)

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All specifications at $T_A = -55^{\circ}\text{C}$ to 175°C , AVDD = 5 V, DVDD = 1.8 V, IOVDD = 3.3 V, $f_{CLK} = 27$ MHz, VREFP = 2.5 V, VREFN = 0 V, and all channels active, unless otherwise noted.

			$T_A = -55^{\circ}C \text{ to } 17$		175°C (PAP Package)		= -55°C to 175°C (PAP Package)	
F	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT		
Stan hand attanuation	High-Resolution mode		95			dB		
Stop band attenuation	All other modes		100					
Stop band	High-Resolution mode		0.547 f _{DATA}		127.453 f _{DATA}	Hz		
Stop barid	All other modes		0.547 f _{DATA}		63.453 f _{DATA}	Hz		
Group delay	High-Resolution mode			39/f _{DATA}		s		
Group delay	All other modes			38/f _{DATA}		s		
Settling time (latency)	High-Resolution mode	Complete settling		78/f _{DATA}		s		
Settling time (latericy)	All other modes	Complete settling		76/f _{DATA}		s		
Voltage Reference Inp	outs							
Reference input voltage		f _{CLK} = 27MHz	0.5	2.5	3.1	V		
(V _{REF} = VREFP - VRE		f _{CLK} = 32.768MHz ⁽²⁾	0.5	2.5	2.6	V		
Negative reference inpo	ut (VREFN)		AGND - 0.1		AGND + 0.1	V		
Positive reference inpu	t (VREFP)		VREFN + 0.5		AVDD + 0.1	V		
	High-Speed mode			0.65		kΩ		
Reference Input	High-Resolution mode			0.65		kΩ		
impedance	Low-Power mode			1.3		kΩ		
	Low-Speed mode			6.5		kΩ		
Digital Input/Output (I	OVDD = 1.8V to 3.6V)							
V _{IH}			0.7 IOVDD		IOVDD	V		
V_{IL}			DGND		0.3 IOVDD	V		
V _{OH}		I _{OH} = 4mA	0.8 IOVDD		IOVDD	V		
V _{OL}		I _{OL} = 4mA	DGND		0.2 IOVDD	V		
Input leakage		0 < V _{IN DIGITAL} < IOVDD			±10	μΑ		
Master clock rate (f _{CLK})		High-Speed mode ⁽⁸⁾	0.1		32.768	MHz		
iviaster clock rate (I _{CLK})		Other modes	0.1		27	MHz		
Power Supply								
AVDD			4.75	5	5.25	V		
DVDD			1.65	1.8	1.95	V		
IOVDD			1.65		3.6	V		
	AVDD			40	60	μΑ		
Power-down current	DVDD			50	85	μΑ		
	IOVDD			24	40	μΑ		
	High-Speed mode			130	150	mA		
AVDD current	High-Resolution mode			130	150	mA		
	Low-Power mode			58	68	mA		
	Low-Speed mode			13	17	mA		
	High-Speed mode			23	30	mA		
DVDD current	High-Resolution mode			16	20	mA		
היא ס canent	Low-Power mode			12	17	mA		
	Low-Speed mode			3.5	4.5	mA		

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⁽⁸⁾ $f_{CLK} = 32.768 MHz$ max for High-Speed mode, and 27MHz max for all other modes. When $f_{CLK} > 27 MHz$, operation is limited to Frame-Sync mode and $V_{REF} \le 2.6 V$.

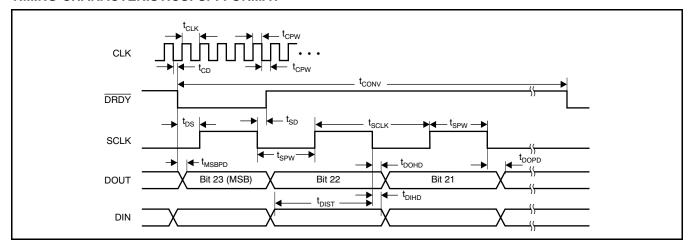


All specifications at $T_A = -55^{\circ}\text{C}$ to 175°C , AVDD = 5 V, DVDD = 1.8 V, IOVDD = 3.3 V, $f_{\text{CLK}} = 27$ MHz, VREFP = 2.5 V, VREFN = 0 V, and all channels active, unless otherwise noted.

			T _A = -55°C to 175°C (PAP Package)			
PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
	High-Speed mode			0.5	1.1	mA
IOVDD current	High-Resolution mode			0.3	0.6	mA
	Low-Power mode			0.3	0.6	mA
	Low-Speed mode			0.1	0.5	mA
	High-Speed mode			530	805	mW
Dower dissipation	High-Resolution mode			515	785	mW
Power dissipation	Low-Power mode			245	440	mW
	Low-Speed mode			50	89	mW



TIMING CHARACTERISTICS: SPI FORMAT



TIMING REQUIREMENTS: SPI FORMAT(1)

For $T_A = -40^{\circ}$ C to 125°C. IOVDD = 1.65 V to 3.6 V, and DVDD = 1.65 V to 1.95 V.

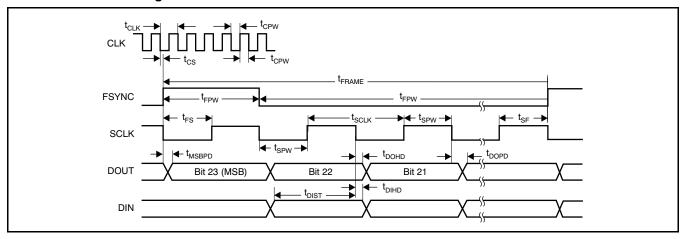
SYMBOL	PARAMETER	MIN	TYP	MAX	UNIT
t _{CLK}	CLK period (1/f _{CLK}) ⁽²⁾	37		10,000	ns
t _{CPW}	CLK positive or negative pulse width	15			ns
t _{CONV}	Conversion period (1/f _{DATA}) ⁽³⁾	256		2560	t_{CLK}
t _{CD} ⁽⁴⁾	Falling edge of CLK to falling edge of DRDY		22		ns
t _{DS} ⁽⁴⁾	Falling edge of DRDY to rising edge of first SCLK to retrieve data	1			t _{CLK}
t _{MSBPD}	DRDY falling edge to DOUT MSB valid (propagation delay)			16	ns
t _{SD} (4)	Falling edge of SCLK to rising edge of DRDY		18		ns
t _{SCLK} (5)	SCLK period	1			t_{CLK}
t _{SPW}	SCLK positive or negative pulse width	0.4			t_{CLK}
t _{DOHD} (4) (6)	SCLK falling edge to new DOUT invalid (hold time)	10			ns
t _{DOPD} (4)	SCLK falling edge to new DOUT valid (propagation delay)			32	ns
t _{DIST}	New DIN valid to falling edge of SCLK (setup time)	6			ns
t _{DIHD} (6)	Old DIN valid to falling edge of SCLK (hold time)	6			ns

- Timing parameters are characerized or guranteed by design for specified temperature but not production tested.
- (2)
- $f_{CLK} = 27 MHz$ maximum. Depends on MODE[1:0] and CLKDIV selection. See Table 10 (f_{CLK}/f_{DATA}).
- (4) (5) Load on \overline{DRDY} and $\overline{DOUT} = 20pF$.
- For best performance, limit f_{SCLK}/f_{CLK} to ratios of 1, 1/2, 1/4, 1/8, etc. t_{DOHD} (DOUT hold time) and t_{DIHD} (DIN hold time) are specified under opposite worst-case conditions (digital supply voltage and ambient temperature). Under equal conditions, with DOUT connected directly to DIN, the timing margin is >4ns.

Product Folder Links: ADS1278-HT



Figure 1. TIMING CHARACTERISTICS: FRAME-SYNC FORMAT



TIMING REQUIREMENTS: FRAME-SYNC FORMAT(1)

For $T_A = -40^{\circ}$ C to 125°C, IOVDD = 1.65 V to 3.6 V, and DVDD = 1.65 V to 1.95 V.

SYMBOL	PARAMETER		MIN	TYP	MAX	UNIT
		All modes	37		10,000	ns
t _{CLK}	CLK period (1/f _{CLK})	High-Speed mode only	30.5			ns
t _{CPW}	CLK positive or negative pulse width		12			ns
t _{CS}	Falling edge of CLK to falling edge of SC	CLK	-0.25		0.25	t _{CLK}
t _{FRAME}	Frame period (1/f _{DATA}) ⁽²⁾		256		2560	t _{CLK}
t _{FPW}	FSYNC positive or negative pulse width		1			t _{SCLK}
t _{FS}	Rising edge of FSYNC to rising edge of SCLK		5			ns
t _{SF}	Rising edge of SCLK to rising edge of FSYNC		5			ns
t _{SCLK}	SCLK period ⁽³⁾		1			t_{CLK}
t _{SPW}	SCLK positive or negative pulse width		0.4			t _{CLK}
t _{DOHD} (4) (5)	SCLK falling edge to old DOUT invalid (hold time)		10			ns
t _{DOPD} (5)	SCLK falling edge to new DOUT valid (propagation delay)				31	ns
t _{MSBPD}	FSYNC rising edge to DOUT MSB valid (propagation delay)				31	ns
t _{DIST}	New DIN valid to falling edge of SCLK (setup time)		6			ns
t _{DIHD} (4)	Old DIN valid to falling edge of SCLK (hold time)		6			ns

- (3)
- Timing parameters are characerized or guranteed by design for specified temperature but not production tested. Depends on MODE[1:0] and CLKDIV selection. See Table 10 (f_{CLK}/f_{DATA}). SCLK must be continuously running and limited to ratios of 1, 1/2, 1/4, and 1/8 of f_{CLK}. t_{DOHD} (DOUT hold time) and t_{DIHD} (DIN hold time) are specified under opposite worst-case conditions (digital supply voltage and ambient temperature). Under equal conditions, with DOUT connected directly to DIN, the timing margin is >4 ns.

Load on DOUT = 20 pF.



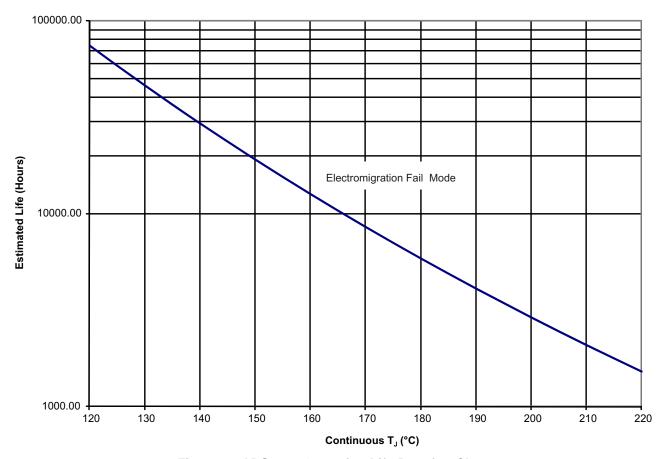


Figure 2. ADS1278 Operating Life Derating Chart

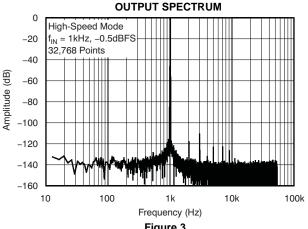
Notes:

- 1. See datasheet for absolute maximum and minimum recommended operating conditions.
- 2. Sillicon operating life design goal is 10 years at 110°C junction temperature.
- 3. The predicted operating lifetime vs. junction temperature is based on reliability modeling using electromigration as the dominant failure mechanism affecting device wearout for the specific device process and design characteristics.
- 4. This device is qualified for 1000 hours of continuous operation at maximum rated temperature



TYPICAL CHARACTERISTICS

At $T_A = 25$ °C, High-Speed mode, AVDD = 5 V, DVDD = 1.8 V, IOVDD = 3.3 V, $f_{CLK} = 27$ MHz, VREFP = 2.5 V, and VREFN = 0 V, unless otherwise noted.





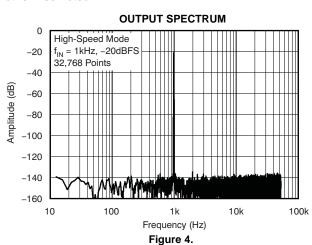
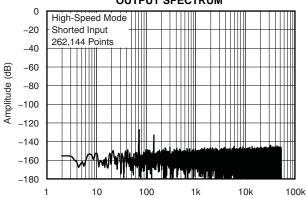


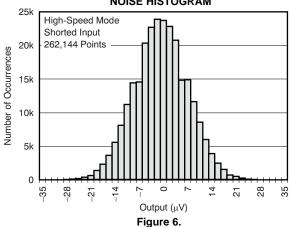
Figure 3.

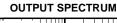




Frequency (Hz) Figure 5.

NOISE HISTOGRAM





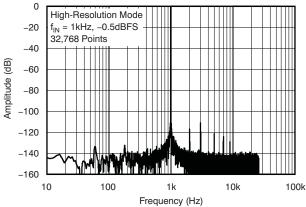


Figure 7.

OUTPUT SPECTRUM

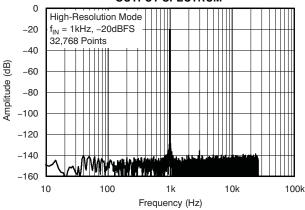


Figure 8.



At $T_A = 25$ °C, High-Speed mode, AVDD = 5 V, DVDD = 1.8 V, IOVDD = 3.3 V, $f_{CLK} = 27$ MHz, VREFP = 2.5 V, and

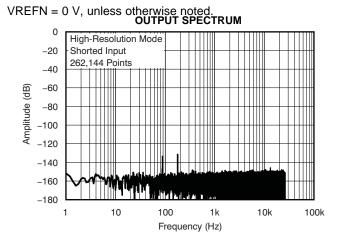


Figure 9.

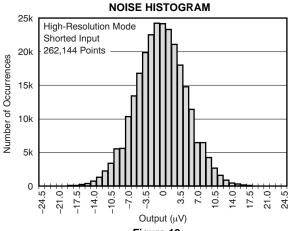


Figure 10.

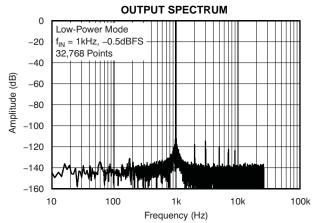


Figure 11.

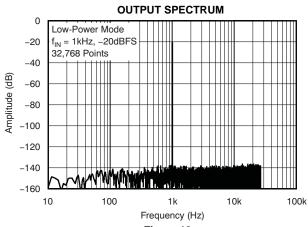
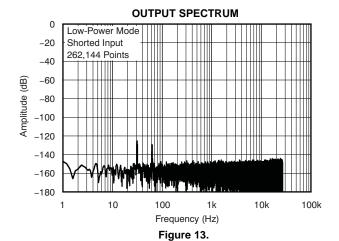
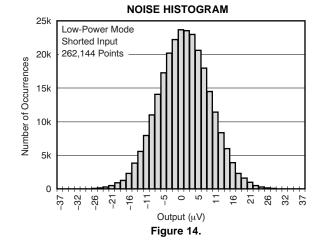


Figure 12.







At $T_A = 25$ °C, High-Speed mode, AVDD = 5 V, DVDD = 1.8 V, IOVDD = 3.3 V, $f_{CLK} = 27$ MHz, VREFP = 2.5 V, and

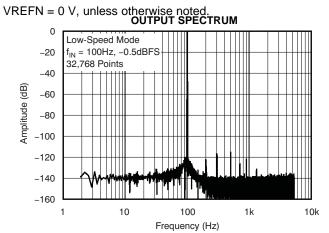


Figure 15.

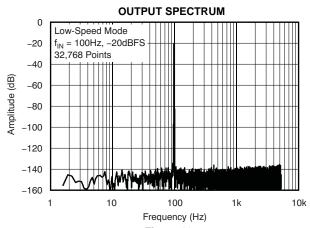


Figure 16.

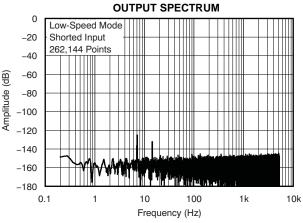
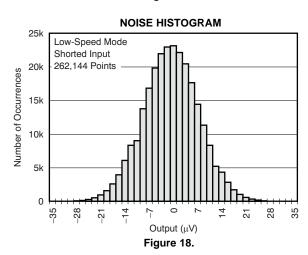
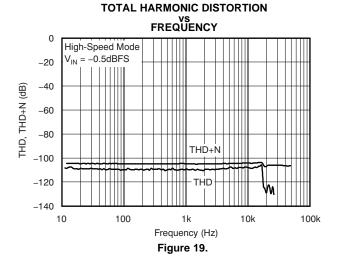


Figure 17.



TOTAL HARMONIC DISTORTION
VS
INPUT AMPLITUDE



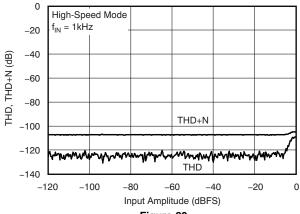


Figure 20.



At $T_A = 25$ °C, High-Speed mode, AVDD = 5 V, DVDD = 1.8 V, IOVDD = 3.3 V, $f_{CLK} = 27$ MHz, VREFP = 2.5 V, and



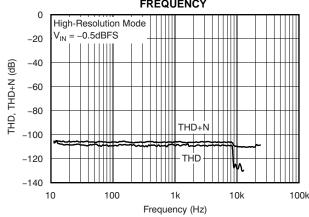


Figure 21.

TOTAL HARMONIC DISTORTION VS INPUT AMPLITUDE

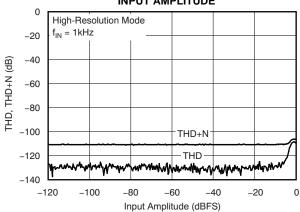


Figure 22.

TOTAL HARMONIC DISTORTION

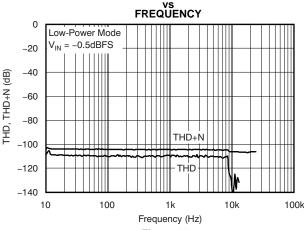


Figure 23.

TOTAL HARMONIC DISTORTION VS INPUT AMPLITUDE

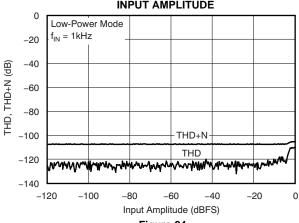


Figure 24.

TOTAL HARMONIC DISTORTION vs

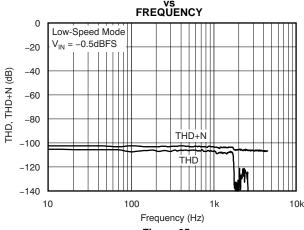


Figure 25.

TOTAL HARMONIC DISTORTION VS INPUT AMPLITUDE

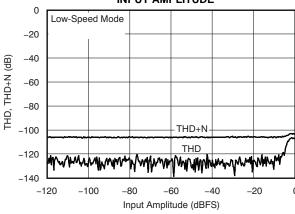
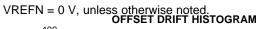


Figure 26.



At $T_A = 25$ °C, High-Speed mode, AVDD = 5 V, DVDD = 1.8 V, IOVDD = 3.3 V, $f_{CLK} = 27$ MHz, VREFP = 2.5 V, and



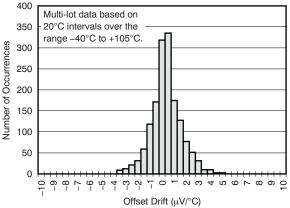


Figure 27.

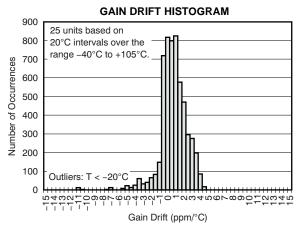


Figure 28.

OFFSET WARMUP DRIFT RESPONSE BAND

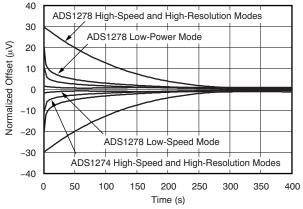


Figure 29.

GAIN WARMUP DRIFT RESPONSE BAND ADS1274/78 High-Speed and High-Resolution Modes ADS1278 Low-Power Mode ADS1278 Low-Power Mode ADS1278 Low-Speed Mode

700 200 Time (s) Figure 30.

250

300

350

400

OFFSET ERROR HISTOGRAM

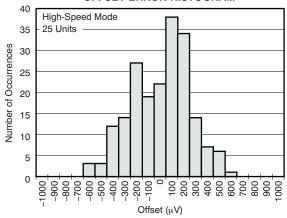


Figure 31.

GAIN ERROR HISTOGRAM

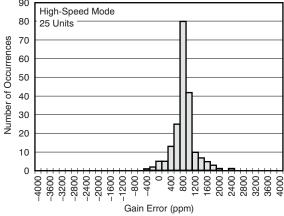


Figure 32.

Submit Documentation Feedback

-30

-40

0

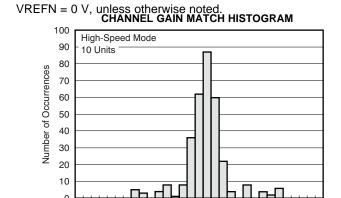
50

100

150



At $T_A = 25$ °C, High-Speed mode, AVDD = 5 V, DVDD = 1.8 V, IOVDD = 3.3 V, $f_{CLK} = 27$ MHz, VREFP = 2.5 V, and



Channel Gain Match (ppm) Figure 33.

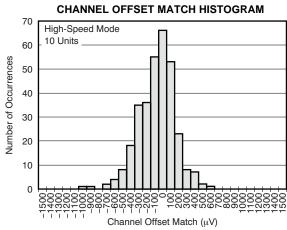


Figure 34.

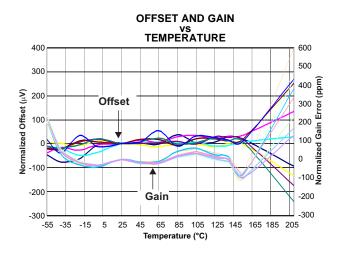


Figure 35.

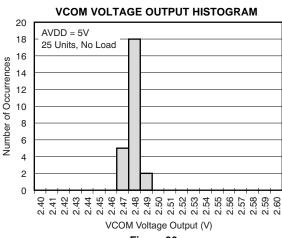
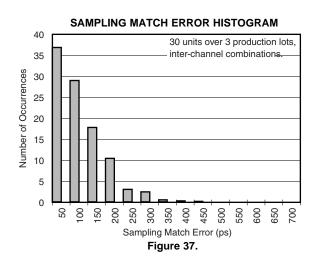


Figure 36.



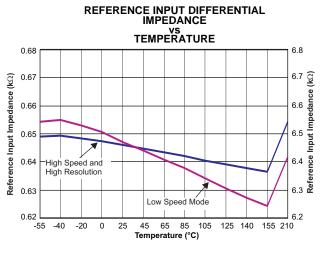
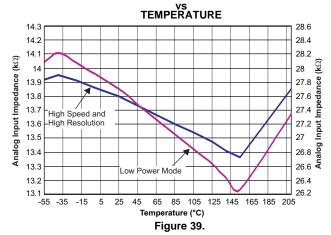


Figure 38.

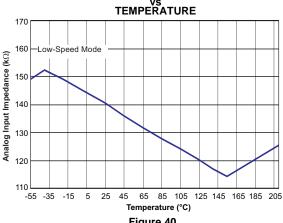


At $T_A = 25$ °C, High-Speed mode, AVDD = 5 V, DVDD = 1.8 V, IOVDD = 3.3 V, $f_{CLK} = 27$ MHz, VREFP = 2.5 V, and

VREFN = 0 V, unless otherwise noted. ANALOG INPUT DIFFERENTIAL IMPEDANCE



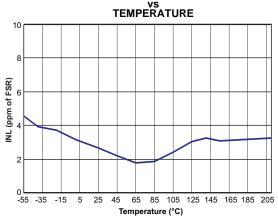
ANALOG INPUT DIFFERENTIAL IMPEDANCE



LINEARITY ERROR

Figure 40.

INTEGRAL NONLINEARITY



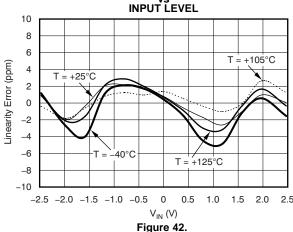
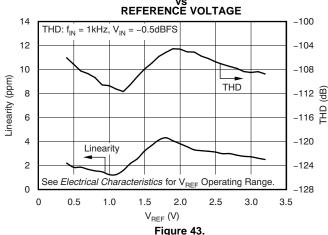


Figure 41.

LINEARITY AND TOTAL HARMONIC DISTORTION



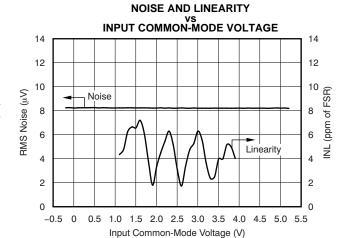
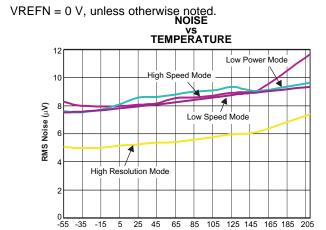


Figure 44.

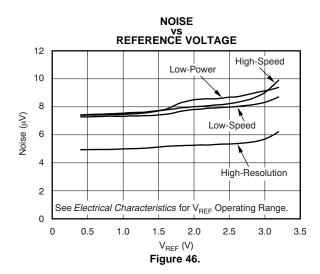


At $T_A = 25$ °C, High-Speed mode, AVDD = 5 V, DVDD = 1.8 V, IOVDD = 3.3 V, $f_{CLK} = 27$ MHz, VREFP = 2.5 V, and



5 25 45

Temperature (°C) Figure 45.



TOTAL HARMONIC DISTORTION AND NOISE

65 85 105 125 145 165 185 205

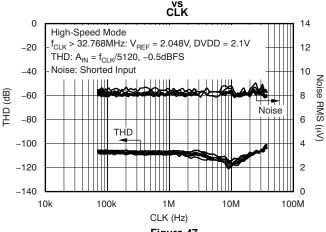
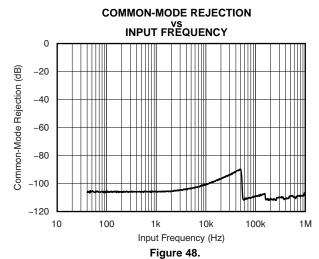


Figure 47.



POWER-SUPPLY REJECTION POWER-SUPPLY FREQUENCY

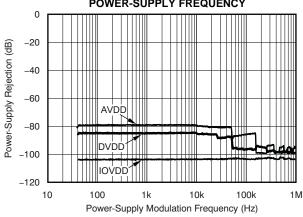


Figure 49.

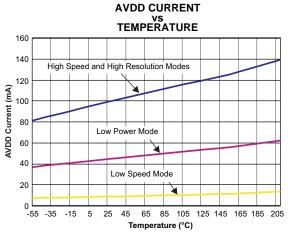


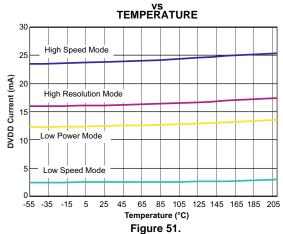
Figure 50.



At $T_A = 25$ °C, High-Speed mode, AVDD = 5 V, DVDD = 1.8 V, IOVDD = 3.3 V, $f_{CLK} = 27$ MHz, VREFP = 2.5 V, and

VREFN = 0 V, unless otherwise noted.

DVDD CURRENT



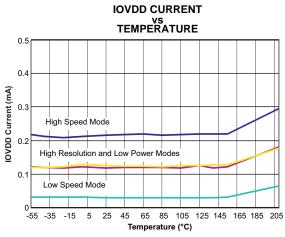
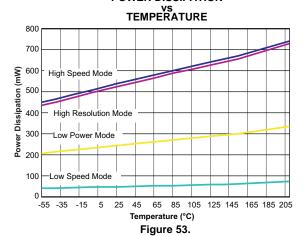


Figure 52.

POWER DISSIPATION





OVERVIEW

The ADS1278 is an octal 24-bit, delta-sigma ADC based on the single-channel ADS1271. It offers the combination of outstanding dc accuracy and superior ac performance. Figure 54 shows the block diagram. The converter is comprised of eight advanced, 6th-order, chopper-stabilized, delta-sigma modulators followed by low-ripple, linear phase FIR filters. The modulators measure the differential input signal, $V_{IN} = (AINP - AINN)$, against the differential reference, $V_{REF} = (VREFP - VREFN)$. The digital filters receive the modulator signal and provide a low-noise digital output. To allow tradeoffs among speed, resolution, and power, four operating modes are supported:

High-Speed, High-Resolution, Low-Power, and Low-Speed. Table 5 summarizes the performance of each mode.

In High-Speed mode, the maximum data rate is 128 kSPS (when operating at 128 kSPS, Frame-Sync format must be used). In High-Resolution mode, the SNR = 111dB ($V_{REF} = 3.0 \text{ V}$); in Low-Power mode, the power dissipation is 31 mW/channel; and in Low-Speed mode, the power dissipation is only 7 mW/channel at 10.5 kSPS. The digital filters can be bypassed, enabling direct access to the modulator output.

The ADS1278 is configured by simply setting the appropriate I/O pins—there are no registers to program. Data are retrieved over a serial interface that supports both SPI and Frame-Sync formats. The ADS1278 has a daisy-chainable output and the ability to synchronize externally, so it can be used conveniently in systems requiring more than eight channels.

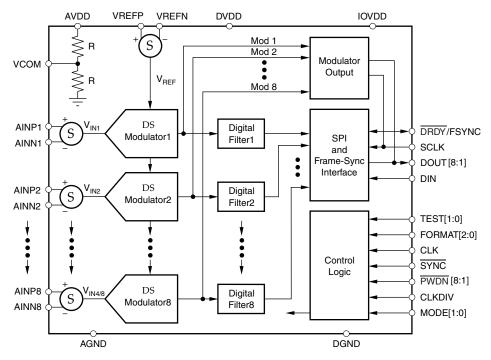


Figure 54. Block Diagram

Table 5. Operating Mode Performance Summary

MODE	MAX DATA RATE (SPS)	PASSBAND (kHz)	SNR (dB)	NOISE (µV _{RMS})	POWER/CHANNEL (mW)
High-Speed	128,000	57,984	106	8.5	70
High-Resolution	52,734	23,889	110	5.5	64
Low-Power	52,734	23,889	106	8.5	31
Low-Speed	10,547	4,798	107	8.0	7

Product Folder Links: ADS1278-HT



FUNCTIONAL DESCRIPTION

The ADS1278 is a delta-sigma ADC consisting of eight independent converters that digitize eight input signals in parallel.

The converter is composed of two main functional blocks to perform the ADC conversions: the modulator and the digital filter. The modulator samples the input signal together with sampling the reference voltage to produce a 1s density output stream. The density of the output stream is proportional to the analog input level relative to the reference voltage. The pulse stream is filtered by the internal digital filter where the output conversion result is produced.

In operation, the input signal is sampled by the modulator at a high rate (typically 64x higher than the final output data rate). The quantization noise of the modulator is moved to a higher frequency range where the internal digital filter removes it. Oversampling results in very low levels of noise within the signal passband.

Since the input signal is sampled at a very high rate, input signal aliasing does not occur until the input signal frequency is at the modulator sampling rate. This architecture greatly relaxes the requirement of external antialiasing filters because of the high modulator sampling rate.

SAMPLING APERTURE MATCHING

The ADS1278 converter operates from the same CLK input. The CLK input controls the timing of the modulator sampling instant. The converter is designed such that the sampling skew, or modulator sampling aperture match between channels, is controlled. Furthermore, the digital filters are synchronized to start the convolution phase at the same modulator clock cycle. This design results in excellent phase match among the ADS1278 channels.

Figure 37 shows the inter-device channel sample matching for the ADS1278.

FREQUENCY RESPONSE

The digital filter sets the overall frequency response. The filter uses a multi-stage FIR topology to provide linear phase with minimal passband ripple and high stop band attenuation. The filter coefficients are identical to the coefficients used in the ADS1271. The oversampling ratio of the digital filter (that is, the ratio of the modulator sampling to the output data rate, or $f_{\text{MOD}}/f_{\text{DATA}}$) is a function of the selected mode, as shown in Table 6.

Table 6. Oversampling Ratio versus Mode

MODE SELECTION	OVERSAMPLING RATIO (f _{MOD} /f _{DATA})
High-Speed	64
High-Resolution	128
Low-Power	64
Low-Speed	64



High-Speed, Low-Power, and Low-Speed Modes

The digital filter configuration is the same in High-Speed, Low-Power, and Low-Speed modes with the oversampling ratio set to 64. Figure 55 shows the frequency response in High-Speed, Low-Power, and Low-Speed modes normalized to f_{DATA} . Figure 56 shows the passband ripple. The transition from passband to stop band is shown in Figure 57. The overall frequency response repeats at 64x multiples of the modulator frequency f_{MOD} , as shown in Figure 58.

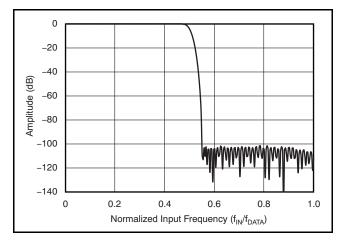


Figure 55. Frequency Response for High-Speed, Low-Power, and Low-Speed Modes

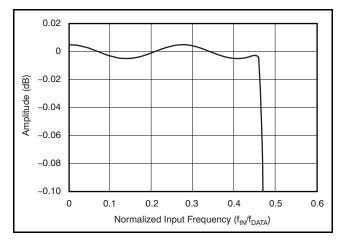


Figure 56. Passband Response for High-Speed, Low-Power, and Low-Speed Modes

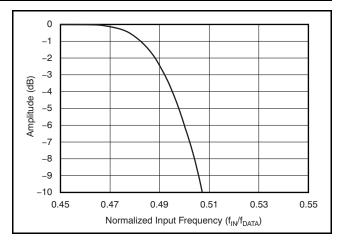


Figure 57. Transition Band Response for High-Speed, Low-Power, and Low-Speed Modes

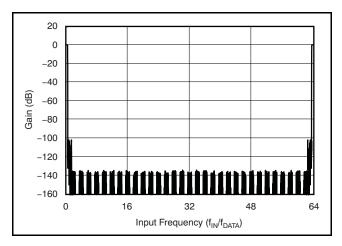


Figure 58. Frequency Response Out to f_{MOD} for High-Speed, Low-Power, and Low-Speed Modes

These image frequencies, if present in the signal and not externally filtered, will fold back (or alias) into the passband, causing errors. The stop band of the ADS1278 provides 100 dB attenuation of frequencies that begin just beyond the passband and continue out to f_{MOD} . Placing an antialiasing, low-pass filter in front of the ADS1278 inputs is recommended to limit possible high-amplitude, out-of-band signals and noise. Often, a simple RC filter is sufficient. Table 7 lists the image rejection versus external filter order.

Table 7. Antialiasing Filter Order Image Rejection

ANTIALIASING	IMAGE REJECTION (dB) (f _{-3dB} at f _{DATA})				
FILTER ORDER	HS, LP, LS	HR			
1	39	45			
2	75	87			
3	111	129			



High-Resolution Mode

The oversampling ratio is 128 in High-Resolution mode. Figure 59 shows the frequency response in High-Resolution mode normalized to $f_{DATA}.$ Figure 60 shows the passband ripple, and the transition from passband to stop band is shown in Figure 61. The overall frequency response repeats at multiples of the modulator frequency f_{MOD} (128 × f_{DATA}), as shown in Figure 62. The stop band of the ADS1278 provides 100 dB attenuation of frequencies that begin just beyond the passband and continue out to $f_{MOD}.$ Placing an antialiasing, low-pass filter in front of the ADS1278 inputs is recommended to limit possible high-amplitude out-of-band signals and noise. Often, a simple RC filter is sufficient. Table 7 lists the image rejection versus external filter order.

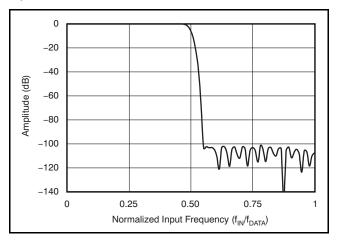


Figure 59. Frequency Response for High-Resolution Mode

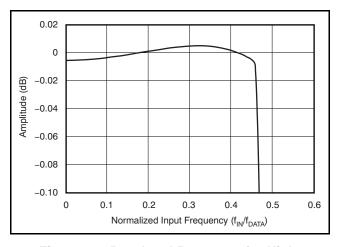


Figure 60. Passband Response for High-Resolution Mode

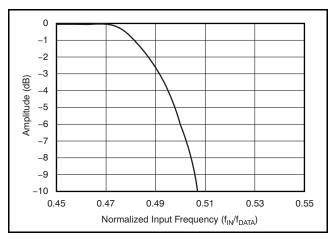


Figure 61. Transition Band Response for High-Resolution mode

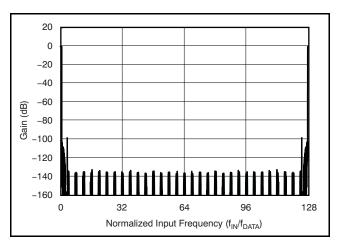


Figure 62. Frequency Response Out to f_{MOD} for High-Resolution Mode



PHASE RESPONSE

The ADS1278 incorporates a multiple stage, linear phase digital filter. Linear phase filters exhibit constant delay time versus input frequency (constant group delay). This characteristic means the time delay from any instant of the input signal to the same instant of the output data is constant and is independent of input signal frequency. This behavior results in essentially zero phase errors when analyzing multi-tone signals.

SETTLING TIME

As with frequency and phase response, the digital filter also determines settling time. Figure 63 shows the output settling behavior after a step change on the analog inputs normalized to conversion periods. The X-axis is given in units of conversion. Note that after the step change on the input occurs, the output data change very little prior to 30 conversion periods. The output data are fully settled after 76 conversion periods for High-Speed and Low-Power modes, and 78 conversion periods for High-Resolution mode.

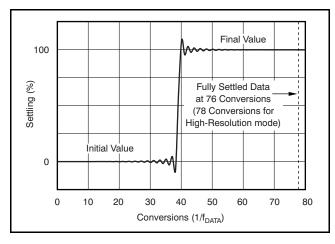


Figure 63. Step Response

DATA FORMAT

The ADS1278 outputs 24 bits of data in twos complement format.

A positive full-scale input produces an ideal output code of 7FFFFFh, and the negative full-scale input produces an ideal output code of 800000h. The output clips at these codes for signals exceeding full-scale. Table 8 summarizes the ideal output codes for different input signals.

Table 8. Ideal Output Code versus Input Signal

INPUT SIGNAL V _{IN} (AINP – AINN)	IDEAL OUTPUT CODE ⁽¹⁾
≥ +V _{REF}	7FFFFh
$\frac{+ V_{REF}}{2^{23} - 1}$	000001h
0	000000h
$\frac{-V_{REF}}{2^{23}-1}$	FFFFFFh
$\leq -V_{REF}\left(\frac{2^{23}}{2^{23}-1}\right)$	800000h

(1) Excludes effects of noise, INL, offset, and gain errors.

ANALOG INPUTS (AINP, AINN)

The ADS1278 measures each differential input signal $V_{IN} = (AINP - AINN)$ against the common differential reference $V_{REF} = (VREFP - VREFN)$. The most positive measurable differential input is $+V_{REF}$, which produces the most positive digital output code of 7FFFFh. Likewise, the most negative measurable differential input is $-V_{REF}$, which produces the most negative digital output code of 800000h.

For optimum performance, the inputs of the ADS1278 are intended to be driven differentially. For single-ended applications, one of the inputs (AINP or AINN) can be driven while the other input is fixed (typically to AGND or 2.5 V). Fixing the input to 2.5 V permits bipolar operation, thereby allowing full use of the entire converter range.

While the ADS1278 measures the differential input signal, the absolute input voltage is also important. This value is the voltage on either input (AINP or AINN) with respect to AGND. The range for this voltage is:

$$-0.1 \text{ V} < (AINN \text{ or AINP}) < AVDD + 0.1 \text{ V}$$

If either input is taken below -0.4 V or above (AVDD + 0.4 V), ESD protection diodes on the inputs may turn on. If these conditions are possible, external Schottky clamp diodes or series resistors may be required to limit the input current to safe values (see the Absolute Maximum Ratings table).

The ADS1278 is a very high-performance ADC. For optimum performance, it is critical that the appropriate circuitry be used to drive the ADS1278 inputs. See the *Application Information* section for several recommended circuits.



The ADS1278 uses switched-capacitor circuitry to measure the input voltage. Internal capacitors are charged by the inputs and then discharged. Figure 64 shows a conceptual diagram of these circuits. Switch S_2 represents the net effect of the modulator circuitry in discharging the sampling capacitor; the actual implementation is different. The timing for switches S_1 and S_2 is shown in Figure 65. The sampling time (t_{SAMPLE}) is the inverse of modulator sampling frequency (t_{MOD}) and is a function of the mode, the CLKDIV input, and CLK frequency, as shown in Table 9.

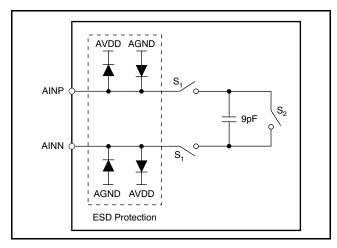


Figure 64. Equivalent Analog Input Circuitry

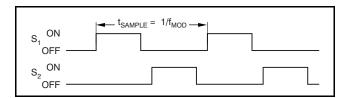


Figure 65. S₁ and S₂ Switch Timing for Figure 64

Table 9. Modulator Frequency (f_{MOD}) Mode Selection

MODE SELECTION	CLKDIV	f _{MOD}
High-Speed	1	f _{CLK} /4
High-Resolution	1	f _{CLK} /4
	1	f _{CLK} /8
Low-Power	0	f _{CLK} /4
Low Chood	1	f _{CLK} /40
Low-Speed	0	f _{CLK} /8

The average load presented by the switched capacitor input can be modeled with an effective differential impedance, as shown in Figure 66. Note that the effective impedance is a function of f_{MOD} .

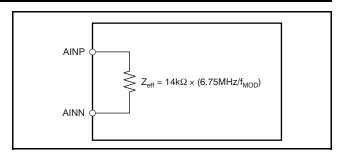


Figure 66. Effective Input Impedances

VOLTAGE REFERENCE INPUTS (VREFP, VREFN)

The voltage reference for the ADS1278 ADC is the differential voltage between VREFP and VREFN: $V_{RFF} = (VREFP - VREFN)$. The voltage reference is common to all channels. The reference inputs use a structure similar to that of the analog inputs with the equivalent circuitry on the reference inputs shown in Figure 67. As with the analog inputs, the load presented by the switched capacitor can be modeled with an effective impedance, as shown in Figure 68. However, the reference input impedance depends on the number of active (enabled) channels in addition to f_{MOD}. As a result of the change of reference input impedance caused by enabling and disabling channels, the regulation and setting time of the external reference should be noted, so as not to affect the readings.

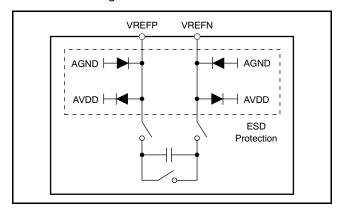


Figure 67. Equivalent Reference Input Circuitry

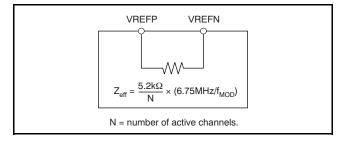


Figure 68. Effective Reference Impedance



ESD diodes protect the reference inputs. To keep these diodes from turning on, make sure the voltages on the reference pins do not go below AGND by more than 0.4 V, and likewise do not exceed AVDD by 0.4 V. If these conditions are possible, external Schottky clamp diodes or series resistors may be required to limit the input current to safe values (see the Absolute Maximum Ratings table).

Note that the valid operating range of the reference inputs is limited to the following parameters:

 $-0.1 \text{ V} \leq \text{VREFN} \leq +0.1 \text{ V}$

 $VREFN + 0.5 V \le VREFP \le AVDD + 0.1 V$

CLOCK INPUT (CLK)

The ADS1278 requires a clock input for operation. The individual converters of the ADS1278 operate from the same clock input. At the maximum data rate, the clock input can be either 27 MHz or 13.5 MHz for Low-Power mode, or 2 7MHz or 5.4 MHz for Low-Speed mode, determined by the setting of the CLKDIV input. For High-Speed mode, the maximum CLK input frequency is 32.768 MHz. For High-Resolution mode, the maximum CLK input frequency is 27 MHz. The selection of the external clock frequency (f_{CLK}) does not affect the resolution of the ADS1278. Use of a slower f_{CLK} can reduce the power consumption of an external clock buffer. The output data rate scales with clock frequency, down to a minimum clock frequency of f_{CLK} = 100 kHz. Table 10 summarizes the ratio of the clock input frequency (f_{CLK}) to data rate (f_{DATA}), maximum data rate and corresponding maximum clock input for the four operating modes.

As with any high-speed data converter, a high-quality, low-jitter clock is essential for optimum performance. Crystal clock oscillators are the recommended clock source. Make sure to avoid excess ringing on the clock input; keeping the clock trace as short as possible, and using a $50-\Omega$ series resistor placed close to the source end, often helps.

Table 10. Clock Input Options

MODE SELECTION	MAX f _{CLK} (MHz)	CLKDIV	f _{CLK} /f _{DATA}	DATA RATE (SPS)
High-Speed	32.768	1	256	128,000
High-Resolution	27	1	512	52,734
Low-Power	27	1	512	FO 704
Low-Power	13.5	0	256	52,734
Law Casad	27	1	2,560	10 5 4 7
Low-Speed	5.4	0	512	10,547

MODE SELECTION (MODE)

The ADS1278 supports four modes of operation: High-Speed, High-Resolution, Low-Power, and Low-Speed. The modes offer optimization of speed, resolution, and power. Mode selection is determined by the status of the digital input MODE[1:0] pins, as shown in Table 11. The ADS1278 continually monitors the status of the MODE pin during operation.

Table 11. Mode Selection

MODE[1:0]	MODE SELECTION	MAX f _{DATA} (1)
00	High-Speed	128,000
01	High-Resolution	52,734
10	Low-Power	52,734
11	Low-Speed	10,547

(1) f_{CLK} = 27 MHz max (32.768MHz max in High-Speed mode).

When using the SPI protocol, \overline{DRDY} is held high after a mode change occurs until settled (or valid) data are ready; see Figure 69 and Table 12.

In Frame-Sync protocol, the DOUT pins are held low after a mode change occurs until settled data are ready; see Figure 69 and Table 12. Data can be read from the device to detect when DOUT changes to logic 1, indicating that the data are valid.



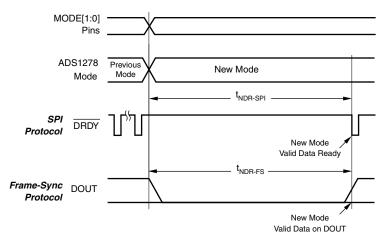


Figure 69. Mode Change Timing

Table 12. New Data After Mode Change

SYMBOL	DESCRIPTION	MIN	TYP	MAX	UNITS
t _{NDR-SPI}	Time for new data to be ready (SPI)			129	Conversions (1/f _{DATA})
t _{NDR-FS}	Time for new data to be ready (Frame-Sync)	127		128	Conversions (1/f _{DATA})

SYNCHRONIZATION (SYNC)

The ADS1278 can be synchronized by pulsing the SYNC pin low and then returning the pin high. When the pin goes low, the conversion process stops, and the internal counters used by the digital filter are reset. When the SYNC pin returns high, the conversion process restarts. Synchronization allows the conversion to be aligned with an external event, such as the changing of an external multiplexer on the analog inputs, or by a reference timing pulse.

Because the ADS1278 converters operate in parallel from the same master clock and use the same SYNC input control, they are always in synchronization with each other. The aperture match among internal channels is typically less than 500 ps. However, the synchronization of multiple devices is somewhat different. At device power-on, variations in internal reset thresholds from device to device may result in uncertainty in conversion timing.

The SYNC pin can be used to synchronize multiple devices to within the same CLK cycle. Figure 70 illustrates the timing requirement of SYNC and CLK in SPI format.

See Figure 71 for the Frame-Sync format timing requirement.

After synchronization, indication of valid data depends on whether SPI or Frame-Sync format was used.

In the SPI format, DRDY goes high as soon as SYNC is taken low; see Figure 70. After SYNC is returned high, DRDY stays high while the digital filter is settling. Once valid data are ready for retrieval, DRDY goes low.

In the Frame-Sync format, DOUT goes low as soon as SYNC is taken low; see Figure 71. After SYNC is returned high, DOUT stays low while the digital filter is settling. Once valid data are ready for retrieval, DOUT begins to output valid data. For proper synchronization, FSYNC, SCLK, and CLK must be established before taking SYNC high, and must then remain running. If the clock inputs (CLK, FSYNC or SCLK) are subsequently interrupted or reset, reassert the SYNC pin.

For consistent performance, re-assert SYNC after device power-on when data first appear.



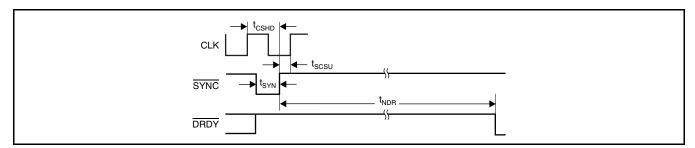


Figure 70. Synchronization Timing (SPI Protocol)

Table 13. SPI Protocol

SYMBOL	DESCRIPTION	MIN	TYP	MAX	UNITS
t _{CSHD}	CLK to SYNC hold time	10			ns
t _{SCSU}	SYNC to CLK setup time	5			ns
t _{SYN}	Synchronize pulse width	1			CLK periods
t _{NDR}	Time for new data to be ready			129	Conversions (1/f _{DATA})

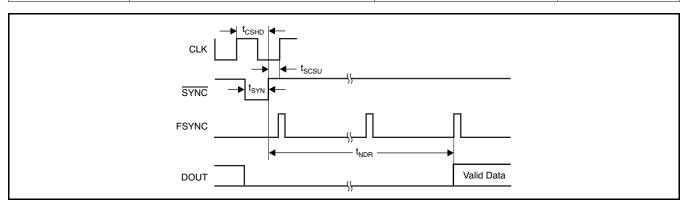


Figure 71. Synchronization Timing (Frame-Sync Protocol)

Table 14. Frame-Sync Protocol

SYMBOL	DESCRIPTION	MIN	TYP	MAX	UNITS
t _{CSHD}	CLK to SYNC hold time	10			ns
t _{SCSU}	SYNC to CLK setup time	5			ns
t _{SYN}	Synchronize pulse width	1			CLK periods
t _{NDR}	Time for new data to be ready	127		128	Conversions (1/f _{DATA})

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POWER-DOWN (PWDN)

The channels of the ADS1278 can be independently powered down by use of the PWDN inputs. To enter the power-down mode, hold the respective PWDN pin low for at least two CLK cycles. To exit power-down, return the corresponding PWDN pin high. Note that when all channels are powered down, the ADS1278 enters a microwatt (µW) power state where all internal biasing is disabled. In this state, the TEST[1:0] input pins must be driven; all other input pins can float. The ADS1278 outputs remain driven.

As shown in Figure 72 and Table 15, a maximum of 130 conversion cycles must elapse for SPI interface, and 129 conversion cycles must elapse for Frame-Sync, before reading data after exiting power-down. Data from channels already running are not affected. The user software can perform the required delay time in any of the following ways:

- 1. Count the number of data conversions after taking the PWDN pin high.
- 2. Delay 129/f_{DATA} or 130/f_{DATA} after taking the PWDN pins high, then read data.

3. Detect for non-zero data in the powered-up channel.

After powering up one or more channels, the channels are synchronized to each other. It is not necessary to use the SYNC pin to synchronize them.

When a channel is powered down in TDM data format, the data for that channel are either forced to zero (fixed-position TDM data mode) or replaced by shifting the data from the next channel into the vacated data position (dynamic-position TDM data mode).

In Discrete data format, the data are always forced to zero. When powering-up a channel in dynamicposition TDM data format mode, the channel data remain packed until the data are ready, at which time the data frame is expanded to include the justpowered channel data. See the Data Format section for details.

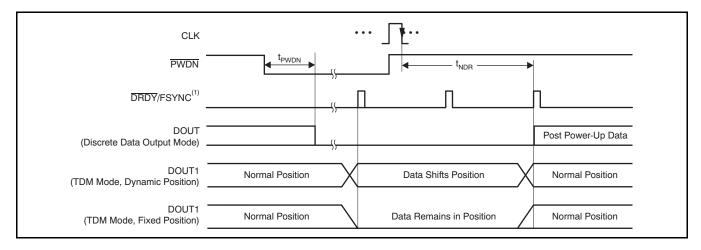


Figure 72. Power-Down Timing

Table 15. Power-Down Timing

SYMBOL	DESCRIPTION	MIN	TYP	MAX	UNITS
t _{PWDN}	PWDN pulse width to enter Power-Down mode	2			CLK periods
t _{NDR}	Time for new data ready (SPI)	129		130	Conversions (1/f _{DATA})
t _{NDR}	Time for new data ready (Frame-Sync)	128		129	Conversions (1/f _{DATA})



FORMAT[2:0]

Data can be read from the ADS1278 with two interface protocols (SPI or Frame-Sync) and several options of data formats (TDM/Discrete and Fixed/Dynamic data positions). The FORMAT[2:0] inputs are used to select among the options. Table 16 lists the available options. See the *DOUT Modes* section for details of the DOUT Mode and Data Position.

Table 16. Data Output Format

FORMAT[2:0]	INTERFACE PROTOCOL	DOUT MODE	DATA POSITION
000	SPI	TDM	Dynamic
001	SPI	TDM	Fixed
010	SPI	Discrete	_
011	Frame-Sync	TDM	Dynamic
100	Frame-Sync	TDM	Fixed
101	Frame-Sync	Discrete	_
110	Modulator Mode	_	_

SERIAL INTERFACE PROTOCOLS

Data are retrieved from the ADS1278 using the serial interface. Two protocols are available: SPI and Frame-Sync. The <u>same</u> pins are used for both interfaces: SCLK, DRDY/FSYNC, DOUT[8:1], and DIN. The FORMAT[2:0] pins select the desired interface protocol.

SPI SERIAL INTERFACE

The SPI-compatible format is a read-only interface. <u>Data ready</u> for retrieval are indicated by the falling <u>DRDY</u> output and are shifted out on the falling edge of SCLK, MSB first. The interface can be daisy-chained using the DIN input when using multiple devices. See the <u>Daisy-Chaining</u> section for more information.

NOTE: The SPI format is limited to a CLK input frequency of 27 MHz, maximum. For CLK input operation above 27 MHz (High-Speed mode only), use Frame-Sync format.

SCLK

The serial clock (SCLK) features a Schmitt-triggered input and shifts out data on DOUT on the falling edge. It also shifts in data on the falling edge on DIN when this pin is being used for daisy-chaining. The device shifts data out on the falling edge and the user normally shifts this data in on the rising edge.

Even though the SCLK input has hysteresis, it is recommended to keep SCLK as clean as possible to prevent glitches from accidentally shifting the data.

SCLK may be run as fast as the CLK frequency. SCLK may be either in free-running or stop-clock operation between conversions. Note that one f_{CLK} is required after the falling edge of \overline{DRDY} until the first rising edge of SCLK. For best performance, limit f_{SCLK}/f_{CLK} to ratios of 1, 1/2, 1/4, 1/8, etc. When the device is configured for modulator output, SCLK becomes the modulator clock output (see the *Modulator Output* section).

DRDY/FSYNC (SPI Format)

In the SPI format, this pin functions as the DRDY output. It goes low when data are ready for retrieval and then returns high on the falling edge of the first subsequent SCLK. If data are not retrieved (that is, SCLK is held low), \overline{DRDY} pulses high just before the next conversion data are ready, as shown in Figure 73. The new data are loaded within one CLK cycle before \overline{DRDY} goes low. All data must be shifted out before this time to avoid being overwritten.

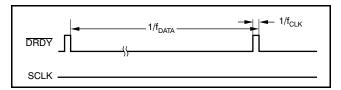


Figure 73. DRDY Timing with No Readback

DOUT

The conversion data are output on DOUT[8:1]. The MSB data are valid on DOUT[8:1] after DRDY goes low. Subsequent bits are shifted out with each falling edge of SCLK. If daisy-chaining, the data shifted in using DIN appear on DOUT after all channel data have been shifted out. When the device is configured for modulator output, DOUT[8:1] becomes the modulator data output for each channel (see the *Modulator Output* section).

DIN

This input is used when multiple ADS1278s are to be daisy-chained together. The DOUT1 pin of the first device connects to the DIN pin of the next, etc. It can be used with either the SPI or Frame-Sync formats. Data are shifted in on the falling edge of SCLK. When using only one ADS1278, tie DIN low. See the *Daisy-Chaining* section for more information.



FRAME-SYNC SERIAL INTERFACE

Frame-Sync format is similar to the interface often used on audio ADCs. It operates in slave fashion—the user must supply framing signal FSYNC (similar to the *left/right clock* on stereo audio ADCs) and the serial clock SCLK (similar to the *bit clock* on audio ADCs). The data are output MSB first or *left-justified* on the rising edge of FSYNC. When using Frame-Sync format, the FSYNC and SCLK inputs must be continuously running with the relationships shown in the Frame-Sync Timing Requirements.

SCLK

The serial clock (SCLK) features a Schmitt-triggered input and shifts out data on DOUT on the falling edge. It also shifts in data on the falling edge on DIN when this pin is being used for daisy-chaining. Even though SCLK has hysteresis, it is recommended to keep SCLK as clean as possible to prevent glitches from accidentally shifting the data. When using Frame-Sync format, SCLK must run continuously. If it is shut down, the data readback will be corrupted. The number of SCLKs within a frame period (FSYNC clock) can be any power-of-2 ratio of CLK cycles (1, 1/2, 1/4, etc), as long as the number of cycles is sufficient to shift the data output from all channels within one frame. When the device is configured for modulator output, SCLK becomes the modulator clock output (see the Modulator Output section).

DRDY/FSYNC (Frame-Sync Format)

In Frame-Sync format, this pin is used as the FSYNC input. The frame-sync input (FSYNC) sets the frame period, which must be the same as the data rate. The required number of f_{CLK} cycles to each FSYNC period depends on the mode selection and the CLKDIV input. Table 10 indicates the number of CLK cycles to each frame (f_{CLK}/f_{DATA}). If the FSYNC period is not the proper value, data readback will be corrupted.

DOUT

The conversion data are shifted out on DOUT[8:1]. The MSB data become valid on DOUT[8:1] after FSYNC goes high. The subsequent bits are shifted out with each falling edge of SCLK. If daisy-chaining, the data shifted in using DIN appear on DOUT[8:1] after all channel data have been shifted out. When the device is configured for modulator output, DOUT becomes the modulator data output (see the *Modulator Output* section).

DIN

This input is used when multiple ADS1278s are to be daisy-chained together. It can be used with either SPI or Frame-Sync formats. Data are shifted in on the falling edge of SCLK. When using only one ADS1278, tie DIN low. See the *Daisy-Chaining* section for more information.

DOUT MODES

For both SPI and Frame-Sync interface protocols, the data are shifted out either through individual channel DOUT pins, in a parallel data format (Discrete mode), or the data for all channels are shifted out, in a serial format, through a common pin, DOUT1 (TDM mode).

TDM Mode

In TDM (time-division multiplexed) data output mode, the data for all channels are shifted out, in sequence, on a single pin (DOUT1). As shown in Figure 74, the data from channel 1 are shifted out first, followed by channel 2 data, etc. After the data from the last channel are shifted out, the data from the DIN input follow. The DIN is used to daisy-chain the data output from an additional ADS1278 or other compatible device. Note that when all channels of the ADS1278 are disabled, the interface is disabled, rendering the DIN input disabled as well. When one or more channels of the device are powered down, the data format of the TDM mode can be fixed or dynamic.

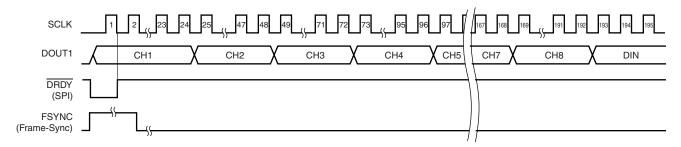


Figure 74. TDM Mode (All Channels Enabled)



TDM Mode, Fixed-Position Data

In this TDM data output mode, the data position of the channels remain fixed, regardless of whether the channels are powered down. If a channel is powered down, the data are forced to zero but occupy the same position within the data stream. Figure 75 shows the data stream with channel 1 and channel 3 powered down.

TDM Mode, Dynamic Position Data

In this TDM data output mode, when a channel is powered down, the data from higher channels shift one position in the data stream to fill the vacated data slot. Figure 76 shows the data stream with channel 1 and channel 3 powered down.

Discrete Data Output Mode

In Discrete data output mode, the channel data are shifted out in parallel using individual channel data output pins DOUT[8:1]. After the 24th SCLK, the channel data are forced to zero. The data are also forced to zero for powered down channels. Figure 77 shows the discrete data output format.

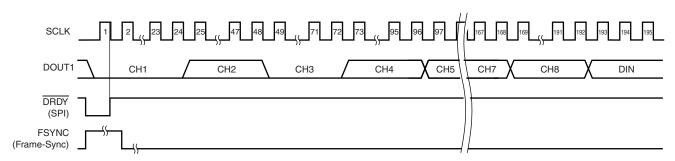


Figure 75. TDM Mode, Fixed-Position Data (Channels 1 and 3 Shown Powered Down)

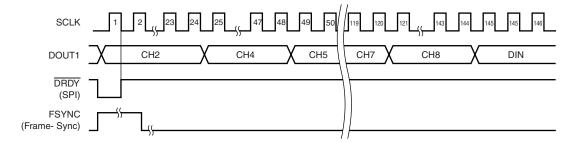


Figure 76. TDM Mode, Dynamic Position Data (Channels 1 and 3 Shown Powered Down)



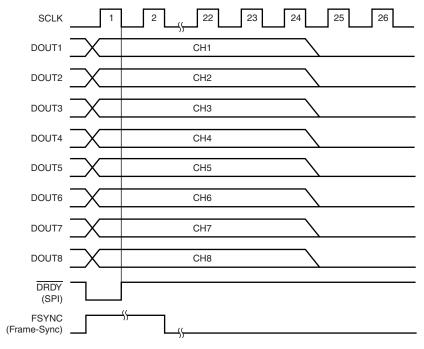


Figure 77. Discrete Data Output Mode

DAISY-CHAINING

Multiple ADS1278s can be daisy-chained together to output data on a single pin. The DOUT1 data output pin of one device is connected to the DIN of the next device. As shown in Figure 78, the DOUT1 pin of device 1 provides the output data to a controller, and the DIN of device 2 is grounded. Figure 79 shows the data format when reading back data.

The maximum number of channels that may be daisy-chained in this way is limited by the frequency of f_{SCLK} , the mode selection, and the CLKDIV input. The frequency of f_{SCLK} must be high enough to completely shift the data out from all channels within one f_{DATA} period. Table 17 lists the maximum number of daisy-chained channels when $f_{SCLK} = f_{CLK}$.

To increase the number of data channels possible in a chain, a segmented DOUT scheme may be used, producing two data streams. Figure 80 illustrates four ADS1278s, with pairs of ADS1278s daisy-chained together. The channel data of each daisy-chained pair are shifted out in parallel and received by the processor through independent data channels.

Table 17. Maximum Channels in a Daisy-Chain

Table 17. Maximum Channels in a Daisy-Chain $(f_{SCLK} = f_{CLK})$ (continued)

 $(f_{SCLK} = f_{CLK})$

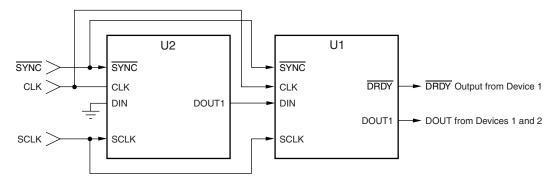
MODE SELECTION	CLKDIV	MAXIMUM NUMBER OF CHANNELS
High-Speed	1	10
High-Resolution	1	21
Low-Power	1	21
Low-Power	0	10
Law Chand	1	106
Low-Speed	0	21

Whether the interface protocol is SPI or Frame-Sync, it is <u>recommended</u> to synchronize all devices by tying the <u>SYNC</u> inputs together. When synchronized <u>in SPI</u> protocol, it is only necessary to monitor the <u>DRDY</u> output of one ADS1278.

In Frame-Sync interface protocol, the data from all devices are ready after the rising edge of FSYNC.

Since DOUT1 and DIN are both shifted on the falling edge of SCLK, the propagation delay on DOUT1 creates a setup time on DIN. Minimize the skew in SCLK to avoid timing violations.





Note: The number of chained devices is limited by the SCLK rate and device mode.

Figure 78. Daisy-Chaining of Two Devices, SPI Protocol (FORMAT[2:0] = 000 or 001)

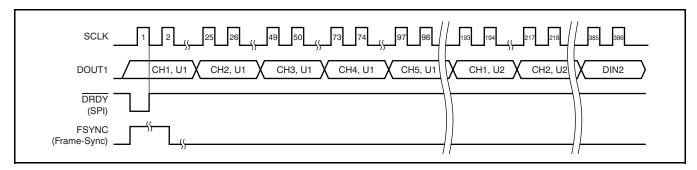
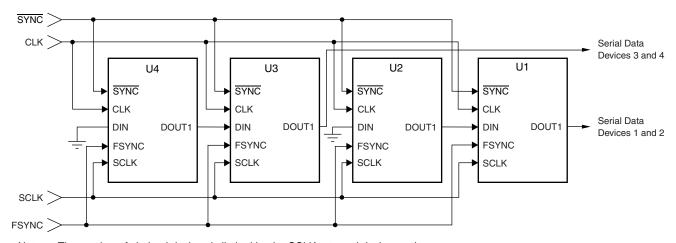


Figure 79. Daisy-Chain Data Format of Figure 78



Note: The number of chained devices is limited by the SCLK rate and device mode.

Figure 80. Segmented DOUT Daisy-Chain, Frame-Sync Protocol (FORMAT[2:0] = 011 or 100)



POWER SUPPLIES

The ADS1278 has three power supplies: AVDD, DVDD, and IOVDD. AVDD is the analog supply that powers the modulator, DVDD is the digital supply that powers the digital core, and IOVDD is the digital I/O power supply. The IOVDD and DVDD power supplies can be tied together if desired (1.8 V). To achieve rated performance, it is critical that the power supplies are bypassed with 0.1-µF and 10-µF capacitors placed as close as possible to the supply pins. A single 10-µF ceramic capacitor may be substituted in place of the two capacitors.

Figure 81 shows the start-up sequence of the ADS1278. At power-on, bring up the DVDD supply first, followed by IOVDD and then AVDD. Check the power-supply sequence for proper order, including the ramp rate of each supply. DVDD and IOVDD may be sequenced at the same time if the supplies are tied together. Each supply has an internal reset circuit whose outputs are summed together to generate a global power-on reset. After the supplies have exceeded the reset thresholds, $2^{18}~\rm f_{CLK}$ cycles are counted before the converter initiates the conversion process. Following the CLK cycles, the data for 129 conversions are suppressed by the ADS1278 to allow output of fully-settled data. In SPI protocol, DRDY is held high during this interval. In frame-sync protocol, DOUT is forced to zero. The power supplies should be applied before any analog or digital pin is driven. For consistent performance, assert SYNC after device power-on when data first appear.

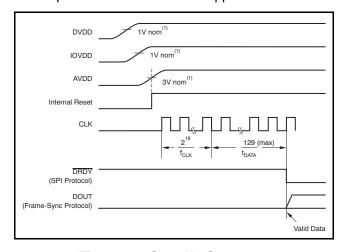


Figure 81. Start-Up Sequence

MODULATOR OUTPUT

The ADS1278 incorporates a 6th-order, single-bit, chopper-stabilized modulator followed by a multistage digital filter that yields the conversion results. The data stream output of the modulator is available directly, bypassing the internal digital filter. The digital filter is disabled, reducing the DVDD current, as shown in Table 18. In this mode, an external digital filter implemented in an ASIC, FPGA, or similar device is required. To invoke the modulator output, tie FORMAT[2:0], as shown in Figure 82. DOUT[8:1] then becomes the modulator data stream outputs for each channel and SCLK becomes the modulator clock output. The DRDY/FSYNC pin becomes an unused output and can be ignored. The normal operation of the Frame-Sync and SPI interfaces is disabled, and the functionality of SCLK changes from an input to an output, as shown in Figure 82.

Table 18. Modulator Output Clock Frequencies

MODE [1:0]	CLKDIV	MODULATOR CLOCK OUTPUT (SCLK)	DVDD (mA)
00	1	f _{CLK} /4	8
01	1	f _{CLK} /4	7
10	1	f _{CLK} /8	4
10	0	f _{CLK} /4	4
11	1		1
11	0	f _{CLK} /8	1

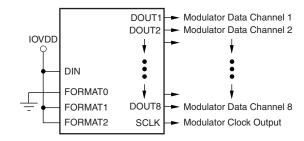


Figure 82. Modulator Output



In modulator output mode, the frequency of the modulator clock output (SCLK) depends on the mode selection of the ADS1278. Table 18 lists the modulator clock output frequency and DVDD current versus device mode.

Figure 83 shows the timing relationship of the modulator clock and data outputs.

The data output is a modulated 1s density data stream. When $V_{IN} = +V_{REF}$, the 1s density is approximately 80% and when $V_{IN} = -V_{REF}$, the 1s density is approximately 20%.

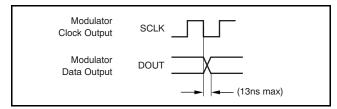


Figure 83. Modulator Output Timing

PIN TEST USING TEST[1:0] INPUTS

The test mode feature of the ADS1278 allows continuity testing of the digital I/O pins. In this mode, the normal functions of the digital pins are disabled and routed to each other as pairs through internal logic, as shown in Table 19. The pins in the left column drive the output pins in the right column. **Note:** some of the digital input pins become outputs; these outputs must be accommodated in the design. The analog input, power supply, and ground pins all remain connected as normal. The test mode is engaged by setting the pins TEST [1:0] = 11. For normal converter operation, set TEST[1:0] = 00. Do not use '01' or '10'.

Table 19. Test Mode Pin Map (TEST[1:0] = 11)

TEST MOI	DE PIN MAP
INPUT PINS	OUTPUT PINS
PWDN1	DOUT1
PWDN2	DOUT2
PWDN3	DOUT3
PWDN4	DOUT4
PWDN5	DOUT5
PWDN6	DOUT6
PWDN7	DOUT7
PWDN8	DOUT8
MODE0	DIN
MODE1	SYNC
FORMAT0	CLKDIV
FORMAT1	FSYNC/DRDY
FORMAT2	SCLK

VCOM OUTPUT

The VCOM pin provides a voltage output equal to AVDD/2. The intended use of this output is to set the output common-mode level of the analog input drivers. The drive capability of the output is limited; therefore, the output should only be used to drive high-impedance nodes (> 1 M Ω). In some cases, an external buffer may be necessary. A 0.1- μ F bypass capacitor is recommended to reduce noise pickup.

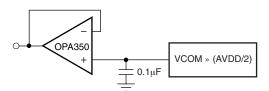


Figure 84. VCOM Output



APPLICATION INFORMATION

To obtain the specified performance from the ADS1278, the following layout and component quidelines should be considered.

- 1. Power Supplies: The device requires three power supplies for operation: DVDD, IOVDD, and AVDD. The allowed range for DVDD is 1.65 V to 1.95 V; the range of IOVDD is 1.65 V to 3.6 V; AVDD is restricted to 4.75 V to 5.25 V. For all supplies, use a 10-µF tantalum capacitor, bypassed with a 0.1-µF ceramic capacitor, placed close to the device pins. Alternatively, a single 10-µF ceramic capacitor can be used. The supplies should be relatively free of noise and should not be shared with devices that produce voltage spikes (such as relays, LED display drivers, etc.). If a switching power-supply source is used, the voltage ripple should be low (less than 2 mV) and the switching frequency outside the passband of the converter.
- Ground Plane: A single ground plane connecting both AGND and DGND pins can be used. If separate digital and analog grounds are used, connect the grounds together at the converter.
- 3. **Digital Inputs:** It is recommended to source-terminate the digital inputs to the device with 50- Ω series resistors. The resistors should be placed close to the driving end of digital source (oscillator, logic gates, DSP, etc.) This placement helps to reduce ringing on the digital lines (ringing may lead to degraded ADC performance).
- 4. Analog/Digital Circuits: Place analog circuitry (input buffer, reference) and associated tracks together, keeping them away from digital circuitry (DSP, microcontroller, logic). Avoid crossing digital tracks across analog tracks to reduce noise coupling and crosstalk.
- 5. Reference Inputs: It is recommended to use a minimum 10-μF tantalum with a 0.1-μF ceramic capacitor directly across the reference inputs, VREFP and VREFN. The reference input should be driven by a low-impedance source. For best performance, the reference should have less than 3 μV_{RMS} in-band noise. For references with noise higher than this level, external reference filtering may be necessary.

- 6. Analog Inputs: The analog input pins must be differentially driven to achieve specified performance. A true differential driver or transformer (ac applications) can be used for this purpose. Route the analog inputs tracks (AINP, AINN) as a pair from the buffer to the converter using short, direct tracks and away from digital tracks. A 1-nF to 10-nF capacitor should be used directly across the analog input pins, AINP and AINN. A low-k dielectric (such as COG or film type) should be used to maintain low THD. Capacitors from each analog input to ground can be used. They should be no larger than 1/10 the size of the difference capacitor (typically 100 pF) to preserve the ac common-mode performance.
- 7. Component Placement: Place the power supply, analog input, and reference input bypass capacitors as close as possible to the device pins. This layout is particularly important for small-value ceramic capacitors. Larger (bulk) decoupling capacitors can be located farther from the device than the smaller ceramic capacitors.

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PACKAGING INFORMATION

Orderable part number	Status	Material type	Package Pins	Package qty Carrier	RoHS	Lead finish/ Ball material	MSL rating/ Peak reflow	Op temp (°C)	Part marking (6)
	. , ,				. , ,	(4)	(5)		` '
ADS1278HPAP	Active	Production	HTQFP (PAP) 64	160 JEDEC TRAY (10+1)	Yes	NIPDAU	Level-4-260C-72 HR	-55 to 175	ADS1278
ADS1278HPAPG4	Active	Production	HTQFP (PAP) 64	160 JEDEC TRAY (10+1)	·		Level-4-260C-72 HR	-55 to 210	ADS1278
ADS1278SHFQ	Active	Production	CFP (HFQ) 84				-55 to 210	ADS1278 SHFQ	
ADS1278SHKP	Active	Production	CFP (HKP) 84	1 OTHER			Call TI	-55 to 210	ADS1278 SHKP
ADS1278SKGDA	Active	Production	XCEPT (KGD) 0	36 OTHER	Yes	Call TI	N/A for Pkg Type	-55 to 210	

⁽¹⁾ Status: For more details on status, see our product life cycle.

- (3) RoHS values: Yes, No, RoHS Exempt. See the TI RoHS Statement for additional information and value definition.
- (4) Lead finish/Ball material: Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.
- (5) MSL rating/Peak reflow: The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.
- (6) Part marking: There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

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⁽²⁾ Material type: When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

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In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

OTHER QUALIFIED VERSIONS OF ADS1278-HT:

Catalog: ADS1278

● Enhanced Product : ADS1278-EP

• Space : ADS1278-SP

NOTE: Qualified Version Definitions:

• Catalog - TI's standard catalog product

• Enhanced Product - Supports Defense, Aerospace and Medical Applications

• Space - Radiation tolerant, ceramic packaging and qualified for use in Space-based application



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TRAY



Chamfer on Tray corner indicates Pin 1 orientation of packed units.

*All dimensions are nominal

Device	Package Name	Package Type	Pins	SPQ	Unit array matrix	Max temperature (°C)	L (mm)	W (mm)	Κ0 (μm)	P1 (mm)	CL (mm)	CW (mm)
ADS1278HPAP	PAP	HTQFP	64	160	8 x 20	150	315	135.9	7620	15.2	13.1	13
ADS1278HPAPG4	PAP	HTQFP	64	160	8 x 20	150	315	135.9	7620	15.2	13.1	13

10 x 10, 0.5 mm pitch

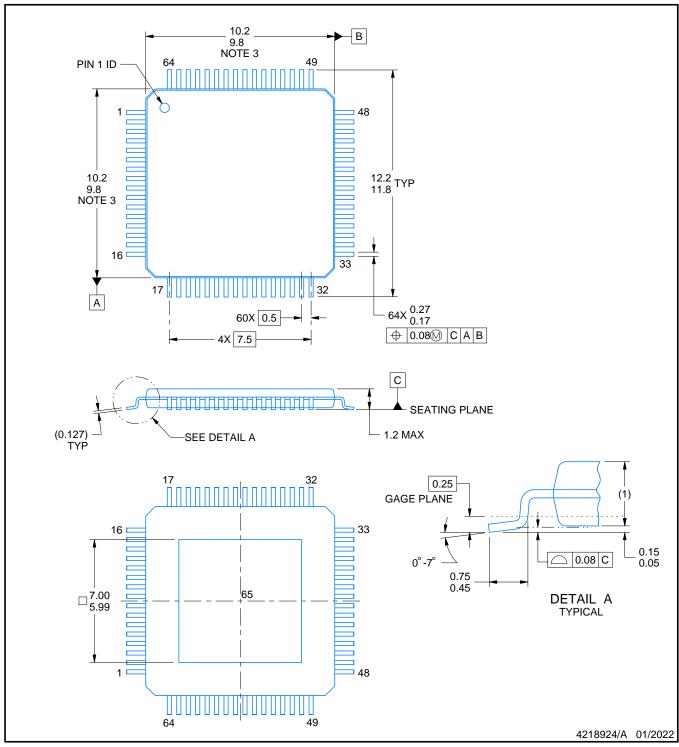
QUAD FLATPACK

This image is a representation of the package family, actual package may vary. Refer to the product data sheet for package details.





PLASTIC QUAD FLATPACK



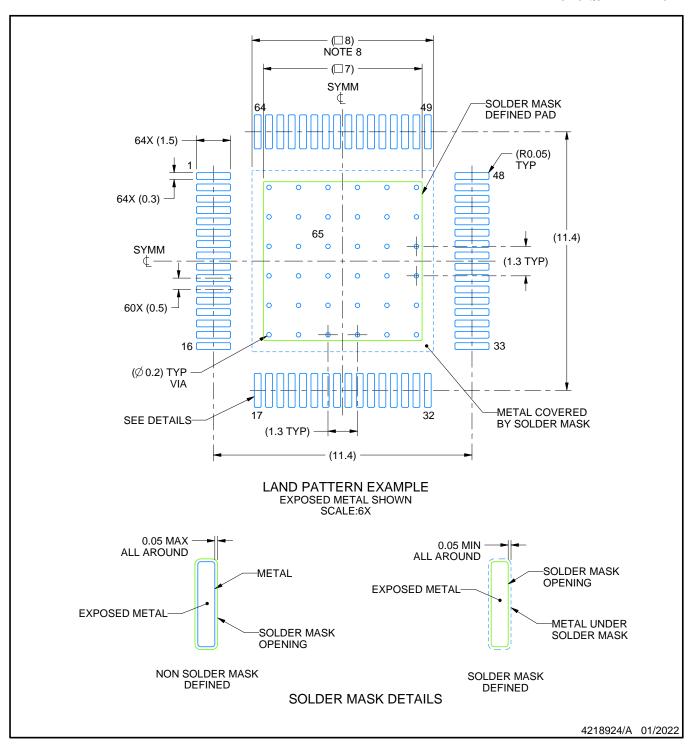
NOTES:

PowerPAD is a trademark of Texas Instruments.

- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
 2. This drawing is subject to change without notice.
- 3. This dimension does not include mold flash, protrusions, or gate burrs.
- 4. Strap features may not be present.
- 5. Reference JEDEC registration MS-026.



PLASTIC QUAD FLATPACK

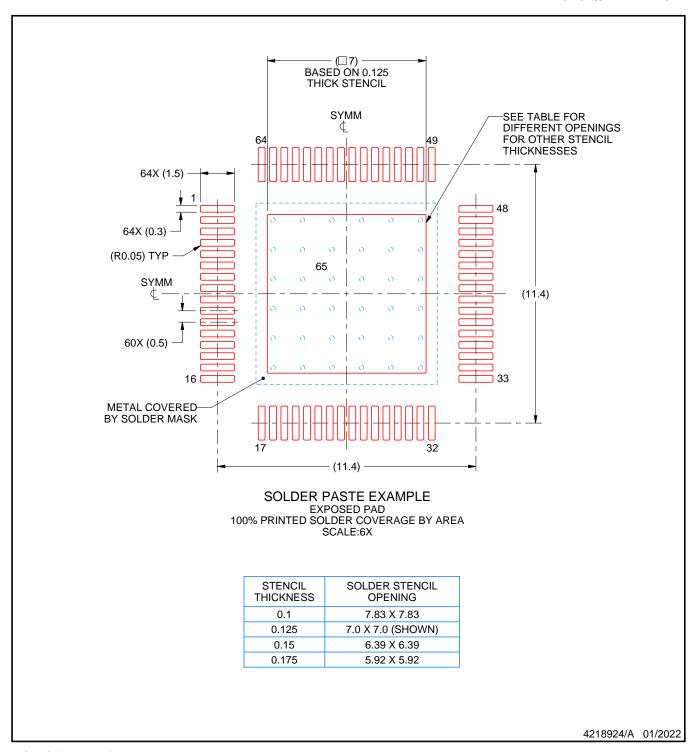


NOTES: (continued)

- 6. Publication IPC-7351 may have alternate designs.
- 7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.
- 8. This package is designed to be soldered to a thermal pad on the board. See technical brief, Powerpad thermally enhanced package, Texas Instruments Literature No. SLMA002 (www.ti.com/lit/slma002) and SLMA004 (www.ti.com/lit/slma004).
- Vias are optional depending on application, refer to device data sheet. It is recommended that vias under paste be filled, plugged or tented.
- 10. Size of metal pad may vary due to creepage requirement.



PLASTIC QUAD FLATPACK

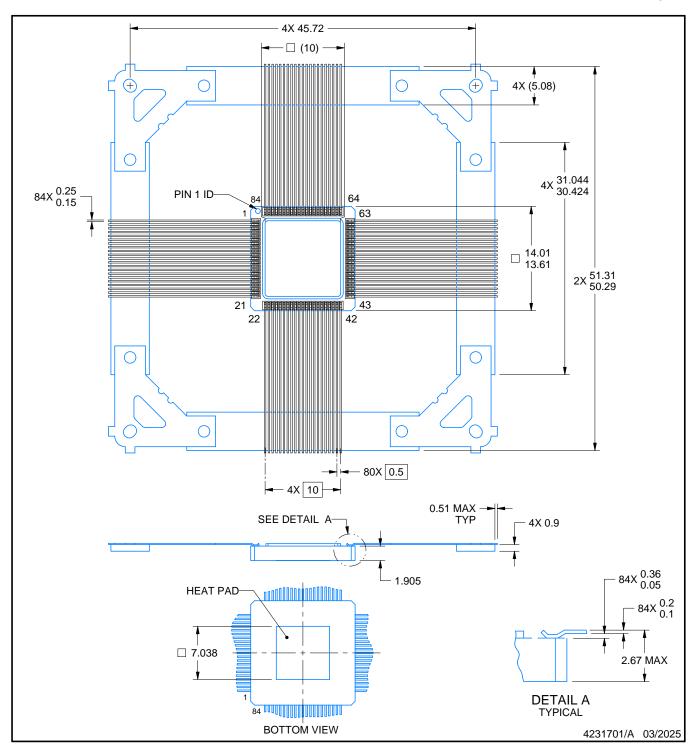


NOTES: (continued)

- 11. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
- 12. Board assembly site may have different recommendations for stencil design.







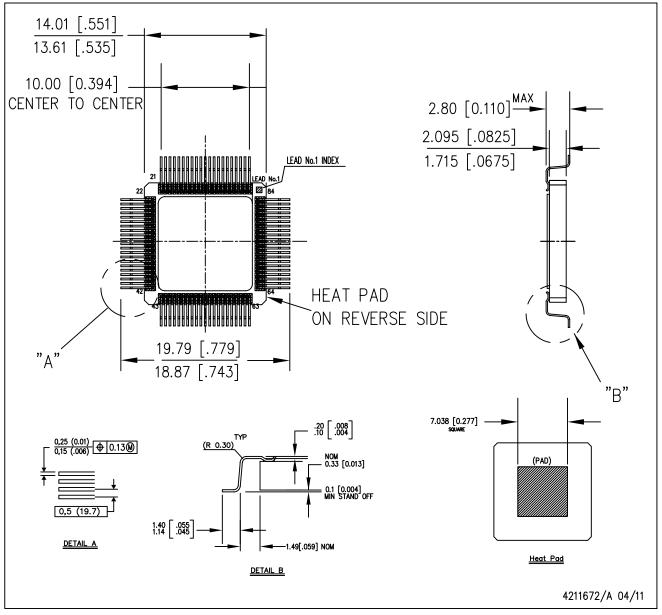
NOTES:

- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
- This drawing is subject to change without notice.
 Ceramic quad flatpack with flat leads brazed to non-conductive tie bar carrier.
 This package is hermetically sealed with a metal lid.
- 5. The leads are gold plated and can be solder dipped.
- 6. The lid and the heat sink are connected to ground leads.



HKP (S-CQFP-G84)

CERAMIC QUAD FLATPACK - GULL WING



NOTES:

- A. All linear dimensions are in millimeters (inches).
- B. This drawing is subject to change without notice.
- C. Ceramic quad flatpack with formed leads.
- D. This package is hermetically sealed with a metal lid.
- E. The leads are gold plated and can be solderdipped.
- F. Lid and heat pad are electrically connected.



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Last updated 10/2025